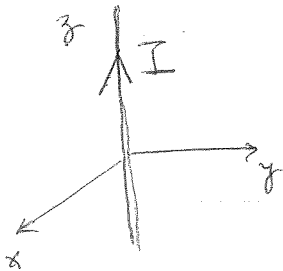


! Straight wire along z axis with current I.

Solution via Maxwell's equations

$$\vec{\nabla} \cdot \vec{B} = 0, \quad \vec{\nabla} \times \vec{B} = \mu_0 \vec{j} \Rightarrow \int_{\Gamma} d\vec{\ell} \cdot \vec{B} = \mu_0 I_{\text{encl}}$$



By symmetry, expect $\vec{B}(\vec{r}) = B(r) \hat{\phi}$
 ↳ cylindrical radial coord

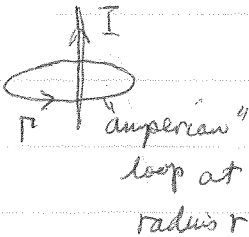
\vec{B} is indep of z by translational symmetry along z axis

\vec{B} must be indep of ϕ by rotation symmetry about z axis

⇒ \vec{B} depends only on r.

\vec{B} must point in $\hat{\phi}$ direction to have correct symmetry under reflections.

integral solution



$$\oint_{\Gamma} d\vec{\ell} \cdot \vec{B} = \int_0^{2\pi} \underbrace{d\phi r \hat{\phi}}_{d\vec{\ell}} \cdot \vec{B}(r) = \int_0^{2\pi} d\phi r B(r) = 2\pi r B(r) = \mu_0 I$$

$$d\vec{\ell} = r d\phi \hat{\phi}$$

$$\Rightarrow B(r) = \frac{\mu_0 I}{2\pi r}$$

$$\vec{B}(\vec{r}) = \frac{\mu_0 I}{2\pi r} \hat{\phi} \text{ as before}$$

differential solution

$$\vec{\nabla} \times \vec{B} = \mu_0 \vec{j} = \mu_0 I \delta(r)$$

↳ cylindrical coord

$\vec{j} = 0$ except on z axis at $r=0$

for $\vec{B} = B(r) \hat{\phi}$

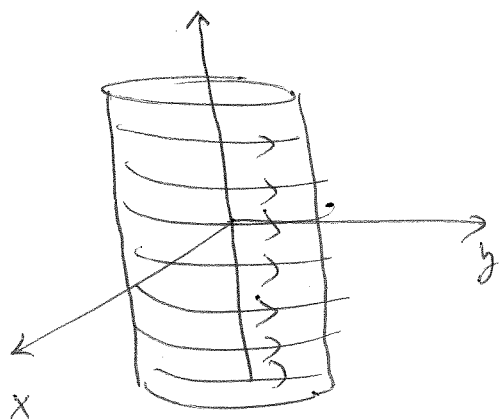
$$\vec{\nabla} \times (B \hat{\phi}) = \frac{1}{r} \left(-\frac{\partial B}{\partial z} \hat{r} + \frac{1}{r} \frac{\partial}{\partial r} (rB) \hat{z} \right) \text{ as } B_r = B_z = 0$$

since $\frac{\partial B}{\partial z} = 0$

$$= \frac{1}{r} \frac{\partial}{\partial r} (rB) \hat{z} = \mu_0 I \delta(r)$$

$$\frac{\partial}{\partial r} (rB) = \mu_0 I r \delta(r)$$

Infinite Solenoid



surface of infinite cylinder of radius R
has surface current $\vec{K} = K \hat{\phi}$.

Can produce solenoid by wrapping
wire around cylinder with N turns
per unit length. Then

$$K = IN$$

where I is current in wire

Symmetries : translational symmetry along z axis

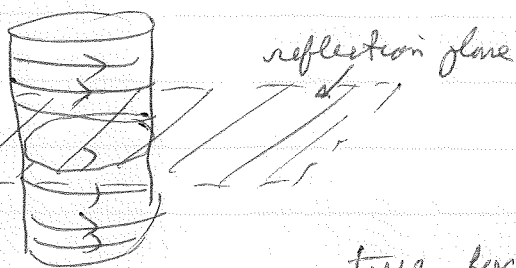
$\Rightarrow \vec{B}$ indep of z

rotational symmetry about z axis

$\Rightarrow \vec{B}$ indep of ϕ

$\Rightarrow \vec{B}$ depends only on cylindrical radial coord r .

Reflect through x, y plane at $z = z_0$ a constant
current is reflection symmetric



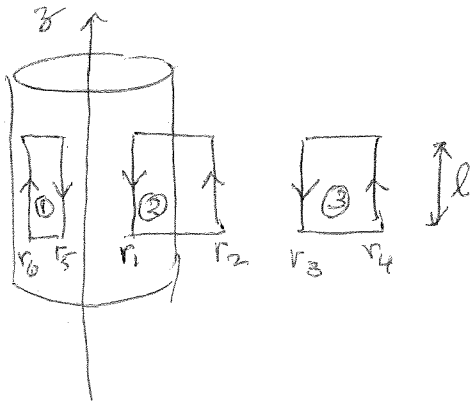
$\Rightarrow \vec{B}$ is antisymmetric

$\Rightarrow \vec{B}(x, y, z_0)$ is \perp symmetry plane
true for all z_0

$$\Rightarrow \vec{B}(x, y, z_0) = B(r) \hat{z}$$

so \vec{B} points only in \hat{z} direction
depends only on radial coord

Conclusion: $\vec{B}(\vec{r}) = B(r) \hat{z}$ ~~along~~ pts along z axis



For any loop with normal in \hat{z} direction with inner edge at r and outer edge at r'

$$\oint \vec{B} \cdot d\vec{l} = \frac{B(r') \hat{z} \cdot \hat{z} l}{B} - \frac{B(r) \hat{z} \cdot \hat{z} l}{B}$$

$$= [B(r') - B(r)] l = \mu_0 I_{\text{enc}} l$$

for loop ① and loop ③, $I_{\text{enc}} = 0$ as no current passes through loop! $\Rightarrow B(r') = B(r)$ r, r' both outside
 $B(r') = B(r)$ r, r' both inside

$\Rightarrow \vec{B}$ is constant outside and inside.

Since we expect $\vec{B} = 0$ as $r \rightarrow \infty$, infinitely far away from solenoid, $\Rightarrow \vec{B}_{\text{outside}} = 0$

for loop ②, $I_{\text{enc}} = -Kl \Rightarrow B(r') - B(r) = -\mu_0 K$
 $\Rightarrow B_{\text{outside}} - B_{\text{inside}} = -\mu_0 K$

$$I_{\text{enc}} = \int d\vec{a} \cdot \vec{j}$$

for orientation of loop shown,

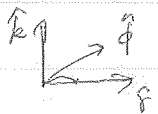
$$\Rightarrow B_{\text{inside}} = \mu_0 K$$

$$d\vec{a} = l(r_2 - r_1)(-\hat{\phi})$$

$$\vec{j} = \vec{K} \delta(r-R) \hat{\phi}$$

$$\Rightarrow I_{\text{enc}} = -Kl$$

$$\vec{B}(\vec{r}) = \begin{cases} \mu_0 K \hat{z} \\ \mu_0 N I \hat{z} & \text{inside} \\ 0 & \text{outside} \end{cases}$$

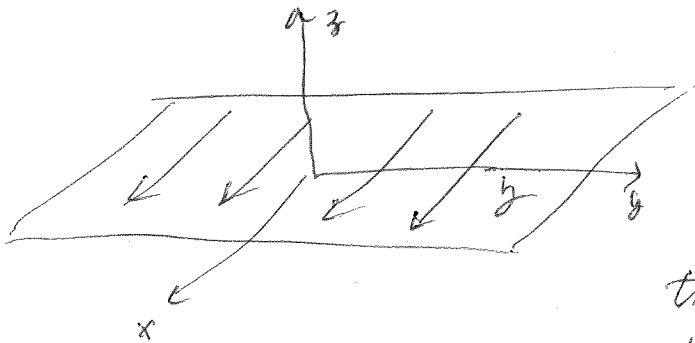


Note: we have a discontinuous jump in \vec{B} as cross

a surface current. $\vec{B}_{\text{above}} - \vec{B}_{\text{below}} = -\mu_0 N I \hat{z} = -\mu_0 K \hat{z}$
 will be generally true!
 $= \mu_0 (\vec{K} \times \hat{m})$

uniform

Infinite flat sheet current



$$\vec{K} = K \hat{x}$$

translational symmetry in x and y directions $\Rightarrow \vec{B}$ indep of x and y
 \vec{B} depends only on z

Reflection symmetries

current has reflection symmetry about xz plane at any fixed y_0

$\Rightarrow \vec{B}$ is reflection antisymmetric

$\Rightarrow \vec{B}(x, y_0, z) \perp xz$ plane i.e. \vec{B} along \hat{y}

true for all $y_0 \Rightarrow \boxed{\vec{B}(\vec{r}) = B(z) \hat{y}}$

this result is consistent with: current has reflection antisymmetry about yz plane at fixed x_0

$\Rightarrow \vec{B}$ is reflection symmetric

$\Rightarrow \vec{B}(x_0, y, z)$ must lie in yz plane

Also: current has reflection symmetry about xy plane at $z=0$

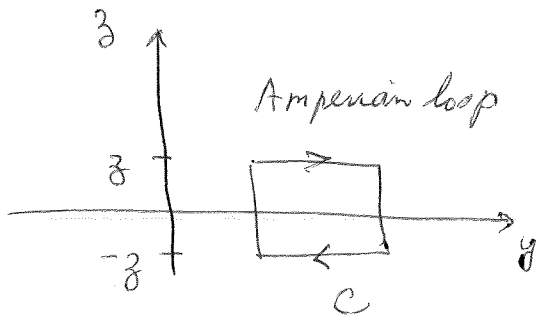
$\Rightarrow \vec{B}$ is reflection antisymmetric

$\Rightarrow B(x, y, z) = -B(x, y, -z)$

for $\vec{B}(\vec{r}) = B(z) \hat{y}$

$$B(z) = -B(-z)$$

$$\Rightarrow B(z=0) = 0$$



$$\oint_C \vec{B} \cdot d\vec{l} = [B(z) - B(-z)] l$$

$$= \mu_0 I_{\text{enc}} = -\mu_0 K l$$

(\rightarrow) come from $I_{\text{enc}} = \int d\vec{a} \cdot \vec{j}$. Right hand rule tells us $d\vec{a}$ points into page, while current \vec{j} points out of page

$$B(z) - B(-z) = 2B(z) = -\mu_0 K$$

$$B(z) = -\frac{\mu_0 K}{2} \quad z > 0$$

$$B(z) = +\frac{\mu_0 K}{2} \quad z < 0$$

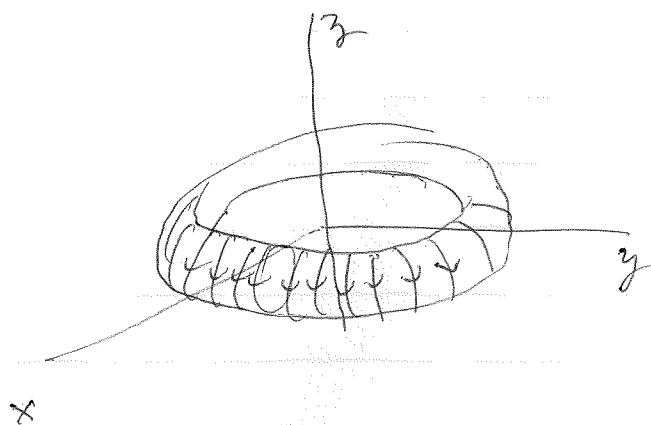
$$\vec{B}(\vec{r}) = \begin{cases} -\frac{\mu_0 K}{2} \hat{y} & z > 0 \\ +\frac{\mu_0 K}{2} \hat{y} & z < 0 \end{cases}$$

As with solenoid, we have:

$$\vec{B}_{\text{above}} - \vec{B}_{\text{below}} = -\frac{\mu_0 K}{2} \hat{y} - \frac{\mu_0 K}{2} \hat{y} = -\mu_0 K \hat{y}$$

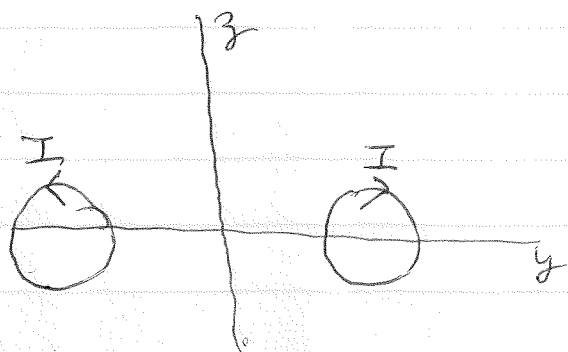
$$\vec{B}_{\text{above}} - \vec{B}_{\text{below}} = \mu_0 (\vec{K} \times \hat{m}) \quad \text{where } \hat{m} = \hat{z}$$

Toroidal Solenoid



donut wrapped with wire as in a solenoid.
 m turns of wire around the solenoid
 cross section of solenoid is any constant shape.

Reflection symmetries



Current is reflection symmetric
 about xz plane, at $y=0$
 $\Rightarrow \vec{B}$ is reflection antisymmetric
 $\Rightarrow \vec{B}(x, 0, z) \perp xz$ plane
 it is along \hat{y} direction

cross section of current distribution
 in yz plane at $x=0$

Rotation invariance about \hat{z} axis then implies the \vec{B} is always in $\hat{\phi}$ direction.

$\Rightarrow \vec{B}(\vec{r})$ is indep of ϕ coord, and points in $\hat{\phi}$ direction
 $\Rightarrow \vec{B}(\vec{r}) = B(r, z) \hat{\phi}$

Take Amperian loop at fixed radius r centered about z axis at fixed z .

$$\oint_C \vec{B} \cdot d\vec{l} = 2\pi r B(r, z) = \mu_0 I_{enc}$$

here $I_{enc} = 0$ if loop is not inside the solenoid

$I_{enc} = nI$ if loop is inside the solenoid

$$\Rightarrow \vec{B}(\vec{r}) = \begin{cases} \frac{\mu_0 m I}{2\pi r} \hat{\phi} & \vec{r} \text{ inside solenoid} \\ 0 & \vec{r} \text{ outside solenoid} \end{cases}$$

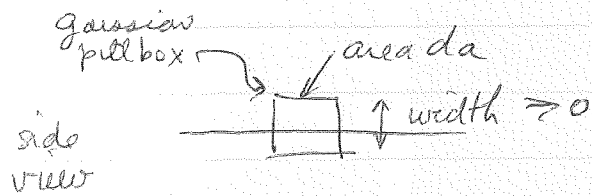
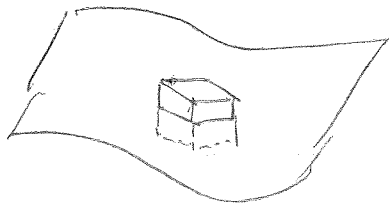
Note, if $m = \frac{N 2\pi R}{2\pi R}$ with $N = \# \text{ turns per unit length}$
 $R = \text{average radius of torus}$

$$\vec{B}(\vec{r}) = \mu_0 N I \left(\frac{R}{r}\right) \hat{\phi}$$

similar to solenoid
 (straight)

Boundary Condition at sheet of surface ~~to~~ current

$$\vec{\nabla} \cdot \vec{B} = 0 \Rightarrow$$

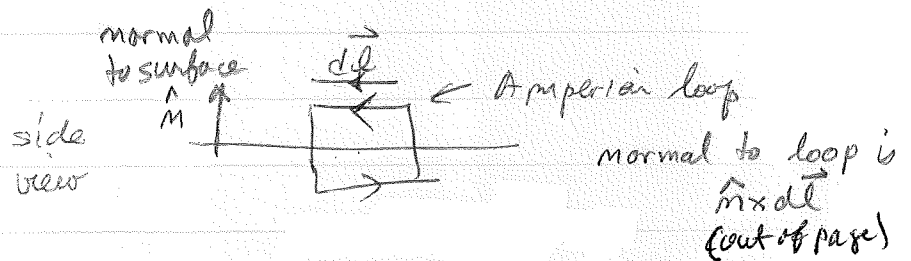
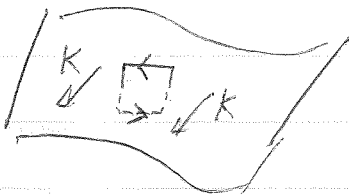


$$\oint \vec{B} \cdot d\vec{a} = (\vec{B}_{\text{above}} - \vec{B}_{\text{below}}) \cdot \hat{m} da = 0$$

$$(\vec{B}_{\text{above}} - \vec{B}_{\text{below}}) \cdot \hat{m} = 0$$

normal component \vec{B} continuous

$$\vec{\nabla} \times \vec{B} = \mu_0 \vec{J}$$



choose $d\vec{l}$ tangent to surface

$$(\vec{B}_{\text{above}} \cdot d\vec{l} - \vec{B}_{\text{below}} \cdot d\vec{l}) = \mu_0 \vec{K} \cdot (\hat{m} \times d\vec{l})$$

tangential component \perp to \vec{K} has jump

$$(\vec{B}_{\text{above}} - \vec{B}_{\text{below}}) \cdot d\vec{l} = \mu_0 (\vec{K} \times \hat{m}) \cdot d\vec{l}$$

$$\Rightarrow \boxed{\vec{B}_{\text{above}} - \vec{B}_{\text{below}} = \mu_0 (\vec{K} \times \hat{m})}$$

contains both results

$$\hat{m} \cdot (\vec{B}_{\text{above}} - \vec{B}_{\text{below}}) = \mu_0 \hat{m} \cdot (\vec{K} \times \hat{m}) = 0$$

as $\vec{K} \times \hat{m} \perp \hat{m}$

$$d\vec{l} \cdot (\vec{B}_{\text{above}} - \vec{B}_{\text{below}}) = \mu_0 d\vec{l} \cdot (\vec{K} \times \hat{m})$$

In terms of potential:

$$\boxed{\frac{\partial \vec{A}_{\text{above}}}{\partial m} - \frac{\partial \vec{A}_{\text{below}}}{\partial m} = -\mu_0 \vec{K}}$$