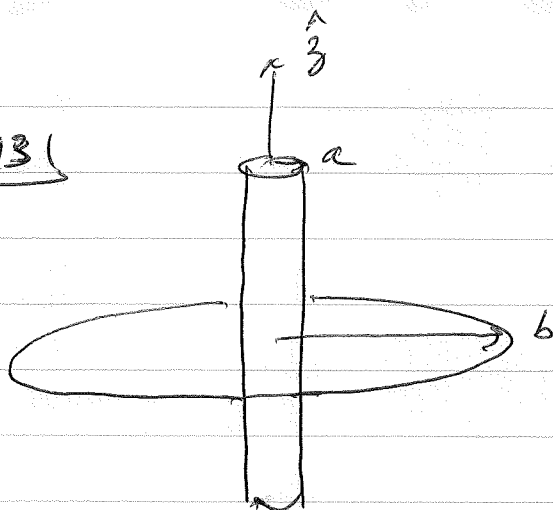


8131



solenoid of radius a ,
surrounded by a circular
wire ring of radius b
 $a \ll b$

solenoid has current I_s
flowing in N turns of wire
per unit length

a) \vec{B} field from solenoid is

$$\vec{B} = \begin{cases} \mu_0 N I_s \hat{z} & \text{for } r < a \\ 0 & \text{for } r > a \end{cases}$$

Flux through circular wire is

$$\Phi = \pi a^2 B = \mu_0 \pi a^2 N I_s$$

If Φ changes (because I_s changes) then there is
an emf \mathcal{E} induced in the circular wire ring

$$\mathcal{E} = -\frac{d\Phi}{dt} = -\mu_0 \pi a^2 N \frac{dI_s}{dt}$$

If the circular wire ring has a total resistance R
then the current induced in the ring is

$$\vec{I}_r = \frac{\mathcal{E}}{R} \hat{\phi} = -\frac{\mu_0 \pi a^2 N}{R} \frac{dI_s}{dt} \hat{\phi}$$

Note: Φ computed in $+\hat{z}$ direction $\Rightarrow \mathcal{E}$ computed in the
 $+\hat{\phi}$ (counterclockwise) direction (right hand rule)

$\Rightarrow \vec{I}_r$ is in the $\hat{\phi}$ direction

If $\frac{dI_s}{dt} > 0$ then $\mathcal{E} < 0 \Rightarrow I_r$ is flowing

in the $-\hat{\phi}$ direction, \mathcal{E} flowing clockwise.

b) power dissipated in ring is $P = I_r^2 R = I_r \mathcal{E}$
where does this power come from? It must be coming from the solenoid!

Compute the flux of energy flowing away from the solenoid.

energy flux given by the Poynting vector

$$\vec{S} = \frac{1}{\mu_0} \vec{E} \times \vec{B}$$

we want to evaluate this on the outside surface of the solenoid.

The \vec{E} field in this \vec{S} is just the \vec{E} field induced by Faradays Law. By symmetry we expect $\vec{E}(\vec{r}) = E(r) \hat{\phi}$

$$\vec{\nabla} \times \vec{E} = -\frac{\partial \vec{B}}{\partial t} \Rightarrow \oint \vec{E} \cdot d\vec{l} = -\frac{d}{dt} \int d\vec{a} \cdot \vec{B}$$

for a circular path of radius r we then get

$$2\pi r E(r) = -\frac{d\Phi}{dt} = \mathcal{E} \leftarrow \text{the emf in the ring}$$

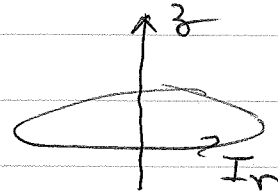
So we can write

$$\vec{E}(r) = \frac{\Sigma}{2\pi r} \hat{\phi} \quad E = -\mu_0 \pi a^2 N \frac{dI_s}{dt} \text{ from (a)}$$

What is the \vec{B} that appears in \vec{S} ? It is NOT the \vec{B} field from the solenoid as that is zero outside the solenoid. Rather the \vec{B} outside the solenoid must be the \vec{B} produced by the current I_r in the circular ring!

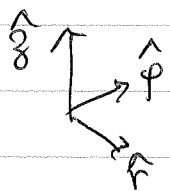
From example 5-6 in the text we have for \vec{B} along the \hat{z} from a circular ring

$$\vec{B}(z) = \frac{\mu_0 I_r}{2} \frac{b^2 \hat{z}}{(b^2 + z^2)^{3/2}}$$



We really want \vec{B} at $r=a$ on the surface of the solenoid, but since $a \ll b$ it will be a good enough approximation to use the above \vec{B} at $r=0$ along the z axis.

$$\text{So now } \vec{S} = \frac{1}{\mu_0} \vec{E} \times \vec{B} = \frac{1}{\mu_0} \left(\frac{E}{2\pi a} \right) \left(\frac{\mu_0 I_r b^2}{2 (b^2 + z^2)^{3/2}} \right) \hat{\phi} \times \hat{z}$$



$$\hat{\phi} \times \hat{z} = \hat{r}$$

$$\begin{matrix} \uparrow & \uparrow \\ E(r=a) & B \end{matrix}$$

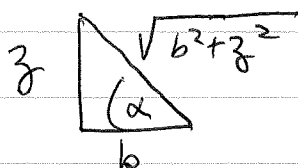
$$\vec{S} = \frac{E I_r b^2}{2\pi a} \frac{1}{2(b^2 + z^2)^{3/2}} \hat{r}$$

on surface of solenoid.

To get the total energy per unit time flowing away from the solenoid we integrate the flux of \vec{S} through the surface of the solenoid.

$$\begin{aligned}
 P &= \int d\vec{a} \cdot \vec{S} = \int_{-\infty}^{\infty} dz \int_0^{2\pi} d\phi a \hat{r} \cdot \vec{S} \\
 &= \epsilon I r \frac{b^2}{2\pi a} 2\pi a \int_{-\infty}^{\infty} dz \frac{1}{z(b^2+z^2)^{3/2}} \\
 &= \epsilon I r \int_{-\infty}^{\infty} dz \frac{b^2}{z(b^2+z^2)^{3/2}}
 \end{aligned}$$

to do the integral we make a trig substitution



$$b \tan \alpha = z \Rightarrow dz = \frac{b}{\cos^2 \alpha} d\alpha$$

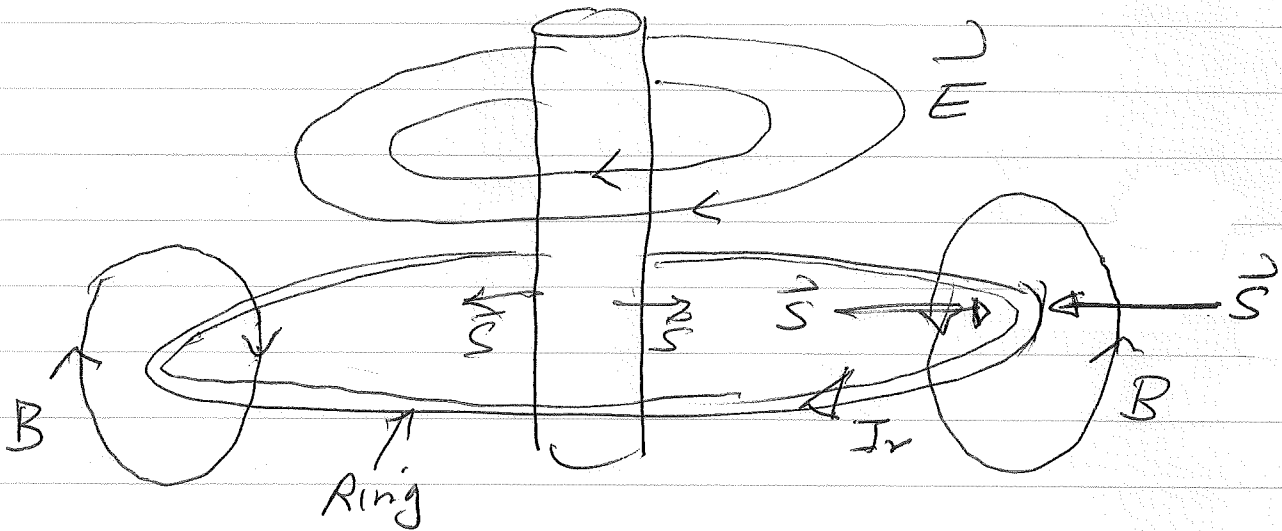
$$\frac{1}{\sqrt{z^2+b^2}} = \frac{\cos \alpha}{b}$$

$$\begin{aligned}
 \int_{-\infty}^{\infty} dz \frac{1}{(b^2+z^2)^{3/2}} &= \int_{-\pi/2}^{\pi/2} d\alpha \frac{b}{\cos^2 \alpha} \frac{\cos^3 \alpha}{b^3} = \int_{-\pi/2}^{\pi/2} d\alpha \frac{\cos \alpha}{b^2} \\
 &= \frac{2}{b^2}
 \end{aligned}$$

$$\text{So } \int_{-\infty}^{\infty} dz \frac{b^2}{z(b^2+z^2)^{3/2}} = 1 \text{ and } P = \epsilon I r$$

power leaving solenoid = power dissipated in ring!

More generally



At surface of ring, one can see that \vec{S} is always directed inward into the ring.

Momentum Conservation

want similar conservation law for mechanical + electromagnetic momentum

$$\frac{\partial}{\partial t} (p_{mi} + p_{EBi}) = \vec{\nabla} \cdot \vec{T}_i \quad i = x, y, z$$

p_{mi} = i^{th} component of a ^{mechanical} momentum density

p_{EBi} = i^{th} component of electromagnetic momentum density

\vec{T}_i = -flux density of i^{th} component of momentum density
(or "current")

Since \vec{T}_i is a vector with 3 components, and there are three such vectors, for $i = x, y, z$, we will see that these 3 vectors form the components of a 3×3 tensor (ie matrix)

$$\left. \begin{array}{l} \text{mechanical momentum density} \\ \text{given by Newton's law} \end{array} \right\} \frac{\partial \vec{p}_m}{\partial t} = \vec{f} = \rho \vec{E} + \vec{j} \times \vec{B}$$

$$\text{force density } \vec{f} = \rho \vec{E} + \vec{j} \times \vec{B} = \epsilon_0 (\vec{\nabla} \cdot \vec{E}) \vec{E} + \left(\frac{1}{\mu_0} \vec{\nabla} \times \vec{B} - \epsilon_0 \frac{\partial \vec{E}}{\partial t} \right) \times \vec{B}$$

Now apply vector algebra + Maxwell's eqn (see text) to manipulate into the form see 8.2.2

$$\vec{f} = \epsilon_0 \left[(\vec{\nabla} \cdot \vec{E}) \vec{E} + (\vec{E} \cdot \vec{\nabla}) \vec{E} \right] + \frac{1}{\mu_0} \left[(\vec{\nabla} \cdot \vec{B}) \vec{B} + (\vec{B} \cdot \vec{\nabla}) \vec{B} \right] - \frac{1}{2} \vec{\nabla} (\epsilon_0 E^2 + \frac{1}{\mu_0} B^2) - \epsilon_0 \frac{\partial}{\partial t} (\vec{E} \times \vec{B})$$

~~(7.9)~~
(8.15)

\vec{f} above looks like mess, but it simplifies if one introduces the following 3x3 matrix, known as the "Maxwell Stress Tensor"

$$T_{ij} = \epsilon_0 (E_i E_j - \frac{1}{2} \delta_{ij} E^2) + \frac{1}{\mu_0} (B_i B_j - \frac{1}{2} \delta_{ij} B^2)$$

$$i = x, y, z \quad \text{and} \quad \delta_{ij} = \begin{cases} 0 & \text{if } i \neq j \\ 1 & \text{if } i = j \end{cases}$$

$$\vec{T} = \begin{bmatrix} \epsilon_0 (E_x^2 - \frac{1}{2} E^2) + \frac{1}{\mu_0} (B_x^2 - \frac{1}{2} B^2) & \epsilon_0 E_x E_y + \frac{1}{\mu_0} B_x B_y & \epsilon_0 E_x E_z + \frac{1}{\mu_0} B_x B_z \\ \epsilon_0 E_x E_y + \frac{1}{\mu_0} B_x B_y & \epsilon_0 (E_y^2 - \frac{1}{2} E^2) + \frac{1}{\mu_0} (B_y^2 - \frac{1}{2} B^2) & \epsilon_0 E_y E_z + \frac{1}{\mu_0} B_y B_z \\ \epsilon_0 E_x E_z + \frac{1}{\mu_0} B_x B_z & \epsilon_0 E_y E_z + \frac{1}{\mu_0} B_y B_z & \epsilon_0 (E_z^2 - \frac{1}{2} E^2) + \frac{1}{\mu_0} (B_z^2 - \frac{1}{2} B^2) \end{bmatrix}$$

$$T_{ij} = T_{ji} \Rightarrow T \text{ is symmetric}$$

$$(\vec{\nabla} \cdot \vec{T}) = \left(\frac{\partial}{\partial x}, \frac{\partial}{\partial y}, \frac{\partial}{\partial z} \right) \begin{pmatrix} T_{xx} & T_{xy} & T_{xz} \\ T_{yx} & T_{yy} & T_{yz} \\ T_{zx} & T_{zy} & T_{zz} \end{pmatrix}$$

$$(\vec{\nabla} \cdot \vec{T})_j = \sum_i \frac{\partial}{\partial x_i} T_{ij} = \sum_i \left[\epsilon_0 \left(\frac{\partial E_i}{\partial x_i} E_j + E_i \frac{\partial E_j}{\partial x_i} - \frac{1}{2} \frac{\partial E^2}{\partial x_i} \delta_{ij} \right) + \frac{1}{\mu_0} \left(\frac{\partial B_i}{\partial x_i} B_j + B_i \frac{\partial B_j}{\partial x_i} - \frac{1}{2} \frac{\partial B^2}{\partial x_i} \delta_{ij} \right) \right]$$

$$(\vec{\nabla} \cdot \vec{T}) = \epsilon_0 \left[(\vec{\nabla} \cdot \vec{E}) \vec{E} + (\vec{E} \cdot \vec{\nabla}) \vec{E} - \frac{1}{2} \vec{\nabla} E^2 \right]$$

$$+ \frac{1}{\mu_0} \left[(\vec{\nabla} \cdot \vec{B}) \vec{B} + (\vec{B} \cdot \vec{\nabla}) \vec{B} - \frac{1}{2} \vec{\nabla} B^2 \right]$$

$$= \vec{f} + \epsilon_0 \frac{\partial}{\partial t} (\vec{E} \times \vec{B}) = \vec{f} + \epsilon_0 \mu_0 \frac{\partial \vec{S}}{\partial t}$$

$$\vec{f} = \frac{\partial \vec{p}_m}{\partial t} = -\epsilon_0 \mu_0 \frac{\partial \vec{S}}{\partial t} + \vec{\nabla} \cdot \vec{T}$$

$$\frac{\partial}{\partial t} [\vec{p}_m + \epsilon_0 \mu_0 \vec{S}] = \vec{\nabla} \cdot \vec{T} \quad \text{this is the desired conservation law for momentum}$$

$$\Rightarrow \boxed{\epsilon_0 \mu_0 \vec{S} = \vec{p}_{EM}} \quad \text{electromagnetic momentum density}$$

$$- \vec{T} \cdot \vec{e}_i = \text{current } j_{ix}$$

$$- T_{ij} \quad \text{is } i^{\text{th}} \text{ component of current, of } j^{\text{th}} \text{ component of electromagnetic momentum density}$$

$$\text{ie the vector } \begin{pmatrix} T_{xx} \\ T_{yx} \\ T_{zx} \end{pmatrix} \text{ is the current for}$$

$$x\text{-component } \vec{p}_{EMx} \text{ of E-M momentum}$$

$$\text{integral form: } \int_{Vol} d^3r \left[\frac{\partial}{\partial t} \vec{p}_m + \frac{\partial}{\partial t} \vec{p}_{EB} \right] = \frac{d}{dt} \int_{Vol} d^3r (\vec{p}_m + \vec{p}_{EB})$$

$$= \int_{Vol} d^3r \vec{\nabla} \cdot \vec{T} = \oint_S d\vec{a} \cdot \vec{T}$$

total mechanical + electromagnetic field momentum contained in Vol

(\leftarrow) flux of field momentum out through surface S bounding Vol

or we can write

$$\frac{d}{dt} \int_{\text{vol}} d^3r \vec{p}_{\text{mech}} = \frac{d\vec{p}_{\text{mech}}}{dt} = - \frac{d}{dt} \int_{\text{vol}} d^3r \vec{p}_{\text{EM}} + \oint_S d\vec{a} \cdot \vec{T}$$

$$\frac{d\vec{p}_{\text{mech}}}{dt} = - \frac{d\vec{p}_{\text{EM}}}{dt} + \oint_S d\vec{a} \cdot \vec{T}$$

total electromagnetic force on the volume

$$\vec{F}_{\text{EM}} = \frac{d\vec{p}_{\text{mech}}}{dt}$$

For a situation where \vec{E} and \vec{B} are constant in time,

$$\frac{d\vec{p}_{\text{EM}}}{dt} = 0 \quad \text{and so}$$

$$\frac{d\vec{p}_{\text{mech}}}{dt} = \oint_S d\vec{a} \cdot \vec{T} \quad \leftarrow \text{gives total electromagnetic force on the volume}$$

this is why \vec{T} is called the Maxwell stress tensor

It is like a pressure acting on the walls of the volume.

Numerically compute $\epsilon_0 \mu_0$, find $\epsilon_0 \mu_0 = \frac{1}{c^2}$ with $c = \text{speed of light}$

$$\vec{S} = c^2 \vec{p}_{EB}$$

↑ energy current
↑ momentum density

Suppose energy current is made of "particles" that travel with velocity \vec{c} . Then $\vec{S} = \vec{c} u_{EB}$ u_{EB} is energy density

$$u_{EB} = c p_{EB} \quad = \text{energy-momentum relation for photons.}$$

also can do same for angular momentum

$$\begin{aligned} \vec{L}_{EB} &= \vec{r} \times \vec{p}_{EB} = \epsilon_0 \vec{r} \times (\vec{E} \times \vec{B}) \\ &= \text{angular momentum density} \\ &\quad \text{contained in } \vec{E} \text{ and } \vec{B} \text{ fields} \end{aligned}$$

see Griffiths Sec 8.2.4

Magnetic monopoles Sec 7.3.4

Maxwell's equations:

$$\begin{aligned} \vec{\nabla} \cdot \vec{E} &= \rho / \epsilon_0 & \vec{\nabla} \cdot \vec{B} &= 0 \\ \vec{\nabla} \times \vec{E} &= -\frac{\partial \vec{B}}{\partial t} & \vec{\nabla} \times \vec{B} &= \mu_0 \vec{j} + \mu_0 \epsilon_0 \frac{\partial \vec{E}}{\partial t} \end{aligned}$$

Maxwell's equations would have a much more symmetric look to them, if one imagined that there were such things as magnetic monopoles (ie. magnetic charges)

$\vec{\nabla} \cdot \vec{B} = 0$ is purely expt result. Suppose we found a magnetic monopole, so that we would now have

$$\vec{\nabla} \cdot \vec{B} = \mu_0 \eta$$

η = volume density of magnetic charge.

$\eta = \sum_i q_i \delta(\vec{r} - \vec{r}_i)$
for point monopoles

A point magnetic monopole would produce a magnetic field $\vec{B} = \frac{\mu_0}{4\pi} \frac{q}{r^2} \hat{r}$

There would be conservation law of magnetic charge $\vec{\nabla} \cdot \vec{k} = -\frac{\partial \eta}{\partial t}$ where \vec{k} is the magnetic charge current density.

Then Faraday's Law would have to be fixed, like Maxwell fixed Ampere's Law

~~$$\vec{\nabla} \cdot (\vec{\nabla} \times \vec{E}) = 0 = \vec{\nabla} \cdot \vec{k}$$~~

$$\vec{\nabla} \cdot (\vec{\nabla} \times \vec{E} + \frac{\partial \vec{B}}{\partial t}) = 0 + \frac{\partial \vec{\nabla} \cdot \vec{B}}{\partial t} = \mu_0 \frac{\partial \eta}{\partial t} = -\mu_0 \vec{\nabla} \cdot \vec{k}$$

New Faraday's law would be $\vec{\nabla} \times \vec{E} = -\mu_0 \vec{k} - \frac{\partial \vec{B}}{\partial t}$

Now Maxwell's equations would look symmetric!

$$\left. \begin{aligned} \vec{\nabla} \cdot \vec{E} &= \rho / \epsilon_0 & \vec{\nabla} \cdot \vec{B} &= \mu_0 \eta \\ \vec{\nabla} \times \vec{E} &= -\mu_0 \vec{k} - \frac{\partial \vec{B}}{\partial t} & \vec{\nabla} \times \vec{B} &= \mu_0 \vec{j} + \mu_0 \epsilon_0 \frac{\partial \vec{E}}{\partial t} \end{aligned} \right\}$$