

back to $\boxed{\frac{\partial F_{\mu\nu}}{\partial x_\nu} = \mu_0 j_\mu}$

to see this is so, substitute in definition of $F_{\mu\nu}$ in terms of 4-potential A_μ

$$\frac{\partial F_{\mu\nu}}{\partial x_\nu} = \frac{\partial}{\partial x_\nu} \left(\frac{\partial A_\nu}{\partial x_\mu} - \frac{\partial A_\mu}{\partial x_\nu} \right) = \frac{\partial}{\partial x_\mu} \left(\frac{\partial A_\nu}{\partial x_\nu} \right) - \frac{\partial^2 A_\mu}{\partial x_\nu^2}$$

1st term = 0 by Lorentz gauge condition. So

$$\frac{\partial F_{\mu\nu}}{\partial x_\nu} = -\frac{\partial^2 A_\mu}{\partial x_\nu^2} = -\square^2 A_\mu = \mu_0 j_\mu$$

$$\frac{\partial F_{\mu\nu}}{\partial x_\nu} = \mu_0 j_\mu \Rightarrow \begin{cases} \vec{\nabla} \times \vec{B} - \frac{1}{c^2} \frac{\partial \vec{E}}{\partial t} = \mu_0 \vec{j} & \text{spatial components} \\ \vec{\nabla} \cdot \vec{E} = \mu_0 c^2 \rho = \rho / \epsilon_0 & \text{temporal component} \end{cases}$$

We still need to have a Lorentz covariant way to write the homogeneous Maxwell Equations.

$$\vec{\nabla} \cdot \vec{B} = 0 \quad \text{and} \quad \vec{\nabla} \times \vec{E} + \frac{\partial \vec{B}}{\partial t} = 0$$

Homogeneous Maxwell Equations

Construct the 3rd rank co-variant tensor

$$\boxed{\tilde{G}_{\mu\nu\lambda} \equiv \frac{\partial F_{\mu\nu}}{\partial x_\lambda} + \frac{\partial F_{\lambda\mu}}{\partial x_\nu} + \frac{\partial F_{\nu\lambda}}{\partial x_\mu}}$$

transforms as $\tilde{G}'_{\mu\nu\lambda} = a_{\mu\alpha} a_{\nu\beta} a_{\lambda\gamma} \tilde{G}_{\alpha\beta\gamma}$

also, one has

$$\tilde{G}_{123} = \frac{\partial F_{12}}{\partial x_3} + \frac{\partial F_{31}}{\partial x_2} + \frac{\partial F_{23}}{\partial x_1} = \frac{\partial B_3}{\partial x_3} + \frac{\partial B_2}{\partial x_2} + \frac{\partial B_1}{\partial x_1} = 0$$

$$\tilde{G}_{123} = 0 \Rightarrow \vec{\nabla} \cdot \vec{B} = 0$$

$$\begin{aligned} \tilde{G}_{412} &= \frac{\partial F_{41}}{\partial x_2} + \frac{\partial F_{24}}{\partial x_1} + \frac{\partial F_{12}}{\partial x_4} = \frac{i \partial E_1}{c \partial x_2} + \frac{-i \partial E_2}{c \partial x_1} + \frac{\partial B_3}{i c \partial t} \\ &= \frac{i}{c} \left[\frac{\partial E_1}{\partial x_2} - \frac{\partial E_2}{\partial x_1} - \frac{\partial B_3}{\partial t} \right] = -\frac{i}{c} \left[(\vec{\nabla} \times \vec{E})_3 + \frac{\partial B_3}{\partial t} \right] = 0 \end{aligned}$$

this is the z-component of Faraday's law $\vec{\nabla} \times \vec{E} + \frac{\partial \vec{B}}{\partial t} = 0$

$\tilde{G}_{413} = 0$ and $\tilde{G}_{423} = 0$ give x and y components of Faraday's law.

An alternative way to write the homogeneous Maxwell's Equations

Note: we can get the homogeneous Maxwell's equations from the inhomogeneous equations by making the substitutions

$$\vec{j} \rightarrow 0, \rho \rightarrow 0, \vec{E} \rightarrow \vec{B}, \vec{B} \rightarrow -\frac{\vec{E}}{c}$$

so we define the dual field strength tensor

$$G_{\mu\nu} = \begin{pmatrix} 0 & -E_3/c & E_2/c & -iB_1 \\ E_3/c & 0 & -E_1/c & -iB_2 \\ -E_2/c & E_1/c & 0 & -iB_3 \\ iB_1 & iB_2 & iB_3 & 0 \end{pmatrix}$$

or equivalently if

generalization of the Levi-Civita symbol

$$\epsilon_{\mu\nu\sigma\lambda} = \begin{cases} +1 & \text{if } \mu\nu\sigma\lambda \text{ is an even permutation of } 1234 \\ -1 & \text{if } \mu\nu\sigma\lambda \text{ is an odd permutation of } 1234 \\ 0 & \text{otherwise, i.e. any two indices equal} \end{cases}$$

then $G_{\mu\nu} = \frac{1}{2i} \epsilon_{\mu\nu\sigma\lambda} F_{\sigma\lambda}$

pseudo-tensor gives wrong sign under parity transform.

then $\frac{\partial G_{\mu\nu}}{\partial x_\nu} = 0$

gives the homogeneous Maxwell's equations

From $F_{\mu\nu}$ and $G_{\mu\nu}$ we can construct the following Lorentz invariant scalars

$$\left. \begin{aligned} \frac{1}{2} F_{\mu\nu} F_{\mu\nu} &= B^2 - \frac{E^2}{c^2} \\ -\frac{1}{4} F_{\mu\nu} G_{\mu\nu} &= \frac{\vec{B} \cdot \vec{E}}{c} \end{aligned} \right\} \text{these have the same value in any inertial frame of reference!}$$

\Rightarrow 1) If $\vec{E} \perp \vec{B}$ and $|\vec{B}| = \frac{|\vec{E}|}{c}$ in one frame of reference, then it is so in all frames of reference, ($\vec{E} \cdot \vec{B} = 0$ and $|\vec{B}|^2 - \frac{|\vec{E}|^2}{c^2} = 0$)

This property is satisfied by EM waves in the vacuum

2) If in one frame $\vec{E} \cdot \vec{B} = 0$ and $\frac{E^2}{c^2} > B^2$, then there exists a frame in which $\vec{B}' = 0$. If in one frame $\vec{E} \cdot \vec{B} = 0$ and $B^2 > \frac{E^2}{c^2}$, then there exists a frame in which $\vec{E}' = 0$.

Relativistic Kinematics

4-momentum of a particle $p_\mu = m \dot{x}_\mu = m u_\mu = (m\gamma\vec{v}, i m c\gamma)$

m is mass of particle as measured in the frame in which the particle is instantaneous at rest. $m =$ "rest mass"

p_μ is a 4-vector since m is a scalar and u_μ is a 4-vector

$$p_\mu^2 = m^2 u_\mu^2 = -m^2 c^2 \quad \text{since } u_\mu^2 = -c^2$$

4-force $K_\mu = (\vec{K}, i K_0)$ also called "Minkowski force"

We guess that the relativistic generalization of Newton's 2nd law of motion is

$$m \frac{d^2 x_\mu}{ds^2} = K_\mu \quad \text{or} \quad m \frac{d u_\mu}{ds} = K_\mu$$

$$\text{or} \quad \frac{d p_\mu}{ds} = K_\mu \quad (p_\mu = m u_\mu = m \dot{x}_\mu)$$

Now since $p_\mu^2 = -m^2 c^2$ is a constant, we have

$$0 = \frac{d}{ds} (p_\mu^2) = 2 p_\mu \frac{d p_\mu}{ds} = 2 p_\mu K_\mu$$

$$\Rightarrow p_\mu K_\mu = 0$$

$$p_\mu K_\mu = m\gamma\vec{v} \cdot \vec{K} - m c\gamma K_0 = 0$$

$$\text{so } \boxed{K_0 = \frac{\vec{v} \cdot \vec{K}}{c}}$$

Time component of 4-force is determined by the spatial components \vec{K}

Define the usual 3-force by

$$\frac{d\vec{p}}{dt} = \vec{F}$$

(we identify the Newtonian momentum \vec{p} with the spatial components of p^μ)

$$\frac{d\vec{p}}{ds} = \vec{K} \quad \text{spatial part of relativistic Newton's law}$$

$$\frac{d\vec{p}}{ds} = \gamma \frac{d\vec{p}}{dt} = \gamma \vec{F} \quad \text{since } ds = dt/\gamma$$

$$\Rightarrow \boxed{\vec{K} = \gamma \vec{F}} \quad \text{relation between spatial part of 4-force and the usual 3-force } \vec{F}$$

$$\Rightarrow K_0 = \frac{\vec{v}}{c} \cdot \vec{K} = \gamma \frac{\vec{v}}{c} \cdot \vec{F}$$

Consider now the 4-th component of Newton's equation

$$\frac{dp_4}{ds} = m \frac{du_4}{ds} = m \frac{d}{ds} (ic\gamma) = iK_0 = i\gamma \frac{\vec{v}}{c} \cdot \vec{F}$$

$$\Rightarrow \frac{d}{ds} (m\gamma c^2) = \gamma \vec{v} \cdot \vec{F}$$

$$d(m\gamma c^2) = \gamma \vec{v} \cdot \vec{F} ds = \gamma \vec{v} \cdot \vec{F} \frac{dt}{\gamma}$$

$$= \vec{v} \cdot \vec{F} dt = d\vec{r} \cdot \vec{F}$$

\Rightarrow

$$\text{Work-energy theorem: } d(m\gamma c^2) = d\vec{r} \cdot \vec{F}$$

theorem

\uparrow

\uparrow work done on particle

\Rightarrow change in kinetic energy of particle

$$\text{relativistic kinetic energy } \boxed{E = m\gamma c^2}$$