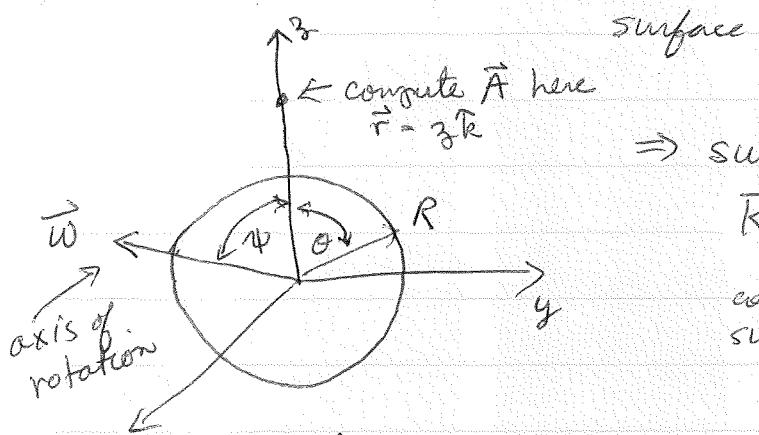


B Field of uniformly rotating charged sphere of radius R



surface charge σ

\Rightarrow surface current

$$\vec{K}(0, \phi) = \sigma \vec{v}(0, \phi) = \sigma \vec{\omega} \times \vec{r}'$$

coords on
surface of
sphere

pt on surface
at (θ, ϕ)

$$\vec{\omega} = \omega (\cos \psi \hat{z} + \sin \psi \hat{x})$$

$$\vec{r}' = R (\cos \theta \hat{z} + \sin \theta \cos \phi \hat{x} + \sin \theta \sin \phi \hat{y})$$

$$\vec{K} = \sigma \vec{\omega} \times \vec{r}' = \sigma \omega R \left((\cos \psi \sin \theta \cos \phi - \sin \psi \cos \theta) \hat{y} \right. \\ \left. - \cos \psi \sin \theta \sin \phi \hat{x} + \sin \psi \sin \theta \sin \phi \hat{z} \right)$$

$$\vec{A}(\vec{r}) = \frac{\mu_0}{4\pi} \int d\alpha' \frac{\vec{K}(\vec{r}')}{|\vec{r} - \vec{r}'|}$$

$$\text{here } \vec{r} = z \hat{z}, \quad \vec{r}' = R (\cos \theta \hat{z} + \sin \theta \cos \phi \hat{x} + \sin \theta \sin \phi \hat{y}) \\ |\vec{r} - \vec{r}'| = (r^2 + r'^2 - 2 \vec{r} \cdot \vec{r}')^{1/2} \\ = (z^2 + R^2 - 2 z R \cos \theta)^{1/2}$$

$$d\alpha' = R^2 \sin \theta d\theta d\phi$$

$$A(z \hat{z}) = \frac{\mu_0 \sigma \omega R}{4\pi} \int_0^{2\pi} d\phi \int_0^\pi d\theta \sin \theta \left[(\cos \psi \sin \theta \cos \phi - \sin \psi \cos \theta) \hat{y} - \cos \psi \sin \theta \sin \phi \hat{x} + \sin \psi \sin \theta \sin \phi \hat{z} \right] \\ (z^2 + R^2 - 2 z R \cos \theta)^{1/2}$$

$$\vec{A}(z \hat{k}) = \frac{\mu_0 \sigma w R^3}{4\pi} \int_0^{2\pi} d\phi \int_0^\pi \sin\theta d\theta \frac{(-\sin\theta \cos\theta \hat{y})}{(z^2 + R^2 - 2zR \cos\theta)^{1/2}}$$

$$\text{let } \mu = -\cos\theta, \quad d\mu = \sin\theta \, d\theta \quad \int d\phi = 2\pi$$

$$= +\frac{\mu_0 \sigma w R^3}{2} \sin\psi \hat{y} \int_{-1}^1 d\mu \frac{\mu}{(z^2 + R^2 + 2zR\mu)^{1/2}}$$

integrate
by parts

$$\rightarrow = \left[\mu \frac{(z^2 + R^2 + 2zR\mu)^{1/2}}{3R} \right]_{-1}^1 - \int_{-1}^1 d\mu \frac{(z^2 + R^2 + 2zR\mu)^{1/2}}{3R}$$

$$= \left[\mu \frac{(z^2 + R^2 + 2zR\mu)^{1/2}}{3R} \right]_{-1}^1 - \left[\frac{(z^2 + R^2 + 2zR)^{3/2}}{3z^2 R^2} \right]_{-1}^1$$

$$= \frac{(z^2 + R^2 + 2zR)^{1/2}}{3R} + \frac{(z^2 + R^2 - 2zR)^{1/2}}{3R} - \frac{(z^2 + R^2 + 2zR)^{3/2}}{3z^2 R^2} - \frac{(z^2 + R^2 - 2zR)^{3/2}}{3z^2 R^2}$$

for $z > R$ outside:

$$= \frac{z+R+(z-R)}{3R} - \frac{(z+R)^3 - (z-R)^3}{3z^2 R^2}$$

$$= \frac{2z}{3R} - \left(\frac{z^3 + R^3 + 3z^2 R + 3zR - z^3 + R^3 + 3z^2 R - 3zR^2}{3z^2 R^2} \right)$$

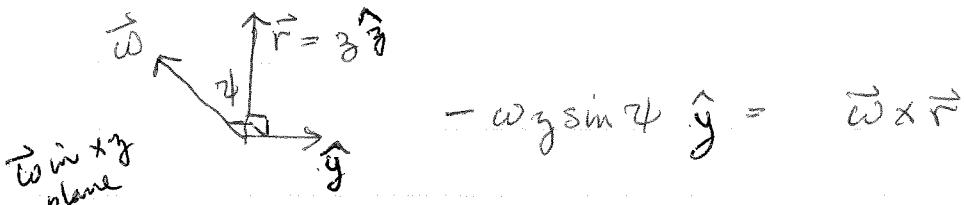
$$= \frac{2z}{3R} - \frac{2R^3 + 6z^2 R}{3z^2 R^2} = \frac{2}{R} - \frac{2R}{3z^2} - \frac{2}{R} = -\frac{2}{3} \frac{R}{z^2}$$

for $z < R$ inside

$$= \frac{2R}{3R} - \frac{2z^3 + 6R^2 z}{3z^2 R^2} = \frac{2}{3} - \frac{2z}{3} \frac{R}{R^2} - \frac{2}{3} = -\frac{2}{3} \frac{z}{R^2}$$

$$\vec{A}(z\hat{k}) = -\frac{\mu_0 \sigma w R^3}{3} \sin \psi \hat{j} \times \begin{cases} \frac{R^2}{r^2} & \text{outside} \\ \frac{z}{r^2} & \text{inside} \end{cases}$$

$$= \begin{cases} -\frac{\mu_0 \sigma w R^4 \sin \psi}{3r^2} \hat{j} & \text{outside} \\ \frac{\mu_0 \sigma w z R \sin \psi}{3} \hat{j} & \text{inside} \end{cases}$$

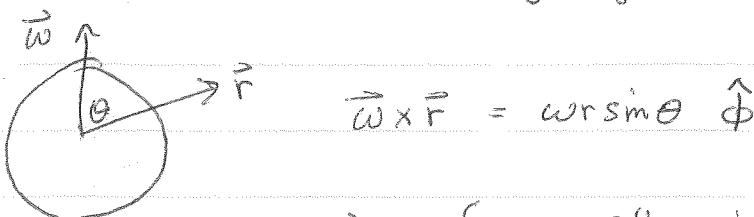


\Rightarrow without reference to any particular coordinate system

$$\vec{A}(\vec{r}) = \begin{cases} \frac{\mu_0 \sigma R^4}{3} \vec{\omega} \times \vec{r} & \text{outside} \\ \frac{\mu_0 \sigma R}{3} \vec{\omega} \times \vec{r} & \text{inside} \end{cases}$$

Now compute $\vec{B} = \vec{\nabla} \times \vec{A}$.

Easiest to do this in spherical coords, where we now choose $\vec{\omega}$ along z axis,



$$\vec{A}(\vec{r}) = \begin{cases} \frac{\mu_0 \sigma R^4}{3} w \sin \theta \hat{\phi} & \text{outside} \\ \frac{\mu_0 \sigma R r w \sin \theta}{3} \hat{\phi} & \text{inside} \end{cases}$$

$$\vec{\nabla} \times \vec{A} = \frac{1}{r \sin \theta} \left(\frac{\partial}{\partial \theta} (\sin \theta A_\phi) - \frac{\partial A_\theta}{\partial \phi} \right) \hat{r}$$

$$+ \frac{1}{r} \left[\frac{1}{\sin \theta} \frac{\partial A_r}{\partial \phi} - \frac{\partial}{\partial r} (r A_\phi) \right] \hat{\theta} + \frac{1}{r} \left[\frac{\partial}{\partial r} (r A_\theta) - \frac{\partial A_r}{\partial \theta} \right] \hat{\phi}$$

Here $A_r = A_\theta = 0$, $A_\phi \neq 0$

$$\vec{\sigma} \times \vec{A} = \frac{1}{r \sin \theta} \frac{\partial}{\partial \theta} (\sin \theta A_\phi) \hat{r} - \frac{1}{r} \frac{\partial}{\partial r} (r A_\phi) \hat{\theta}$$

outside

$$= \frac{\mu_0 \sigma R^4 \omega}{3} \left\{ \frac{1}{r \sin \theta} \frac{\partial}{\partial \theta} \left(\frac{\sin^2 \theta}{r^2} \right) \hat{r} - \frac{1}{r} \frac{\partial}{\partial r} \left(r \frac{\sin \theta}{r^2} \right) \hat{\theta} \right\}$$

$$\left\{ \frac{2 \sin \theta \cos \theta}{r^3 \sin \theta} \hat{r} + \frac{\sin \theta}{r^3} \hat{\theta} \right\}$$

$$\vec{B}(\vec{r}) = \frac{\mu_0 \sigma R^4 \omega}{3} \left[\frac{2 \cos \theta + \sin \theta}{r^3} \right] \times \left\{ \frac{2 \cos \theta}{r^3} \hat{r} + \frac{\sin \theta}{r^3} \hat{\theta} \right\}$$

$$\boxed{\vec{B}(\vec{r}) = \frac{\mu_0 \sigma R^4 \omega}{r^3} (2 \cos \theta \hat{r} + \sin \theta \hat{\theta})}$$

same functional form
as for electric dipole!

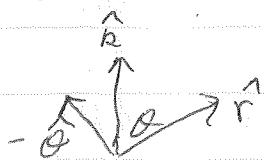
inside

$$= \frac{\mu_0 \sigma R \omega}{3} \left\{ \frac{1}{r \sin \theta} \frac{\partial}{\partial \theta} (\sin^2 \theta r) \hat{r} - \frac{1}{r} \frac{\partial}{\partial r} (r^2 \sin \theta) \hat{\theta} \right\}$$

$$\left\{ \frac{2 \sin \theta \cos \theta}{\sin \theta} \hat{r} - 2 \sin \theta \hat{\theta} \right\}$$

$$= \frac{2}{3} \mu_0 \sigma R \omega \left\{ \underbrace{\cos \theta \hat{r} - \sin \theta \hat{\theta}}_{\vec{z}} \right\}$$

$$\vec{z} \text{ since } \vec{\omega} = \omega \vec{z}$$

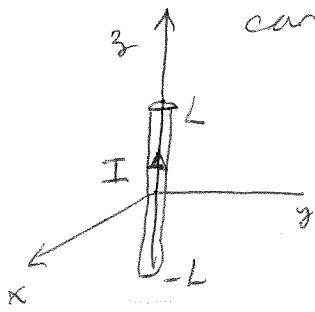


$$\boxed{\vec{B}(\vec{r}) = \frac{2}{3} \mu_0 \sigma R \vec{\omega}}$$

\vec{B} is uniform inside sphere
and aligned with axis
of rotation.

5.25

Find \vec{A} of finite segment of straight wire carrying current I



problem is artificial since current not conserved at ends of wire. But we can't do infinite wire case since

$$\vec{A}(\vec{r}) = \frac{\mu_0}{4\pi} \int d^3 r' \frac{\vec{j}(r')}{|\vec{r}-\vec{r}'|}$$

only works when $j(r') \rightarrow 0$ as $r' \rightarrow \infty$ — this isn't true for infinite wire. Nevertheless, we can do finite wire problem and see if we get the correct answer for \vec{B} when we let $L \rightarrow \infty$ at end of calculation.

$$\vec{A}(\vec{r}) = \frac{\mu_0}{4\pi} \int dl' \frac{\vec{I}(r')}{|\vec{r}-\vec{r}'|}$$

here, $\vec{I}(r') = I \hat{z}$, $dl' = dz$ from $-L$ to $+L$

$$\vec{r}' = z \hat{z}$$

$\vec{r} = r \hat{r}$ in spherical coords

$$\Rightarrow |\vec{r}-\vec{r}'| = (r^2 + z^2 - 2rz \cos\theta)^{1/2}$$

$$\vec{A}(\vec{r}) = \frac{\mu_0}{4\pi} \int_{-L}^L dz \frac{I \hat{z}}{(r^2 + z^2 - 2rz \cos\theta)^{1/2}}$$

$$= \frac{\mu_0 I \hat{z}}{4\pi} \ln \left[2\sqrt{r^2 + z^2 - 2rz \cos\theta} + 2z - 2r \cos\theta \right]_{-L}^L$$

$$A(\vec{r}) = \frac{\mu_0}{4\pi} I \hat{z} \left\{ \ln \left[2\sqrt{L^2+r^2-2rL\cos\theta} \right] + 2L - 2r\cos\theta \right\}$$

$$- \ln \left[2\sqrt{L^2+r^2+2rL\cos\theta} - 2L - 2r\cos\theta \right]$$

consider $L \gg r$ so that observer won't see unphysical ends of the wire.

$$2\sqrt{L^2+r^2-2rL\cos\theta} + 2L - 2r\cos\theta$$

$$= 2L \sqrt{1 + \left(\frac{r}{L}\right)^2 - 2\frac{r}{L}\cos\theta} + 2L - 2r\cos\theta \quad \sqrt{1+\epsilon} \approx 1 + \frac{\epsilon}{2} - \frac{\epsilon^2}{8}$$

$$= 2L \left(1 - \frac{r}{2}\cos\theta + \frac{1}{2}\left(\frac{r}{L}\right)^2 - \frac{1}{2}\left(\frac{r}{L}\right)^2\cos^2\theta + O\left(\frac{r}{L}\right)^3 \right) + 2L - 2r\cos\theta$$

$$\approx 2L - 2r\cos\theta + \frac{r^2}{L} - \frac{r^2}{L}\cos^2\theta + 2L - 2r\cos\theta$$

$$= 4L - 4r\cos\theta + \frac{r^2}{L}(1 - \cos^2\theta) = 4L - 4r\cos\theta + \frac{r^2}{L}\sin^2\theta$$

similarly: $2\sqrt{L^2+r^2+2rL\cos\theta} - 2L - 2r\cos\theta$

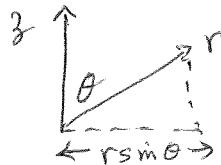
$$= 2L \left(1 + \frac{r}{2}\cos\theta + \frac{1}{2}\left(\frac{r}{L}\right)^2 - \frac{1}{2}\left(\frac{r}{L}\right)^2\cos^2\theta + O\left(\frac{r}{L}\right)^3 \right) - 2L - 2r\cos\theta$$

$$= 2L + 2r\cos\theta + \frac{r^2}{L} - \frac{r^2}{L}\cos^2\theta - 2L - 2r\cos\theta$$

$$= \frac{r^2}{L}(1 - \cos^2\theta) = \frac{r^2}{L}\sin^2\theta$$

$$\vec{A}(\vec{r}) = \frac{\mu_0}{4\pi} I \hat{z} \ln \left[\frac{4L - 4r\cos\theta + \frac{r^2}{L}\sin^2\theta}{\frac{r^2}{L}\sin^2\theta} \right]$$

$$= \frac{\mu_0}{4\pi} I \hat{z} \ln \left[\frac{4 - 4\left(\frac{r}{L}\right)\cos\theta + \left(\frac{r}{L}\right)^2\sin^2\theta}{\left(\frac{r}{L}\right)^2\sin^2\theta} \right]$$



As $L \rightarrow \infty$

$$\vec{A}(r) = \frac{\mu_0}{4\pi} I \hat{\phi} \ln \left(\frac{4L^2}{r^2 \sin^2 \theta} \right)$$

$$\underbrace{\vec{A}(r, \phi, z)}_{\text{cylindrical coords}} = \frac{\mu_0}{2\pi} I \hat{\phi} \ln \left(\frac{2L}{r} \right)$$

note $r \sin \theta$ = projection
of \vec{r} into xy plane
= cylindrical word "r"

evaluate $\nabla \times \vec{A}$ in cylindrical coords, where $A_r = A_\phi = 0$
 A_z depends only on r

$$\vec{B} = \nabla \times \vec{A} = - \frac{\partial A_z}{\partial r} \hat{\phi}$$

$$= - \frac{\mu_0}{2\pi} I \underbrace{\frac{\partial}{\partial r} \left(\ln \frac{2L}{r} \right)}_{-\frac{1}{r}} \hat{\phi}$$

$\vec{B} = \frac{\mu_0 I}{2\pi r} \hat{\phi}$	agrees with <u>earlier result!</u>
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Multipole expansion for $\vec{A}(\vec{r})$

$$\vec{A}(\vec{r}) = \frac{\mu_0}{4\pi} \int d^3 r' \frac{\vec{f}(\vec{r}')}{|\vec{r} - \vec{r}'|}$$

we saw when doing the multipole expansion for $V(r)$ that

$$\frac{1}{|\vec{r} - \vec{r}'|} = \frac{1}{r} \sum_{n=0}^{\infty} \left(\frac{r'}{r} \right)^n P_n(\cos\theta)$$

so

$$\vec{A}(\vec{r}) = \frac{\mu_0}{4\pi r} \sum_{n=0}^{\infty} \int d^3 r' \vec{f}(\vec{r}') \left(\frac{r'}{r} \right)^n P_n(\cos\theta)$$

$n=0$ monopole term

$$\vec{A}_{\text{mono}}(\vec{r}) = \frac{\mu_0}{4\pi r} \int d^3 r' \vec{f}(\vec{r}')$$

$$\text{use } \vec{\nabla} \cdot (\vec{r}_\mu \vec{f}) = r_\mu \vec{\nabla} \cdot \vec{f} + \vec{f} \cdot \vec{\nabla} r_\mu$$

$\vec{\nabla} r_\mu = \hat{\mu}$ unit vector in direction μ

$$= r_\mu \vec{\nabla} \cdot \vec{f} + j_\mu$$

$$\text{example } \frac{\partial}{\partial x}(x, y, z) = (1, 0, 0) = \hat{x}$$

$$= -r_\mu \frac{\partial \phi}{\partial t} + j_\mu$$

$$\text{using } \vec{\nabla} \cdot \vec{f} = -\frac{\partial \phi}{\partial t}$$

so

$$\int d^3 r \vec{f}_\mu(\vec{r}) = \int d^3 r \left[\vec{\nabla} \cdot (r_\mu \vec{f}) + r_\mu \frac{\partial \phi}{\partial t} \right]$$

$$= \underbrace{\int d^3 r}_{S} r_\mu \vec{f} + \int d^3 r r_\mu \frac{\partial \phi}{\partial t}$$

assuming $S \rightarrow 0$ and current \vec{f} is localized

$$= \frac{d}{dt} \int d^3 r r_\mu f = \frac{dP_\mu}{dt}$$

P_μ is μ component of electric dipole moment

$$= 0 \quad \text{since in statics } \frac{dP}{dt} = 0$$

$\Rightarrow \int d^3r \vec{f}(\vec{r}) = 0$ in magnetostatics

monopole term always vanishes!

$n=1$ dipole term

$$\begin{aligned}\vec{A}_{\text{dipole}}(\vec{r}) &= \frac{\mu_0}{4\pi r^2} \int d^3r' \vec{f}(\vec{r}') r' \cos\theta = \frac{\mu_0}{4\pi r^2} \int d^3r' \vec{f}(\vec{r}') (\vec{r}' \cdot \hat{r}) \\ &= \frac{\mu_0}{4\pi r^2} \hat{r} \cdot \int d^3r' [\vec{r}' \vec{f}(\vec{r}')] \quad \text{Tensor}\end{aligned}$$

we need to compute the tensor $\int d^3r r_\mu j_\nu \quad \mu, \nu = x, y, z$

$$\text{use } \vec{\nabla} \cdot (r_\mu r_\nu \vec{f}) = r_\mu \vec{\nabla} \cdot (r_\nu \vec{f}) + (r_\nu \vec{f}) \cdot \vec{\nabla} r_\mu = r_\mu j_\nu + r_\nu j_\mu$$

$$\int d^3r r_\mu j_\nu = \int d^3r [\vec{\nabla} \cdot (r_\mu r_\nu \vec{f}) - r_\nu j_\mu] \quad \left(\begin{array}{l} \text{from monopole calc} \\ (\vec{\nabla} \cdot (r_\nu \vec{f})) = j_\nu \text{ in magnetostatics} \end{array} \right)$$

$$= \oint d\sigma \cdot (r_\mu r_\nu \vec{f}) - \int d^3r r_\nu j_\mu$$

$\xrightarrow{s} 0$ as $s \rightarrow \infty$ for localized \vec{f}

$$\Rightarrow \int d^3r r_\mu j_\nu = - \int d^3r r_\nu j_\mu \quad \text{tensor is antisymmetric}$$

$$\int d^3r r_\mu j_\nu = \frac{1}{2} \int d^3r [r_\mu j_\nu - r_\nu j_\mu]$$

$$\text{or in tensor form } \int d^3r \vec{r} \vec{f} = \frac{1}{2} \int d^3r [\vec{r} \vec{f} - \vec{f} \vec{r}]$$

$$\text{where } [\vec{r} \vec{f}]_{\mu\nu} = r_\mu j_\nu$$

$$\begin{aligned}
 \text{Now } \hat{r} \cdot \int d^3 r' [\vec{r}' \vec{f}(\vec{r}')] &= \frac{1}{2} \int d^3 r' \hat{r} \cdot [\vec{r}' \vec{f} - \vec{f} \vec{r}'] \\
 &= \frac{1}{2} \int d^3 r' [(F \cdot \vec{r}') \vec{f} - (\vec{r} \cdot \vec{f}) \vec{r}'] \quad \text{triple product rule} \\
 &= \frac{1}{2} \int d^3 r' \hat{r} \times (\vec{f} \times \vec{r}')$$

$$\text{So } \vec{A}_{\text{dip}}(\vec{r}) = \frac{\mu_0}{4\pi r^2} \hat{r} \times \frac{1}{2} \int d^3 r' \vec{f} \times \vec{r}' = -\frac{\mu_0}{4\pi r^2} \hat{r} \times \frac{1}{2} \int d^3 r' \vec{r}' \times \vec{f}$$

define the magnetic dipole moment

$$\boxed{\vec{m} = \frac{1}{2} \int d^3 r' [\vec{r}' \times \vec{f}(\vec{r}')] }$$

$$\vec{A}_{\text{dip}}(\vec{r}) = -\frac{\mu_0}{4\pi r^2} \hat{r} \times \vec{m} = \boxed{\frac{\mu_0}{4\pi r^2} \vec{m} \times \hat{r} = \vec{A}_{\text{dip}}(\vec{r})}$$

$$\text{For a wire loop } \vec{m} = \frac{1}{2} I \oint \vec{r}' \times d\vec{l} \quad \text{using } d\vec{l} \vec{I} = I d\vec{l}$$

\vec{m} is independent of the choice of the origin

If we shift origin by transforming to new coordinate system
 $\tilde{\vec{r}} = \vec{r} + \vec{d}$

Then in the $\tilde{\vec{r}}$ coordinate system

$$\tilde{\vec{m}} = \frac{1}{2} \int d^3 \tilde{r} (\tilde{\vec{r}} \times \vec{f}) = \frac{1}{2} \int d^3 r (\tilde{\vec{r}} + \vec{d}) \times \vec{f}$$

$$= \frac{1}{2} \int d^3 r (\vec{r} \times \vec{f}) + \frac{1}{2} \vec{d} \times \underbrace{\int d^3 r \vec{f}}_{=0}$$

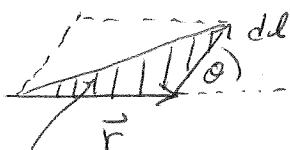
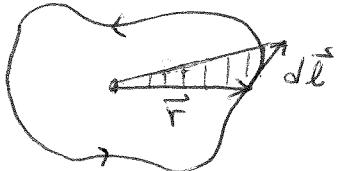
$$\tilde{\vec{m}} = \vec{m}$$

we have seen that
 2nd term vanishes
 in magnetostatics

For a planar loop:

$$\vec{m} = \frac{1}{2} I \oint \vec{r} \times d\vec{l}$$

$$\vec{r} \times d\vec{l} = r dl \sin \theta \hat{m}$$



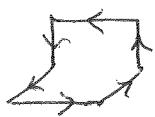
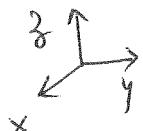
$$\text{area is } (r dl \sin \theta) \left(\frac{1}{2}\right)$$

\hat{m} normal to plane.
use right hand rule
for direction

$$\Rightarrow \vec{m} = \hat{m} I \oint dl \frac{r \sin \theta}{2} = \hat{m} I (\text{area of loop})$$

$$\text{if } \vec{a} = \text{area } \hat{m} \text{ then } \vec{m} = I \vec{a}$$

can use this to get \vec{m} for a piecewise planar loop
for example:



$$= \text{superposition of } \begin{array}{c} \text{rectangle} \\ \text{area } a_1 \end{array} \xrightarrow{\textcircled{1}} \vec{m}_1 + \begin{array}{c} \text{rectangle} \\ \text{area } a_2 \end{array} \xrightarrow{\textcircled{2}} \vec{m}_2 = \vec{m}$$

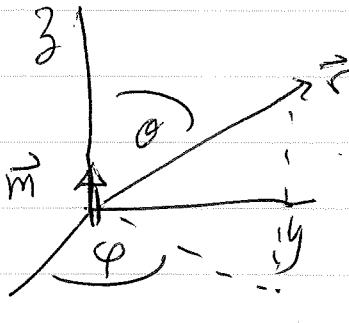
$$\text{where } \vec{m}_1 = I a_1 \hat{x}, \quad I a_2 \hat{z} = \vec{m}_2$$

Where a_1 and a_2 are areas of the two pieces.

Magnetic field w/ dipole approximation

$$\vec{B}_{\text{dip}} = \vec{\nabla} \times \vec{A}_{\text{dip}} = \vec{\nabla} \times \left[\frac{\mu_0}{4\pi r^2} (\vec{m} \times \hat{r}) \right]$$

write in spherical coordinates choose \hat{z} axis to lie along \vec{m}



$$\vec{m} \times \hat{r} = m \sin \theta \hat{\phi}$$

$$\vec{A}_{\text{dip}}(\vec{r}) = \frac{\mu_0}{4\pi r^2} m \sin \theta \hat{\phi}$$

$$\vec{B}_{\text{dip}} = \vec{\nabla} \times \vec{A}_{\text{dip}} = \frac{1}{r \sin \theta} \left[\frac{\partial}{\partial \theta} (\sin \theta A_\phi) \right] \hat{r} - \frac{1}{r} \left[\frac{\partial}{\partial r} (r A_\phi) \right] \hat{\theta}$$

since $A_r = A_\theta = 0$

$$\vec{B}_{\text{dip}}(\vec{r}) = \frac{1}{r \sin \theta} \left[\frac{\partial}{\partial \theta} \left(\sin^2 \theta \frac{\mu_0 m}{4\pi r^2} \right) \right] \hat{r} - \frac{1}{r} \left[\frac{\partial}{\partial r} \left(r \frac{\mu_0}{4\pi r^2} m \sin \theta \right) \right] \hat{\theta}$$

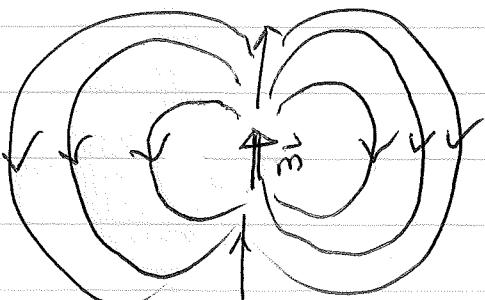
$$= \frac{1}{r \sin \theta} \frac{2 \sin \theta \cos \theta}{4\pi r^2} \frac{\mu_0 m}{r} \hat{r} + \frac{1}{r^3} \frac{\mu_0}{4\pi} m \sin \theta \hat{\theta}$$

$$\boxed{\vec{B}_{\text{dip}}(\vec{r}) = \frac{\mu_0 m}{4\pi r^3} [2 \cos \theta \hat{r} + \sin \theta \hat{\theta}]}$$

← same form as \vec{E} field from electric dipole \vec{p}

$$= \frac{\mu_0}{4\pi r^3} [3(\vec{m} \cdot \hat{r}) \hat{r} - \vec{m}]$$

← just like we found for \vec{E}_{dip} , expresses \vec{B}_{dip} without reference to any particular coordinate system



\vec{B} field lines for dipole \vec{m}

5.37

Circular loop of radius R in xy plane, current I .

$$\Rightarrow \vec{m} = I \text{ area } \hat{\vec{z}} = I\pi R^2 \hat{\vec{z}}$$

$$\vec{B} = \frac{\mu_0}{4\pi} \frac{I\pi R^2}{r^3} (2\cos\theta \hat{r} + \sin\theta \hat{\theta})$$

along z axis, $\theta = 0$ for $z > 0$

$\theta = \pi$ for $z < 0$

$$\vec{B}(z\hat{z}) = \frac{\mu_0 I R^2}{4z^3} 2\hat{z} \quad \text{for } z > 0$$

$$\frac{\mu_0 I R^2}{4z^3} (-2)(-\hat{z}) \quad \text{for } z < 0$$

$$\vec{B}(z\hat{z}) = \frac{\mu_0 I R^2}{2z^3} \hat{z} \quad \text{for both } z > 0 \text{ and } z < 0$$

exact solution (Ex 6) was

$$\vec{B}(z\hat{z}) = \frac{\mu_0 I R^2}{2} \frac{\hat{z}}{(R^2+z^2)^{3/2}}$$

for $z \gg R$, $(R^2+z^2)^{3/2} \approx z^3$, so exact answer
agrees with dipole approx
in field limit $z \gg R$