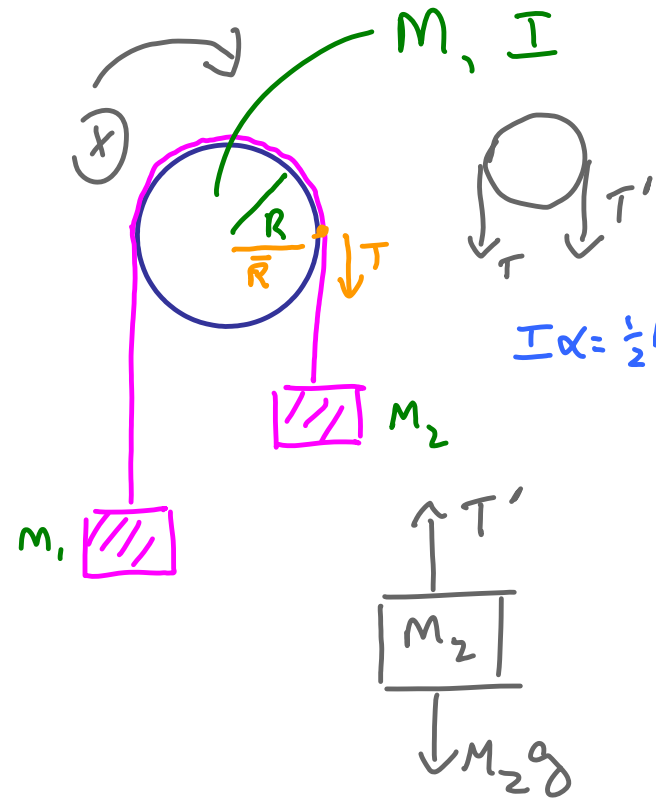
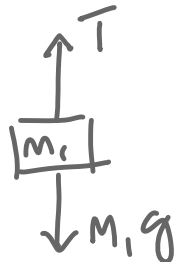


Physics 113 - November 6, 2012

Last Time

$$m_1 a = T - M_1 g$$



$$I \alpha = \frac{1}{2} M R^2 \frac{a}{R} = T' r - T R$$

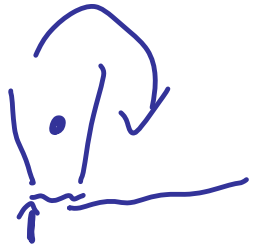
$$M_2 a = M_2 g - T'$$

Please Vote!
We need the voice
of the young
and Educated
to be heard!

a few Moments of Reflection



Rotation
→
You

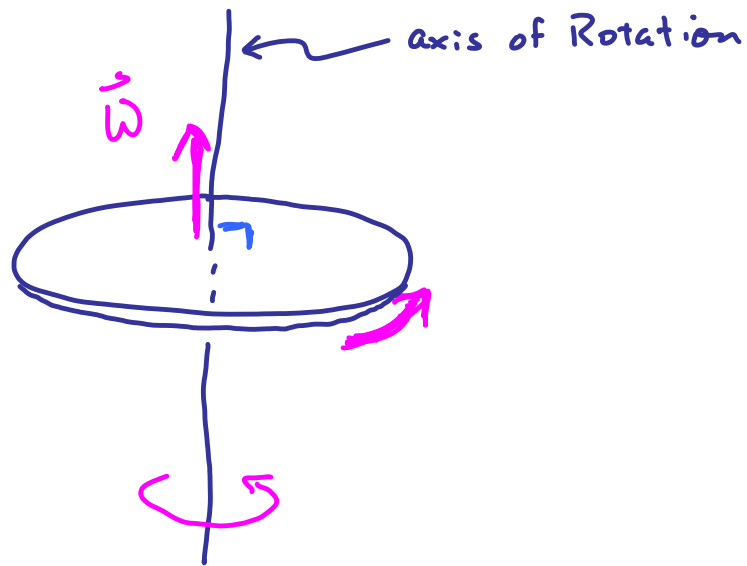


Rotational dynamics

... rotation ω

(chapter 11)

vectors



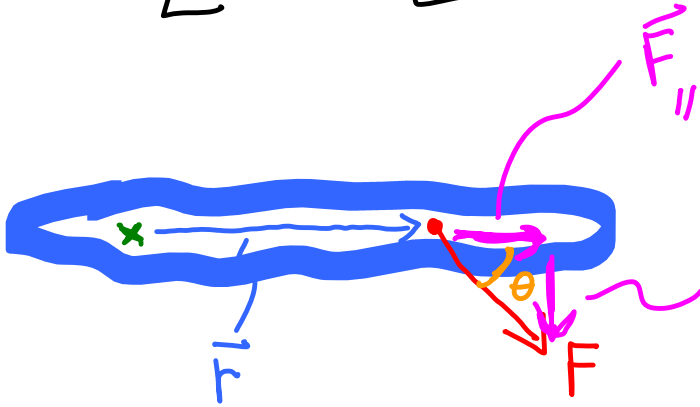
If $\vec{\omega}$ increasing w/ time

$\vec{\alpha}$ is a vector along $\vec{\omega}$

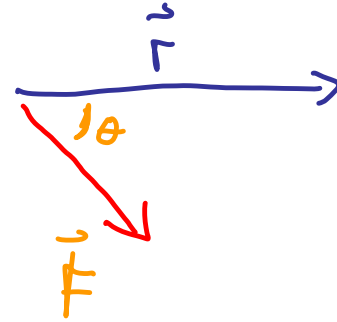
If $\vec{\omega}$ is decreasing w/ time

$\vec{\alpha}$ is vector in a direction opposite of $\vec{\omega}$

$$\vec{L} = I \vec{\alpha}$$



$$\vec{F}_{\perp} = \vec{F} \sin \theta$$

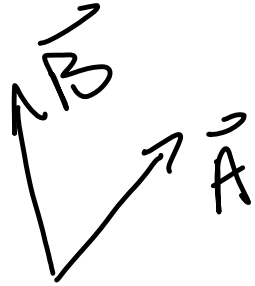


"dot" Scalar product

$$\vec{r} \cdot \vec{F} = |\vec{r}| |\vec{F}| \cos \theta$$

CROSS product

$$\vec{r} \times \vec{F} = |\vec{r}| |\vec{F}| \sin \theta \quad \text{into paper}$$

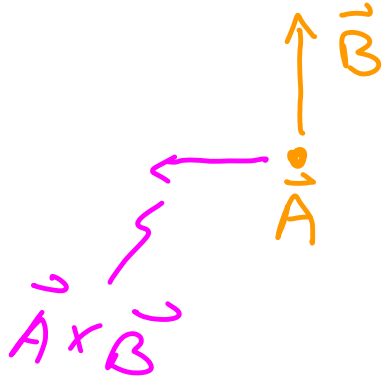


$$\vec{A} \times \vec{B}$$

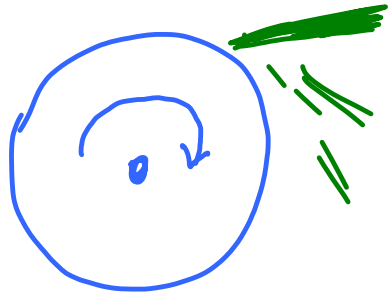


• vector
going
out of
paper

x vector going
into
paper

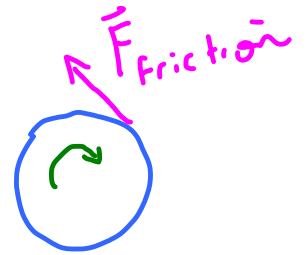


$$\vec{A} \times \vec{B} = -\vec{B} \times \vec{A}$$



what is the direction
of $\vec{\alpha}$

up
down
Right
left
in
out
along \vec{F}



$\vec{\omega}$ is into screen
 \vec{F} gives torque that
is in opposite direction
of $\vec{\omega}$
 $\vec{\alpha}$ is out of screen

Linear world

Rotational world

$$s \xrightarrow{s = r\theta}$$

$$\vec{v} \xrightarrow{v = r\omega}$$

$$\vec{a} \xrightarrow{a = r\alpha}$$

M

$$\vec{F} \xrightarrow{\vec{L} = \vec{r} \times \vec{F}}$$

$$\frac{1}{2} m v^2$$



$$\frac{1}{2} I \omega^2$$

$$\vec{p} = m \vec{v}$$

$$I = \int r^2 dm$$

Angular momentum $\equiv \vec{L} = I \vec{\omega}$

$$\vec{p} = m \vec{v}$$

$$\left. \begin{array}{l} \downarrow \\ \downarrow \end{array} \right\} I \omega$$

$$\vec{F} = \frac{d\vec{p}}{dt} = \frac{d(m\vec{v})}{dt} = m \frac{d\vec{v}}{dt} = m\vec{a}$$

$$\vec{L} = \frac{d\vec{L}}{dt} = I \frac{d\vec{\omega}}{dt} = I \vec{\alpha}$$

Angular momentum
in "isolated"
(no external torque)
system
is conserved

$$\vec{L}_{\text{start}} = \vec{L}_{\text{end}}$$

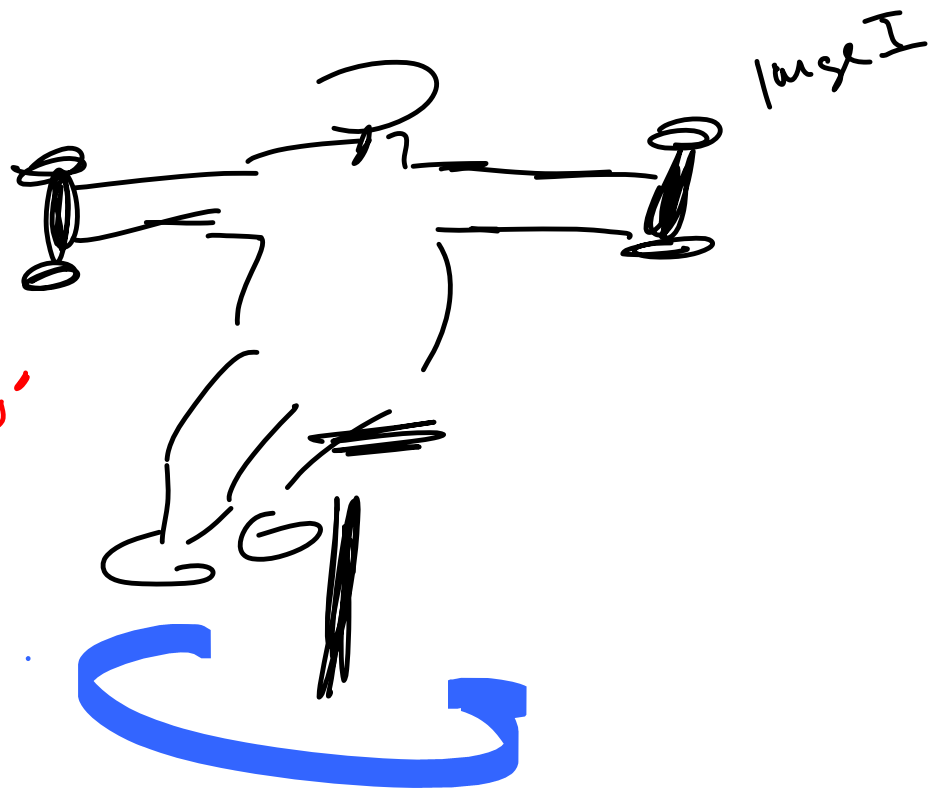
demo



small I

$$I\omega = I'\omega'$$

fast rotation



large I

slow rotation