

Given \vec{E} , we can in principle determine ϕ via

$$\phi(\vec{r}) = - \int_{\vec{r}_0}^{\vec{r}} \vec{E} \cdot d\vec{s}$$

Similarly, given $\phi(\vec{r})$, we can determine $\vec{E}(\vec{r})$

Consider

$$d\phi \equiv \phi(\vec{r} + d\vec{r}) - \phi(\vec{r}) = - \int_{\vec{r}}^{\vec{r} + d\vec{r}} \vec{E} \cdot d\vec{s} = - \vec{E} \cdot d\vec{r}$$

for sufficiently small $d\vec{r}$

From calculus we have

$$\begin{aligned} \phi(\vec{r} + d\vec{r}) &= \phi(x + dx, y + dy, z + dz) \\ &= \phi(x, y, z) + \frac{\partial \phi}{\partial x} dx + \frac{\partial \phi}{\partial y} dy + \frac{\partial \phi}{\partial z} dz \end{aligned}$$

where partial derivatives evaluated at $\vec{r} = (x, y, z)$

So

$$\begin{aligned} \phi(\vec{r} + d\vec{r}) - \phi(\vec{r}) &= \left(\frac{\partial \phi}{\partial x} dx + \frac{\partial \phi}{\partial y} dy + \frac{\partial \phi}{\partial z} dz \right) \\ &= \left(\frac{\partial \phi}{\partial x}, \frac{\partial \phi}{\partial y}, \frac{\partial \phi}{\partial z} \right) \cdot (dx, dy, dz) \\ &= - \vec{E} \cdot d\vec{r} = (E_x, -E_y, -E_z) \cdot (dx, dy, dz) \end{aligned}$$

Since this is true for all $d\vec{r}$ infinitesimally small in length but in arbitrary direction, it must be true that

$$\left(\frac{\partial \phi}{\partial x}, \frac{\partial \phi}{\partial y}, \frac{\partial \phi}{\partial z} \right) = (E_x, -E_y, -E_z)$$

or in vector notation

$$\vec{E} = - \left[\frac{\partial \phi}{\partial x} \hat{x} + \frac{\partial \phi}{\partial y} \hat{y} + \frac{\partial \phi}{\partial z} \hat{z} \right]$$

the vector

$$\frac{\partial \phi}{\partial x} \hat{x} + \frac{\partial \phi}{\partial y} \hat{y} + \frac{\partial \phi}{\partial z} \hat{z}$$

is called the gradient of ϕ and is written symbolically as $\text{grad } \phi$ or as $\vec{\nabla} \phi$.

The symbol $\vec{\nabla}$ represents the differential operator

$$\hat{x} \frac{\partial}{\partial x} + \hat{y} \frac{\partial}{\partial y} + \hat{z} \frac{\partial}{\partial z}$$

$$\text{so } \vec{\nabla} \phi = \hat{x} \frac{\partial \phi}{\partial x} + \hat{y} \frac{\partial \phi}{\partial y} + \hat{z} \frac{\partial \phi}{\partial z}$$

Note

$$d\phi = \phi(\vec{r} + d\vec{r}) - \phi(\vec{r}) = \vec{\nabla} \phi \cdot d\vec{r}$$

$d\phi$ is maximum when $\vec{\nabla} \phi$ and $d\vec{r}$ are parallel. Hence the direction of $\vec{\nabla} \phi$, giving the direction in which the function ϕ changes most rapidly.

If $d\vec{r}$ is \perp to $\vec{\nabla} \phi$, then $d\phi = 0$. Such a $d\vec{r}$ therefore points in a direction along a contour of constant ϕ . $\Rightarrow \vec{\nabla} \phi$ is always \perp to contours of constant ϕ .

Potential $\phi(\vec{r})$ from a continuous charge distribution

$\rho(\vec{r})$

from a point charge at origin

$$\phi(\vec{r}) = \frac{q}{r} \quad (\text{reference point } \vec{r}_0 \rightarrow \infty)$$

For a point charge q_1 at a position \vec{r}_1 , we must replace r in the above by the distance from \vec{r}_1 to \vec{r}

$$\phi(\vec{r}) = \frac{q_1}{|\vec{r}-\vec{r}_1|}$$

For many charges q_i at positions \vec{r}_i

$$\phi(\vec{r}) = \sum_i \frac{q_i}{|\vec{r}-\vec{r}_i|}$$

For a continuous charge density $\rho(\vec{r})$

$$\phi(\vec{r}) = \int_{\substack{\text{all space} \\ \text{where} \\ \rho \neq 0}} \frac{\rho(\vec{r}') dV'}{|\vec{r}-\vec{r}'|} = \int \frac{\rho(x',y',z') dx' dy' dz'}{\sqrt{(x-x')^2 + (y-y')^2 + (z-z')^2}}$$

For continuous surface charge density $\sigma(\vec{r})$

$$\phi(\vec{r}) = \int_{\text{surface}} \frac{\sigma(\vec{r}') d\alpha'}{|\vec{r}-\vec{r}'|}$$

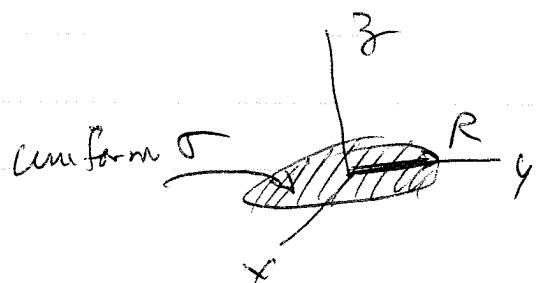
\vec{r}' varies over surface

For a continuous line charge density

$$\phi(\vec{r}) = \int_{\text{curve}} \frac{\lambda(\vec{r}') d\vec{s}'}{|\vec{r}-\vec{r}'|}$$

\vec{r}' varies along line

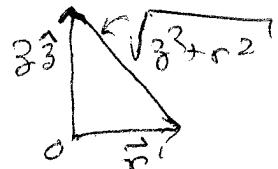
Example potential from a uniformly charged disk



Note: I'll use ϕ for potential and θ for angle

for $\vec{r} = z\hat{z}$ on z axis $\vec{r}' = r\cos\theta\hat{x} + r\sin\theta\hat{y}$

$$\phi(z) = \underbrace{\int_0^R dr r \int_0^{2\pi} d\theta}_{\int da} \frac{\sigma}{\sqrt{z^2 + r^2}}$$



$$= 2\pi\sigma \int_0^R dr \frac{r}{\sqrt{z^2+r^2}}$$

$$= 2\pi\sigma \left[\sqrt{z^2+r^2} \right]_0^R$$

$$\sqrt{z^2} = |z|$$

$$\phi(z) = 2\pi\sigma \left[\sqrt{z^2+R^2} - |z| \right]$$

If we want to compute $\vec{E} = -\vec{\nabla}\phi$ we can only compute

$$E_z = -\frac{\partial \phi}{\partial z}$$

with the above result, because we

don't know how ϕ varies with x or y if we have only

Computed ϕ along the z axis, i.e. $\phi(0, 0, z)$.

But by symmetry we know $E_x = E_y = 0$ for $\vec{r} = z\hat{z}$.

$$E_z = -\frac{\partial}{\partial z} \left\{ 2\pi\sigma \left[\sqrt{z^2 + R^2} - |z| \right] \right\}$$

$$= -2\pi\sigma \left[\frac{z}{\sqrt{z^2 + R^2}} - \frac{z}{|z|} \right]$$

$$E_z = 2\pi\sigma \left[\frac{z}{|z|} - \frac{z}{\sqrt{z^2 + R^2}} \right]$$

↑ since $\frac{\partial |z|}{\partial z} = \begin{cases} +1 & z > 0 \\ -1 & z < 0 \end{cases}$

$$= 2\pi\sigma z \left[\frac{1}{|z|} - \frac{1}{\sqrt{z^2 + R^2}} \right]$$

which is the same as we found earlier from Coulomb's law.

Note that the computation of ϕ is in general easier than the computation of \vec{E} .

$$\phi(\vec{r}) = \int dV' \frac{\rho(\vec{r}')}{|\vec{r} - \vec{r}'|}$$

↑ scalar integral

$$\vec{E}(\vec{r}) = \int dV' \frac{\rho(\vec{r}')}{|\vec{r} - \vec{r}'|^2} \hat{r} - \vec{r}'$$

↑ vector integral

Since ϕ involves a scalar integral while \vec{E} involves a vector integral.

Potential Energy and the electrostatic potential

From before, for a set of charges $\{q_j\}$ at positions $\{\vec{r}_j\}$

$$U = \frac{1}{2} \sum_{j=1}^N q_j \sum_{k \neq j} \frac{q_k}{|\vec{r}_j - \vec{r}_k|}$$

$$= \frac{1}{2} \sum_{j=1}^N q_j \phi(\vec{r}_j)$$

↑ potential at \vec{r}_j due to all charges except q_j

For a continuous distribution of charges, the above becomes

$$d^3r = dx dy dz$$

$$U = \frac{1}{2} \int d^3r \int d^3r' \frac{f(\vec{r}) f(\vec{r}')}{|\vec{r} - \vec{r}'|}$$

$$d^3r' = dx' dy' dz'$$

but for the continuous f , when we do double integral, the amount of space where $\vec{r} = \vec{r}'$ gives a negligible contribution

$$U = \frac{1}{2} \int d^3r f(\vec{r}) \int d^3r' \frac{f(\vec{r}')}{|\vec{r} - \vec{r}'|}$$

$$U = \frac{1}{2} \int d^3r f(\vec{r}) \phi(\vec{r}')$$

Divergence of a vector field

We already met the vector differential operator

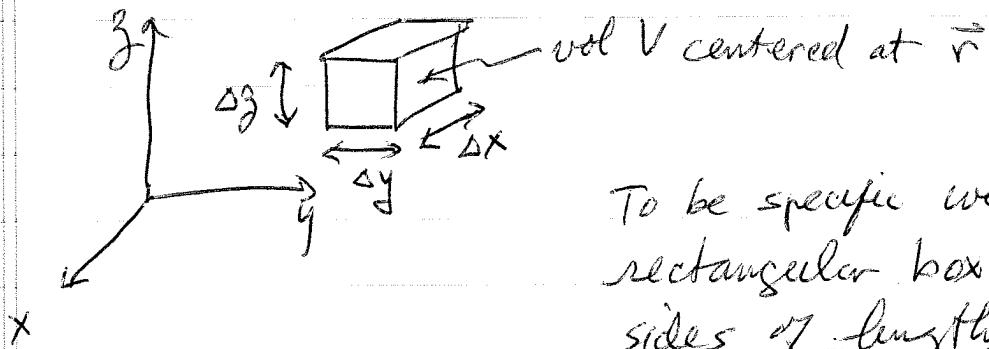
$$\vec{\nabla} = \left(\frac{\partial}{\partial x}, \frac{\partial}{\partial y}, \frac{\partial}{\partial z} \right) \text{ or } \hat{x} \frac{\partial}{\partial x} + \hat{y} \frac{\partial}{\partial y} + \hat{z} \frac{\partial}{\partial z}$$

Since $\vec{\nabla}$ looks like a vector we can define its dot product with a vector field $\vec{F}(\vec{r})$

$$\begin{aligned}\vec{\nabla} \cdot \vec{F}(F) &= \left(\frac{\partial}{\partial x}, \frac{\partial}{\partial y}, \frac{\partial}{\partial z} \right) \cdot (F_x, F_y, F_z) \\ &= \frac{\partial F_x}{\partial x} + \frac{\partial F_y}{\partial y} + \frac{\partial F_z}{\partial z}\end{aligned}$$

This is called the divergence of \vec{F} and written as $\vec{\nabla} \cdot \vec{F}$ or $\text{div } \vec{F}$

To find the physical meaning of the divergence, consider the flux of \vec{F} through the surface S' bounding an infinitesimally small volume V of space at a position \vec{r} .



To be specific we take a rectangular box with sides of lengths $\Delta x, \Delta y, \Delta z$

Consider the flux of \vec{F} through the surface S abounding the box

$$\oint_S \vec{F} \cdot d\vec{a} = \int_{\text{top + bottom sides}} \vec{F} \cdot d\vec{a} + \int_{\text{front + back sides}} \vec{F} \cdot d\vec{a} + \int_{\text{left + right sides}} \vec{F} \cdot d\vec{a}$$

Consider the integral over the top side at $z + \frac{\Delta z}{2}$

$$\int_{\text{top}} \vec{F} \cdot d\vec{a} = \int_{x-\frac{\Delta x}{2}}^{x+\frac{\Delta x}{2}} dx' \int_{y-\frac{\Delta y}{2}}^{y+\frac{\Delta y}{2}} dy' F_3(x', y', z + \frac{\Delta z}{2})$$

↑ F_3 since $\hat{n} = \hat{j}$ on this side

Similarly

$$\int_{\text{bottom}} \vec{F} \cdot d\vec{a} = \int_{x-\frac{\Delta x}{2}}^{x+\frac{\Delta x}{2}} dx' \int_{y-\frac{\Delta y}{2}}^{y+\frac{\Delta y}{2}} dy' [-F_3(x', y', z - \frac{\Delta z}{2})]$$

↑ $-F_3$ since $\hat{n} = -\hat{j}$ on this side

If the box is infinitesimally small, then F_3 does not vary much over the length Δy .

For small Δy we can expand the integrand

$$F_3(x', y', z \pm \frac{\Delta z}{2}) \approx F_3(x', y', z) \pm \frac{\partial F_3(x', y', z)}{\partial y} \frac{\Delta y}{2}$$

and so get

$$\int_{\text{top}} \vec{F} \cdot d\vec{a} + \int_{\text{bottom}} \vec{F} \cdot d\vec{a}$$

$$= \int_{x-\frac{\Delta x}{2}}^{x+\frac{\Delta x}{2}} \int_{y-\frac{\Delta y}{2}}^{y+\frac{\Delta y}{2}} \left[\left(F_3(x', y', z) + \frac{\partial F_3}{\partial z}(x', y', z) \frac{\Delta z}{2} \right) - \left(F_3(x', y', z) - \frac{\partial F_3}{\partial z}(x', y', z) \frac{\Delta z}{2} \right) \right]$$

$$= \int_{x-\frac{\Delta x}{2}}^{x+\frac{\Delta x}{2}} \int_{y-\frac{\Delta y}{2}}^{y+\frac{\Delta y}{2}} \frac{\partial F_3}{\partial z}(x', y', z) \Delta z$$

Now if Δx and Δy are sufficiently small $\frac{\partial F_3}{\partial z}(x', y', z)$

varies negligibly over the range of integration, and so we may approximate by

$$\int_{\text{top}} \vec{F} \cdot d\vec{a} + \int_{\text{bottom}} \vec{F} \cdot d\vec{a} = \frac{\partial F_3}{\partial z}(x, y, z) \Delta x \Delta y \Delta z$$

Similarly

$$\int_{\text{front}} \vec{F} \cdot d\vec{a} + \int_{\text{back}} \vec{F} \cdot d\vec{a} = \frac{\partial F_x}{\partial x}(x, y, z) \Delta x \Delta y \Delta z$$

and

$$\int_{\text{right}} \vec{F} \cdot d\vec{a} + \int_{\text{left}} \vec{F} \cdot d\vec{a} = \frac{\partial F_y}{\partial y}(x, y, z) \Delta x \Delta y \Delta z$$

Adding all the terms gives

$$\begin{aligned} \oint_S \vec{F} \cdot d\vec{a} &= \left(\frac{\partial F_x}{\partial x} + \frac{\partial F_y}{\partial y} + \frac{\partial F_z}{\partial z} \right) \Delta x \Delta y \Delta z \\ &= \vec{\nabla} \cdot \vec{F}(\vec{r}) (\Delta x \Delta y \Delta z) \end{aligned}$$

or

$\vec{\nabla} \cdot \vec{F}(\vec{r}) =$	$\frac{\oint_S \vec{F} \cdot d\vec{a}}{\text{Vol}}$
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for infinitesimally
small volume Vol
bounded by surface S'
centered at position \vec{r}

Above does not depend on size of box $\Delta x, \Delta y, \Delta z$ in
the limit $\Delta x, \Delta y, \Delta z \rightarrow 0$

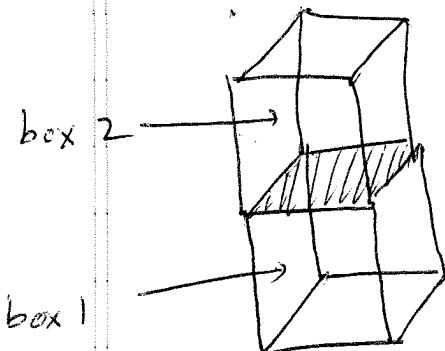
We have proven the above for the specific case of
a rectangular volume. We leave it to your
math class to prove that this result remains true
no matter what the shape of the volume, as long
as it is infinitesimally small.

$$\vec{\nabla} \cdot \vec{F}(\vec{r}) = \lim_{V \rightarrow 0} \left[\frac{\oint_S \vec{F} \cdot d\vec{a}}{V} \right]$$

for any shape V
bounded by
surface S'
centered at
position \vec{r}

Gauss' Theorem of Vector Calculus

Consider two rectangular boxes stacked on top of one another



let S' be the exterior sides that form the outside surface of the two boxes.

let S_1 and S_2 be the surfaces of box 1 and box 2 respectively

When we do $\oint \vec{F} \cdot d\vec{a}$ there is a contribution from the S_1

shaded side that is common with surface S_2 .

But if we add

$$\int_{S_1} \vec{F} \cdot d\vec{a} + \int_{S_2} \vec{F} \cdot d\vec{a}$$

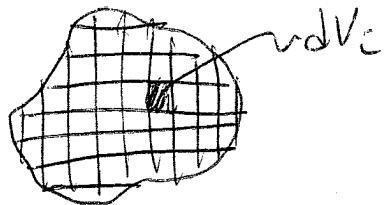
the contribution from the shaded side in the \int_{S_1} exactly cancels the contribution from the side in \int_{S_2} . This is because the outward normal of the side in \int_{S_2} points in the opposite direction from when we do \int_{S_1} . Hence the

contributions of this side to \int_{S_1} and \int_{S_2} are

equal in magnitude but opposite in sign.
So when we add them they cancel.

$$\text{Thus } \oint_S \vec{F} \cdot d\vec{a} = \oint_{S_1} \vec{F} \cdot d\vec{a} + \oint_{S_2} \vec{F} \cdot d\vec{a}$$

In a similar manner one can divide any finite volume V , bounded by surface S , into many infinitesimal volumes dV_i , centered at positions \vec{r}_i , each bounded by the surface S_i .



Then,

$$\oint_S \vec{F} \cdot d\vec{a} = \sum_i \oint_{S_i} \vec{F} \cdot d\vec{a}$$

\uparrow
contributions from internal
sides all cancel in pairs.

But as $dV_i \rightarrow 0$ we have

$$\oint_{S_i} \vec{F} \cdot d\vec{a} = dV_i \vec{\nabla} \cdot \vec{F}(\vec{r}_i)$$

$$\text{So } \oint_S \vec{F} \cdot d\vec{a} = \sum_i dV_i \vec{\nabla} \cdot \vec{F}(\vec{r}_i)$$

as $dV_i \rightarrow 0$ the sum becomes an integral and

$$\boxed{\oint_S \vec{F} \cdot d\vec{a} = \int_V dV \vec{\nabla} \cdot \vec{F}}$$

Gauss' Theorem

Apply to Gauss Law of electrostatics

$$\oint \vec{E} \cdot d\vec{a} = 4\pi Q_{\text{enc}}$$

S || h

$$\int dV \vec{\nabla} \cdot \vec{E} = 4\pi \int dV \rho$$

Since the integrals are equal for any volume of integration V , it must be true that the integrands are everywhere equal

$$\Rightarrow \boxed{\vec{\nabla} \cdot \vec{E} = 4\pi \rho}$$

Gauss' law in
differential form

In Cartesian coordinates

$$\frac{\partial E_x(x, y, z)}{\partial x} + \frac{\partial E_y(x, y, z)}{\partial y} + \frac{\partial E_z(x, y, z)}{\partial z} = 4\pi \rho(x, y, z)$$