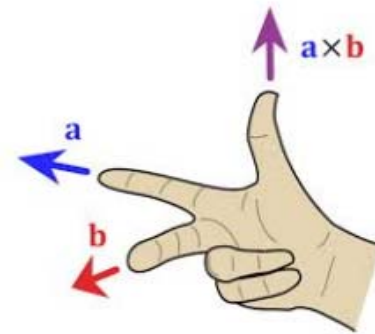
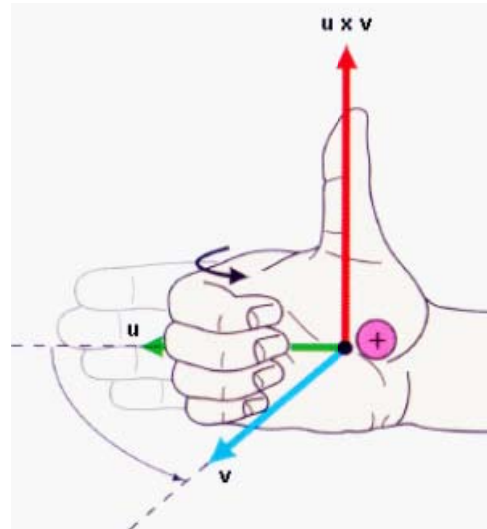
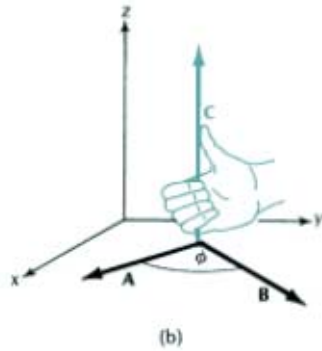
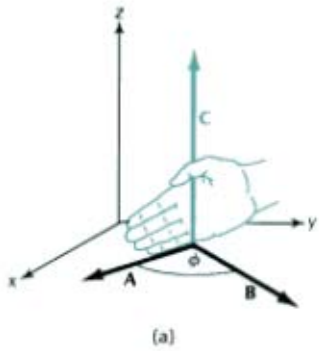


Physics 113 - November 14, 2013

Posted a RHR/cross product applet
also a "precession of a Top" applet

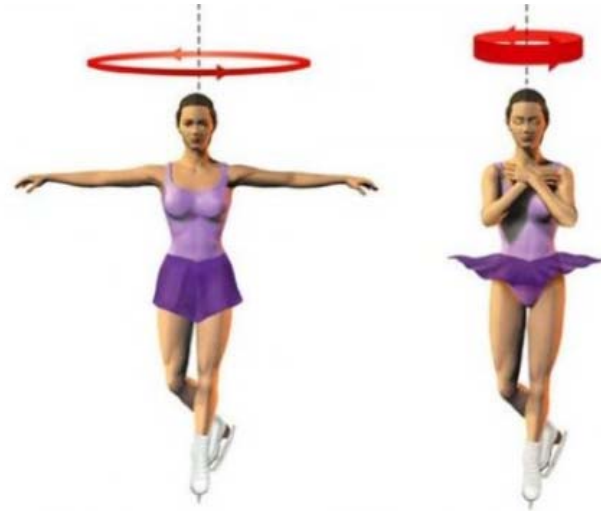


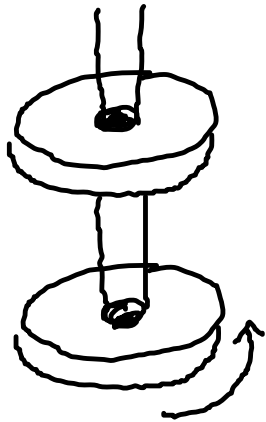
$$\vec{L} = \vec{r} \times \vec{F}$$

$$\vec{L} = I \vec{\omega}$$

$$\vec{L} = \frac{d\vec{L}}{dt} = I \frac{d\vec{\omega}}{dt}$$

Angular Momentum is conserved
(isolated system)
(vector!)





M, R, ω

$$I_{\text{disk}} = \frac{1}{2}MR^2$$

Top disk Not rotation

Identical

Falls and "sticks" to bottom

Disk without slipping

What is the final ω ?

Conservation of Energy

inelastic collision

$$\frac{1}{2}I\omega^2$$

~~=~~

for single disk
↓

$$\frac{1}{2}\left(\frac{1}{2}MR^2\right)\omega^2$$

$$= \frac{1}{2}\left(\frac{1}{2}MR^2\right)\omega'^2$$

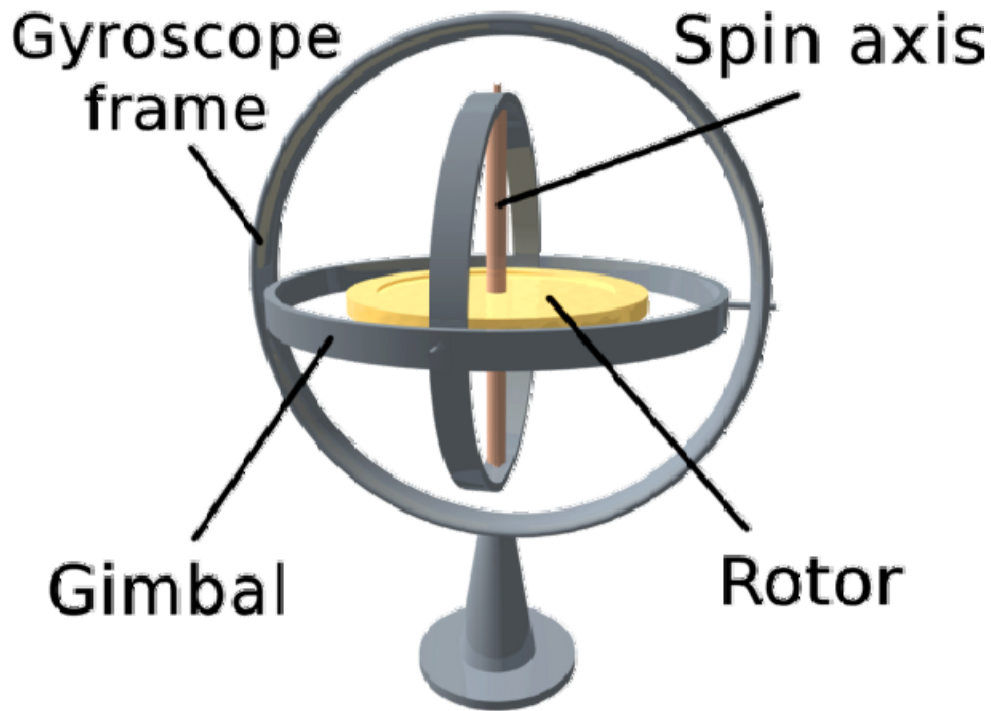
Use cons. of angular momentum

$$\vec{L}_{\text{start}} = \vec{L}_{\text{end}}$$

$$I\omega = I'\omega'$$

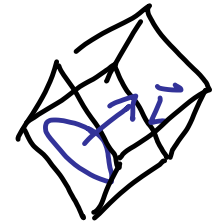
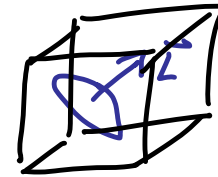
$$\frac{1}{2}MR^2\omega = \frac{(2)}{2}MR^2\omega'$$

$$\frac{\omega'}{\omega} = \frac{1}{2}$$



Free Spinning wheel from
external torques ... orientation is
fixed due to Ang. MOM. conservation

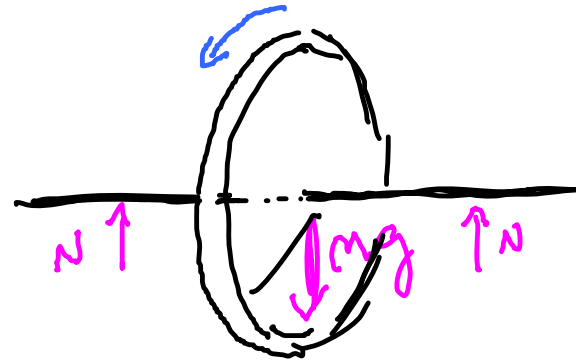
The gyroscope



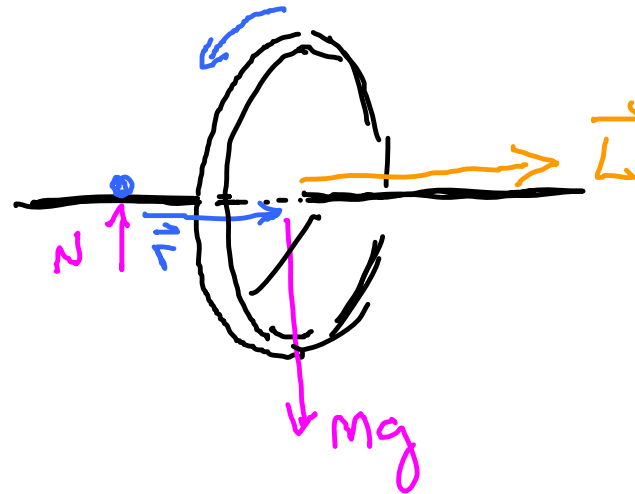
very imp. development for
navigation

$$\vec{L} = I\vec{\omega}$$

$$\vec{\tau} = \frac{d\vec{L}}{dt}$$

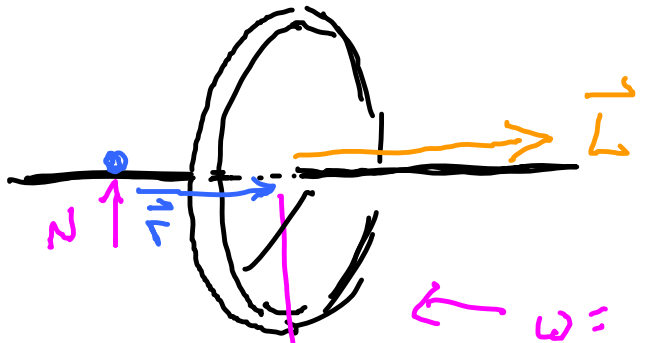


$$2N = mg$$

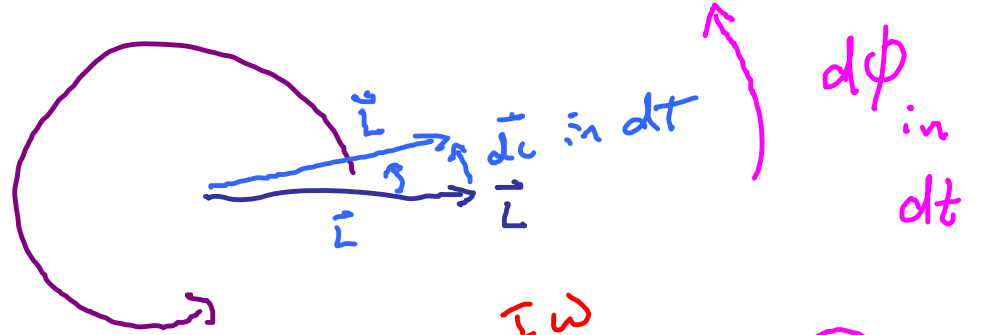


$$N = mg$$

A



$\omega =$
Angular
Vel. of
wheel rotation



$$\tau = \frac{dL}{dt}$$

$$Mg r = \tau = \frac{dL}{dt} = |\vec{L}| \frac{d\phi}{dt}$$

Ω ↑
Precession
velocity

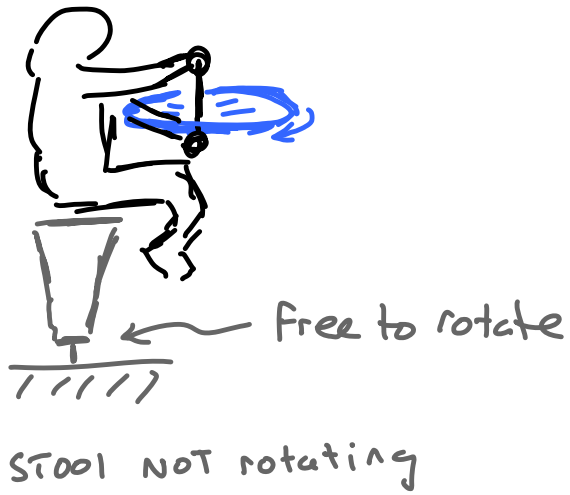
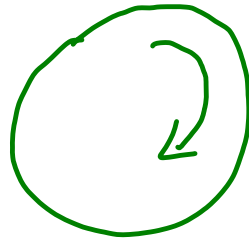
$I\omega$

↑

$$mgr = I\omega \Omega$$

$$\Omega = \frac{mgr}{I\omega}$$

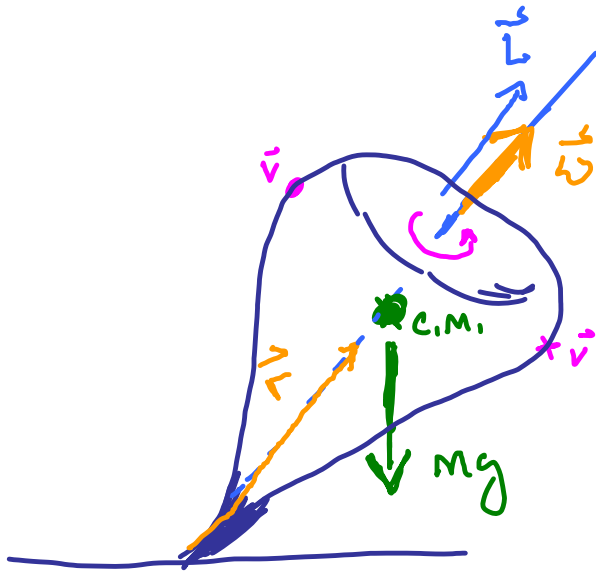
L →



How does stool rotate
as viewed from above?

- A) clockwise
- B) counter-clockwise
- C) no rotation

Spinning
Top



into
board

what direction is $\vec{\omega}$

what direction is \vec{L}

what direction is \vec{v}

what direction will the
Top precess?

