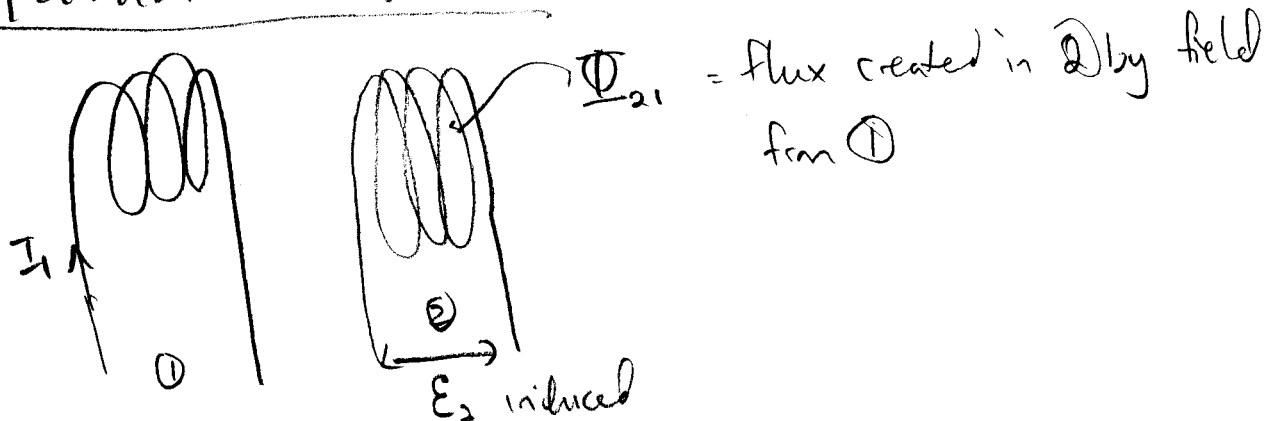


Chapter 30 Inductance, Electromagnetic Oscillations, + AC circuits

Mutual Inductance



flux in 2 $\propto I_1$

$N_2 \Phi_{21} \propto I_1$

$$\frac{N_2 \Phi_{21}}{I_1} = M_{21}$$

prop. constant, called Mutual Inductance

$\epsilon_2 = -N_2 \frac{d\Phi_{21}}{dt}$ but $\Phi_{21} = \frac{M_{21} I_1}{N_2}$

$= -N_2 \frac{d}{dt} \left(\frac{M_{21} I_1}{N_2} \right)$

$$\epsilon_2 = -M_{21} \frac{dI_1}{dt}$$

M_{21} constant in time
↳ depends on geometry

likewise

$\epsilon_1 = -M_{12} \frac{dI_2}{dt}$

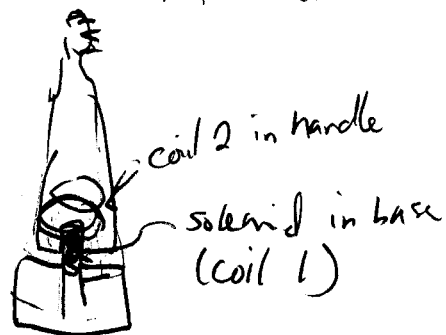
it turns out $M_{12} = M_{21}$

$$\mathcal{E}_1 = -M \frac{dI_2}{dt} \quad \mathcal{E}_2 = -M \frac{dI_1}{dt}$$

unit for M is henry H $1 H = 1 V \cdot s / A = 1 \Omega \cdot s$

ex ample: electric tooth brush charger

given: base is solenoid of length l , N_B turns, and area A , current I . The handle has N_H turns. find the mutual inductance



$$M = \frac{N_H \Phi_{BH}}{I} = \frac{N_H BA}{I} \quad B = \mu_0 \frac{N_B I}{l}$$

$$M = \frac{\mu_0 N_B N_H A}{l}$$

Self-Inductance



As current increases B created by current increases and so does flux ($\Phi_B = \vec{B} \cdot \vec{A}$)
This induces an emf which resists the increasing current.

$$\mathcal{E} = -N \frac{d\Phi_B}{dt}$$

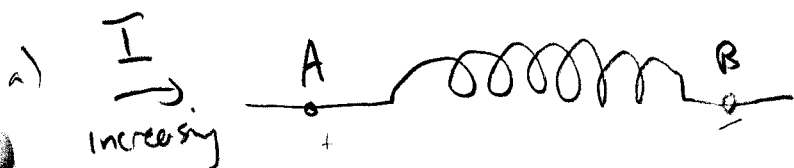
define $L = \frac{N\Phi_B}{I} \rightarrow \Phi_B = \frac{LI}{N}$
↑
self inductance

$$\mathcal{E} = -N \frac{d}{dt} \left(\frac{LI}{N} \right)$$

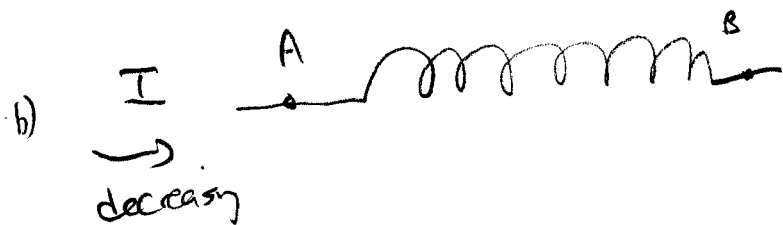
$$\mathcal{E} = -L \frac{dI}{dt}$$

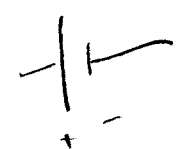
A coil in a circuit is called an inductor

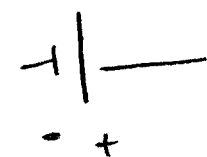




which way is end?



a) like  makes current flow in opposite direction

b) like 

eg tesla coil
to demo

Energy Stored in a Magnetic field

$$P = IV \Rightarrow P = IE = L \frac{dI}{dt}$$

$$dW = P dt = L I dI = L I dI$$

$$W = \int dW = \int L I dI = \frac{L I^2}{2}$$

work done = energy stored

$$U = \frac{1}{2} L I^2$$

→ similar to cap $U = \frac{1}{2} C V^2$

in terms of magnetic field

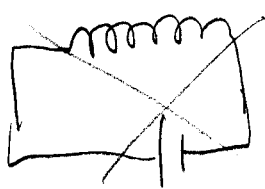
$$B = \mu_0 I n = \mu_0 I \frac{N}{l} \rightarrow I = \frac{B l}{\mu_0 N}$$

$$L = N \frac{\Phi_B}{I} = \frac{N \mu_0 N I A}{l I} = \frac{N^2 \mu_0 A}{l}$$

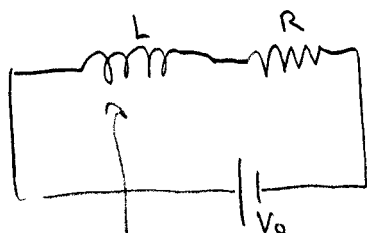
$$U = \frac{1}{2} \left(\frac{N^2 \mu_0 A}{l} \right) \left(\frac{B l}{\mu_0 N} \right)^2 = \frac{1}{2} \frac{B^2}{\mu_0} (A l) \text{ volume!}$$

energy density
$$u = \frac{1}{2} \frac{B^2}{\mu_0}$$

Induction in Circuits



impossible - wires have resistance



"LR circuit"

"Charging"

recall $\mathcal{E} = -L \frac{dI}{dt}$

loop rule: $V_0 - L \frac{dI}{dt} - IR = 0$

$$L \frac{dI}{dt} + IR = V_0$$

separate variables:

$$L dI = (V_0 - IR) dt$$

$$\int_{I=0}^I \frac{dI}{V_0 - IR} = \int_0^t \frac{dt}{L}$$

$$-\frac{1}{R} \ln(V_0 - IR) \Big|_0^I = \frac{t}{L}$$

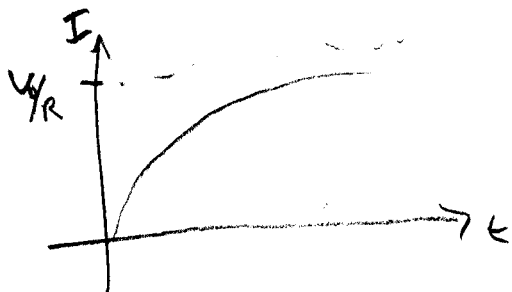
$$\ln\left(\frac{V_0 - IR}{V_0}\right) = -\frac{t}{L} R$$

$$1 - \frac{IR}{V_0} = \frac{V_0 - IR}{V_0} = e^{-\frac{tR}{L}}$$

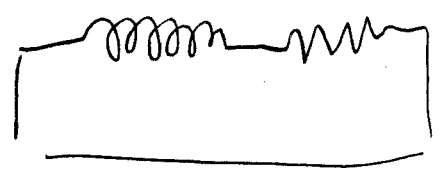
time constant

$$I = \frac{V_0}{R} (1 - e^{-t/\tau})$$

where $\tau = \frac{L}{R}$



take out battery: at $t=0$



$$\cancel{V_0} - IR - L \frac{dI}{dt} = 0$$

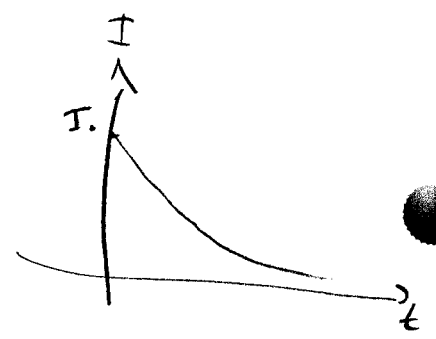
$$-IR = -L \frac{dI}{dt}$$

$$-\int_0^t \frac{R}{L} dt = \int_{I_0}^I \frac{1}{I} dI$$

$$-\frac{R}{L} t = \ln\left(\frac{I}{I_0}\right)$$

$$e^{-tR/L} = I/I_0$$

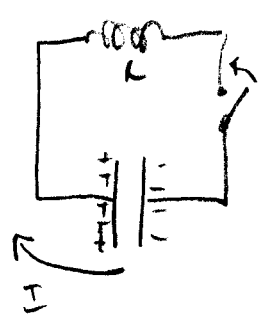
$$I = I_0 e^{-t/\tau} \quad \tau = L/R$$



Add capacitors LR C circuits.

first: consider idealized circuit - LC:

charged capacitor + inductor =



switch closed @ $t=0$

$$\text{loop: } -L \frac{dI}{dt} + \frac{Q}{C} = 0$$

$$I = -\frac{dQ}{dt}$$

charge leaving capacitor is creating the current

$$-L \frac{d}{dt} \left(-\frac{dQ}{dt} \right) + \frac{Q}{C} = 0$$

divide by L

$$\frac{d^2 Q}{dt^2} + \frac{Q}{CL} = 0$$

2nd order diffy Q

$$\frac{d^2 Q}{dt^2} = -\frac{1}{CL} Q$$

$$\Rightarrow Q = Q_0 \cos(\omega t + \phi)$$

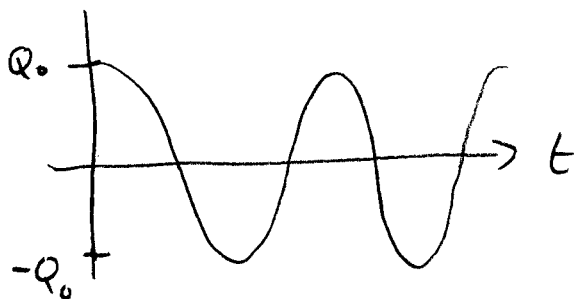
$$\text{check: } \frac{dQ}{dt} = Q_0 \omega (-\sin(\omega t + \phi))$$

$$\frac{d^2 Q}{dt^2} = -Q_0 \omega^2 \cos(\omega t + \phi)$$

$$= -\omega^2 Q$$

$$\text{so } \frac{1}{LC} = \omega^2 \Rightarrow \omega = \sqrt{\frac{1}{LC}}$$

← frequency of the circuit



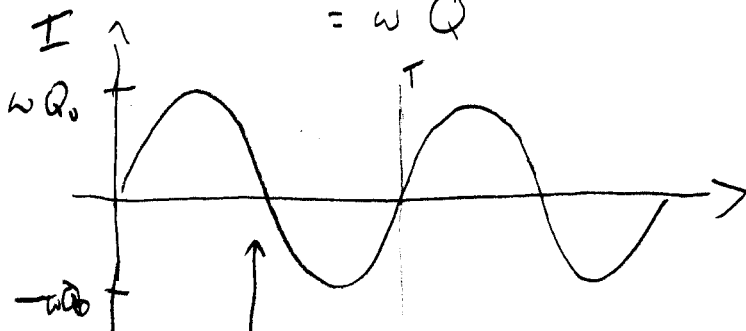
charge on the capacitor oscillating

what about I?

$$I = -\frac{dQ}{dt} \Rightarrow \frac{d}{dt} (Q_0 \cos(\omega t + \phi))$$

$$= \omega Q_0 \sin(\omega t + \phi)$$

$$= \omega Q$$



current in the inductor

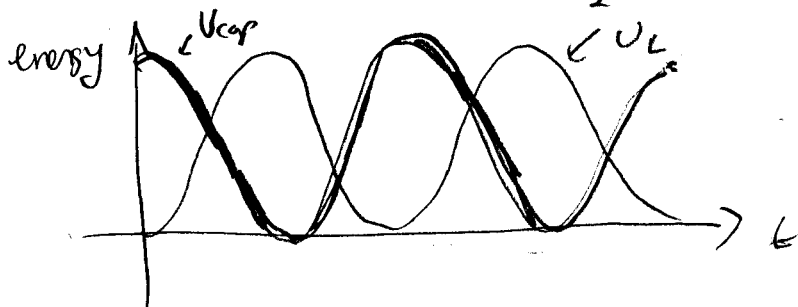
current reverses - (discharging, charging, etc. ... on an

what's happening to the energy?

$$U_{\text{cap}} = \frac{1}{2} \frac{Q^2}{C} = \frac{Q_0^2}{2C} \cos^2(\omega t + \phi)$$

$$U_{\text{induct}} = \frac{1}{2} LI^2 = L \frac{\omega^2 Q_0^2}{2} \sin^2(\omega t + \phi) = \frac{Q_0^2}{2C} \sin^2(\omega t + \phi)$$

$$\omega^2 = \frac{1}{LC}$$



total energy

$$U_{\text{total}} = \frac{Q_0^2}{2C} \cos^2(\omega t + \phi) + \frac{Q_0^2}{2C} \sin^2(\omega t + \phi)$$

$$= \frac{Q_0^2}{2C} \left(\underbrace{\cos^2(\omega t + \phi) + \sin^2(\omega t + \phi)}_{=1} \right)$$

$$= \frac{Q_0^2}{2C} \leftarrow \text{constant!}$$

✓ energy conserved

Real life: LRC

→ guess what will happen?

loop:

$$-L \frac{dI}{dt} - IR + \frac{Q}{C} = 0$$

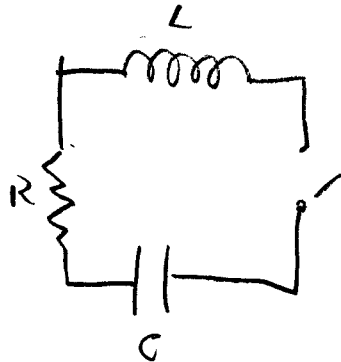
$$I = -\frac{dQ}{dt}$$

$$+L \frac{d^2 Q}{dt^2} + R \frac{dQ}{dt} + \frac{Q}{C} = 0$$

$$\frac{d^2 Q}{dt^2} + \frac{R}{L} \frac{dQ}{dt} + \frac{Q}{LC} = 0$$

$$m \frac{d^2 x}{dt^2} + b \frac{dx}{dt} + kx = 0$$

← damped harmonic oscillator



Solution $e^{\lambda t}$

$$L \frac{d^2 e^{\lambda t}}{dt^2} + R \frac{d e^{\lambda t}}{dt} + \frac{1}{C} e^{\lambda t} = 0$$

$$L \lambda^2 e^{\lambda t} + R \lambda e^{\lambda t} + \frac{1}{C} e^{\lambda t} = 0$$

$$L \lambda^2 + R \lambda + \frac{1}{C} = 0$$

$$\lambda = -R \pm \sqrt{R^2 - 4 \frac{R}{C}}$$

if $R^2 > 4 \frac{R}{C}$ \uparrow real #, "over damped"

$$Q = C_1 e^{(-R + \sqrt{R^2 - 4 \frac{R}{C}})t} + C_2 e^{(-R - \sqrt{R^2 - 4 \frac{R}{C}})t}$$

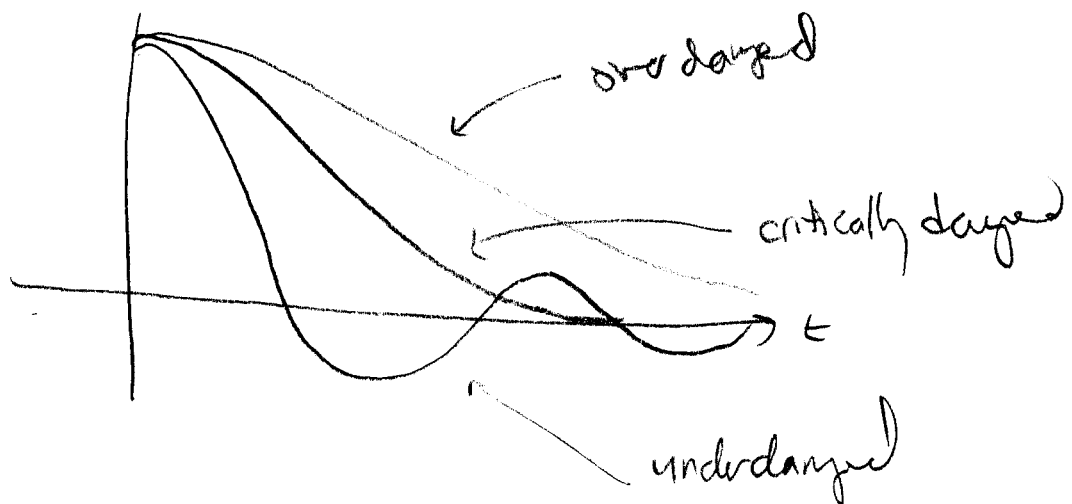
$$= e^{-Rt} \left[C_1 e^{\sqrt{R^2 - 4 \frac{R}{C}}t} + C_2 e^{-\sqrt{R^2 - 4 \frac{R}{C}}t} \right]$$

if $R^2 < 4 \frac{R}{C}$ imaginary roots \Rightarrow oscillating solution
"under damped"

$$Q = Q_0 e^{-\frac{R}{2L}t} \cos(\omega' t + \phi)$$

$$\omega' = \sqrt{\frac{1}{LC} - \frac{R^2}{4L^2}}$$

if $R^2 = 4 \frac{R}{C}$ $Q = C_1 e^{\lambda t} + C_2 \lambda e^{\lambda t}$



LRC-6

Example: At $t=0$, a 40-mH inductor is placed in series w/ a resistance $R=3\ \Omega$ and a charged cap $C=4.8\ \mu\text{F}$.

(a) Will this circuit oscillate?

sol is it underdamped? $R^2 < \frac{4L}{C}$?

$$R^2 = 9\ \Omega^2$$

$$\frac{4L}{C} = \frac{4(0.04)}{4.8 \times 10^{-6}} = 3.3 \times 10^4\ \Omega^2$$

b) Determine the frequency

$$f' = \frac{\omega'}{2\pi} = \frac{1}{2\pi} \sqrt{\frac{1}{LC} - \frac{R^2}{4L^2}} = 3.6 \times 10^2\ \text{Hz}$$

c) What ~~time~~ is the time req. for the charge amplitude to drop to half its steady value?

$$Q = \underbrace{Q_0 e^{-\frac{R}{2L}t}}_{\text{amplitude}} \cos(\omega't + \phi)$$

$$\frac{1}{2}Q_0 = Q_0 e^{-\frac{R}{2L}t}$$

$$\ln \frac{1}{2} = -\frac{R}{2L}t \rightarrow t = \frac{2L}{R} \ln 2 = 18\ \text{ms}$$

d) what value of R will make the circuit non-oscillatory?

critically damped when

$$R^2 = \frac{4L}{C} = 3.3 \times 10^4\ \Omega^2$$

$$R = 180\ \Omega$$

so $R \geq 180\ \Omega$ for no oscillations

AC Source

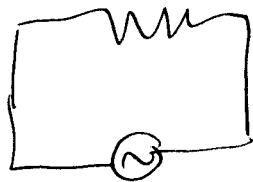
what happens if the source is oscillating?



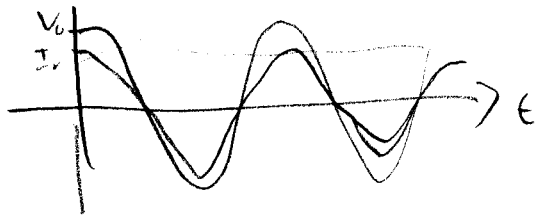
$$I = I_0 \cos 2\pi f t = I_0 \cos \omega t$$

$$\left(V_{rms} = \frac{V_0}{\sqrt{2}} \quad I_{rms} = \frac{I_0}{\sqrt{2}} \right)$$

I resistor:



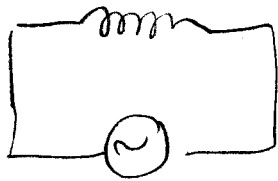
$$V = IR = I_0 R \cos \omega t = V_0 \cos \omega t$$



current and voltage
"in phase"
in a resistor

$$\bar{P} = I\bar{V} = I_{rms}^2 R = V_{rms}^2 / R$$

II inductor



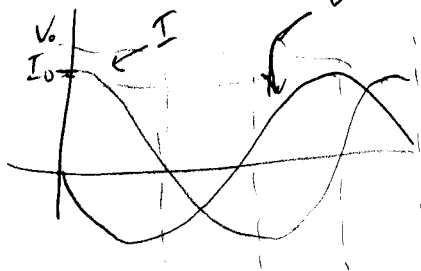
loop rule $V - L \frac{dI}{dt} = 0$

$$V = L \frac{dI}{dt} = L \frac{d}{dt} (I_0 \cos \omega t)$$

$$= L I_0 (-\omega) \sin \omega t$$

$$= -\omega L I_0 \sin(\omega t) \quad \leftarrow \sin \theta = -\cos(\theta + 90)$$

$$V = \omega L I_0 \cos(\omega t + 90)$$



voltage + current 90° out of phase

current lags voltage by 90° in an inductor

Similarly define X_c capacitive reactance

$$V_0 = I_0 X_c \quad \leftarrow \text{* Applies only at max w rms values}$$

$$X_c = \frac{V_0}{I_0} = \frac{\frac{I_0}{\omega C}}{I_0} = \frac{1}{\omega C} = \frac{1}{2\pi f C}$$

reactances and resistances are examples of impedance

Put it all together: LRC series AC circuit

(who imagined this one up? ---)

$$V - V_R - V_L + V_C = 0$$

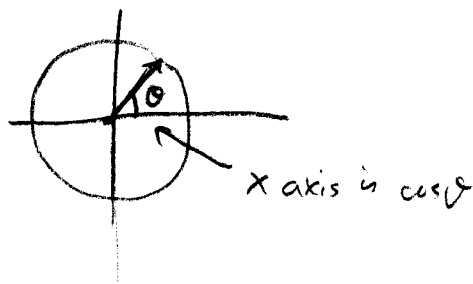
$$V = V_R + V_L + V_C$$

things are all out of phase...
gets messy...

technique: Phasor Diagram



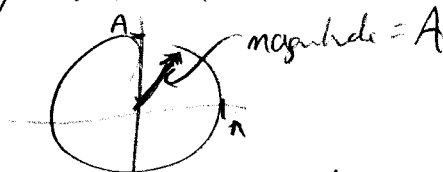
consider the unit circle:



$$\cos \theta = \frac{\text{adj}}{\text{hyp}} = \frac{x}{1} = x$$

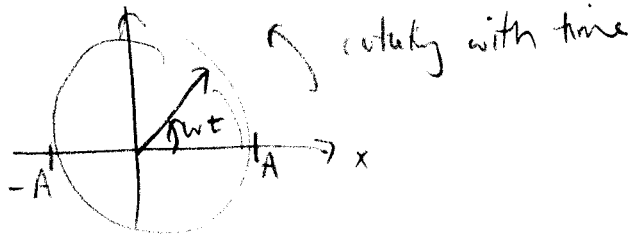
$$\sin \theta = \frac{\text{opp}}{\text{hyp}} = \frac{y}{1} = y$$

A $\cos \theta$ could be rep by unit x A circle.

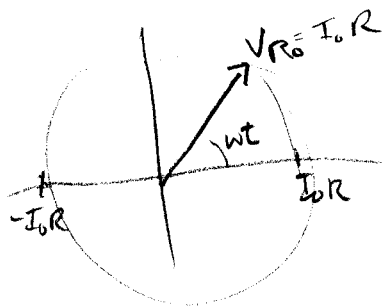


$A \cos \theta$ = projection of vector onto x-axis at any θ

if $\theta = \omega t$ (θ changing at some rate ω wrt time)

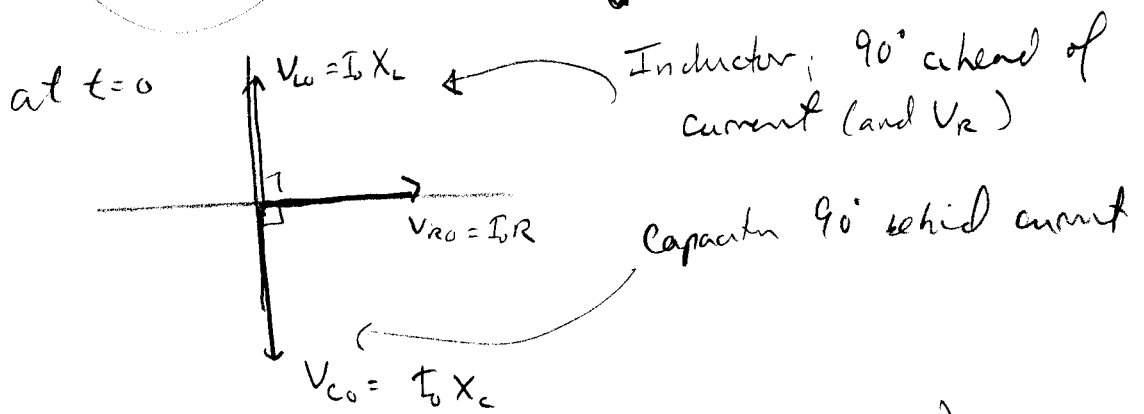


Similarly, we can draw arrows for voltage in our circuit!

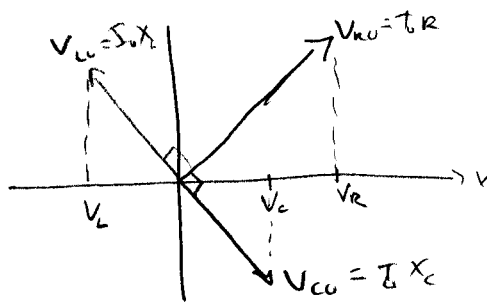


$$V_R = V_0 \cos \omega t = I_0 R \cos \omega t$$

(in phase w/ current)



After a time t : (rotate whole system)

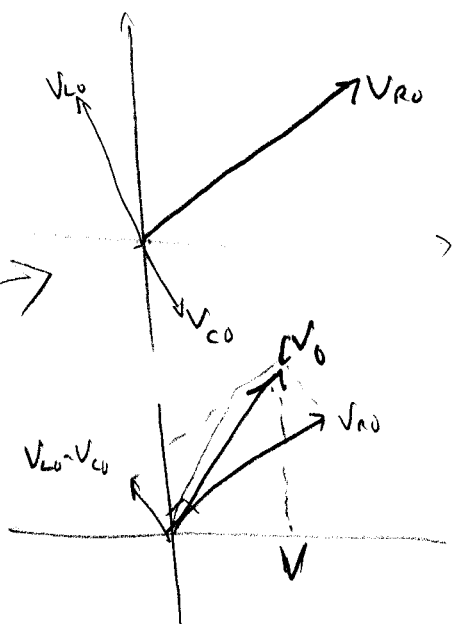


← projections on x-axis represent voltages at any given point in time

What is the voltage across the source?

$$V = V_R + V_L + V_C$$

Choose
 $X_L > X_C$
 $V_L > V_C$
 $I_L > I_C$



add vectors

$$V = V_0 \cos(\omega t + \phi)$$

↑
 some angle, by which
 it is out of phase
 with the current

$$V_0 = \sqrt{V_{R0}^2 + (V_{L0} - V_{C0})^2}$$

$$= \sqrt{I_0 R^2 + (I_0 X_L - I_0 X_C)^2}$$

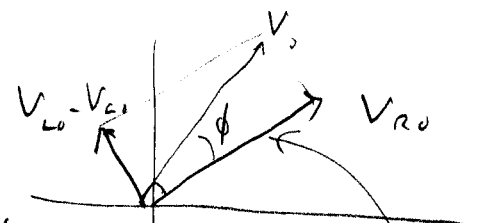
$$V_0 = I_0 \sqrt{R^2 + (X_L - X_C)^2}$$

define Z total impedance

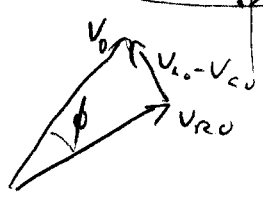
$$V_0 = I_0 Z$$

$$Z = \sqrt{R^2 + (X_L - X_C)^2} = \sqrt{R^2 + \left(\omega L - \frac{1}{\omega C}\right)^2}$$

what is ϕ ?



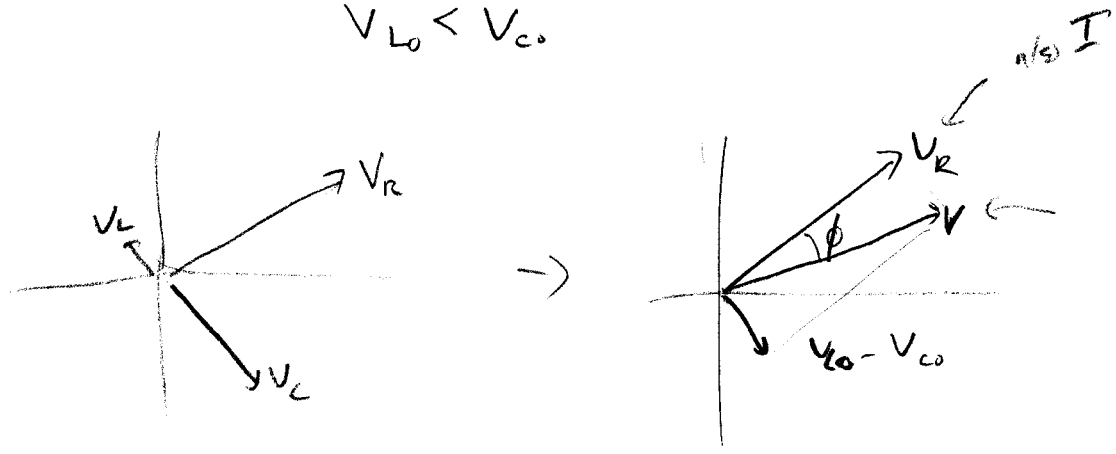
triangle



$$\tan \phi = \frac{V_{L0} - V_{C0}}{V_{R0}} = \frac{I_0 (X_L - X_C)}{I_0 R} = \frac{X_L - X_C}{R}$$

$$\text{Or } \cos \phi = \frac{V_{R0}}{V_0} = \frac{I_0 R}{I_0 Z} = \frac{R}{Z}$$

what if ~~$X_L > X_C$~~ $X_L < X_C$
 $V_L < V_C$



now current leads the voltage

for $X_L < X_C$
current leads the voltage by ϕ

for $X_L > X_C$
current lags the voltage by ϕ

Example 30-11