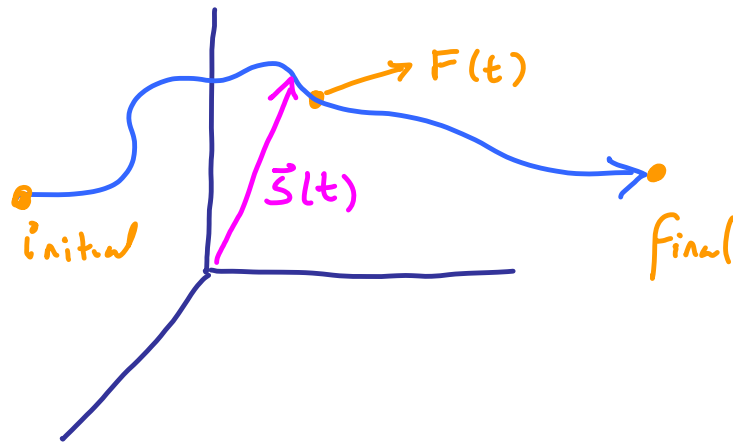


Physics 113 - October 4, 2012

- Time early for exam return is 1 week
- P.S. 4 issue
- Next week's workshop cycle

Last Time



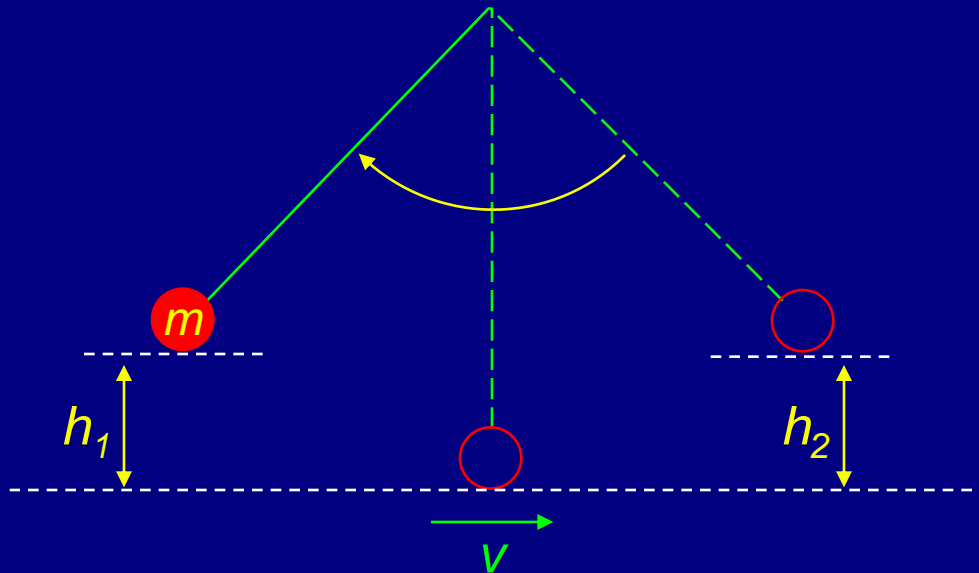
$$W = \int_{\text{initial}}^{\text{Final}} \vec{F} \cdot d\vec{s}$$

Potential energy - Potential to do work

Kinetic energy - energy of motion = $\frac{1}{2}mv^2$

Example: The simple pendulum

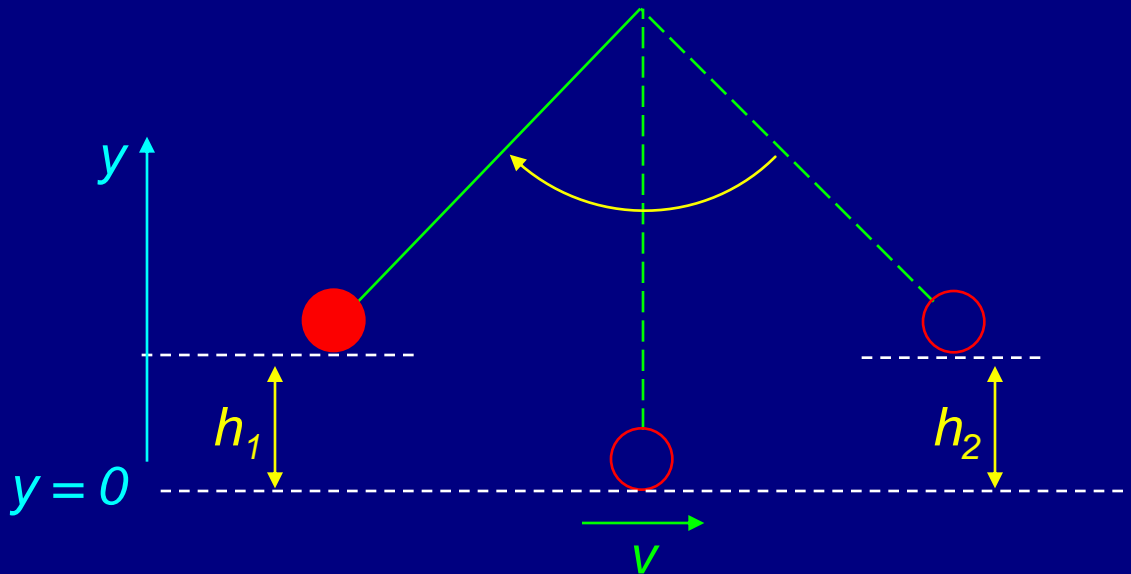
- Suppose we release a mass m from rest a distance h_1 above its lowest possible point.
 - ← What is the maximum speed of the mass and where does this happen?
 - ← To what height h_2 does it rise on the other side?



Example: The simple pendulum

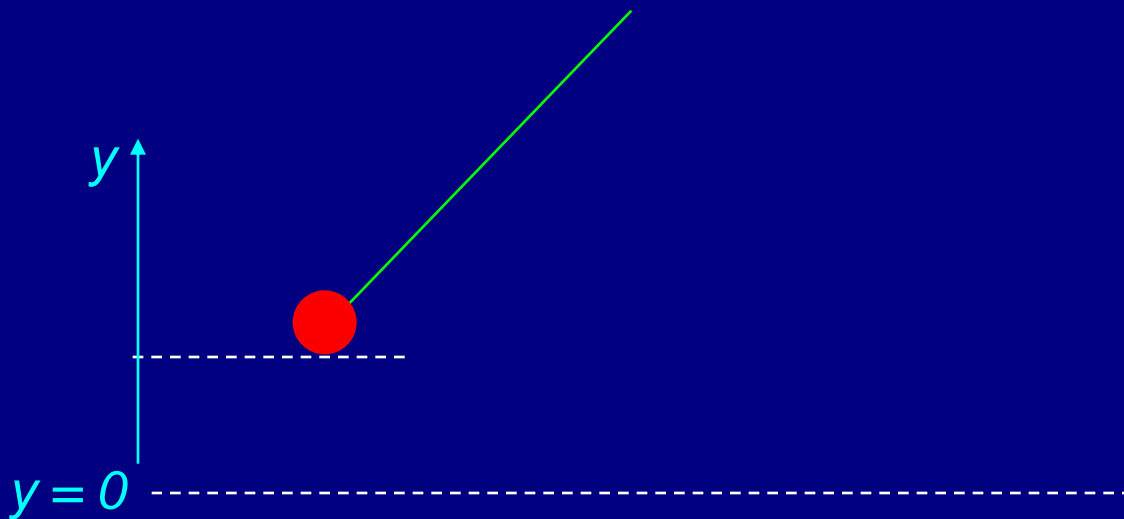
- Kinetic+potential energy is conserved since gravity is a conservative force ($E = K + U$ is constant)
- Choose $y = 0$ at the bottom of the swing, and $U = 0$ at $y = 0$ (arbitrary choice)

$$E = \frac{1}{2}mv^2 + mgy$$



Example: The simple pendulum

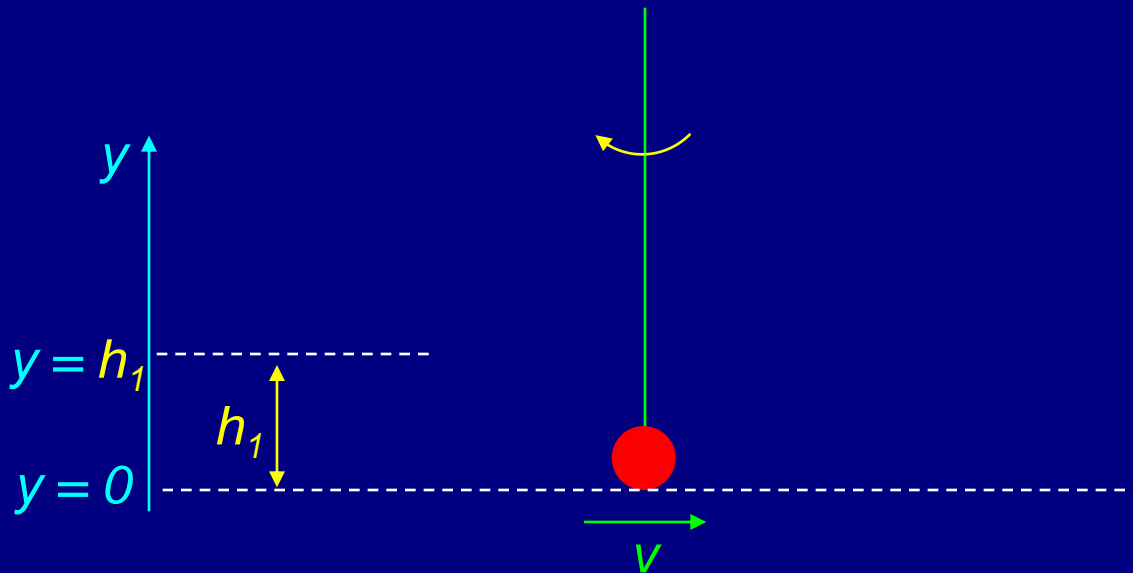
- $E = \frac{1}{2}mv^2 + mgy$.
 - ← Initially, $y = h_1$ and $v = 0$, so $E = mgh_1$.
 - ← Since $E = mgh_1$ initially, $E = mgh_1$ always since energy is conserved.



Example: The simple pendulum

- $\frac{1}{2}mv^2$ will be maximum at the bottom of the swing.
- So at $y = 0$ $\Rightarrow \frac{1}{2}mv^2 = mgh_1$ $\Rightarrow v^2 = 2gh_1$

$$v = \sqrt{2gh_1}$$



Example: The simple pendulum

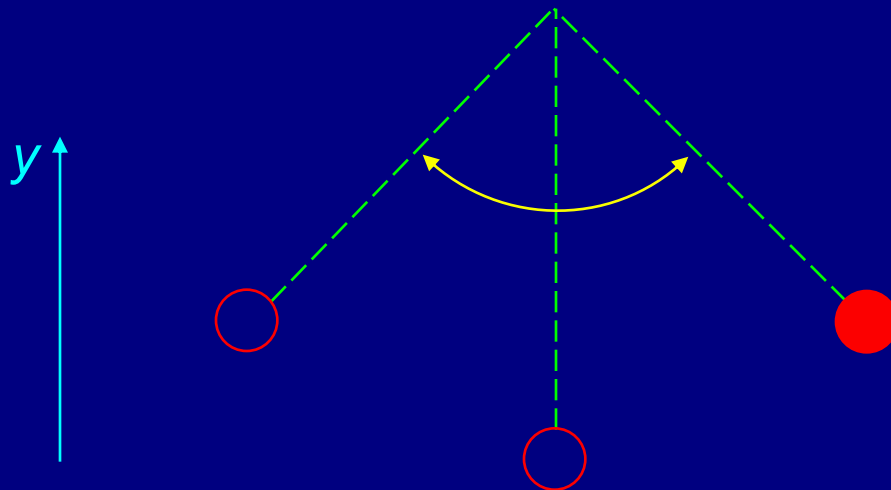
- Since $E = mgh_1 = \frac{1}{2}mv^2 + mgy$ it is clear that the maximum height on the other side will be at $y = h_1 = h_2$ and $v = 0$.
- The ball returns to its original height.



Example: The simple pendulum

- The ball will oscillate back and forth. The limits on its height and speed are a consequence of the sharing of energy between K and U .

$$E = \frac{1}{2}mv^2 + mgy = K + U = \text{constant.}$$



Generalized Work/Energy Theorem:

$$W_{NC} = \Delta K + \Delta U = \Delta E_{mechanical}$$

- The change in kinetic+potential energy of a system is equal to the work done on it by non-conservative forces.

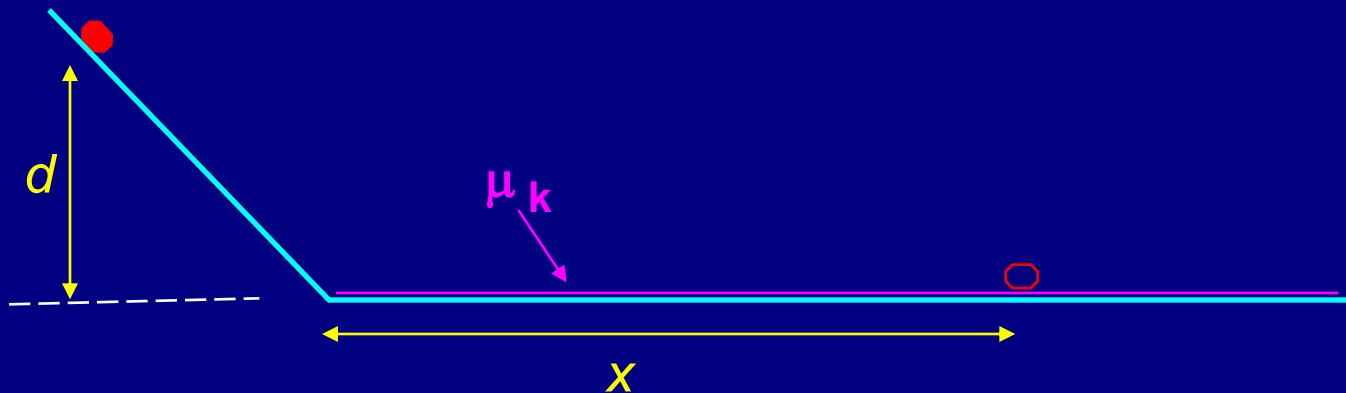
$E_{mechanical} = K + U$ of system not conserved!

← If all the forces are conservative, we know that $K + U$ energy is conserved: $\Delta K + \Delta U = \Delta E_{mechanical} = 0$ which says that $W_{NC} = 0$.

← If some non-conservative force (like friction) does work, $K + U$ energy will not be conserved and $W_{NC} = \Delta E$.

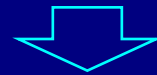
Problem: Block Sliding with Friction

- A block slides down a frictionless ramp. Suppose the horizontal (bottom) portion of the track is rough, such that the coefficient of kinetic friction between the block and the track is μ_k .
 - ← How far, x , does the block go along the bottom portion of the track before stopping?

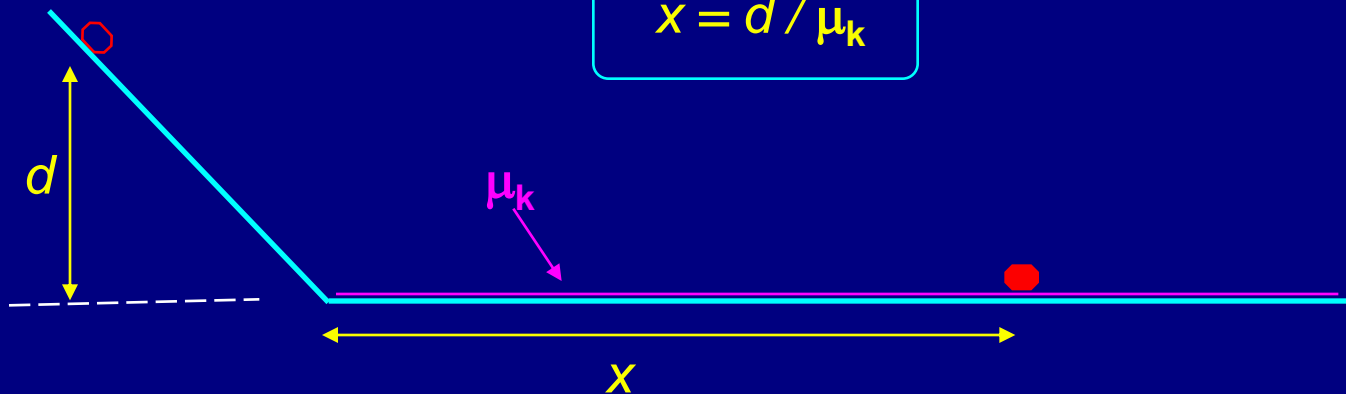


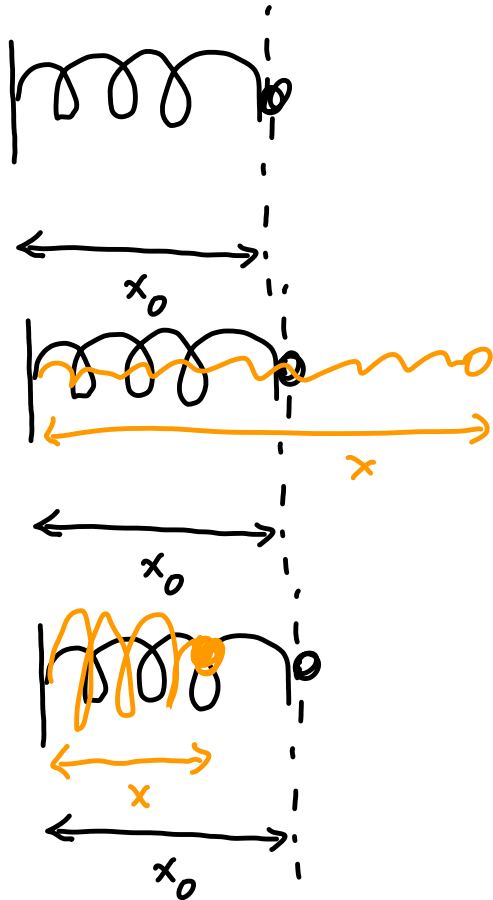
Problem: Block Sliding with Friction...

- Using $W_{NC} = \Delta K + \Delta U$
- As before, $\Delta U = -mgd$
- $W_{NC} =$ work done by friction $= -\mu_k mgx$.
- $\Delta K = 0$ since the block starts out and ends up at rest.
- $W_{NC} = \Delta U \quad \Rightarrow \quad -\mu_k mgx = -mgd$



$$x = d / \mu_k$$





Spring

$$F \propto |x - x_0|$$

$x_0 \equiv$ natural length

$$|F| = k|x - x_0|$$

$k \equiv$ Spring constant

$$\vec{F} = -k(x - x_0)$$

Hooke's Law

restoring force

$F = k|x - x_0|$ Magnitude form - use common sense

$$F = kx \quad (\text{define } x_0 = 0)$$

We'll come back to springs shortly ...

Energy is conserved

U = Potential energy

$$\sum E_{\text{initial}} = \sum E_{\text{Final}}$$

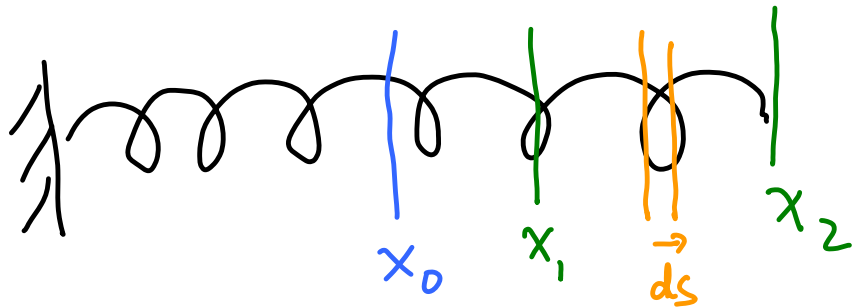
\sum KE
and
PE

$$W_{\text{done}} = \Delta KE + \Delta PE$$

(nonconservative)
friction

$$= \Delta K + \Delta U$$

Energy in Springs



Stretch Spring from x_1 to x_2

Work done ~~on~~ Spring
to move it from
 $x_1 \rightarrow x_2$

$$W = \int_{x_1}^{x_2} \vec{F} \cdot \vec{ds} = \int_{x_1}^{x_2} F dx = \int_{x_1}^{x_2} k(x-x_0) dx$$

\vec{ds} is labeled dx in orange below it.

$$\leftarrow \text{ } \rightarrow \text{ } F_{\text{exerted}} = k(x-x_0)$$

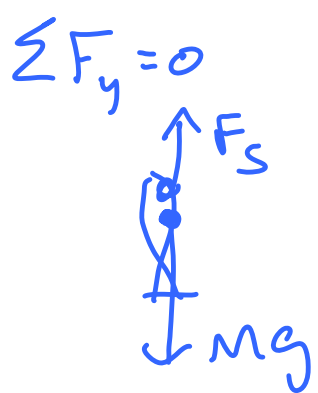
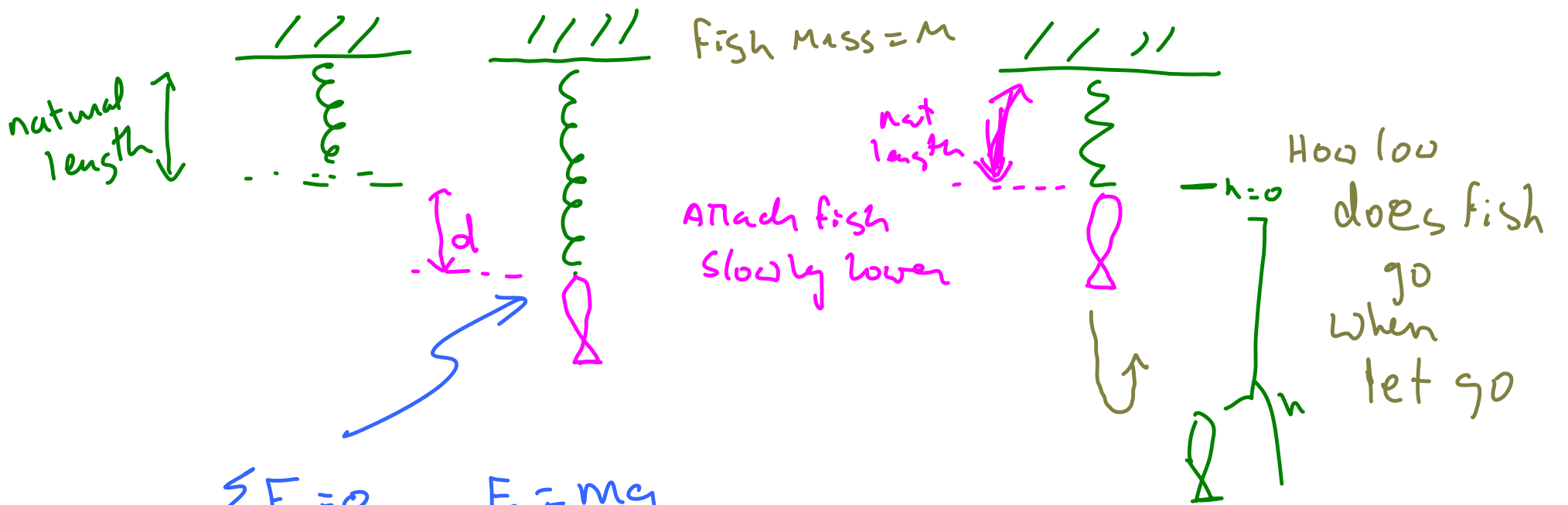
let $x_0 = 0$

$$\int_{x_1}^{x_2} kx dx = \frac{1}{2} k(x_2^2 - x_1^2)$$

$$W = PE_{\text{end}} - PE_{\text{start}}$$

$$PE_{\text{spring}} = \frac{1}{2} k x^2$$

|
dist from nat. length



$F_s = mg$

$Kd = mg$

$K = \frac{mg}{d}$

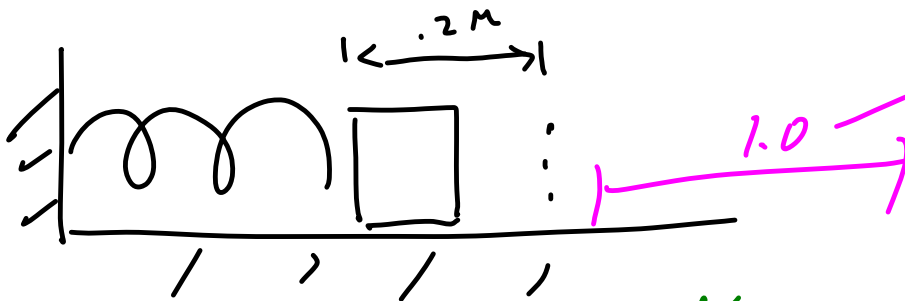
$mgh = \frac{1}{2}kh^2$

$\Delta PE_{spring} = mgh$

$\Delta PE_{spring} = \frac{1}{2}kh^2$

$$\begin{array}{c} \downarrow \quad \swarrow \\ \cancel{mgh} = \frac{1}{2} \cancel{mg} \frac{h}{d} \end{array}$$

$$h = 2d$$



$k_{\text{spring}} = 100 \text{ N/m}$
 Block has mass 0.5 kg
 Spring compressed 0.2 m

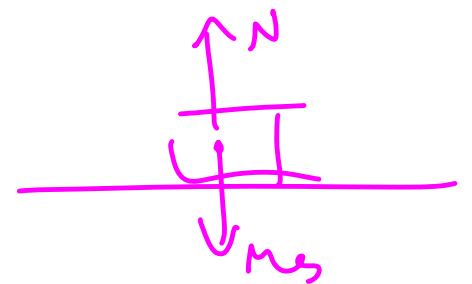
release block
 moves 1.0 m
 before comes to rest
 what is μ_k

$PE_{\text{spring initial}} \rightarrow W_{\text{done by friction}}$

100

$$\frac{1}{2} k x^2 = \mu_k N d$$

(Annotations: $x = 0.2 \text{ m}$, $d = 1.0 \text{ m}$, $N = Mg$)



$$\mu_{12} = \frac{Kx^2}{2mgd}$$

$$\mu_{12} = 0.41$$

$$\text{Power} = \frac{\Delta W}{\Delta t}$$

$$P = \frac{dW}{dt} = \frac{\text{Joules}}{\text{s}} \equiv \text{Watt}$$

Potential Energy + force

$$W = Fd$$

$$\underline{dW} = Fdx$$

$$\underline{dU} = Fdx$$

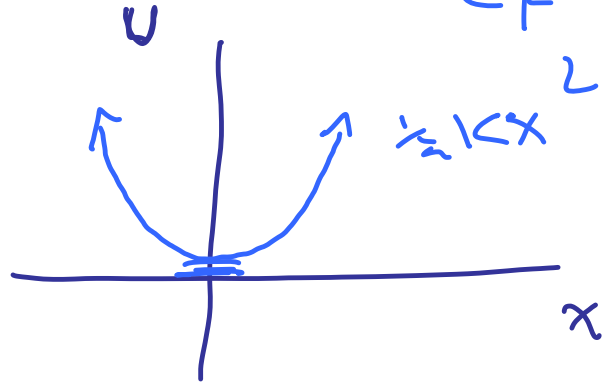
Pot.
Energy

$$\frac{dU}{dx} \sim F_x$$

Spring $PE = \frac{1}{2}kx^2$

$$\frac{dU}{dx} = \underline{kx}$$

$\sim F$



$$F_s = -\frac{dU}{ds}$$