Physics 221A
Fall 2010
Notes 17
Coupling of Angular Momenta

1. Introduction

In these notes we discuss the coupling or addition of angular momenta, a problem that arises whenever different subsets of the degrees of freedom of a system, each possessing its own angular momentum operator, are combined to form the whole system. In such cases, the whole system also possesses an angular momentum operator. Alternatively, we may say that there is an action of the rotations on each of the subsets of degrees of freedom, which induces an action of rotations on the whole system. Such problems are very common in applications, and are important for computing and classifying energy eigenstates and for many other purposes.

2. The Tensor Product of Kets and Ket Spaces

We begin with the tensor product, a mathematical operation used in quantum mechanics to combine together the ket spaces corresponding to different degrees of freedom to obtain a ket space for a composite system. For example, one can combine the ket spaces for two individual particles, to obtain the ket space for a two-particle system; or one can combine the orbital and spin degrees of freedom for a single particle.

To be specific, suppose we have two spinless distinguishable particles, labeled 1 and 2, and let the ket spaces for these particles be denoted $E_1$ and $E_2$. These ket spaces can be identified with spaces of wave functions on 3-dimensional space, so we write

$$E_1 = \{ \phi(r), \text{ particle 1} \}$$
$$E_2 = \{ \chi(r), \text{ particle 2} \}. \quad (1)$$

We regard these two ket spaces as two distinct spaces, because they are associated with two different particles. The use of two symbols ($\phi$ and $\chi$) for the wave functions is just a way of reminding ourselves which particle is being referred to. Now the wave function space for the combined, two-particle system is another space, the space $E$ of wave functions defined on the combined, 6-dimensional configuration space ($r_1, r_2$):

$$E = \{ \psi(r_1, r_2) \}. \quad (2)$$

A special case of a two-particle wave function is a product of single particle wave functions,

$$\psi(r_1, r_2) = \phi(r_1)\chi(r_2), \quad (3)$$
but not every two-particle wave function can be written in this form. On the other hand, every two-particle wave function can be written as a linear combination of products of single particle wave functions. To see this, we simply introduce a basis \{u_n(r)\} of wave functions in \(E_1\), and another basis \{v_m(r)\} of wave functions in \(E_2\). Then an arbitrary two-particle wave function can be written,

\[
\psi(r_1, r_2) = \sum_{n,m} c_{nm} u_n(r_1) v_m(r_2),
\]

(4)

where the \(c_{nm}\) are expansion coefficients. In other words, the products of single particle basis wave functions forms a basis in the wave function space for two particles.

In the construction we have just presented, we say that the space \(E\) is the tensor product of the spaces \(E_1\) and \(E_2\), and we write

\[
E = E_1 \otimes E_2.
\]

(5)

Loosely speaking, one can say that the tensor product space is the space spanned by the products of wave functions from the two constituent spaces.

In addition to forming the tensor product of ket spaces, one can also form the tensor product of kets. An example is given in wave function language by Eq. (3), which in ket language would be written

\[
|\psi\rangle = |\phi\rangle \otimes |\chi\rangle.
\]

(6)

Thus, the tensor product of kets corresponds to the ordinary product of wave functions. Often in casual physics notation, the tensor product sign \(\otimes\) is omitted from a tensor product such as (6), and one simply writes \(|\psi\rangle = |\phi\rangle|\chi\rangle\).

More generally, suppose \(E_1\) is a ket space spanned by the basis \(|u_n\rangle\), and \(E_2\) is a ket space spanned by the basis \(|v_m\rangle\). Then \(E_1 \otimes E_2\) is a new ket space spanned by the basis kets \(|u_n\rangle \otimes |v_m\rangle\). If \(E_1\) and \(E_2\) are finite-dimensional, then so is \(E\), and we have

\[
\dim E = (\dim E_1)(\dim E_2).
\]

(7)

If either \(E_1\) or \(E_2\) is infinite-dimensional, then so is \(E\).

3. The Case of Particles with Spin

An important example of the tensor product occurs when we combine the spatial or orbital degrees of freedom of a single particle with the spin degrees of freedom. We can define orbital and spin ket spaces by

\[
E_{\text{orb}} = \text{span}\{|r\rangle\},
\]

\[
E_{\text{spin}} = \text{span}\{|m\rangle\},
\]

(8)

where \(m = -s, \ldots, +s\). Notice that \(E_{\text{orb}}\) is infinite-dimensional, whereas \(E_{\text{spin}}\) is finite-dimensional. Then the total Hilbert space for the particle is

\[
E = E_{\text{orb}} \otimes E_{\text{spin}} = \text{span}\{|r\rangle \otimes |m\rangle\}.
\]

(9)
Let us write
\[ |r, m⟩ = |r⟩ \otimes |m⟩ \] (10)
for the basis vectors of the tensor product space, so that an arbitrary ket \(|ψ⟩\) belonging to \(E\) can be written as a linear combination of these basis vectors. Then we have
\[ |ψ⟩ = \sum_m \int d^3r |r, m⟩⟨r, m|ψ⟩ = \sum_m \int d^3r |r⟩ \psi_m(r), \] (11)
where
\[ ψ_m(r) = ⟨r, m|ψ⟩. \] (12)
These operations illustrate how we can go back and forth between ket language and wave function language for a particle with spin; the wave function \(ψ_m(r)\) is a multi-component or spinor wave function, which one can imagine as a column vector. For example, in the case of a spin-\(\frac{1}{2}\) particle, we can write
\[ ψ_+(r) = \begin{pmatrix} ψ_+(r) \\ ψ_-(r) \end{pmatrix}. \] (13)

4. The Tensor Product of Operators

One can also form the tensor product of operators. Suppose \(A_1\) is an operator that acts on \(E_1\), and \(A_2\) is an operator that acts on \(E_2\), and let \(E = E_1 \otimes E_2\). Then we define an operator \(A_1 \otimes A_2\), whose action on a tensor product of vectors from \(E_1\) and \(E_2\) is given by
\[ (A_1 \otimes A_2)(|α⟩_1 \otimes |β⟩_2) = (A_1|α⟩_1) \otimes (A_2|β⟩_2). \] (14)
In this equation, the subscripts 1, 2 on the kets indicate which space (\(E_1\) or \(E_2\)) the kets belong to. But since an arbitrary vector in \(E\) can be represented as a linear combination of tensor products of vectors from \(E_1\) and \(E_2\), we can use linear superposition to extend Eq. (14) to define the action of \(A_1 \otimes A_2\) on an arbitrary vector in \(E\). Again, in casual physics notation, the tensor product sign is often omitted in a product of operators such as \(A_1 \otimes A_2\), and one would simply write \(A_1 A_2\).

A special case of the above is when one or the other of the operators \(A_1\) or \(A_2\) is the identity. For example, if \(A_2 = 1\), we have
\[ (A_1 \otimes 1)(|α⟩_1 \otimes |β⟩_2) = (A_1|α⟩_1) \otimes |β⟩_2. \] (15)
In such cases it would be normal in casual physics notation to write simply \(A_1\) instead of \(A_1 \otimes 1\), thereby confusing an operator that acts on \(E_1\) with an operator that acts on \(E\). Similar considerations apply to operators of the form \(1 \otimes A_2\), where \(A_1 = 1\). We note that operators of the type \(A_1, A_2\), when regarded as acting on the tensor product space \(E\), always commute with one another,
\[ [A_1 \otimes 1, 1 \otimes A_2] = [A_1, A_2] = 0, \] (16)
as follows from Eq. (14). As we say, \(A_1\) and \(A_2\) commute because they act on different spaces.
5. The Problem of Addition of Angular Momenta

Now suppose we have two ket spaces $E_1$ and $E_2$ upon which two angular momentum operators $J_1$ and $J_2$ act, each of which satisfies the angular momentum commutation relations (13.1). The case of the orbital and spin ket spaces discussed above is a good example; if $E_1 = E_{\text{orb}}$ and $E_2 = E_{\text{spin}}$, then the angular momentum $J_1$ is the orbital angular momentum $L$ and $J_2$ is the spin angular momentum $S$. Then in accordance with the general theory laid out in Notes 13, we know that each space $E_1$ and $E_2$ breaks up into the direct sum of a set of irreducible subspaces, each with a definite $j$ value. For example, the irreducible subspaces of $E_{\text{orb}}$ are spanned by wave functions of the form $u_n(r)Y_{\ell m}(\theta, \phi)$ for a definite element of a basis $\{u_n(r)\}$ of radial wave functions, a definite value of $\ell$, and for $-\ell \leq m \leq +\ell$. This subspace has dimensionality $2\ell + 1$. As for the space $E_{\text{spin}}$, it consists of a single irreducible subspace of dimensionality $2s + 1$, characterized by the value $s$ of the spin.

In the general case, the spaces $E_1$ and $E_2$ possess standard angular momentum bases, say, $\{|\gamma_1 j_1 m_1\rangle\}$ and $\{|\gamma_2 j_2 m_2\rangle\}$, in the notation of Notes 13. We denote the corresponding irreducible subspaces by $E_{1\gamma_1 j_1}$ and $E_{2\gamma_2 j_2}$, so that

$$E_1 = \bigoplus_{\gamma_1 j_1} \oplus E_{1\gamma_1 j_1},$$

$$E_2 = \bigoplus_{\gamma_2 j_2} \oplus E_{2\gamma_2 j_2}.$$  

We assume that since operators $J_1$ and $J_2$ are given, we know what values of $j_1$ and $j_2$ occur in these decompositions of $E_1$ and $E_2$ and with what multiplicity, we know what the standard angular momentum bases are on $E_1$ and $E_2$.

Next consider the tensor product space $E = E_1 \otimes E_2$. We define a “total” angular momentum operator acting on $E$ by

$$J = J_1 \otimes 1 + 1 \otimes J_2 = J_1 + J_2,$$  

where the final expression is in casual physics notation. We note that $J_1$ and $J_2$ commute,

$$[J_1, J_2] = 0,$$  

since they act on different spaces. (This commutator means that every component of $J_1$ commutes with every component of $J_2$.) From this it easily follows that $J$ also satisfies the angular momentum commutation relations,

$$[J_i, J_j] = i\hbar \epsilon_{ijk} J_k.$$  

Therefore we have a new space $E$ upon which a vector $J$ of angular momentum operators acts; in accordance with the theory of Notes 13, this space breaks up into the direct sum of a sequence of irreducible subspaces, each characterized by some $j$ value. Furthermore, we know that there exists a standard basis $|\gamma j m\rangle$ on $E$. The basic problem of the addition of angular momenta is to find which values of $j$ occur in $E$ and with what multiplicity, and to find some convenient way of constructing the standard basis $|\gamma j m\rangle$. 

6. Restricting Spaces $\mathcal{E}_1$ and $\mathcal{E}_2$

In solving this problem it suffices to consider the case in which $\mathcal{E}_1$ and $\mathcal{E}_2$ consist of a single irreducible subspace. For example, in the case of the combination of orbital and spin degrees of freedom, instead of considering the infinite dimensional space of wave functions in $\mathcal{E}_{\text{orb}}$, we can consider a single, finite-dimensional space spanned by the wave functions \{\(u(r)Y_{\ell m}(\theta, \phi), m = -\ell, \ldots, +\ell\)\} for a definite radial wave function $u(r)$ and a definite value of $\ell$. The spin space $\mathcal{E}_{\text{spin}}$ already consists of a single irreducible subspace, and need not be restricted. This is because (in the general case) the product space $\mathcal{E}$ is the direct sum of tensor products of the irreducible subspaces $\mathcal{E}_1^{\gamma_1 \ell_1}$ and $\mathcal{E}_2^{\gamma_2 \ell_2}$, and these tensor products can be handled one at a time. That is,\[
\mathcal{E} = \mathcal{E}_1 \otimes \mathcal{E}_2 = \sum_{\gamma_1 \ell_1, \gamma_2 \ell_2} (\mathcal{E}_{\gamma_1 \ell_1} \otimes \mathcal{E}_{\gamma_2 \ell_2}),\]
(21)
as follows from Eq. (17). Therefore in the following we will restrict $\mathcal{E}_1$ to one of its subspaces $\mathcal{E}_1^{\gamma_1 \ell_1}$ and $\mathcal{E}_2$ to one of its subspaces $\mathcal{E}_2^{\gamma_2 \ell_2}$, so that $\mathcal{E} = \mathcal{E}_1 \otimes \mathcal{E}_2$ will henceforth stand for just one of the terms in the sum (21).

This means that $\mathcal{E}_1$ and $\mathcal{E}_2$ are $(2\ell_1 + 1)$- and $(2\ell_2 + 1)$-dimensional, respectively, with standard bases \{|j_1 m_1\}\) and \{|j_2 m_2\}\). The indices $\gamma_1$ and $\gamma_2$ are dropped because we now only have one irreducible subspace. Similarly, the indices $\ell_1$ and $\ell_2$ are constants characterizing the subspaces $\mathcal{E}_1$ and $\mathcal{E}_2$. If these were understood, it would be possible to drop them as well, and write the standard bases in $\mathcal{E}_1$ and $\mathcal{E}_2$ simply as \{|m_1\}\) and \{|m_2\}\), respectively, but for clarity we shall retain indices $\ell_1$ and $\ell_2$ in the following discussion. As for the space $\mathcal{E} = \mathcal{E}_1 \otimes \mathcal{E}_2$, it also possesses a standard angular momentum basis, \{|j \gamma m\}\), in which for all we know at this point an index $\gamma$ is necessary to indicate possible multiple occurrences of different $j$ values. As it will turn out, however, the maximum multiplicity of the different $j$ values is 1, so the $\gamma$ index is unnecessary here as well. The space $\mathcal{E}$ has dimensionality\[
\dim \mathcal{E} = (2\ell_1 + 1)(2\ell_2 + 1).\]
(22)

We can now rephrase the problem of the addition of angular momenta. It is to find which $j$ values occur in the space $\mathcal{E} = \mathcal{E}_1 \otimes \mathcal{E}_2$ and with what multiplicity as a function of the given parameters $\ell_1$ and $\ell_2$, and to find convenient ways of constructing the standard angular momentum basis in $\mathcal{E}$.

7. Two Bases in $\mathcal{E}$

The standard basis kets in $\mathcal{E}_1$, \{|j_1 m_1\}\), are eigenkets of the operators $J^2$ and $J_z$ with eigenvalues $j_1(j_1 + 1)\hbar^2$ and $m_1\hbar$, respectively, and similarly for space $\mathcal{E}_2$ with its standard basis kets \{|j_2 m_2\}\). The tensor products of these basis kets form a basis in $\mathcal{E} = \mathcal{E}_1 \otimes \mathcal{E}_2$. We adopt the shorthand notation for this basis in $\mathcal{E}$,\[
|j_1 j_2 m_1 m_2) = |j_1 m_1) \otimes |j_2 m_2),\]
(23)
where $m_1 = -j_1, \ldots, j_1$ and $m_2 = -j_2, \ldots, j_2$. We will call the basis \{\ket{j_1 j_2 m_1 m_2}\} in $\mathcal{E}$ the tensor product basis or uncoupled basis.

The standard basis in $\mathcal{E}$ will be denoted \{\ket{jm}\}, without the $\gamma$ in anticipation of the fact that it will not be needed. We will call this basis the coupled basis. We will be interested in the unitary matrix that connects the coupled with the uncoupled basis.

### 8. Allowed Values of $j$ and $m$

The kets of the coupled or standard basis in $\mathcal{E}$, \ket{jm}, are eigenkets of the operators $J^2 = (J_1 + J_2)^2$ and $J_z = J_{1z} + J_{2z}$ with eigenvalues $j(j+1)\hbar^2$ and $m\hbar$, respectively. We will now find which values of $j$ and $m$ occur.

We start by finding the eigenstates of $J_z$. This is easy, because the vectors of the tensor product basis are all eigenkets of $J_z = J_{1z} + J_{2z}$, with eigenvalues $(m_1 + m_2)\hbar$:

$$J_z \ket{j_1 j_2 m_1 m_2} = (J_{1z} + J_{2z}) \ket{j_1 m_1} \ket{j_2 m_2} = (m_1 + m_2)\hbar \ket{j_1 j_2 m_1 m_2} = m\hbar \ket{j_1 j_2 m_1 m_2},$$

where we set

$$m = m_1 + m_2$$

for the quantum number of $J_z$. The spectrum of $J_z$ ranges from the maximum value of $m_1 + m_2$, which is $j_1 + j_2$, down to the minimum, which is $-(j_1 + j_2)$.

![Fig. 1](image)

**Fig. 1.** Each dot in the rectangular array stands for one vector of the uncoupled or tensor product basis, $\ket{j_1 j_2 m_1 m_2} = \ket{j_1 m_1} \ket{j_2 m_2}$. The dashed lines are contours of $m = m_1 + m_2$.

These eigenvalues of $J_z$ are in general degenerate. To follow the subsequent argument, it helps to have an example. Let us take the case $j_1 = \frac{5}{2}$ and $j_2 = 1$, so that $2j_1 + 1 = \dim \mathcal{E}_1 = 6$ and
2j_2 + 1 = \dim \mathcal{E}_2 = 3. Thus, the dimensionality of \mathcal{E} = \mathcal{E}_1 \otimes \mathcal{E}_2 is 6 \times 3 = 18. It is convenient to make a plot in the m_1-m_2 plane of the basis vectors of the tensor product basis, by placing a dot at each allowed m_1 and m_2 value. We then obtain a rectangular array of dots, as illustrated in Fig. 1. As illustrated in the figure, lines of constant m = m_1 + m_2 are straight lines, dashed in the figure, sloping downwards. The number of dots each dashed line passes through is the number of kets of the uncoupled basis with a given m value; we see that the degeneracies of the different m values range from one to three, as summarized in Table 1.

In particular, the stretched state (the one for which (m_1, m_2) = (j_1, j_2), in the upper right hand corner in the figure) is a nondegenerate eigenstate of J_z with quantum number m = \frac{7}{2}. But since [J^2, J_z] = 0, this state is also an eigenstate of J^2, in accordance with Theorem 1.5. But what is the eigenvalue of J^2, that is, what is the quantum number j? Certainly we cannot have j < \frac{7}{2}, because then this would violate the rule m \leq j. Nor can we have j > \frac{7}{2}, because, for example, if the stretched state were the state |jm\rangle = |\frac{9}{2}, \frac{7}{2}\rangle, then we could apply the raising operator J_+ and obtain the state |\frac{9}{2}, \frac{9}{2}\rangle. But there is no state with m = \frac{9}{2}, as we see from the figure or table. Therefore the j quantum number of the stretched state must be j = \frac{7}{2}; this state is the state |\frac{7}{2}, \frac{7}{2}\rangle of the coupled basis. But given this state, we can apply lowering operators J_- to obtain all eight states |\frac{7}{2}, m\rangle, which are indicated in the third column of the table.

<table>
<thead>
<tr>
<th>m</th>
<th>g(m)</th>
<th>j = \frac{7}{2}</th>
<th>j = \frac{9}{2}</th>
<th>j = \frac{3}{2}</th>
</tr>
</thead>
<tbody>
<tr>
<td>\frac{7}{2}</td>
<td>1</td>
<td>1</td>
<td></td>
<td></td>
</tr>
<tr>
<td>\frac{5}{2}</td>
<td>2</td>
<td>1</td>
<td>1</td>
<td></td>
</tr>
<tr>
<td>\frac{3}{2}</td>
<td>3</td>
<td>1</td>
<td>1</td>
<td>1</td>
</tr>
<tr>
<td>\frac{1}{2}</td>
<td>3</td>
<td>1</td>
<td>1</td>
<td>1</td>
</tr>
<tr>
<td>-\frac{1}{2}</td>
<td>3</td>
<td>1</td>
<td>1</td>
<td>1</td>
</tr>
<tr>
<td>-\frac{3}{2}</td>
<td>2</td>
<td>1</td>
<td>1</td>
<td></td>
</tr>
<tr>
<td>-\frac{5}{2}</td>
<td>1</td>
<td>1</td>
<td></td>
<td></td>
</tr>
<tr>
<td>Total</td>
<td>18</td>
<td>8</td>
<td>6</td>
<td>4</td>
</tr>
</tbody>
</table>

Table 1. The first column contains m, the quantum number of J_z; the second column contains g(m), the degeneracy of m; columns 3, 4 and 5 contain a unit for each vector |jm\rangle of the standard or coupled basis with given j and m values.

Now let us consider the 2-dimensional eigenspace of J_z corresponding to quantum number m = \frac{5}{2}. This space is spanned by the kets of the uncoupled basis corresponding to (m_1, m_2) = (\frac{5}{2}, 0) and (\frac{5}{2}, 1). Furthermore, the ket |\frac{7}{2}, \frac{5}{2}\rangle of the coupled basis also lies in this space. Let us consider the ket, call it |x\rangle, that is orthogonal to |\frac{7}{2}, \frac{5}{2}\rangle in this space. Certainly |x\rangle is an eigenket of J_z with eigenvalue \frac{5}{2}. And it is also an eigenket of J^2, a fact that is left as an exercise (the logic is an extension of the proof of Theorem 1.5). But what is the j value? Certainly we cannot have j < \frac{5}{2}, because this would violate the m \leq j rule. Nor can we have j > \frac{5}{2}, because if we had j = \frac{7}{2}, for example, for the state |x\rangle, then we would have two linearly independent states, both with m = \frac{5}{2}.
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and \( j = \frac{7}{2} \). We could then apply the raising operator \( J_+ \) to both of them, and obtain two linearly independent states with \( m = \frac{7}{2}, j = \frac{7}{2} \). But there is only one state with \( m = \frac{3}{2} \), as we see from the figure or table. Therefore we must have \( j = \frac{5}{2} \) for the state \( |x\rangle \), which otherwise is the ket \( |\frac{5}{2}, \frac{1}{2}\rangle \) of the coupled basis. Then, by applying lowering operators to this, we obtain all six vectors \( |\frac{3}{2} m\rangle \), which are indicated in the fourth column of the table. Finally, we carry out the same procedure for the 3-dimensional space corresponding to \( m = \frac{3}{2} \), and we obtain four more vectors \( |\frac{3}{2} m\rangle \) of the coupled basis.

In this way, all 18 dimensions of \( E \) are used up, as indicated by the totals at the bottom of the table. We see that the tensor product space \( E \) consists of the direct sum of three irreducible subspaces, corresponding to \( j = \frac{3}{2}, \frac{5}{2}, \) and \( \frac{7}{2} \), and that each of these \( j \) values occurs with multiplicity one. These facts are summarized by the notation,

\[
\frac{5}{2} \otimes 1 = \frac{3}{2} \oplus \frac{5}{2} \oplus \frac{7}{2},
\]

which corresponds to the dimensionality count,

\[
18 = 6 \times 3 = 4 + 6 + 8.
\]

By using diagrams like these, it is easy to work out the general case in which we combine arbitrary angular momenta \( j_1 \) and \( j_2 \). The result is

\[
j_1 \otimes j_2 = |j_1 - j_2| \oplus |j_1 - j_2| + 1 \oplus \ldots \oplus j_1 + j_2,
\]

that is, the \( j \) values in \( j_1 \otimes j_2 \) range from a minimum of \( |j_1 - j_2| \) to a maximum of \( j_1 + j_2 \) in integer steps, and each \( j \) value in this range occurs once. Since no \( j \) value occurs more than once, there is no need for the index \( \gamma \), and the vectors of the coupled basis can be denoted simply \( |jm\rangle \). Also, since the dimensionalities of the subspaces must add up to the dimensionality of the tensor product space, we have the identity

\[
\sum_{j=|j_1 - j_2|}^{j_1 + j_2} 2j + 1 = (2j_1 + 1)(2j_2 + 1).
\]

This identity can be proved by elementary algebra, as a check on the count of dimensions.

9. The Clebsch-Gordan Coefficients

At this point we have two bases in \( E = \mathcal{E}_1 \otimes \mathcal{E}_2 \), the uncoupled basis \( |j_1 j_2 m_1 m_2\rangle \) with \(-j_1 \leq m_1 \leq j_1 \) and \(-j_2 \leq m_2 \leq j_2 \) and the coupled basis \( |jm\rangle \) with \( |j_1 - j_2| \leq j \leq j_1 + j_2 \) and \(-j \leq m \leq j \). These two bases must be connected by a unitary matrix, the components of which are just the scalar products of the vectors from one basis with the vectors from the other. That is, we have

\[
|jm\rangle = \sum_{m_1 = -j_1}^{j_1} \sum_{m_2 = -j_2}^{j_2} |j_1 j_2 m_1 m_2\rangle \langle j_1 j_2 m_1 m_2|jm\rangle,
\]

\[
|j_1 j_2 m_1 m_2\rangle = \sum_{j=|j_1 - j_2|}^{j_1 + j_2} \sum_{m=-j}^{j} |jm\rangle \langle jm|j_1 j_2 m_1 m_2\rangle,
\]
which can be regarded as the insertion of two resolutions of the identity in two different ways. The expansion coefficients \( \langle j_1 j_2 m_1 m_2 | j m \rangle \) or \( \langle j m | j_1 j_2 m_1 m_2 \rangle \) are called the Clebsch-Gordan coefficients or the vector coupling coefficients. Note the effect of the selection rule (34) on the sums (30): many of the terms are zero.

The Clebsch-Gordan coefficients can be calculated in a straightforward way by using lowering operators and by constructing states (such as \( | x \rangle \) in the discussion above) that are orthogonal to all known states in a subspace of given \( m \). In this process, it is necessary to make certain phase conventions; the standard is to follow the phase conventions discussed in Notes 13, in which the matrix elements of \( J_\pm \) in the standard basis are real and positive, and to require in addition

\[
\langle j j | j_1 j_2 j_1 - j_1 \rangle > 0,
\]

for each allowed \( j \) value. Under these phase conventions, the Clebsch-Gordan coefficients are real, that is,

\[
\langle j m | j_1 j_2 m_1 m_2 \rangle = \langle j_1 j_2 m_1 m_2 | j m \rangle ,
\]

so that the unitary matrix connecting the coupled and uncoupled bases is in fact a real, orthogonal matrix.

The Clebsch-Gordan coefficients also satisfy various recursion relations. We can obtain one of these by applying \( J_- = J_{1-} + J_{2-} \) to Eq. (30a). This gives

\[
\frac{1}{\hbar} J_- | j m \rangle = \sqrt{(j + m)(j - m + 1)} | j, m - 1 \rangle
\]

\[
= \sum_{m_1 m_2} \left( \sqrt{(j_1 + m_1)(j_1 - m_1 + 1)} | j_1 j_2, m_1 - 1, m_2 \rangle + \sqrt{(j_2 + m_2)(j_2 - m_2 + 1)} | j_1 j_2 m_1, m_2 - 1 \rangle \right) \langle j_1 j_2 m_1 m_2 | j m \rangle
\]

\[
= \sum_{m_1 m_2} \left( \sqrt{(j_1 + m_1 + 1)(j_1 - m_1)} | j_1 j_2, m_1 + 1, m_2 \rangle \right) \langle j_1 j_2 m_1 m_2 | j m \rangle
\]
\[ + \sqrt{(j_2 + m_2 + 1)(j_2 - m_2)} \langle j_1, j_2 m_1, m_2 + 1|jm \rangle \]
\[ \times |j_1, j_2 m_1 m_2\rangle, \quad (35) \]
to which we apply the bra \( \langle j_1, j_2 m_1' m_2'| \) from the left and rearrange indices to obtain,
\[ \langle j_1, j_2 m_1 m_2|jm \rangle = \frac{1}{\sqrt{(j + m + 1)(j - m)}} \]
\[ \left[ \sqrt{(j_1 + m_1 + 1)(j_1 - m_1)} \langle j_1, j_2 m_1 + 1, m_2|jm \rangle \right. \]
\[ \left. + \sqrt{(j_2 + m_2 + 1)(j_2 - m_2)} \langle j_1, j_2 m_1, m_2 + 1|jm \rangle \right]. \quad (36) \]

Similar recursion relations follow by using \( J_+ \), or by working with Eq. (30b). These recursion relations are of use in calculating the Clebsch-Gordan coefficients.

Other properties of the Clebsch-Gordan coefficients include the following identities:
\[ \langle j_1, j_2 m_1 m_2|jm \rangle = (-1)^{j_1 + j_2 - j} \langle j_2, j_1 m_2 m_1|jm \rangle, \quad (37a) \]
\[ = (-1)^{j_1 - j + m_2} \frac{2j + 1}{2j_1 + 1} \langle jj_2 m_1, m_2|jm \rangle, \quad (37b) \]
\[ = (-1)^{j_1 - j - m_1} \frac{2j + 1}{2j_2 + 1} \langle j_1, j_2, m_1, m_2|jm \rangle, \quad (37c) \]
\[ = (-1)^{j_1 + j_2 - j} \langle j_1, j_2, m_1, m_2|jm \rangle. \quad (37d) \]

We will not prove these identities here. If you ever have to use such identities in a serious way, you should look into the Wigner 3j-symbols, which provide a more symmetrical way of dealing with Clebsch-Gordan coefficients.

It is convenient to regard the Clebsch-Gordan coefficient \( \langle jm|j_1, j_2 m_1 m_2 \rangle \) as being equal to zero if any of the parameters lie outside the range for which they are meaningful, for example, if \( j > j_1 + j_2 \) or \( m > j \).

10. Rotations, \( D \)-matrices and Clebsch-Gordan Coefficients

Let us now consider the effect of the rotation operator \( U(\hat{n}, \theta) \) on the tensor product space \( \mathcal{E} = \mathcal{E}_1 \otimes \mathcal{E}_2 \). This rotation operator is defined in the usual way, and can be expressed in terms of the rotation operators \( U_1(\hat{n}, \theta) \) and \( U_2(\hat{n}, \theta) \) that act on the constituent spaces \( \mathcal{E}_1 \) and \( \mathcal{E}_2 \):
\[ U(\hat{n}, \theta) = e^{-i\hat{n} \cdot J / \hbar} = e^{-i\hat{n} \cdot (J_1 + J_2) / \hbar} \]
\[ = e^{-i\hat{n} \cdot J_1 / \hbar} e^{-i\hat{n} \cdot J_2 / \hbar} = U_1(\hat{n}, \theta) U_2(\hat{n}, \theta). \quad (38) \]
Here the exponential of the sum factors into a product of exponentials because \( J_1 \) and \( J_2 \) commute.
Interesting results can be obtained from this. First let us apply a rotation operator $U$ to a
vector of the uncoupled basis. We find

$$U|j_1 j_2 m_1 m_2⟩ = (U_1 |j_1 m_1⟩)(U_2 |j_2 m_2⟩) = \sum_{m'_1} |j_1 j_2 m'_1 m'_2⟩ D^j_{m'_1 m_1} D^j_{m'_2 m_2}$$

where we use Eqs. (13.65) and (30b), and where it is understood that all $D$ matrices have the same
axis and angle $(\hat{n}, \theta)$. Then we multiply this on the left by $⟨j_1 j_2 m'_1 m'_2 |$ and rearrange indices, to
obtain,

$$D^j_{m'_1 m_1} D^j_{m'_2 m_2} = \sum_{m m'} ⟨j_1 j_2 m_1 m_2 | jm⟩ D^j_{m m'} ⟨jm' | j_1 j_2 m'_1 m'_2⟩.$$  \hspace{1cm} (40)

In a similar manner we can obtain the identity,

$$D^j_{m m'} = \sum_{m_1 m_2} \sum_{m'_1} ⟨j_1 j_2 m_1 m_2 | D^j_{m_1 m'_1} D^j_{m_2 m'_2} (j_1 j_2 m'_1 m'_2 | jm⟩.$$  \hspace{1cm} (41)

These identities are useful for a variety of purposes; for example, Eq. (40) can be used whenever
it is necessary to express a product of $D$ matrices as a linear combination of single $D$ matrices (a
problem that arises often in atomic, molecular, and nuclear physics), and Eq. (41) shows that $D$
matrices for small values of $j$ can be combined to find the $D$ matrices for larger values of $j$.

11. The Three-$Y_{\ell m}$ Formula

We present here one application of Eq. (40), in which we use Eq. (15.66) to obtain an identity
involving the $Y_{\ell m}$'s. First we change notation in Eq. (40), setting $j_1 = \ell_1$, $j_2 = \ell_2$ and $j = \ell$
(indicating integer angular momenta), and we set $m'_1 = m'_2 = 0$. Then because of the selection rule
(34), the $m'$ sum on the right hand side is replaced by the single term $m' = 0$. Then we take the
complex conjugate of both sides and use Eq. (15.66), to obtain

$$Y_{\ell_1 m_1}(\theta, \phi) Y_{\ell_2 m_2}(\theta, \phi) = \sum_{\ell m} \sqrt{\frac{(2\ell_1 + 1)(2\ell_2 + 1)}{4\pi(2\ell + 1)}} \times Y_{\ell m}(\theta, \phi) ⟨0|\ell_1 \ell_2 00⟩ ⟨\ell_1 \ell_2 m_1 m_2 | \ell m⟩.$$  \hspace{1cm} (42)

Of course, the product of two $Y_{\ell m}$'s is a function on the unit sphere, which can be expanded as a
linear combination of other $Y_{\ell m}$'s; this formula gives the expansion explicitly. We see that the $\ell$
values that contribute are exactly those which occur in $\ell_1 \otimes \ell_2$. Finally, we can multiply this by
$Y^*_{\ell_3 m_3}$ and integrate to obtain the useful formula,

$$\int d\Omega Y^*_{\ell_3 m_3} Y_{\ell_1 m_1} Y_{\ell_2 m_2} = \sqrt{\frac{(2\ell_1 + 1)(2\ell_2 + 1)}{4\pi(2\ell_3 + 1)}} ⟨\ell_3 0|\ell_1 \ell_2 00⟩ ⟨\ell_1 \ell_2 m_1 m_2 | \ell_3 m_3⟩.$$  \hspace{1cm} (43)
Notes 17: Coupling of Angular Momenta

We will call this the three-$Y_{lm}$ formula; it is very useful in atomic physics. This formula and Eq. (40) can be regarded as a special cases of the Wigner-Eckart theorem, which we consider later.

Problems

1. About wave functions of particles, including spin.

(a) The wave function of a particle with spin was defined in Eq. (12). If $\psi_m(r)$ is the wave function of a spinning particle in state $|\psi\rangle$, then what is the wave function of the particle in the rotated state, $U(R)|\psi\rangle$? The rotation operator $U(R)$ is the product of a spatial rotation times a spin rotation, both parameterized by the same $R$.

(b) The Pauli equation is the Schrödinger equation for an electron interacting with electric and magnetic fields, including the spin degrees of freedom. The Pauli Hamiltonian is

$$H = \frac{1}{2m} \left( \mathbf{p} - \frac{q}{c} \mathbf{A} \right)^2 + q\Phi - \mu \cdot \mathbf{B},$$

and the wave function is understood to be that of a spin-$\frac{1}{2}$ particle with $q = -e$ and $g = \text{the electron } g\text{-factor}$. Here $\Phi$ and $\mathbf{A}$ are the electromagnetic scalar and vector potentials.

Consider an electron in a central force potential $V(r)$, plus a uniform magnetic field $\mathbf{B} = B\hat{b}$. Let $\omega_0 = eB/mc$. Use the gauge $\mathbf{A} = \frac{1}{2}B \times r$. Consider the time-dependent Pauli equation for the electron,

$$i\hbar \frac{\partial}{\partial t}|\psi(t)\rangle = H|\psi(t)\rangle,$$

where $H$ is the Pauli Hamiltonian (44) and where $q\Phi = V(r)$.

Define a new state $|\phi(t)\rangle$ by

$$|\psi(t)\rangle = U(\hat{b}, \omega t)|\phi(t)\rangle,$$

where $U(\hat{b}, \omega t)$ is a rotation operator that rotates the whole system (orbital and spin degrees of freedom). This means that $|\phi(t)\rangle$ is the state in a frame rotating with angular velocity $\omega$ about the axis $\hat{b}$.

Find a frequency $\omega$ that eliminates the effect of the magnetic field on the orbital motion of the particle, apart from the centrifugal potential which is proportional to $(\mathbf{b} \times \mathbf{r})^2$. Find a frequency $\omega$ that eliminates the effect of the magnetic field on the spin. Express your answers as some multiple of $\omega_0$. Can you eliminate the effects of the magnetic field entirely, apart from the centrifugal potential?

2. In Notes 10 we worked out the energy levels of a “spinless electron” in a uniform magnetic field. Including the spin, find the energy levels of an electron in a uniform magnetic field. Express your answer in terms of $\omega_0 = eB/mc$, the orbital frequency of a classical electron in a uniform magnetic field. This is a short problem, and does not require any lengthy calculations.
3. I won’t ask you to work out any numerical values of Clebsch-Gordan coefficients, but you should be comfortable in doing so. The following is a related problem.

Consider the angular momentum problem $\ell \otimes \frac{1}{2}$, where $\ell$ is arbitrary and could be very large. We write $j = \ell + \frac{1}{2}$ or $j = \ell - \frac{1}{2}$ for the resulting angular momentum. By beginning with the doubly stretched state,

$$|\ell + \frac{1}{2}, \ell + \frac{1}{2}\rangle = |\ell\ell\rangle|\frac{1}{2}\frac{1}{2}\rangle,$$

apply lowering operators to construct the states $|\ell + \frac{1}{2}, m\rangle$ for $m$ going down to $\ell - \frac{5}{2}$. By this time a pattern should be evident; guess it, and prove that it is right by induction, to obtain a general formula for $|\ell + \frac{1}{2}, m\rangle$. You may simplify notation by omitting the total angular momenta $\ell$ and $\frac{1}{2}$ in the kets on the right hand sides of your equations, because they are always the same; for example, the right hand side of Eq. (47) can be written simply $|\ell\rangle|\frac{1}{2}\rangle$.

Now construct the stretched state for $j = \ell - \frac{1}{2}$, namely $|\ell - \frac{1}{2}, \ell - \frac{1}{2}\rangle$. Use the standard phase convention given by Eq. (31). Then lower this enough times to see a pattern, guess it, and prove it by induction.

The following are some useful formulas that can be derived by the methods of this problem. We present them here for future reference. We combine $\ell \otimes 1$, and find, for the three cases $j = \ell + 1$, $j = \ell$, and $j = \ell - 1$, the following:

$$|\ell + 1, m\rangle = \sqrt{\frac{(\ell + m + 1)(\ell + m)}{(2\ell + 2)(2\ell + 1)}} |m - 1\rangle|1\rangle$$

$$+ \sqrt{\frac{(\ell - m + 1)(\ell + m + 1)}{(\ell + 1)(2\ell + 1)}} |m\rangle|0\rangle + \sqrt{\frac{(\ell - m)(\ell - m + 1)}{(2\ell + 2)(2\ell + 1)}} |m + 1\rangle | - 1\rangle. \tag{48a}$$

$$|\ell m\rangle = - \frac{\sqrt{(\ell - m + 1)(\ell + m)}}{2\ell(\ell + 1)} |m - 1\rangle|1\rangle$$

$$+ \frac{m}{\sqrt{\ell(\ell + 1)}} |m\rangle|0\rangle + \frac{(\ell - m)(\ell + m + 1)}{2\ell(\ell + 1)} |m + 1\rangle | - 1\rangle. \tag{48b}$$

$$|\ell - 1, m\rangle = \frac{\sqrt{(\ell - m)(\ell - m + 1)}}{2\ell(2\ell + 1)} |m - 1\rangle|1\rangle$$

$$- \frac{\sqrt{(\ell - m)(\ell + m)}}{\ell(2\ell + 1)} |m\rangle|0\rangle + \frac{(\ell + m + 1)(\ell + m)}{2\ell(2\ell + 1)} |m + 1\rangle | - 1\rangle. \tag{48c}$$