

Stellar photometry

User guides for IDL
photometry routines:

ATV
Aperture photometry

XStarFinder
PSF-fitter/deconvolver
for photometry in
crowded fields

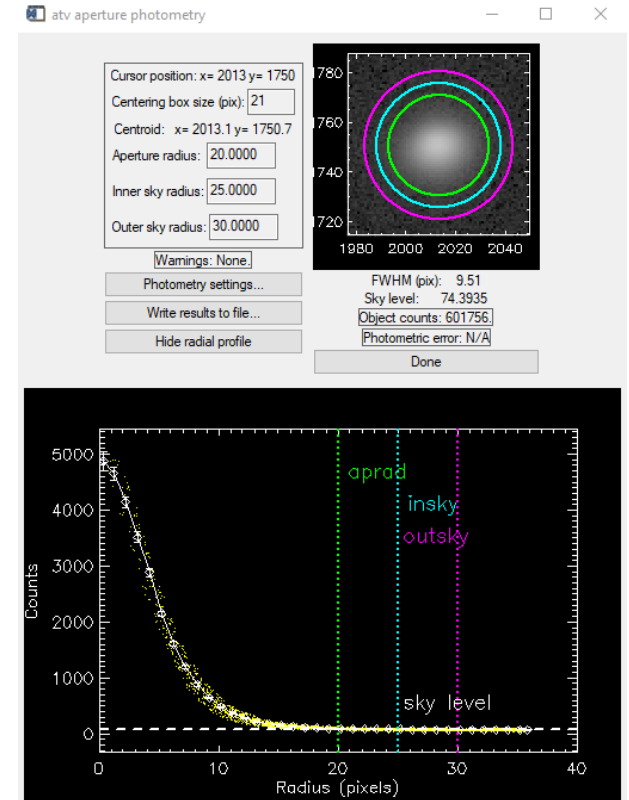
M 15, LRGB,
from Mees.

For calibration stars and uncrowded fields

If stars in an image are not very close together, most of us will measure the stellar fluxes or magnitudes using **aperture photometry**.

- ❑ Add the DNs from each pixel within
 - an aperture centered on the star, with aperture radius large enough to contain all the stellar flux, and
 - within an annulus centered on the star that contains nothing but background emission.

- ❑ Multiply the annulus DNs by ratio of number of pixels in aperture and annulus, and subtract from aperture DNs.
 - This is automatic, in ATV.



For calibration stars and uncrowded fields (continued)

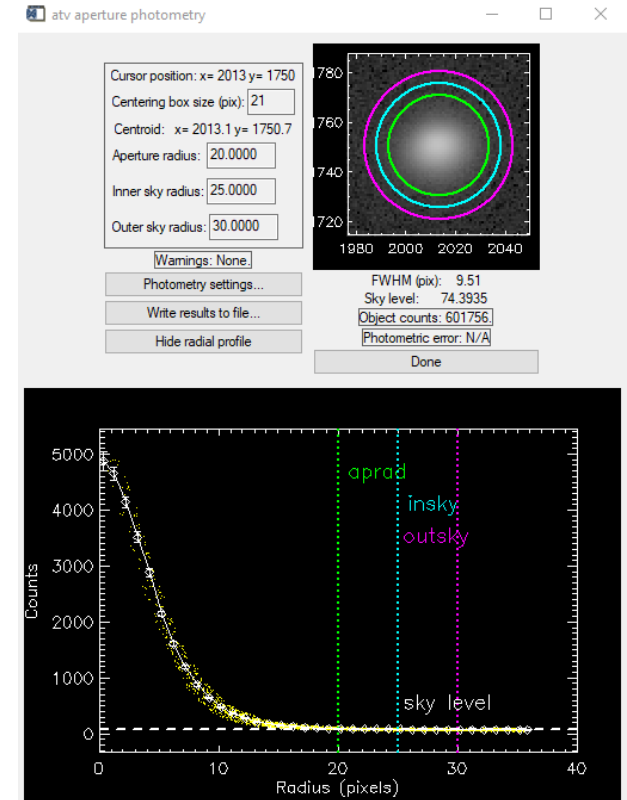
- If the target is a calibration star, this is one measurement of the flux density-to-DN conversion ratio, C : as discussed in Lesson 2:

$$C = \frac{F}{DN_{\text{aperture}} - DN_{\text{sky}}} = \frac{10^{-m/2.5} F_0}{DN_{\text{aperture}} - DN_{\text{sky}}}$$

where m is the star's magnitude in the filter that's in use, and F_0 the zero-magnitude flux density in that filter, corrected for atmospheric extinction ([Lesson 2](#), page 27).

- If not, its magnitude in that filter is

$$m = 2.5 \log \left(F_0 / C \left[DN_{\text{aperture}} - DN_{\text{sky}} \right] \right) .$$



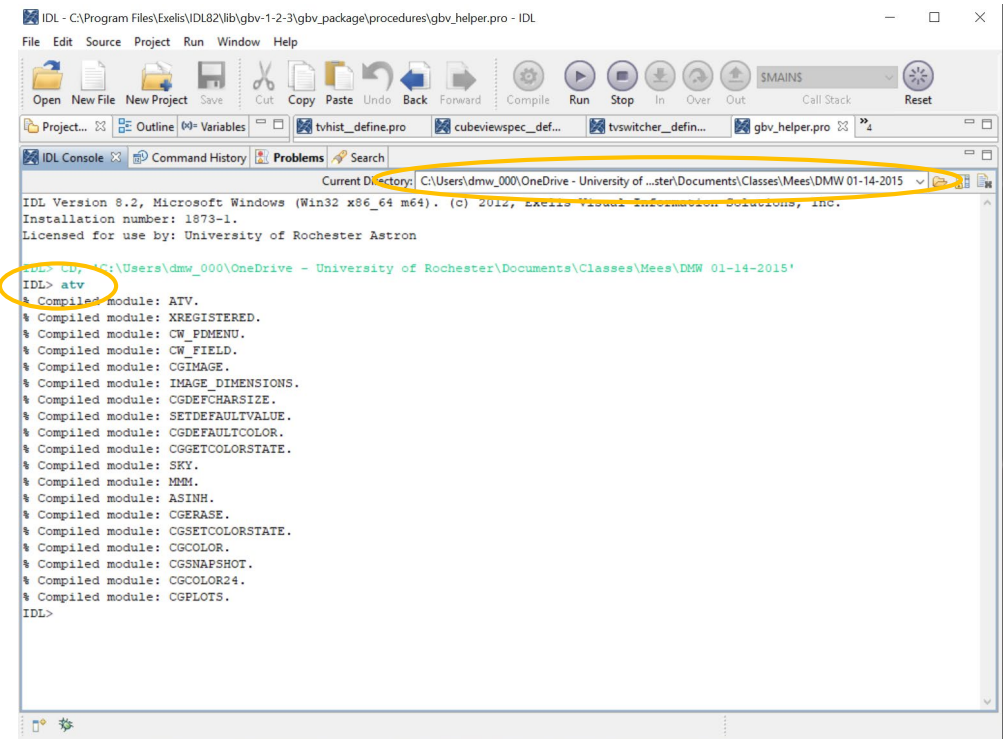
Typical aperture photometry tool: ATV

ATV, written by [Aaron Barth](#), is a widely-used IDL application for browsing images and performing aperture photometry. Here's a basic step-by-step guide.

- ❑ Start IDL.



- ❑ Browse to the directory containing the data.
- ❑ Type `atv` <enter> at the `IDL>` prompt.
- ❑ This produces the main ATV window (next page).

A screenshot of the IDL (Interactive Data Language) console window. The window title is "IDL - C:\Program Files\Exelis\IDL82\lib\gbv-1-2-3\gbv_package\procedures\gbv_helper.pro - IDL". The console shows the following text:

```
IDL Version 8.2, Microsoft Windows (Win32 x86_64 m64). (c) 2012, Exelis Visual Information Solutions, Inc.
Installation number: 1873-1.
Licensed for use by: University of Rochester Astron

C:\Users\dmw_000\OneDrive - University of Rochester\Documents\Classes\Mees\DMW 01-14-2015'
IDL> atv
% Compiled module: ATV.
% Compiled module: XREGISTERED.
% Compiled module: CW_PMENU.
% Compiled module: CW_FIELD.
% Compiled module: CGIMAGE.
% Compiled module: IMAGE_DIMENSIONS.
% Compiled module: CGDEFCHARSIZE.
% Compiled module: SETDEFAULTVALUE.
% Compiled module: CGDEFAULTCOLOR.
% Compiled module: CGSETCOLORSTATE.
% Compiled module: SKY.
% Compiled module: MMV.
% Compiled module: ASINH.
% Compiled module: CGERASE.
% Compiled module: CGSETCOLORSTATE.
% Compiled module: CGCOLOR.
% Compiled module: CGSNAPSHOT.
% Compiled module: CGCOLOR24.
% Compiled module: CGPLOTS.
IDL>
```

The "atv" command and its output are highlighted with a yellow circle. The current directory is shown as "C:\Users\dmw_000\OneDrive - University of Rochester\Documents\Classes\Mees\DMW 01-14-2015'".

ATV (continued)

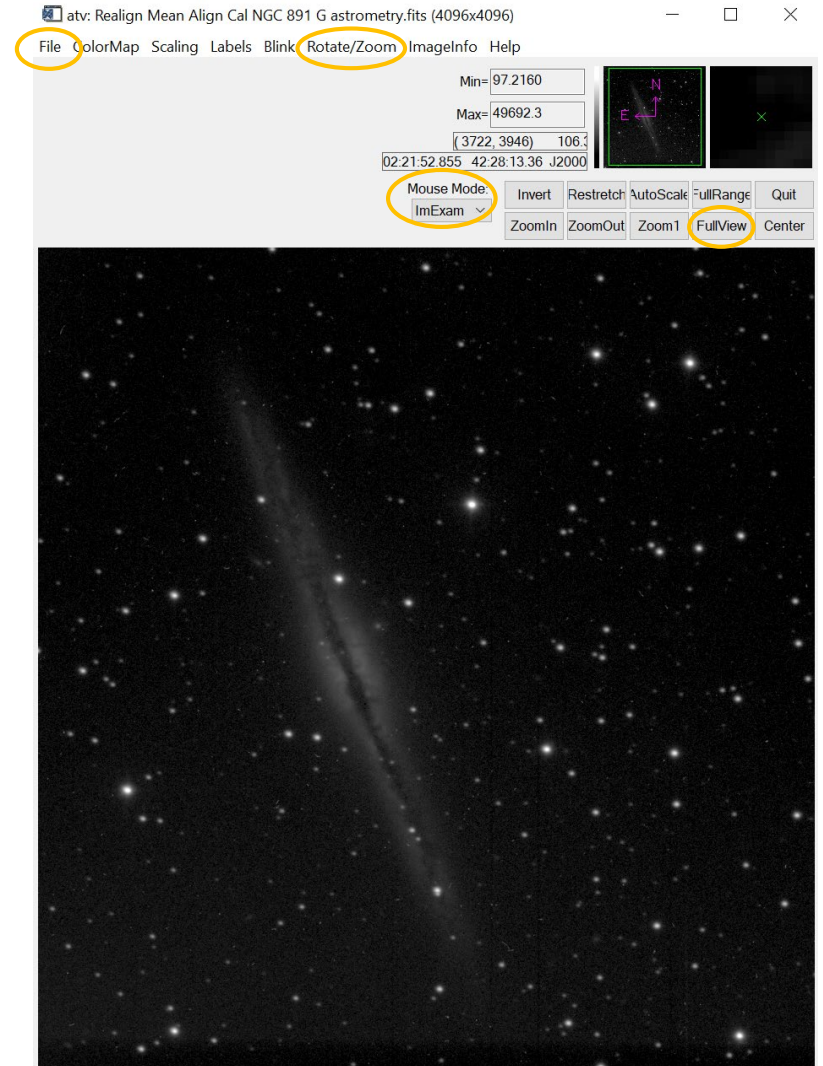
- ❑ File > ReadFits to open image
 - We presume this image is calibrated and normalized

- ❑ FullView button to see whole image

- ❑ Rotate/Zoom > Invert Y to make it right side up, if it's a Mees image

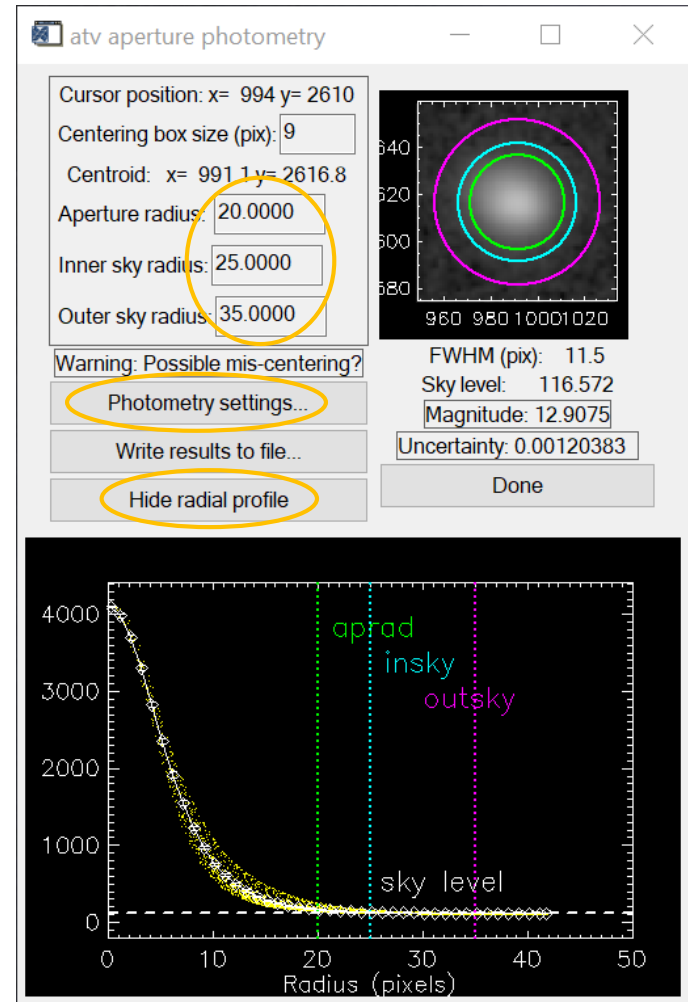
- ❑ Mouse Mode > ImExam to start photometry mode

- ❑ Click a star. This brings up the *atv* aperture photometry window.



ATV (continued)

- ❑ Click [Show radial profile](#) to see the whole window.
- ❑ Adjust the settings:
 - [Aperture radius](#), [inner](#) and [outer sky radius](#), so that aperture contains stellar flux and annulus is unlikely to contain other stars.
 - [<Enter>](#) after changing each parameter.
- ❑ [Photometry settings...](#) button brings up a dialogue by that name, with parameters to set.



ATV (continued)

- ❑ Choose your favorite among counts (DN) and magnitudes. I usually choose counts.
- ❑ If you want magnitudes, set the **Magnitude Zeropoint**, according to the DN/exposure time for zero magnitude (from your flux calibration) and the formula in this window.
- ❑ If you want photometric errors displayed, enter
 - the **CCD Gain** (1.27 e/DN; see Lesson 1)
 - the applicable noise in the image, e.g. from the CCDStack Info window
- ❑ It is very easy to underestimate noise. You will ordinarily deserve to get 0.05 mag, or as small as 0.01 mag with great effort.

atv photometry settings

IDLPhot Sky Mode

Select Sky Algorithm: Median Sky
 No Sky Subtraction

Select Output Units: Counts
 Magnitudes

Magnitude Zeropoint: 21.1890

Exposure Time (s): 300.000
[Magnitude = -2.5 log (DN / exptime) + ZPT]

Calculate photometric errors? No
 Yes

CCD Gain (e-/DN): 1.27000

Readout Noise (e-): 5.00000

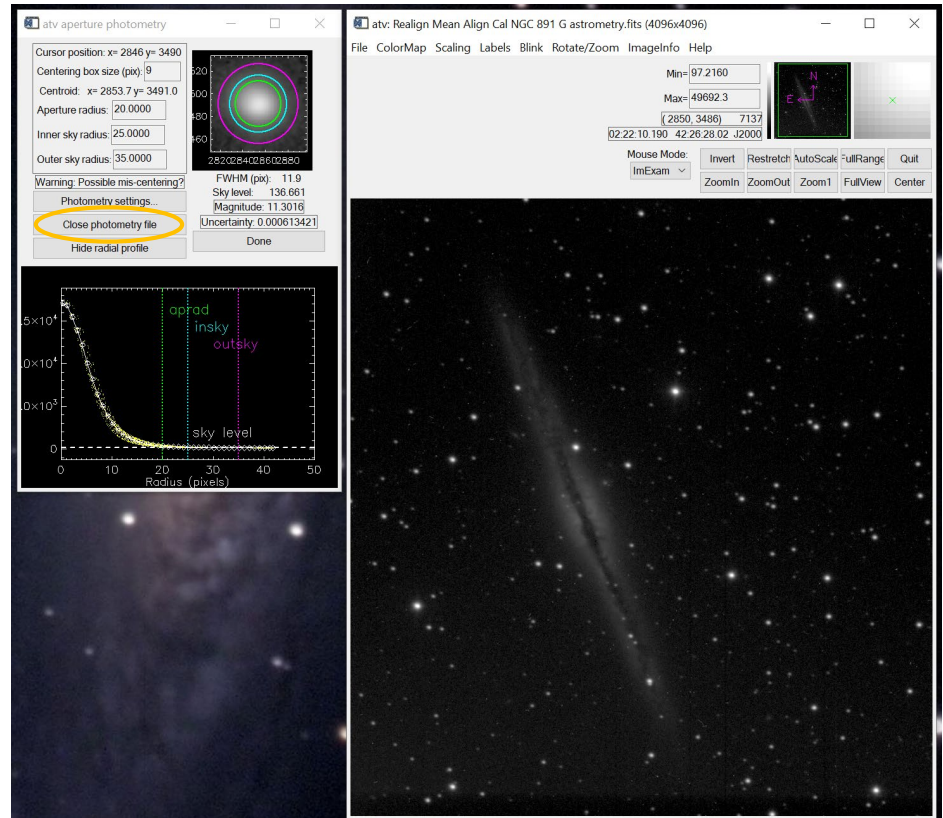
WARNING: Photometric errors only make sense if the gain and readnoise are given correctly accounting for scaling or co-adding of images.

Apply Settings

Cancel

ATV (continued)

- ❑ If you want the counts or magnitudes of several stars in the image, click **Write results** to file in the **atv aperture photometry** window.
- ❑ Then click away on those stars in the image, also pushing the **Close photometry** file when you're done.



x	y	r	insky	outsky	sky	mag	err	fwhm
989.9	2616.9	20.0	25.0	35.0	116.801	12.9054	0.00120174	11.84
856.7	2347.8	20.0	25.0	35.0	123.923	12.0863	0.000832432	11.42
1397.1	1689.7	20.0	25.0	35.0	124.359	12.8910	0.00117970	11.57
1532.1	1670.8	20.0	25.0	35.0	125.657	12.9645	0.00128254	13.97
2264.9	2778.2	20.0	25.0	35.0	216.200	9.98286	0.000395364	13.70
2853.7	3491.0	20.0	25.0	35.0	136.661	11.3016	0.000613421	11.92

Other aperture photometry programs

This process can be automated, using routines in or descended from the Goddard Space Flight Center Astronomy Library:

- ❑ astrolib, for IDL (at right)
- ❑ [photutils](#) within astropy or astroconda, for python
- ❑ All based on [DAOPHOT](#), a well tested set of routines written and maintained by [Peter Stetson](#), and often used with IRAF.
- ❑ Dangerous to automate, without some experience on your images with aperture photometry by hand using the likes of ATV.

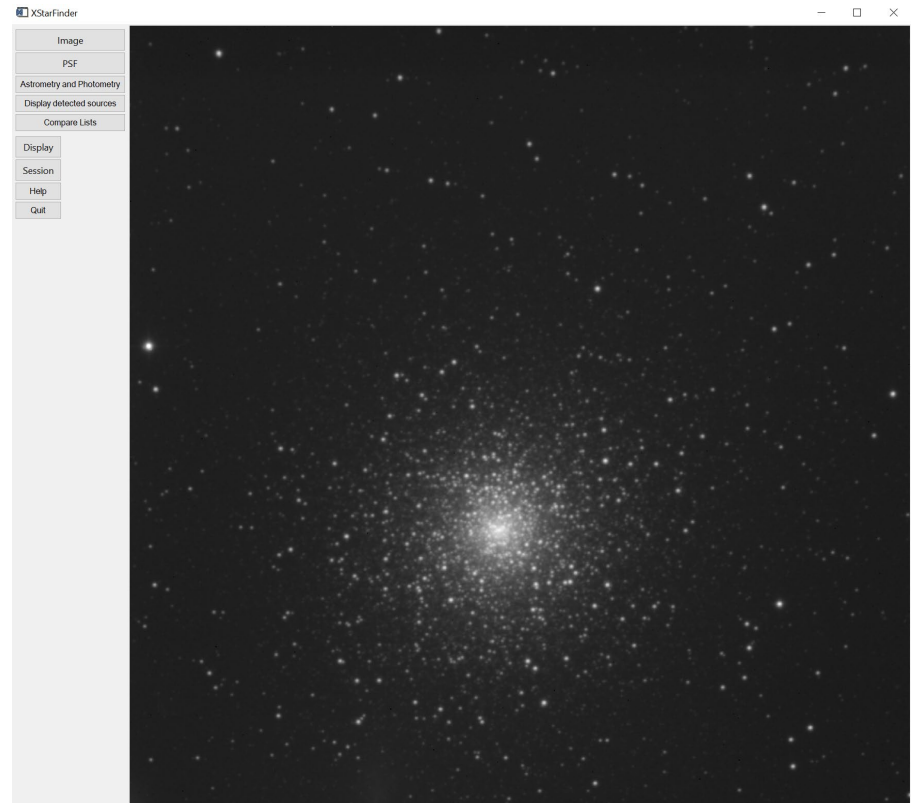
DAOPHOT-Type Photometry Procedures

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For crowded fields

If there are many stars in the image; if they are crowded in parts; and if the stellar images are well sampled; **automated PSF photometry** is best:

- Supply or calculate a PSF for the image.
- Find all the stars in the image above some threshold.
- Iteratively remove all the stars by CLEAN-like PSF subtraction; record centroids and total DN's for each.
- Check DN's on isolated stars with aperture photometry.

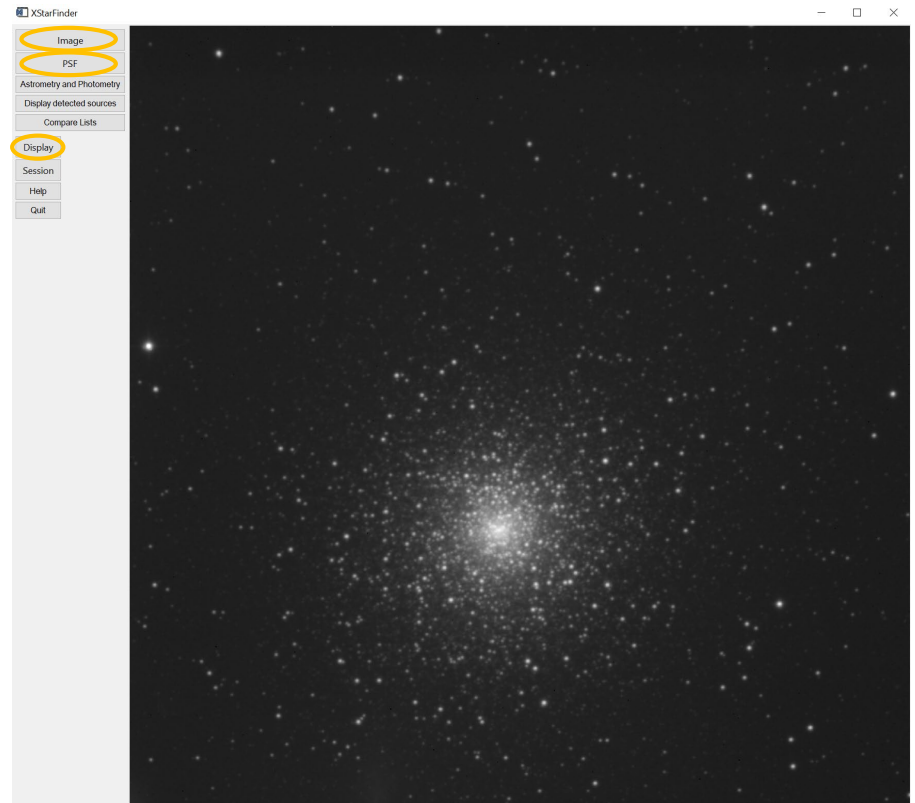


M 15, on a not-so-great night in October 2016.

Typical PSF photometry tool: XStarFinder

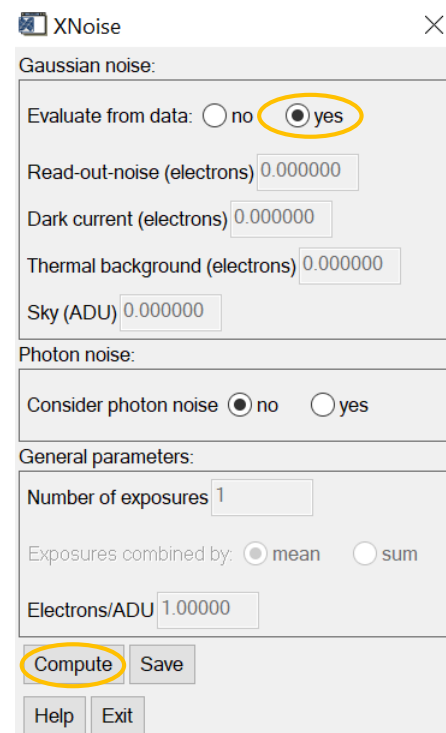
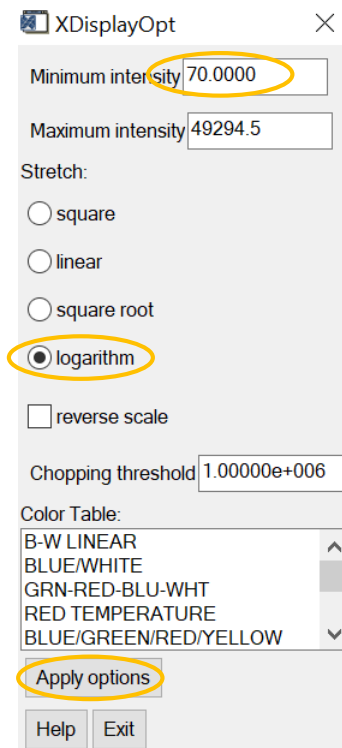
[XStarFinder](#) is an IDL routine for PSF fitting and photometry, in crowded fields of both the diffraction-limited (AO) and the seeing-limited sort. To use it,

- ❑ start IDL, if you haven't already done so.
- ❑ Browse to the directory containing the data.
- ❑ Type `xstarfinder <enter>` at the `IDL>` prompt.
- ❑ This produces the main [XStarFinder](#) window.



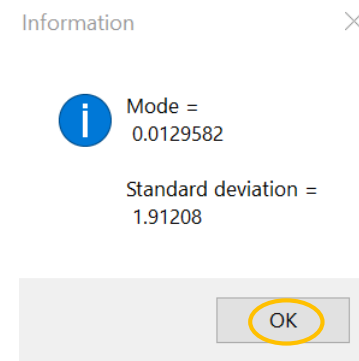
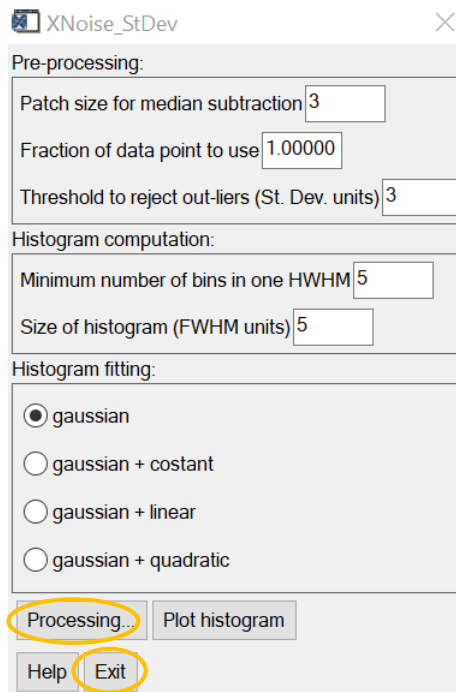
XStarFinder (continued)

- ❑ Push the **Image** button and load a calibrated image (previous pages)
- ❑ Under **Display > Options**, adjust the scale and stretch so that you can see all your stars.
 - Image will be mirror inverted (north down), as in ATV. No Invert Y function this time though.
- ❑ Under **Image > Noise > Compute**, choose **Evaluate from data** and push the **Compute** button.



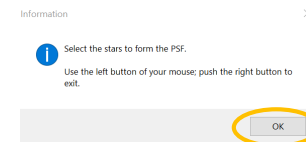
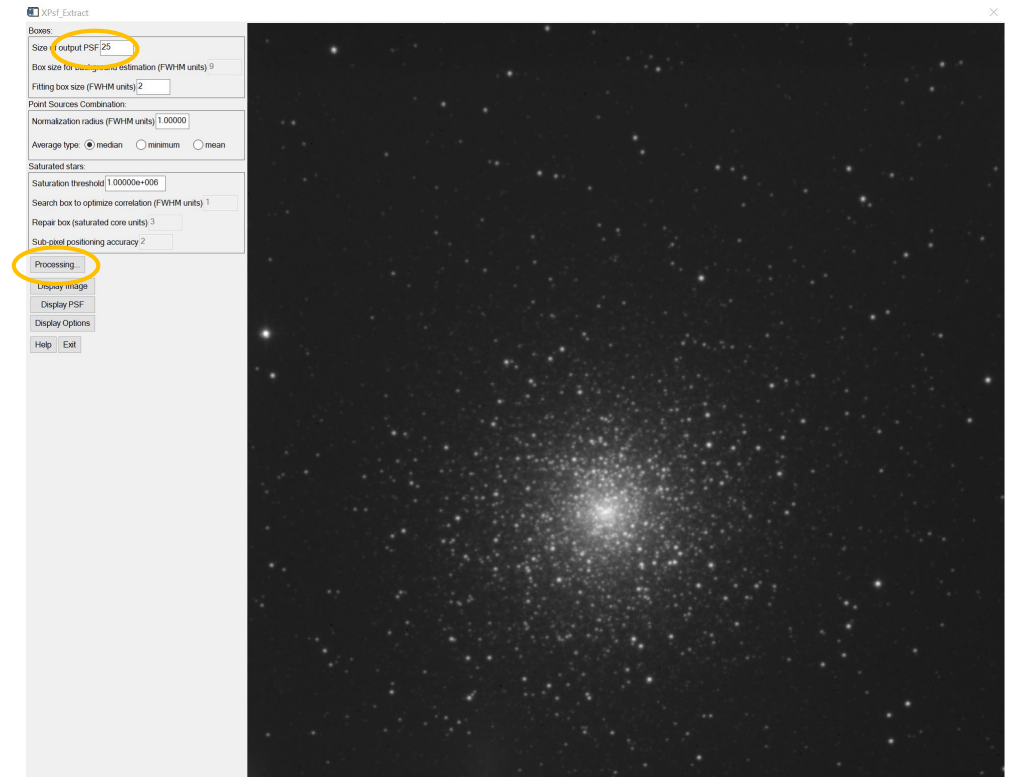
XStarFinder (continued)

- ❑ Push **OK** on the next window to bring up the **XNoise_StDev** window. Accept the defaults and push **Processing...**
- ❑ An information window appears with the grand-total noise result. Push **OK**, **Exit**, **Exit** to get out of the noise-calculation process.
- ❑ Next, define the point spread function to use to deconvolve the image. Choose **PSF > Extract** from image to get the **XPsf_Extract** window (next page).



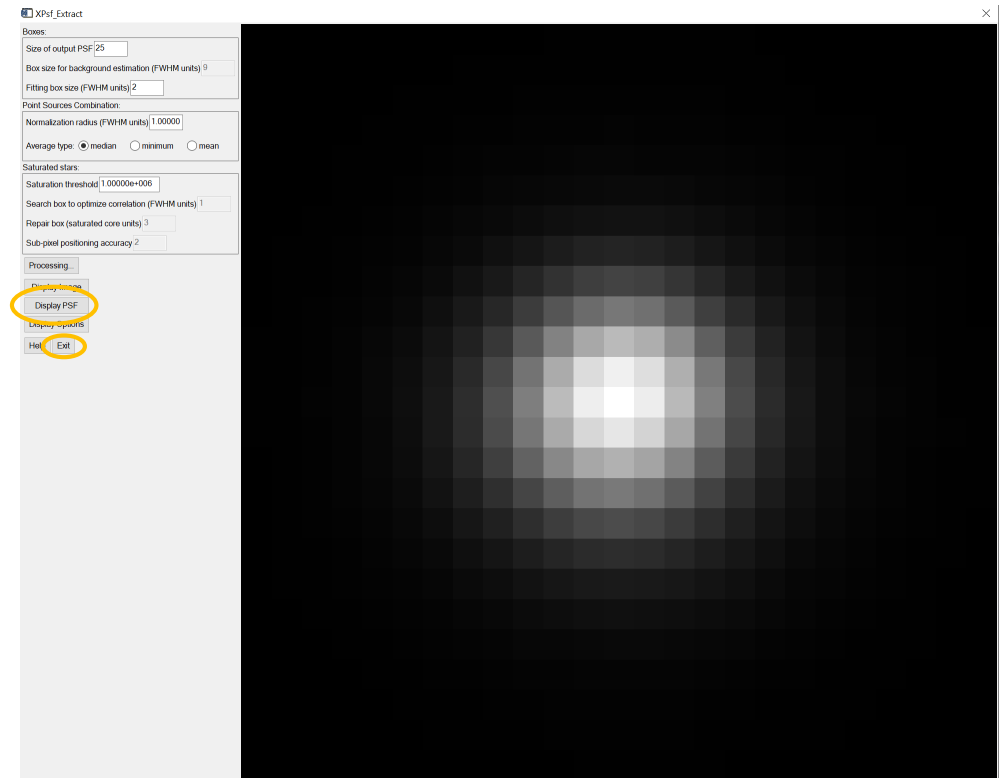
XStarFinder (continued)

- ❑ Set **output PSF** to be about 25; otherwise accept defaults.
- ❑ Press **Processing...**, then **OK** on the next window.
- ❑ Left-click on 5-10 relatively bright and isolated stars; right-click when you're done choosing.
- ❑ Then you'll be asked to confirm (**Yes**) or reject (**No**) your choices. Reject any that don't look like the others, e.g. are not round.



XStarFinder (continued)

- ❑ You should have no secondary sources nearby, so say **No** to the next window.
- ❑ **OK** when done.
- ❑ Non-rejected stellar profiles are averaged to produce the PSF. Choose **Display PSF** to see what you got.
- ❑ **Exit**. You'll be asked if you want to save the PSF stars. Do so if you have more images, aligned with this one, to process. (PSF > Load gets them back.)



XStarFinder (continued)

- ❑ Now you're back on the main XStarFinder window. Choose **Astrometry and Photometry** to bring up the XStarFinder_Run window.
 - This is the part that does the PSF fitting and subtraction.
- ❑ Accept defaults and push **Processing...**
- ❑ Might take 2-4 minutes; will iterate according to number in **Final re-fitting iterations** box.
- ❑ When done you get an info box that says how many stars got found.

XStarFinder_Run

Search:

Detection threshold(s) 3,3

Relative threshold

Correlation:

Correlation threshold 0.700000

No. of sub-pixel offsets 2

Noise and background:

Use noise estimate

Upgrade background

Box size for background estimation (FWHM units) 9

Estimate background by median filtering

Fitting and deblending:

Fit background below sources

Minimum distance of close sources (FWHM units) 1.00000

Deblend detected sources

Deblend rejected sources

Final re-fitting iterations 2

Fit only fluxes

Load list Processing Save results

Help Exit

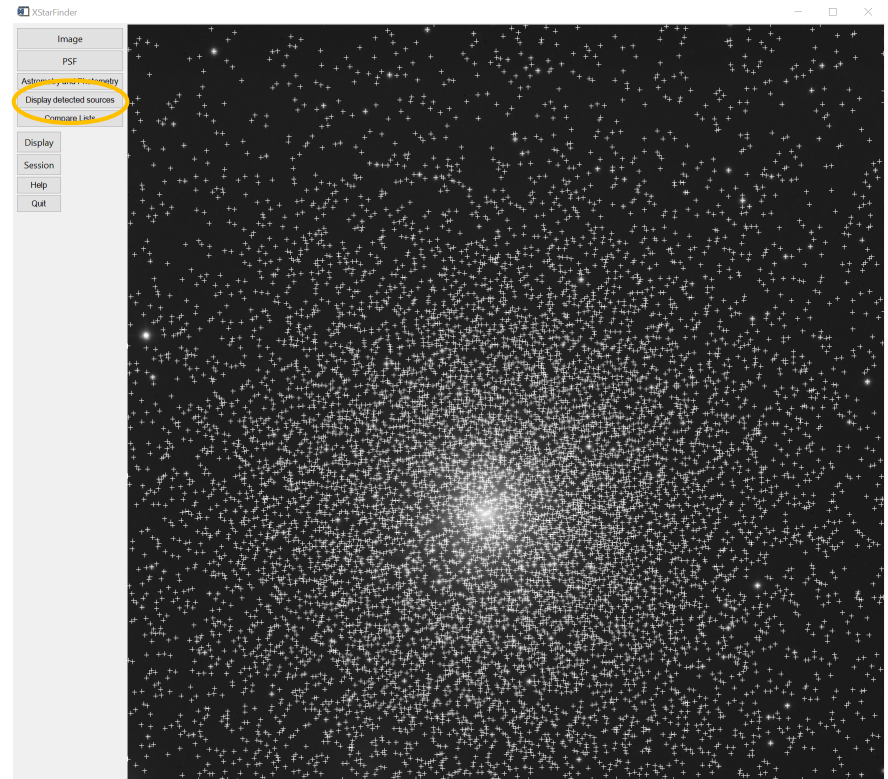
Information

9333 detected stars.

OK

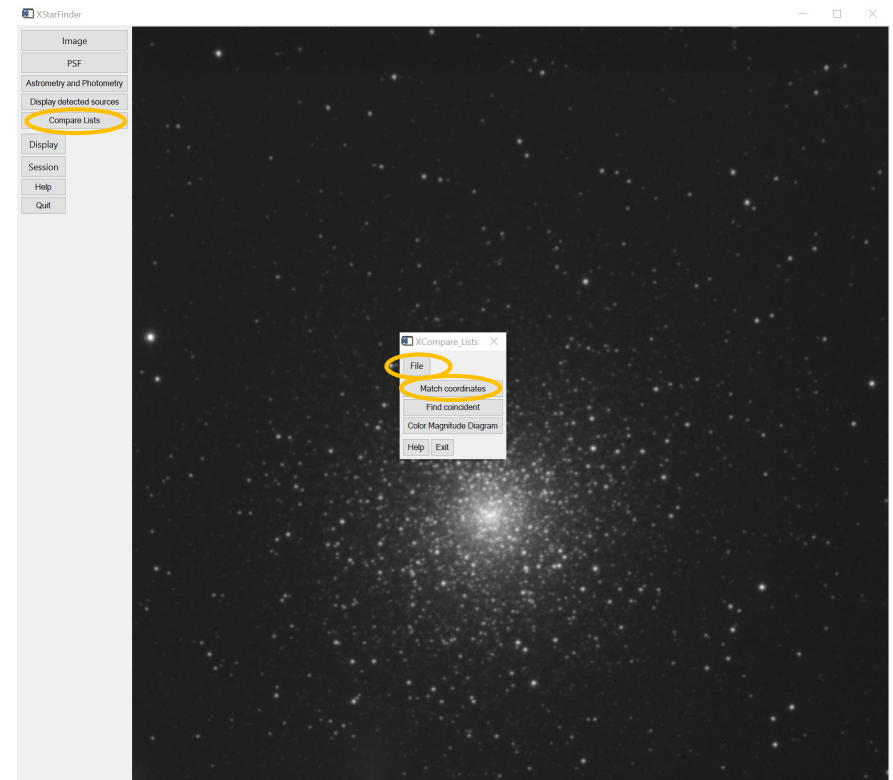
XStarFinder (continued)

- ❑ Reduce **Detection threshold** and/or **Correlation threshold** if you think you deserved to find more stars.
- ❑ **Save results** or you'll have to do the last step over again; then **Exit** to return to the **XStarFinder** window.
- ❑ **Display > Select data > Detected sources** shows what it says.
 - Note that there will often be regions so crowded that point sources can't be extracted.



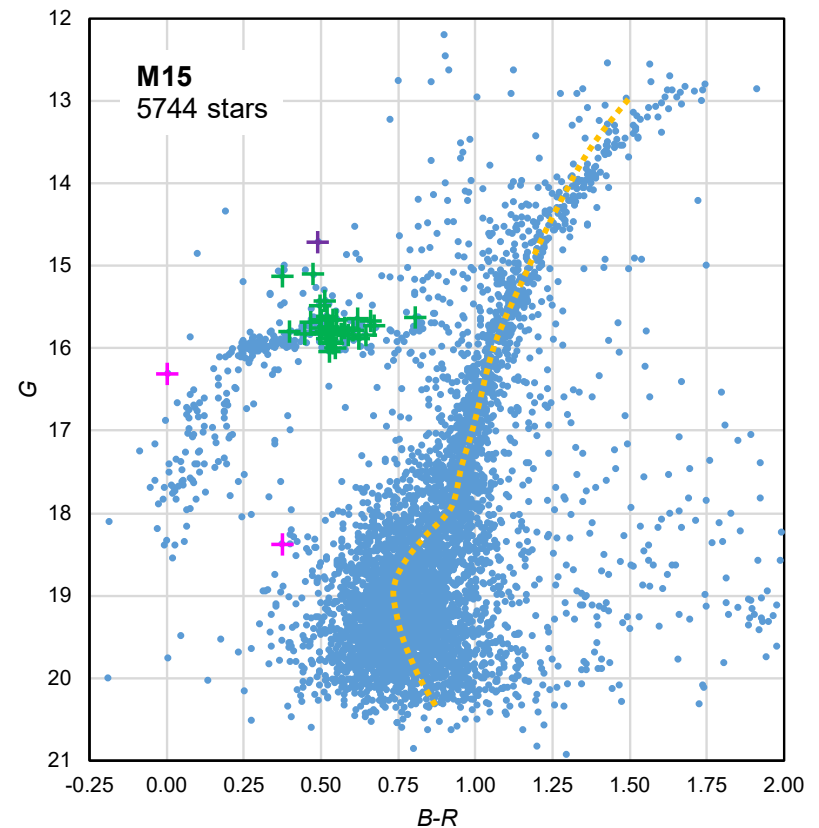
XStarFinder (continued)

- ❑ Once you have extracted the stars from all your images, choose **Compare Lists**.
- ❑ Can load two lists (**File**) and **Match coordinates** between them.
 - Easiest if you've aligned the images as carefully as you can.
- ❑ With our filters it's best to plot HR diagrams as G vs. $B-R$, so you'll need to identify stars in common in all three images.
 - Can do this by using **Match coordinates** cyclically among the three.



XStarFinder (continued)

- ❑ Almost done. Now convert the DNs in your list to fluxes, using your flux calibration in each filter.
- ❑ Or better yet convert them to magnitudes, assuming that you have observed a star cluster and want to plot its HR diagram.



Other PSF-photometry programs

- ❑ DAOPHOT is really a hybrid of star search, aperture photometry, PSF fitting, and precision photometry.
 - All work under IDL or python.
 - Only downside *vis-à-vis* XStarFinder is that the latter has a graphical user interface, and so is newbie-friendlier.
- ❑ Source Extractor (a.k.a. [SExtractor](#)) can pull stars out from moderately crowded fields or (better) from within bright nebulosity.
 - Not what SExtractor is for though. Precision of photometry better in DAOPHOT and XStarFinder.

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