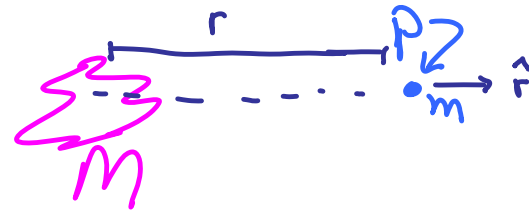


Physics 113 - October 24, 2013

Gravitation

Last Time —

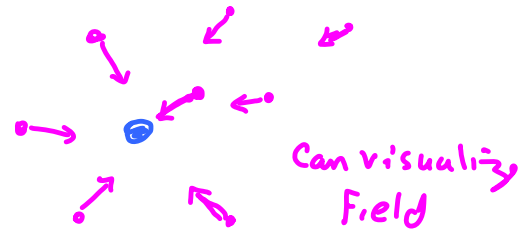


$$\vec{F}_{\text{of } M \text{ on } m} = -\frac{GMm}{r^2} \hat{r}$$

gravitational field

$$\vec{g}(p) = \vec{F}/m = -\frac{GM}{r^2} \hat{r}$$

Vector





$$\Delta PE_{1 \rightarrow 2} = \left(-\frac{GMm}{r_2} \right) - \left(-\frac{GMm}{r_1} \right) > 0$$

$\Delta PE \sim mgh$ if near surface of Earth

define gravitational potential energy = $-\frac{GMm}{r}$

changes in PE are well defined

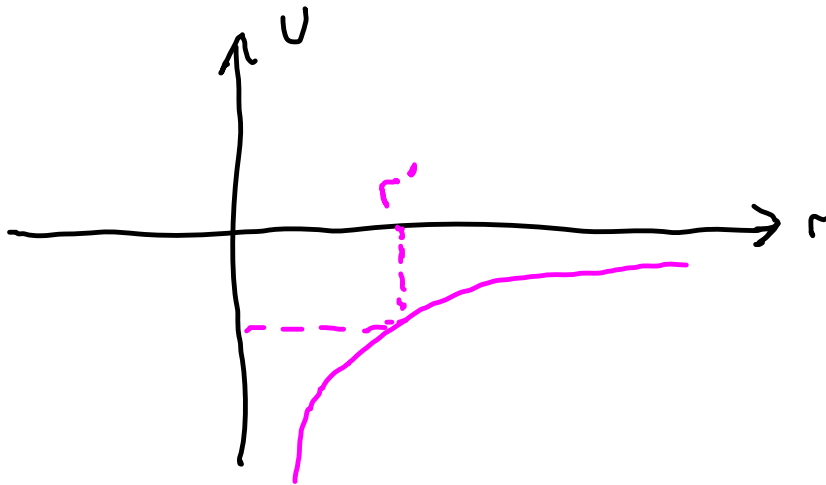
need "zero" to talk about absolute PE (Think height above sea level)

note as $r \rightarrow \infty$ $-\frac{GMm}{r} \rightarrow 0$



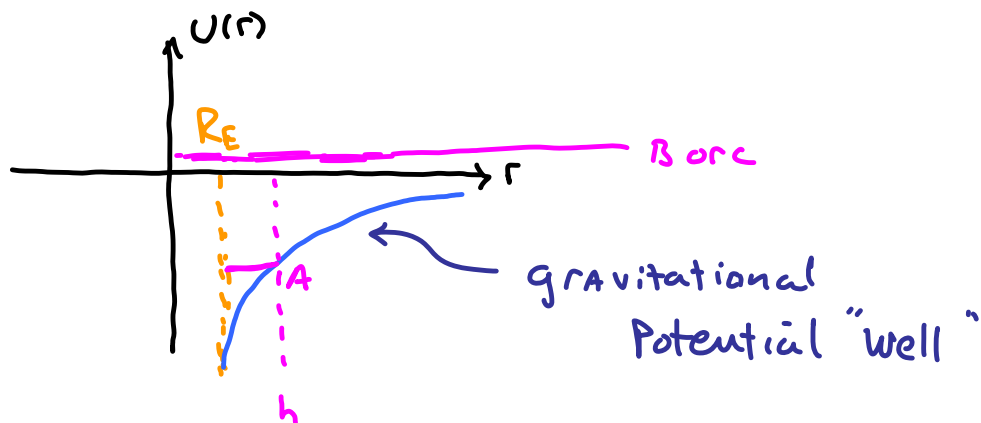
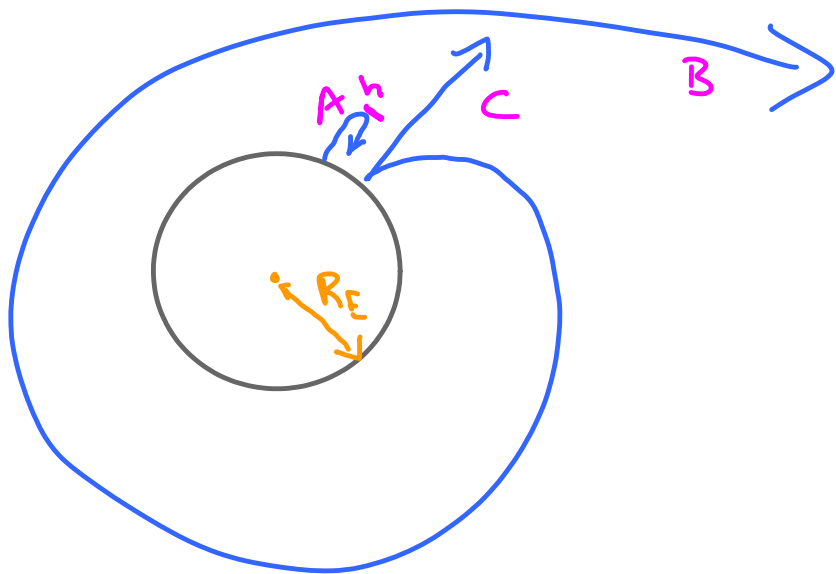
How much energy does this take?
 What is PE of m at position r

$$U = \text{PE}_{\text{at } r} = -\frac{GMm}{r} - \left(-\frac{GMm}{\infty}\right) = -\frac{GMm}{r}$$



what does it mean that
 $U(r)$ is negative?

$$U = -\frac{GMm}{r'}$$



Escape Velocity, V_{es}

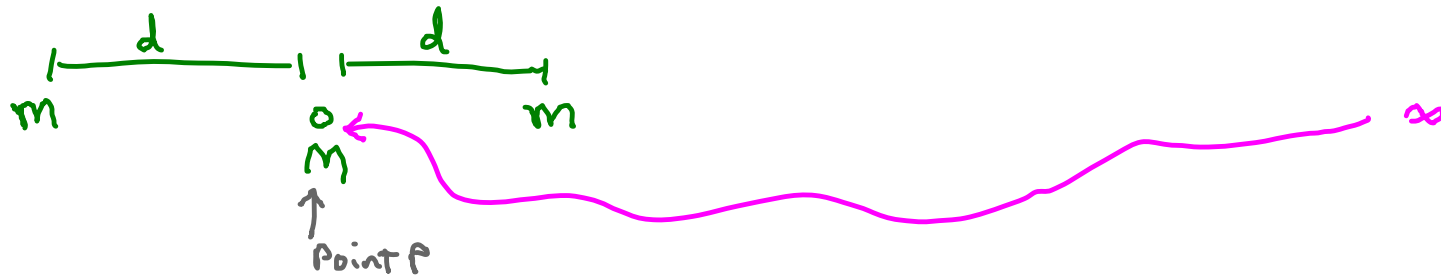
KE PE of "bound" state

$$\frac{1}{2} m V_{es}^2 = \frac{GMm}{r}$$

From Surface of Earth

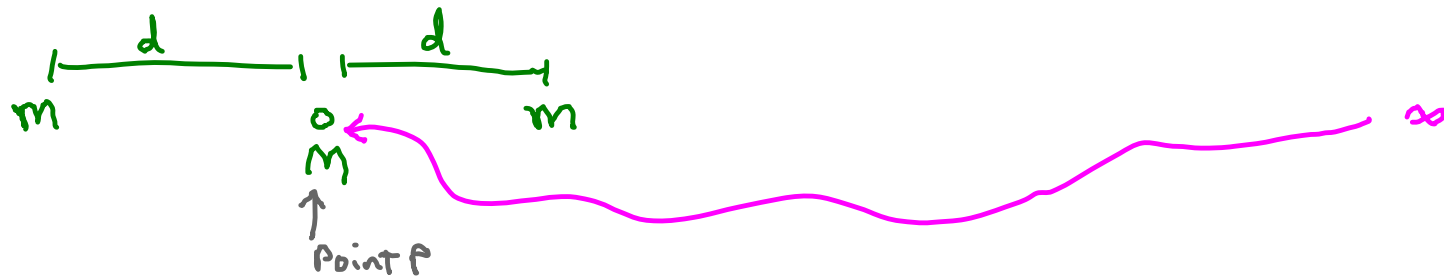
$$\frac{1}{2} m V_{es}^2 = \frac{GM_E m}{R_E}$$

$$V_{es} = \sqrt{\frac{2GM_E}{R_E}}$$



Mass M moved to point P from ∞ and released
 While at point P , what is the gravitational force on M ?

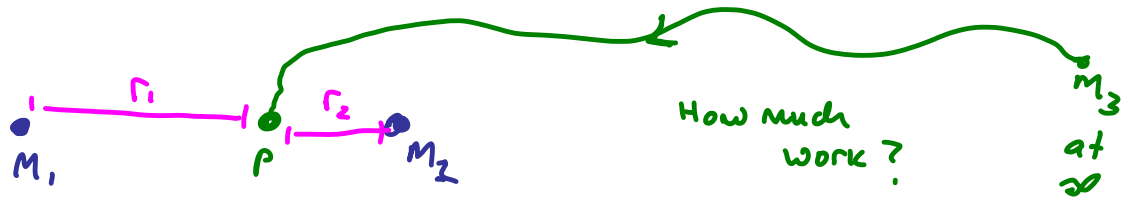
- | | | | | |
|-------------------|-------------------|---------------------|---------------------|---|
| I | II | III | IV | V |
| $-\frac{2GMm}{d}$ | $+\frac{2GMm}{d}$ | $-\frac{2GMm}{d^2}$ | $+\frac{2GMm}{d^2}$ | 0 |



While at point P , what is the Potential Energy Stored in the system?

I	II	III	IV	V
$-2 \frac{GMm}{d}$ $+ - \frac{GmM}{2d}$	$+ 2 \frac{GMm}{d}$	$- \frac{2GMm}{d^2}$	$+ \frac{2GMm}{d^2}$	0

Why potential?



$$\text{Energy to move } M_3 \text{ to point } P = \sum U_i = -\frac{GM_1M_3}{r_1} - \frac{GM_2M_3}{r_2}$$

Easier to calculate than \vec{F}_g

$$F_s = -\frac{dU_s}{ds}$$

$$\Sigma \vec{F} = m \vec{a} \quad \vec{P} \equiv \text{momentum} \quad \text{vector!}$$

$$\Sigma \vec{F} = \frac{d(m\vec{v})}{dt} = m \frac{d\vec{v}}{dt} + \frac{dm}{dt} \vec{v}$$

$\underbrace{\hspace{10em}}_{\vec{a}}$ $\underbrace{\hspace{10em}}_{\text{usually } 0}$

$\underbrace{\hspace{10em}}_{m\vec{a}}$

1D \rightarrow

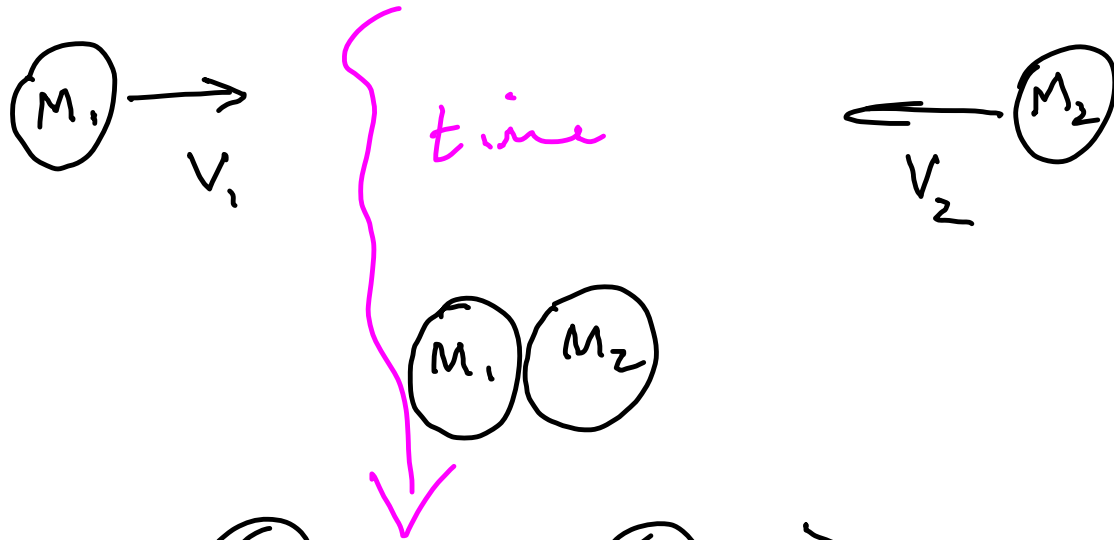
$$\begin{aligned} m v_x &= p_x \\ m v_y &= p_y \\ m v_z &= p_z \end{aligned}$$

$$\vec{F} = \frac{d\vec{p}}{dt}$$

Newton's Second Law

$$d\vec{p} = \vec{F} dt$$

$$\vec{p}_{\text{end}} - \vec{p}_{\text{start}} = \int d\vec{p} = \int_{t_1}^{t_2} \vec{F} dt \equiv \text{Impulse}$$



$$\Delta \vec{P}_1 = \int_{t_1}^{t_2} \vec{F}_{2 \text{ on } 1} dt$$

$$\Delta \vec{P}_2 = \int_{t_1}^{t_2} \vec{F}_{1 \text{ on } 2} dt$$

$$\vec{F}_{2 \text{ on } 1} = -\vec{F}_{1 \text{ on } 2}$$

$$\vec{\Delta P}_1 = -\vec{\Delta P}_2$$

$$\vec{\Delta P}_1 + \vec{\Delta P}_2 = 0$$

$$\vec{\Delta p}_1 + \vec{\Delta p}_2 = 0$$

$$\sum \vec{\Delta p}_i = 0$$

Momentum conservation

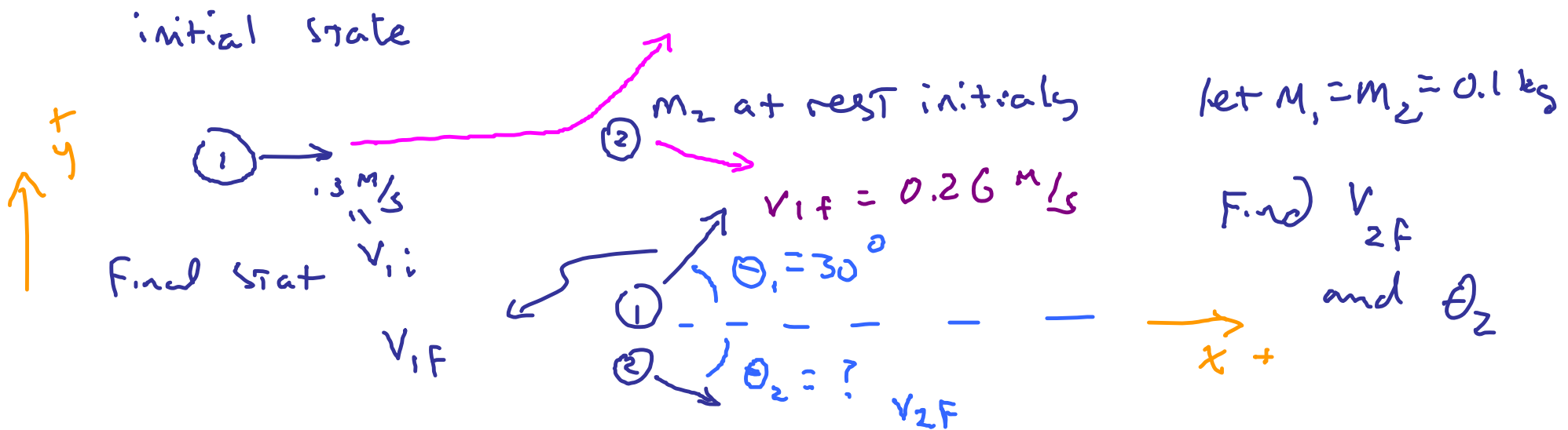
Total change in momentum (vector)
Summed over all bodies is zero

If no external forces on system,
The total momentum of system
is conserved.

$$\sum \vec{p}_i = \sum \vec{p}_f$$

Elastic Collision \equiv \longrightarrow \vec{P} conserved
KE conserved

Inelastic collision \equiv \longrightarrow \vec{P} conserved
KE NOT necessarily conserved

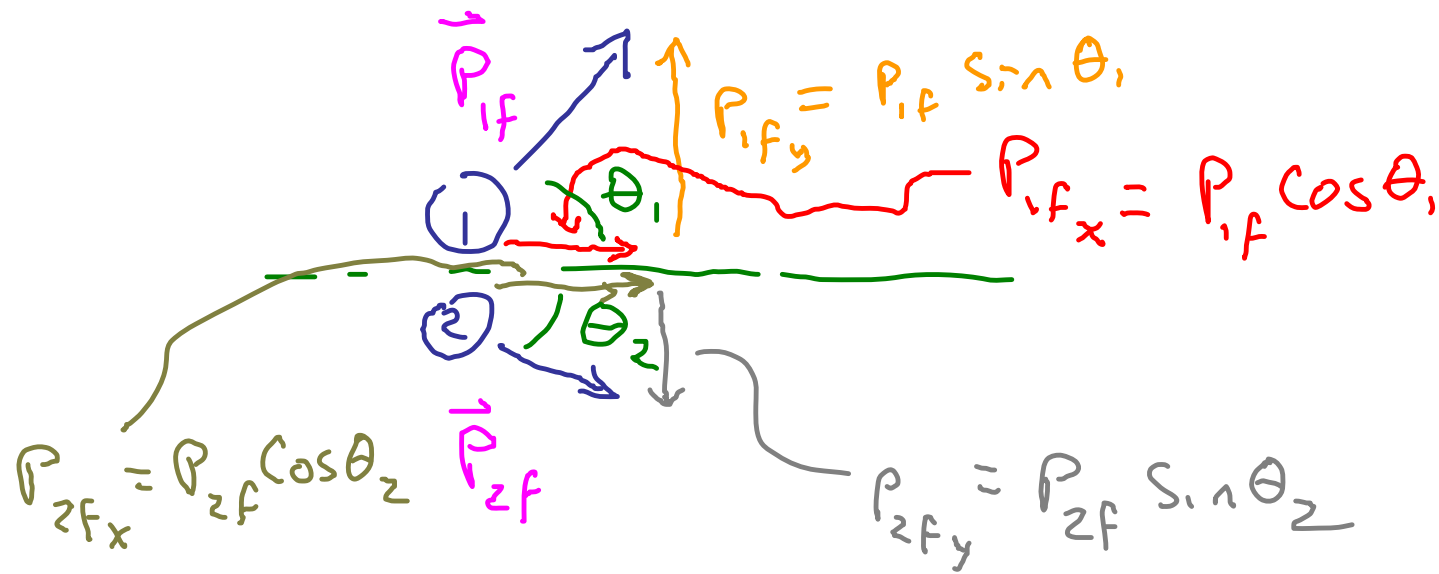


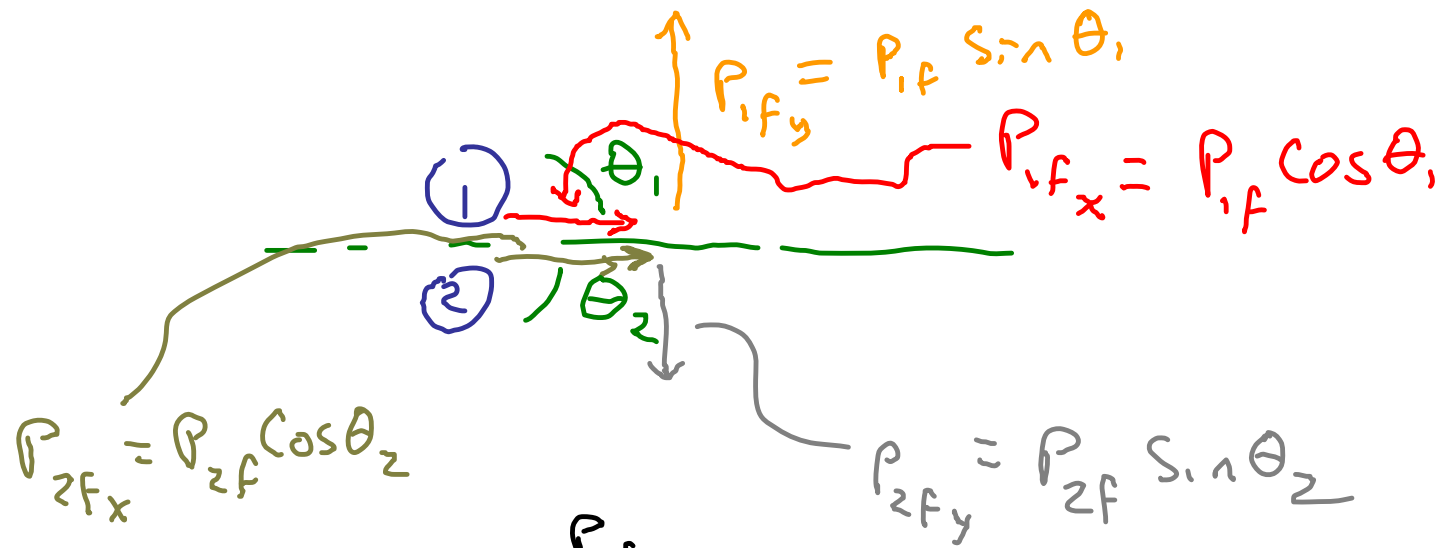
use P conc.

$$\sum \vec{P}_i = \sum \vec{P}_f \Rightarrow$$

$$\sum P_{x_i} = \sum P_{x_f}$$

$$\sum P_{y_i} = \sum P_{y_f}$$





x equ

$$m_1 V_{1i} = m_1 V_{1f} \cos \theta_1 + m_2 \underbrace{V_{2f}}_{P_{2f}} \cos \theta_2$$

y eqn

$$0 = m_1 v_{1f} \sin \theta_1 - m_2 v_{2f} \sin \theta_2$$

2 eqns

2 unknowns

$$|v_{2f}| = 0.15 \text{ m/s}$$

$\theta_2 = 6^\circ$ down from +x axis

$$\sin^2 \theta + \cos^2 \theta = 1$$