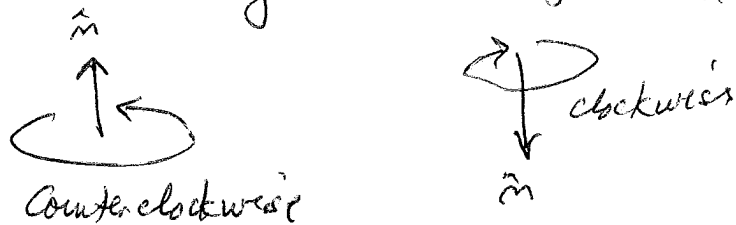


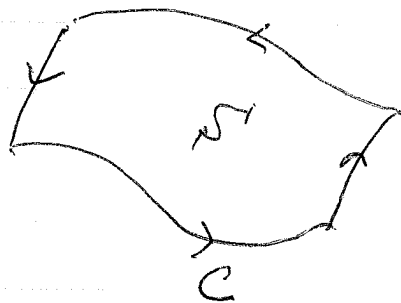
The direction of doing the line integral must be consistent with the direction of the normal \hat{n} according to the Right Hand Rule



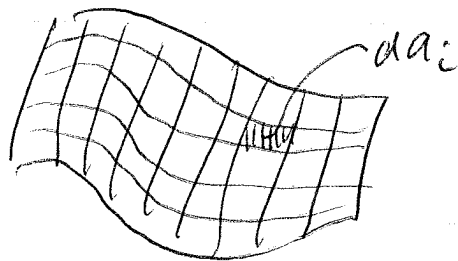
align thumb of right hand along \hat{n} , then fingers curl in direction of the line integral

Stokes Theorem of vector calculus

Consider now any surface S bounded by the curve C . The surface need not be planar



We can now tile S with lots of infinitesimally small tiles with area da_i , normal \hat{n}_i and boundary curves C_i

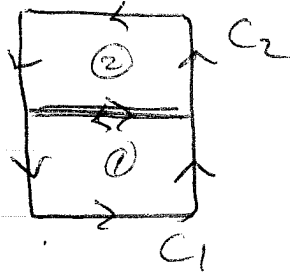


We have

$$\oint_C \vec{E} \cdot d\vec{s} = \sum_i \oint_{C_i} \vec{E} \cdot d\vec{s}$$

This is because all the internal sides of the tiles da_i will cancel pairwise with their neighbors leaving only the terms along the boundary curve of S

For example



C is outer boundary of the two boxes

$C_{1,2}$ is the boundary of box 1, 2

$$\oint_{C_1} \vec{E} \cdot d\vec{s} + \oint_{C_2} \vec{E} \cdot d\vec{s} = \oint_C \vec{E} \cdot d\vec{s}$$

because the integrals over the common line segment between box 1 and box 2 ~~are~~ cancel since they are traveled in opposite directions in C_1 vs C_2 .

$$\begin{aligned} \text{So } \oint_C \vec{E} \cdot d\vec{s} &= \sum_i \oint_{C_i} \vec{E} \cdot d\vec{s} \\ &= \sum_i (\nabla \times \vec{E}) \cdot \hat{m} da_i = \sum_i (\nabla \times \vec{E}) \cdot d\vec{a}_i \\ &= \int_S (\nabla \times \vec{E}) \cdot d\vec{a} \quad \text{as } da_i \rightarrow 0 \end{aligned}$$

This is Stokes Theorem!

$$\oint_C \vec{E} \cdot d\vec{s} = \int_S (\nabla \times \vec{E}) \cdot d\vec{a}$$

line integral of \vec{E} around a closed loop C is equal to the flux of \vec{E} through any surface S bounded by the loop C . Direction of doing line integral must be consistent with direction of normal to S by the right hand rule.

Consider \vec{E} the electric field in an electrostatic problem. We had

$$\oint_C \vec{E} \cdot d\vec{s} = 0 \quad \text{for all loops } C$$

$$\Rightarrow \int_S (\vec{\nabla} \times \vec{E}) \cdot d\vec{a} = 0 \quad \text{over all surfaces } S$$

$$\Rightarrow \vec{\nabla} \times \vec{E} = 0$$

This completes our two laws of electrostatics

Integral form of laws

Differential form of laws

Gauss

$$\oint_S \vec{E} \cdot d\vec{a} = 4\pi Q_{\text{enc}} \quad \Leftrightarrow \quad \vec{\nabla} \cdot \vec{E} = 4\pi \rho$$

$$\oint_C \vec{E} \cdot d\vec{s} = 0 \quad \Leftrightarrow \quad \vec{\nabla} \times \vec{E} = 0$$

we also have the formulation in terms of the electrostatic potential ϕ

$$\vec{E} = -\vec{\nabla}\phi \quad \Rightarrow \quad -\nabla^2\phi = 4\pi\rho \quad \text{Poisson Eq}$$

$$\vec{\nabla} \times \vec{E} = 0$$

$$\Rightarrow \vec{\nabla} \times \vec{\nabla}\phi = 0$$

$$\begin{aligned} & -\oint_C \vec{E} \cdot d\vec{s} \\ &= \oint_C \vec{\nabla}\phi \cdot d\vec{s} \\ &= \oint_C (\vec{\nabla}\phi) \cdot d\vec{s} = 0 \end{aligned}$$

always true: the curl of the gradient of any scalar function is always zero.

Note: $-\int_{r_1}^{r_2} \vec{E} \cdot d\vec{s} = \int_{r_1}^{r_2} \vec{\nabla}\phi \cdot d\vec{s} = \phi(r_2) - \phi(r_1)$

So $\oint \vec{E} \cdot d\vec{s} = 0$ automatically follows from

$$\vec{E} = -\vec{\nabla}\phi$$

Since $\oint \vec{E} \cdot d\vec{s} = 0 \Rightarrow \vec{\nabla} \times \vec{E} = 0$

we have in general that $\vec{\nabla} \times (\vec{\nabla}\phi) = 0$
curl of gradient of any scalar function
always vanishes

Units of electrostatic potential

$$\phi = -\int \vec{E} \cdot d\vec{s}$$

in CGS \vec{E} has units of $\text{esu/cm}^2 = \frac{\text{dyn}}{\text{esu}}$

$$E = \frac{q}{r^2} = \frac{F}{g}$$

$$\Rightarrow \phi = \frac{\text{dyn cm}}{\text{esu}} = \text{"stat volt"}$$

in MKS \vec{E} has units of $\frac{\text{N}}{\text{Coul}}$

$$\Rightarrow \phi = \frac{\text{N} \cdot \text{m}}{\text{Coul}} = \text{"volt"}$$

to get conversion factor between volts and statvolts,

$$1 \text{ volt} = \frac{\text{N} \cdot \text{m}}{\text{Coul}} = \frac{10^5 \text{ dyn} \cdot 10^2 \text{ cm}}{\text{Coul}} = \frac{10^7 \text{ dyn cm}}{\text{Coul}}$$

$$= \frac{10^7 \text{ dyn cm}}{3 \times 10^9 \text{ esu}} = \frac{1}{300} \frac{\text{dyn cm}}{\text{esu}}$$

$$= \frac{1}{300} \text{ stat volt}$$

$$\text{or } \boxed{300 \text{ volt} = 1 \text{ stat volt}}$$

$$\begin{aligned}
 U &= \frac{1}{2} \int \rho \phi \, dV \\
 &= \frac{1}{2} \int \left(\frac{-\nabla^2 \phi}{4\pi} \right) \phi \, dV
 \end{aligned}$$

Use $\nabla \cdot (\phi \nabla \phi) = (\nabla \phi)^2 + \phi \nabla^2 \phi$

$$\begin{aligned}
 U &= \frac{1}{8\pi} \int dV \left[-\nabla \cdot (\phi \nabla \phi) + (\nabla \phi)^2 \right] \\
 &= \frac{1}{8\pi} \int dV E^2 - \frac{1}{8\pi} \int dS \cdot \phi \nabla \phi
 \end{aligned}$$

if choose $\phi \rightarrow 0$ as $r \rightarrow \infty$
 this integral vanishes

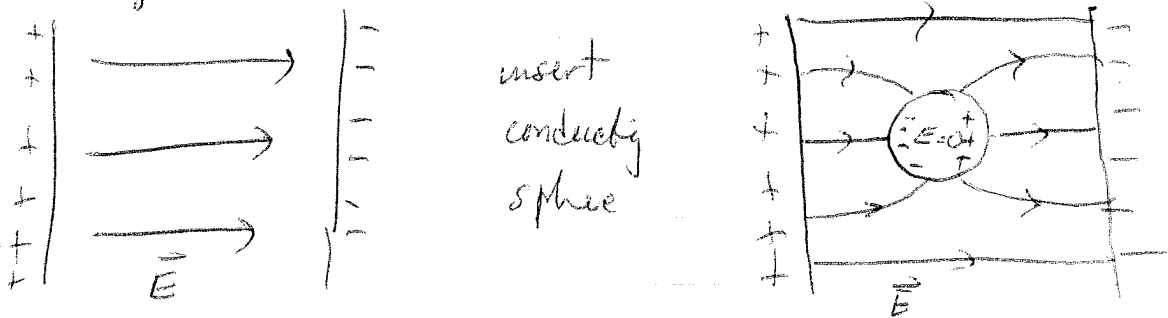
$$\begin{aligned}
 U &= \frac{1}{8\pi} \int dV E^2 \\
 &= \frac{1}{2} \int \rho \phi
 \end{aligned}$$

$$\begin{aligned}
 \nabla \cdot (\phi \nabla \phi) &= \frac{\partial}{\partial x} \left(\phi \frac{\partial \phi}{\partial x} \right) + \frac{\partial}{\partial y} \left(\phi \frac{\partial \phi}{\partial y} \right) + \frac{\partial}{\partial z} \left(\phi \frac{\partial \phi}{\partial z} \right) \\
 &= \phi \frac{\partial^2 \phi}{\partial x^2} + \left(\frac{\partial \phi}{\partial x} \right)^2 + \phi \frac{\partial^2 \phi}{\partial y^2} + \left(\frac{\partial \phi}{\partial y} \right)^2 + \phi \frac{\partial^2 \phi}{\partial z^2} + \left(\frac{\partial \phi}{\partial z} \right)^2 \\
 &= \phi \nabla^2 \phi + \nabla \phi \cdot \nabla \phi
 \end{aligned}$$

Conductors in electrostatics - conductors contain mobile charges

- i) The \vec{E} field inside a conductor must vanish. Otherwise the mobile charges in the conductor would feel a force $q\vec{E}$ and would move - if charges are moving we are not in an electrostatic situation!

Charges move in a way to set up a counter electric field that makes the total electric field zero



-e electrons in sphere move to left side leaving excess of +e charge on right side.



This creates electric field in sphere that exactly cancels out the field from the charged flat planes

Consequences: a) electrostatic potential $\Phi = \text{constant}$ inside a conductor. Since $\vec{E} = -\vec{\nabla}\Phi$ if Φ were not constant, then we would have $\vec{E} \neq 0$.

- b) Any net charge on a conductor must lie on the surface of the conductor. This follows from Gauss law - For any volume inside the conductor bounded by surface S' ,

$$\oint_{S'} \vec{E} \cdot d\vec{a} = 4\pi Q_{\text{encl}}$$

but $\vec{E} = 0$ inside $\Rightarrow Q_{\text{encl}} = 0$ so no net charge inside conductor

- 2) The \vec{E} field at the surface of a conductor must point perpendicular to the surface. If not, there would be a force on charges at the surface moving them along the surface, and again we would not be in an electrostatic situation.

Alternatively; since $\phi = \text{const}$ inside conductor, the surface of the conductor is an equipotential (surface of constant ϕ). Since $\vec{E} = -\vec{\nabla}\phi$ and $\vec{\nabla}\phi$ must always point \perp to surfaces of constant ϕ , \vec{E} is \perp to surface.

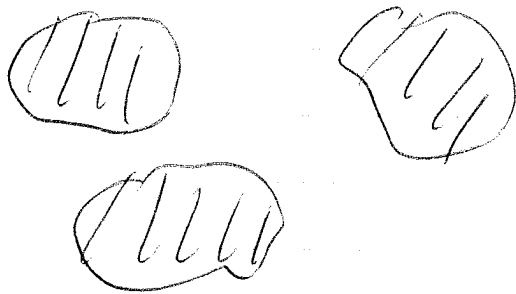
- 3) At the surface of the conductor $\vec{E} = 4\pi\sigma\hat{n}$ where σ is the surface charge density and \hat{n} is the outward pointing normal. This follows from our general result for a charged surface

$$\vec{E}_{\text{above}} - \vec{E}_{\text{below}} = 4\pi\sigma\hat{n}$$

For a conductor, $\vec{E}_{\text{below}} = 0$ since $\vec{E} = 0$ inside

Solving problems for \vec{E} in the presence of conductors is not as straightforward as when you are told explicitly the charge distribution $\rho(\vec{r})$. The reason is that with conductors, we do not a priori know where the charge is. The charge on the conductor will reposition itself so as to make $\vec{E} = 0$ inside the conductor and $\vec{E} \perp$ surface. We therefore have to somehow self-consistently determine both \vec{E} and the location of the charges on the conductor.

The typical problem we have to solve is



a set of conductors ~~on which~~ each of which is specified to be at a constant potential ϕ_i or to

have a total charge Q_i . In between conductors, if there is no charge, then $\nabla^2 \phi = 0$. Such a problem where ϕ satisfies a differential equation within a given ~~for~~ region, and that must satisfy given conditions on the boundary of that region is called a boundary

value problem. One can show that the above electrostatic problem with conductors always has a unique solution.

Proof for the case where each conductor i is specified to be at potential ϕ_i , and $\phi \rightarrow 0$ as $\vec{r} \rightarrow \infty$

Suppose we had two solutions ϕ and ϕ' , i.e. $\nabla^2 \phi = 0$ and $\nabla^2 \phi' = 0$ between the conductors while $\phi(\vec{r}) = \phi_i$ and $\phi'(\vec{r}) = \phi_i$ for \vec{r} on surface conductor i .

Then consider $W \equiv \phi - \phi'$. Clearly $\nabla^2 W = 0$ between conductors and $W(\vec{r}) = 0$ for \vec{r} on surface conductor i , and $W \rightarrow 0$ as $\vec{r} \rightarrow \infty$

Then we must have $W = 0$ everywhere otherwise W would have either a local maximum or minimum somewhere in space between the conductors. But $\nabla^2 W = 0$ there and harmonic functions can have no local max or min. Hence $W = 0$ so $\phi = \phi'$ and there is only one unique solution.