

# Physics 113 - October 18, 2012

■ EXAM 2 - 1 week from now - here

■ No P.S. next week due to EXAM

■ No lecture next Tuesday →

Slides  
Audio

Expect you  
to  
go thru/listen

■ Workshops meet as usual  
next week

Newton's second law - updated version

$$\sum \vec{F} = \frac{d(m\vec{v})}{dt} = \frac{d\vec{P}}{dt}$$

$$\vec{P} = m\vec{v} \equiv \text{Momentum}$$

For isolated system, Momentum is Conserved

$$\sum \vec{P}_i = \sum \vec{P}_F$$

$$\sum P_{ix} = \sum P_{Fx}$$

$$\sum P_{iy} = \sum P_{Fy}$$

$$\sum P_{iz} = \sum P_{Fz}$$

In a collision

Momentum conservation good  
if system isolated

IF KE conserved  $\leftrightarrow$  elastic collision  
(Think billiards)

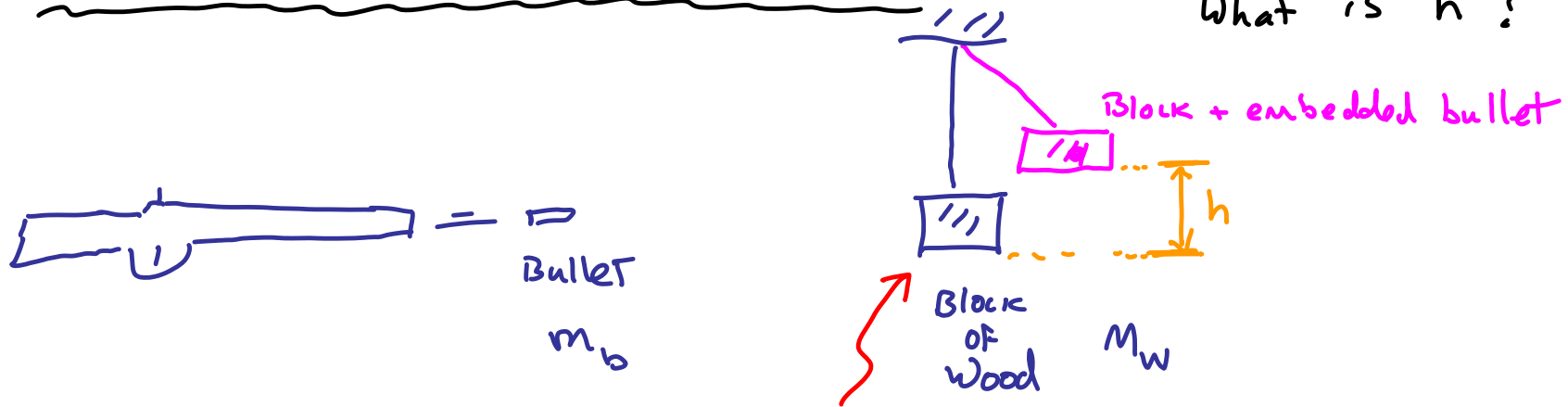
IF KE NOT conserved  $\leftrightarrow$  inelastic collision

IF KE NOT conserved

$$\sum KE_i \neq \sum KE_f$$

# Ballistic Pendulum Example Problem

given  $V_b, m_b, M_w$   
What is  $h$ ?



If know  $V_{w+b}$  after impact  
can use  $E_{cons}$  to get  $h$

How do we determine  $V_{w+b}$  after impact?

$$KE_i = KE_f$$

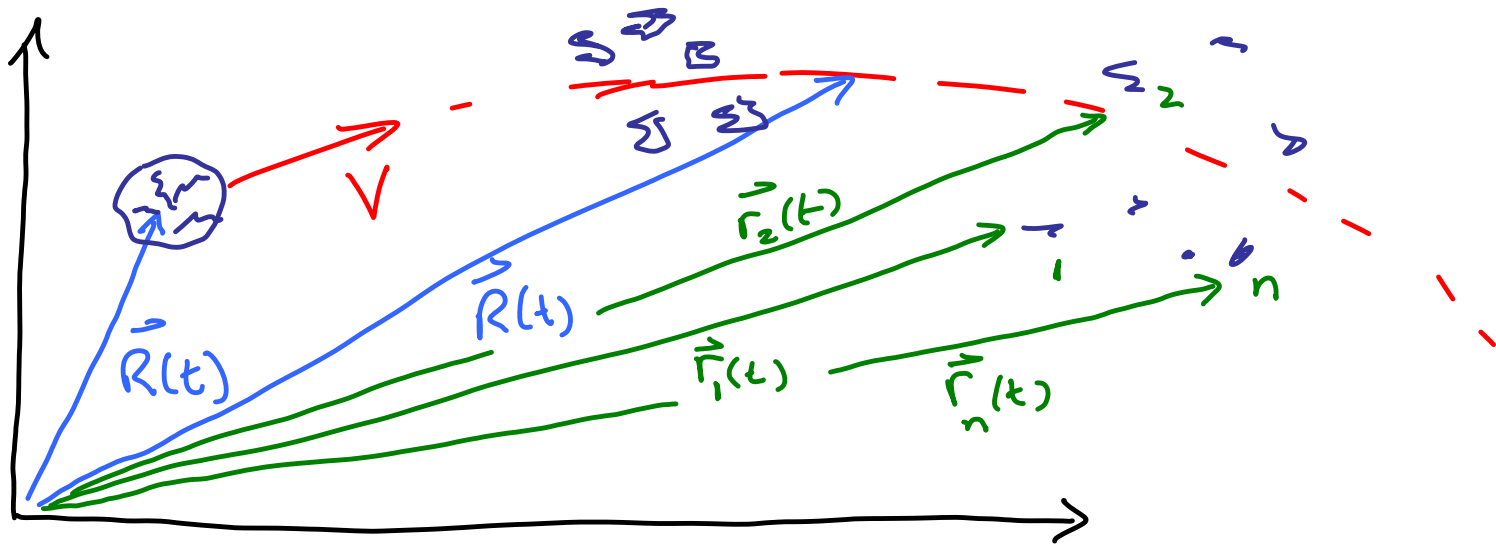
$$\frac{1}{2} m_b V_b^2 = \cancel{\frac{1}{2}} (m_b + M_w) V_{w+b}^2 \quad \text{inelastic collision}$$

use p conservation

$$\underbrace{m_b v_b + m_w v_w}_{\sum P_i} = \underbrace{(m_b + m_w) v_{b+w}}_{\sum P_f} \quad \left. \vphantom{\sum P_i} \right\} \begin{array}{l} \text{get} \\ v_{b+w} \end{array}$$

$$(m_b + m_w) g h = \frac{1}{2} (m_b + m_w) v_{b+w}^2$$

Center of Mass — Center of Mass coordinates



Momentum is conserved

$$M \vec{V} = m_1 \vec{v}_1 + m_2 \vec{v}_2 + \dots + m_n \vec{v}$$

$$M \frac{d\vec{R}}{dt} = m_1 \frac{d\vec{r}_1}{dt} + m_2 \frac{d\vec{r}_2}{dt} + \dots + m_n \frac{d\vec{r}_n}{dt}$$

$$M \vec{R} = m_1 \vec{r}_1 + m_2 \vec{r}_2 + \dots + m_n \vec{r}_n$$

$$\vec{R} = (X, Y, Z)$$

$$\vec{r}_1 = (x_1, y_1, z_1)$$

⋮

$$MX = m_1 x_1 + m_2 x_2 + \dots + m_n x_n$$

$$MY = m_1 y_1 + m_2 y_2 + \dots + m_n y_n$$

$$MZ = m_1 z_1 + m_2 z_2 + \dots + m_n z_n$$

Center of Mass  
Coordinates

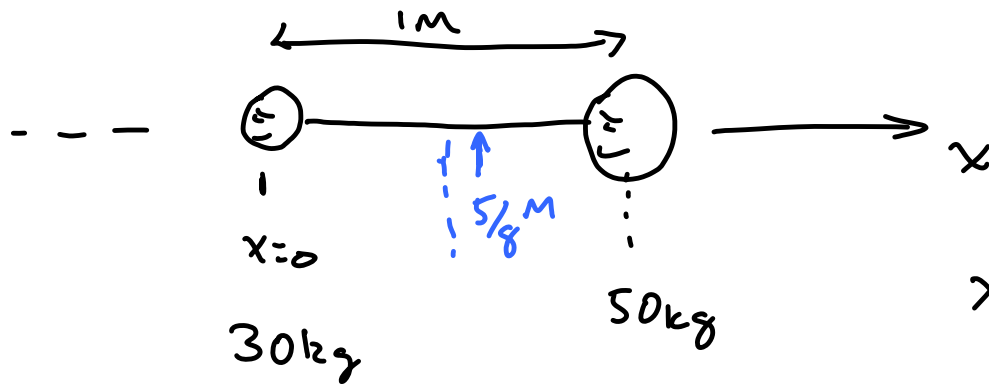
$$X = \frac{m_1 x_1 + m_2 x_2 + \dots + m_n x_n}{M} = \frac{\sum_i m_i x_i}{\sum_i m_i}$$

$$Y = \frac{\sum_i m_i y_i}{\sum_i m_i} = \frac{\sum_i m_i y_i}{M}$$

$$Z = \frac{\sum_i m_i z_i}{\sum_i m_i} = \frac{\sum_i m_i z_i}{M}$$

mass weighted  
x coordinate  
of system

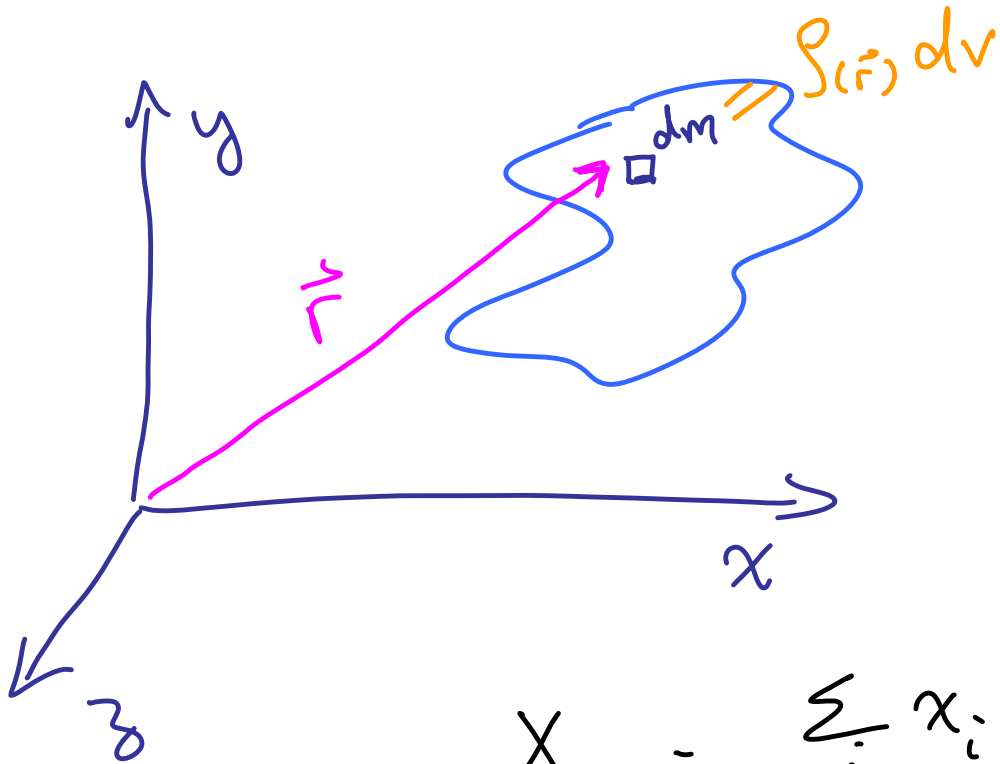




where is  $x_{cm}$

$$x_{cm} = \frac{\sum M_i x_i}{M} = \frac{(0)(30) + (1)(50)}{30 + 50}$$

$$x_{cm} = \frac{5}{8} \text{ m}$$



object has

$\rho(\vec{r})$  mass density

3 d mass density

$$X_{cm} = \frac{\sum_i x_i (dm_i)}{\sum_i dm_i}$$

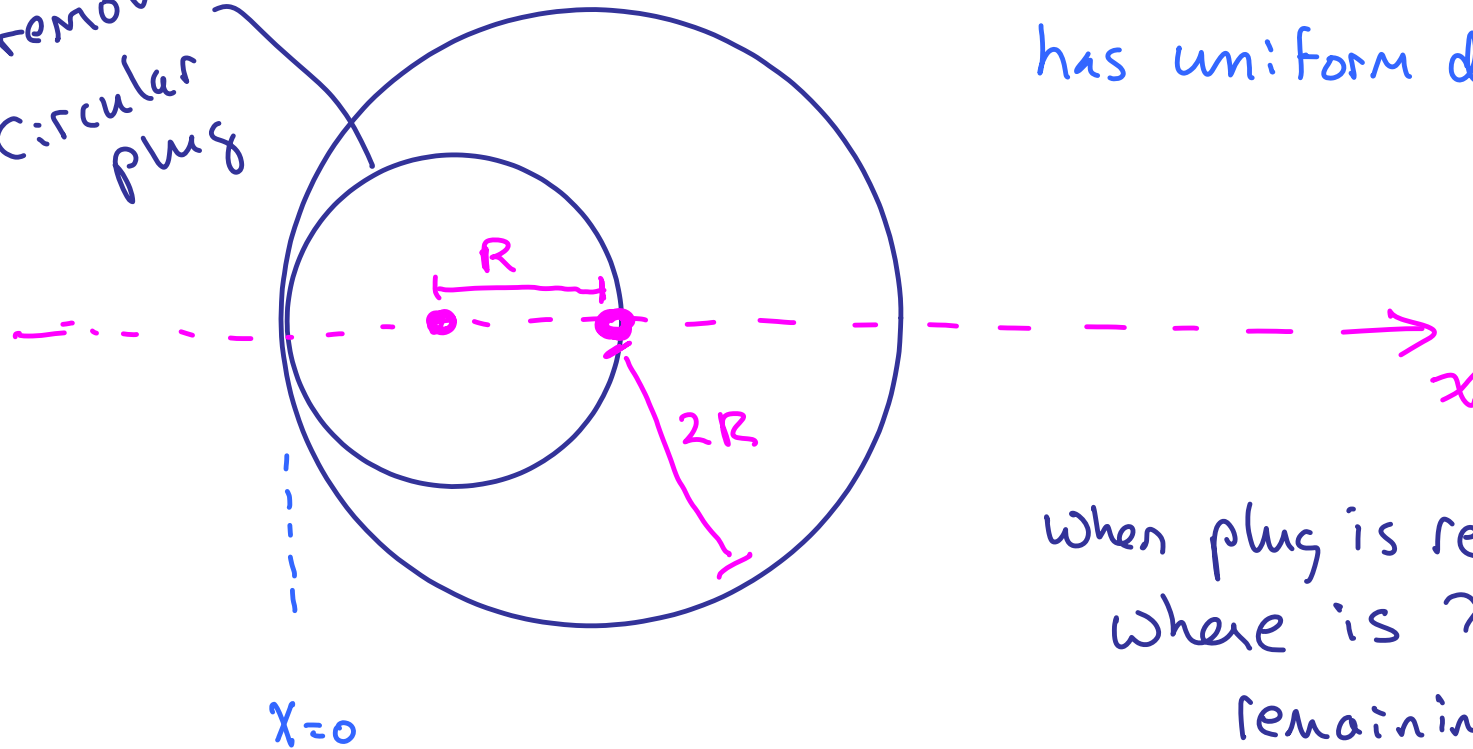
continuous limit  $\rightarrow$

$$\frac{\int_{Vol} x dm}{\int_{Vol} dm} = M$$

Similarly  $Y_{cm} = \frac{\int y dm}{\int dm}$        $Z_{cm} = \frac{\int z dm}{\int dm}$

$$\vec{R} = \frac{\int \vec{r} dm}{\int dm} = \frac{\int \rho(\vec{r}) dV}{\int dm}$$

remove  
Circular  
plug



disk has thickness  $t$   
has uniform density  $\rho$

When plug is removed,  
where is  $x_{cm}$  of  
remaining part of Disk?

$$\chi_{\text{Total disc}} = \frac{M_{\text{plug}} \chi_{\text{plug}} + M_{\text{disc-plug}} \chi_{\text{disc-plug}}}{M_{\text{plug}} + M_{\text{disc-plug}}}$$

Asked to find

$$2R = \frac{M_p R + M_{d-pl} \chi_{d-pl}}{M}$$

$(4R^2 - R^2) \rho \pi t$   
 $= 3R^2 \rho \pi t$

$\int \pi (2R)^2 t = 4R^2 \rho \pi t$   
 vol of big disc

$2 R^2 \rho \pi t$

$$2R = \frac{R^2 g \pi t R + 3R^2 g \pi t \chi_{d-pl}}{4R^2 g \pi t}$$

$$2R = \frac{R + 3\chi_{d-pl}}{4}$$

$$8R = R + 3\chi_{d-pl}$$

$$2\frac{1}{3}R = \frac{7}{3}R = \chi_{d-pl}$$

