

Consider the 4-acceleration

$$\alpha_\mu = \frac{d u_\mu}{ds} = \gamma \frac{d u_\mu}{dt}$$

$$\text{since } ds = dt/\gamma$$

$$\text{use } u_\mu = (\gamma \vec{v}, i\gamma c)$$

$$\vec{\alpha} = \gamma \frac{d}{dt} (\gamma \vec{v}) = \gamma \vec{a} + \dot{\gamma} \vec{v}$$

$$\alpha_4 = \gamma i c \frac{d\gamma}{dt}$$

$$\begin{aligned} \text{we need } \frac{d\gamma}{dt} &= \frac{d}{dt} \left(\frac{1}{\sqrt{1-v^2/c^2}} \right) = \frac{+\frac{\vec{v}}{c^2} \cdot \frac{d\vec{v}}{dt}}{(1-v^2/c^2)^{3/2}} \\ &= + \frac{\vec{v} \cdot \vec{a}}{c^2} \gamma^3 \end{aligned}$$

So

$$\vec{\alpha} = \gamma \vec{a} + \gamma^4 \left(\frac{\vec{v} \cdot \vec{a}}{c^2} \right) \vec{v}$$

$$\alpha_4 = \gamma^4 i \left(\frac{\vec{v} \cdot \vec{a}}{c} \right)$$

$$\alpha_\mu = \gamma^4 \left(\left(\frac{\vec{v} \cdot \vec{a}}{c^2} \right) \vec{v} + \frac{\vec{a}}{\gamma^2}, i \left(\frac{\vec{v} \cdot \vec{a}}{c} \right) \right)$$

in frame K^0 , $\vec{v}^0 = 0$ and $\gamma^0 = 1$, so

$$\alpha_\mu^0 = \left(\vec{a}^0, 0 \right) \quad \text{and so} \quad \alpha^2 = \alpha_\mu^2 \quad \text{Lorentz invariant scalar}$$

So now we can write the relativistic Larmor formula

$$P = \frac{1}{4\pi\epsilon_0} \frac{2}{3} \frac{q^2}{c^3} \alpha^2 = \frac{1}{4\pi\epsilon_0} \frac{2}{3} \frac{q^2}{c^3} \alpha_\mu^2 \quad \text{in any frame } K$$

In a general frame K ,

$$d\mu^2 = |\vec{a}|^2 + a_4^2$$

$$= \gamma^8 \left[\left(\frac{\vec{v} \cdot \vec{a}}{c^2} \right)^2 v^2 + \frac{a^2}{\gamma^4} + 2 \left(\frac{\vec{v} \cdot \vec{a}}{c^2} \right) \frac{(\vec{v} \cdot \vec{a})}{\gamma^2} - \left(\frac{\vec{v} \cdot \vec{a}}{c} \right)^2 \right]$$

$$= \gamma^8 \left[- \left(\frac{\vec{v} \cdot \vec{a}}{c} \right)^2 \left(1 - \frac{v^2}{c^2} \right) + 2 \left(\frac{\vec{v} \cdot \vec{a}}{c} \right)^2 \frac{1}{\gamma^2} + \frac{a^2}{\gamma^4} \right]$$

$$= \gamma^8 \left[\left(\frac{\vec{v} \cdot \vec{a}}{c} \right)^2 \left(\frac{2}{\gamma^2} - \frac{1}{\gamma^2} \right) + \frac{a^2}{\gamma^4} \right]$$

$$= \gamma^8 \left[\frac{a^2}{\gamma^4} + \left(\frac{\vec{v} \cdot \vec{a}}{c} \right)^2 \frac{1}{\gamma^2} \right]$$

$$d\mu^2 = \gamma^4 \left[a^2 + \gamma^2 \left(\frac{\vec{v} \cdot \vec{a}}{c} \right)^2 \right]$$

Note: as $v \rightarrow 0$, $\gamma \rightarrow 1$
and we get $d\mu^2 = a^2$ as
we must.

So power radiated is

$$P = \frac{1}{4\pi\epsilon_0} \frac{2}{3} \frac{q^2}{c^3} \gamma^4 \left[a^2 + \gamma^2 \left(\frac{\vec{v} \cdot \vec{a}}{c} \right)^2 \right]$$

Examples:

(1) For a charge accelerating in linear motion

(such as in a linear particle accelerator such as SLAC)

$\vec{v} \cdot \vec{a} = va$ since \vec{v} and \vec{a} are colinear

$$P = \frac{1}{4\pi\epsilon_0} \frac{2}{3} \frac{q^2}{c^3} \gamma^4 \left[a^2 + \gamma^2 \frac{v^2 a^2}{c^2} \right]$$

$$= \frac{1}{4\pi\epsilon_0} \frac{2}{3} \frac{q^2}{c^3} \gamma^4 a^2 \left[1 + \gamma^2 \frac{v^2}{c^2} \right]$$

$$1 + \gamma^2 \frac{v^2}{c^2} = 1 + \frac{v^2/c^2}{1 - v^2/c^2} = \frac{1}{1 - v^2/c^2} = \gamma^2$$

$$P = \frac{1}{4\pi\epsilon_0} \frac{2}{3} \frac{q^2}{c^3} a^2 \gamma^6$$

relativistic result increased
by factor γ^6 compared to
non-relativistic result

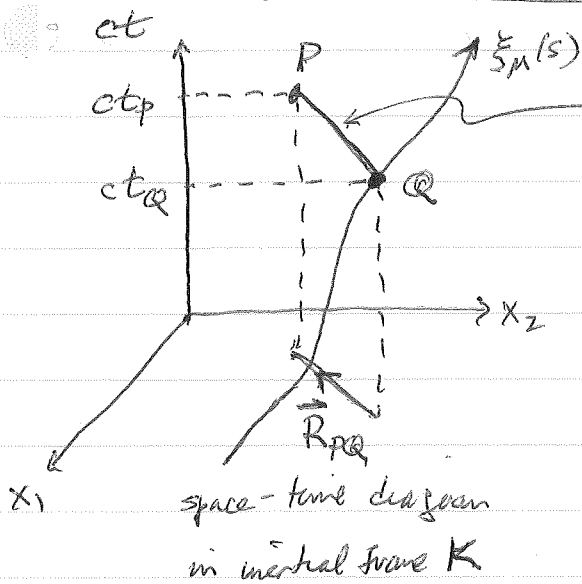
② For a charge accelerating in circular motion
(such as in a synchrotron)

$$\vec{v} \cdot \vec{a} = 0 \quad \text{since } \vec{v} \perp \vec{a}$$

$$P = \frac{1}{4\pi\epsilon_0} \frac{2}{3} \frac{q^2}{c^3} a^2 \gamma^4$$

relativistic result increased
by factor γ^4 compared to
non-relativistic result

Liénard - Wiechert Potentials in Covariant form



light cone of point Q. A pulse of light leaving Q will arrive at P

$\xi_\mu(s)$ is the trajectory of the charged particle 4-position as function of particles proper time s

$$c\Delta t = c(t_P - t_Q) = |\vec{r}_P - \vec{r}_Q| \equiv |\vec{R}_{PQ}|$$

the 4-potential at point P is due to the charge at the earlier point Q. In frame K, \vec{R}_{PQ} is the spatial vector from Q to P, Δt is the time difference between Q and P.

L-W potentials

$$\vec{A}(\vec{r}, t) = \frac{\mu_0}{4\pi} \frac{q \vec{v}(t')}{|\vec{r} - \vec{r}_0(t')|} \frac{1}{1 - \frac{1}{c} \hat{m}(t') \cdot \vec{v}(t')} \quad t' \text{ is the retarded time}$$

$$V(\vec{r}, t) = \frac{q}{4\pi\epsilon_0} \frac{1}{|\vec{r} - \vec{r}_0(t')|} \frac{1}{1 - \frac{1}{c} \hat{m}(t') \cdot \vec{v}(t')} \quad \hat{m}(t') = \frac{\vec{r} - \vec{r}_0(t')}{|\vec{r} - \vec{r}_0(t')|}$$

if we want the potentials at point P, then $(t', \vec{r}_0(t'))$ refers to point Q, so we can rewrite the above as

$$\vec{A}(P) = \frac{\mu_0}{4\pi} \frac{q \vec{v}_Q}{R_{PQ} - \frac{\vec{R}_{PQ} \cdot \vec{v}_Q}{c}} \quad \vec{r} - \vec{r}_0(t') = \vec{R}_{PQ}$$

$$V(P) = \frac{\mu_0 c^2}{4\pi} \frac{q}{R_{PQ} - \frac{\vec{R}_{PQ} \cdot \vec{v}_Q}{c}} \quad \mu_0 \epsilon_0 = \frac{1}{c^2}$$

re-write the denominator in a covariant form

$$R_{PQ} - \vec{R}_{PQ} \cdot \frac{\vec{v}_Q}{c} = \frac{1}{c} (cR_{PQ} - \vec{R}_{PQ} \cdot \vec{v}_Q)$$

use $R_{PQ} = |\vec{R}_{PQ}| = c\Delta t$

$$R_{PQ} - \vec{R}_{PQ} \cdot \frac{\vec{v}_Q}{c} = \frac{1}{c} (c^2\Delta t - \vec{R}_{PQ} \cdot \vec{v}_Q)$$

If x_μ is the 4-position of point P, and ξ_μ is the 4-position of the charge at point Q, then the 4-displacement between the two is

$$R_\mu \equiv x_\mu - \xi_\mu = (\vec{R}_{PQ}, i c \Delta t)$$

the 4-velocity of the charge at point Q is

$$u_\mu = (\gamma \vec{v}_Q, i \gamma c)$$

we then have $R_\mu u_\mu = \gamma \vec{R}_{PQ} \cdot \vec{v}_Q - \gamma c^2 \Delta t$

so $R_{PQ} - \vec{R}_{PQ} \cdot \frac{\vec{v}_Q}{c} = -\frac{1}{c\gamma} R_\mu u_\mu$

the 4-potential is $A_\mu = (\vec{A}, \frac{iV}{c})$ so

$$\frac{iV}{c} = \frac{i}{c} \frac{\mu_0 c^2}{4\pi} \frac{q}{R_\mu u_\mu (-\frac{1}{\gamma c})} = -\frac{i \mu_0 c^2 \gamma}{4\pi} \frac{q}{R_\mu u_\mu}$$

$$\vec{A} = \frac{\mu_0}{4\pi} \frac{q \vec{v}_Q}{R_\mu u_\mu (-\frac{1}{\gamma c})} = -\frac{\mu_0 c \gamma}{4\pi} \frac{q \vec{v}_Q}{R_\mu u_\mu}$$

So $A_\nu = \frac{-\mu_0 c}{4\pi} \frac{q}{R_\mu u_\mu} \delta(\vec{v}_Q, ic)$ $u_\mu = (\gamma \vec{v}_Q, i\gamma c)$

$A_\nu = \frac{-\mu_0 c}{4\pi} \frac{q u_\nu}{R_\mu u_\mu}$

 covariant form for the
 Liénard-Wiechert 4-potential

where $u_\mu = \frac{d\xi_\mu}{ds}$ is the 4-velocity of the charge at point Q.

The retarded time is determined by the condition

$$R_\mu^2 = (x_\mu - \xi_\mu)^2 = 0 \quad \text{holds since P is on the light cone of Q}$$

Define the Lorentz invariant scalar

$$D \equiv -R_\mu u_\mu$$

$$A_\mu(P) = \frac{\mu_0 c}{4\pi} \frac{q u_\mu(s)}{D}$$

x_μ is the position of point P.
 $u_\mu(s)$ is 4-velocity of charge at point Q.

Now we will find the fields, $F_{\mu\nu} = \frac{\partial A_\nu}{\partial x^\mu} - \frac{\partial A_\mu}{\partial x^\nu}$

When we do differentiation with respect to x_μ , we must also take care of the fact s , which locates point Q, also depends on the value of x_μ through the relation

$$R_\lambda^2 = (x_\lambda - \xi_\lambda(s))^2 = 0$$

$$\frac{\partial}{\partial x^\mu} (R_\lambda R_\lambda) = 0 \Rightarrow R_\lambda \frac{\partial R_\lambda}{\partial x^\mu} = R_\lambda \left(\delta_{\mu\lambda} - \frac{\partial \xi_\lambda}{\partial s} \frac{\partial s}{\partial x^\mu} \right) = 0$$

$$\Rightarrow R_\mu = R_\lambda u_\lambda \frac{\partial s}{\partial x^\mu} \Rightarrow \frac{\partial s}{\partial x^\mu} = \frac{R_\mu}{R_\lambda u_\lambda} = \boxed{\frac{-R_\mu}{D} = \frac{\partial s}{\partial x^\mu}}$$

$$\text{Now } \frac{\partial A_V}{\partial x_\mu} = \frac{\mu_0 c q}{4\pi} \frac{\partial}{\partial x_\mu} \left(\frac{u_\nu}{D} \right) = \frac{\mu_0 c q}{4\pi} \left\{ \frac{1}{D} \frac{\partial u_\nu}{\partial s} \frac{\partial s}{\partial x_\mu} - \frac{u_\nu}{D^2} \frac{\partial D}{\partial x_\mu} \right\}$$

$$\text{where } \frac{\partial D}{\partial x_\mu} = -\frac{\partial}{\partial x_\mu} (R_\lambda \cdot u_\lambda) = -R_\lambda \frac{\partial u_\lambda}{\partial s} \frac{\partial s}{\partial x_\mu} - u_\lambda \frac{\partial}{\partial x_\mu} \underbrace{(x_\lambda - s_\lambda)}_{R_\lambda}$$

$$= -R_\lambda \dot{u}_\lambda \left(-\frac{R_\mu}{D} \right) - u_\lambda \left(\delta_{\lambda\mu} - \frac{\partial s_\lambda}{\partial s} \frac{\partial s}{\partial x_\mu} \right)$$

$$= \frac{R_\mu R_\lambda \dot{u}_\lambda}{D} - u_\mu + \underbrace{u_\lambda u_\lambda}_{-c^2} \left(-\frac{R_\mu}{D} \right)$$

$$\frac{\partial D}{\partial x_\mu} = -u_\mu + \frac{R_\mu c^2}{D} \left(1 + \frac{1}{c^2} \dot{u}_\lambda R_\lambda \right)$$

plug back in

$$\frac{\partial A_V}{\partial x_\mu} = \frac{\mu_0 c q}{4\pi} \left\{ \frac{1}{D} \dot{u}_\nu \left(-\frac{R_\mu}{D} \right) - \frac{u_\nu}{D^2} \left[-u_\mu + \frac{R_\mu c^2}{D} \left(1 + \frac{\dot{u}_\lambda R_\lambda}{c^2} \right) \right] \right\}$$

$$= \frac{\mu_0 c q}{4\pi} \left\{ -\frac{R_\mu \dot{u}_\nu}{D^2} + \frac{u_\nu u_\mu}{D^2} - \frac{u_\nu R_\mu c^2}{D^3} \left(1 + \frac{\dot{u}_\lambda R_\lambda}{c^2} \right) \right\}$$

$$F_{\mu\nu} = \frac{\partial A_\nu}{\partial x_\mu} - \frac{\partial A_\mu}{\partial x_\nu} = \frac{\mu_0 c q}{4\pi D^2} \left\{ \dot{u}_\mu R_\nu - \dot{u}_\nu R_\mu \right.$$

$$\left. + \frac{c^2}{D} \left([u_\mu R_\nu] \left[1 + \frac{\dot{u}_\lambda R_\lambda}{c^2} \right] - [u_\nu R_\mu] \left[1 + \frac{\dot{u}_\lambda R_\lambda}{c^2} \right] \right) \right\}$$

$$F_{\mu\nu} = \frac{\mu_0 c q}{4\pi} \frac{q}{D^2} \left\{ \dot{u}_\mu R_\nu - \dot{u}_\nu R_\mu + \frac{c^2}{D} (u_\mu R_\nu - u_\nu R_\mu) \left(1 + \frac{\dot{u}_\lambda R_\lambda}{c^2} \right) \right\}$$

the terms proportional to u_μ are the "velocity terms"

the terms proportional to \dot{u}_μ are the "acceleration terms"

$$F_{\mu\nu} = \frac{\mu_0 c}{4\pi} \frac{q}{D^2} \left\{ \dot{u}_\mu R_\nu - \dot{u}_\nu R_\mu + \frac{c^2}{D} (u_\mu R_\nu - u_\nu R_\mu) \left(1 + \frac{\dot{u}_\lambda R_\lambda}{c^2} \right) \right\}$$

we want to show that this gives the same \vec{E} as in Griffiths

$$F_{4i} = \frac{iE_i}{c} \Rightarrow E_i = -icF_{4i}$$

The pieces we need are:

$$4\text{-velocity } u_\mu = \gamma(\vec{v}, ic)$$

$$4\text{-acceleration } a_\mu = \dot{u}_\mu = \left(\gamma^4 \frac{(\vec{v} \cdot \vec{a})}{c^2} \vec{v} + \gamma^2 \vec{a}, i\gamma^4 \frac{(\vec{v} \cdot \vec{a})}{c} \right)$$

$$4\text{-difference } R_\mu = (\vec{R}, iR) \quad \text{displacement from } Q \text{ to } P$$

$$D = -R_\lambda u_\lambda = \gamma(cR - \vec{v} \cdot \vec{R})$$

$$\dot{u}_\lambda R_\lambda = \gamma^4 \frac{(\vec{v} \cdot \vec{a})}{c^2} (\vec{v} \cdot \vec{R}) + \gamma^2 (\vec{a} \cdot \vec{R}) - \gamma^4 \frac{(\vec{v} \cdot \vec{a})}{c} R$$

$$= \gamma^4 \frac{(\vec{v} \cdot \vec{a})}{c^2} [\vec{v} \cdot \vec{R} - cR] + \gamma^2 (\vec{a} \cdot \vec{R})$$

$$E_i = -\frac{i\mu_0 c^2}{4\pi} \frac{q}{D^3} \left\{ [\dot{u}_4 R_i - \dot{u}_i R_4] D + c^2 (u_4 R_i - u_i R_4) \left(1 + \frac{\dot{u}_\lambda R_\lambda}{c^2} \right) \right\}$$

$$\text{use } \mu_0 c^2 = 1/\epsilon_0$$

$$\vec{E} = \frac{1}{4\pi\epsilon_0} \frac{q}{D^3} \left\{ \underbrace{[\gamma^4 \frac{(\vec{v} \cdot \vec{a})}{c} \vec{R} - \gamma^4 \frac{(\vec{v} \cdot \vec{a})}{c^2} R \vec{v} - \gamma^2 R \vec{a}]}_{u_4 R_i - u_i R_4} \underbrace{\gamma(cR - \vec{v} \cdot \vec{R})}_D \right. \\ \left. + \underbrace{\gamma(c\vec{R} - R\vec{v})}_{c^2 + \dot{u}_\lambda R_\lambda} \underbrace{(c^2 + \gamma^4 \frac{(\vec{v} \cdot \vec{a})}{c^2} [\vec{v} \cdot \vec{R} - cR] + \gamma^2 (\vec{a} \cdot \vec{R}))}_{c^2 + \dot{u}_\lambda R_\lambda} \right\}$$

multiply through

$$= \frac{1}{4\pi\epsilon_0} \frac{q}{D^3} \left\{ \gamma^5 \frac{(\vec{v} \cdot \vec{a})}{c^2} (c\vec{R} - R\vec{v})(cR - \vec{v} \cdot \vec{R}) - \gamma^3 (cR - \vec{v} \cdot \vec{R}) R \vec{a} \right. \\ \left. + \gamma^5 \frac{(\vec{v} \cdot \vec{a})}{c^2} (\vec{v} \cdot \vec{R} - cR)(c\vec{R} - R\vec{v}) + \gamma^3 (c\vec{R} - R\vec{v})(\vec{a} \cdot \vec{R}) + \gamma c^2 (c\vec{R} - R\vec{v}) \right\}$$

The γ^5 terms cancel

$$\vec{E} = \frac{1}{4\pi\epsilon_0} \frac{q}{D^3} \left\{ \gamma c^2 (\vec{c}\vec{R} - R\vec{v}) + \gamma^3 [(\vec{c}\vec{R} - R\vec{v})(\vec{a} \cdot \vec{R}) - \vec{a} (\vec{c}\vec{R} - \vec{v} \cdot \vec{R})R] \right\}$$

rewrite last term

$$= \frac{1}{4\pi\epsilon_0} \frac{q}{D^3} \left\{ \gamma c^2 (\vec{c}\vec{R} - R\vec{v}) + \gamma^3 [(\vec{c}\vec{R} - R\vec{v})(\vec{a} \cdot \vec{R}) - \vec{a} (\vec{c}\vec{R} - R\vec{v}) \cdot \vec{R}] \right\}$$

simplify the γ^3 term by using the triple product rule

$$\vec{A} \times (\vec{B} \times \vec{C}) = \vec{B}(\vec{A} \cdot \vec{C}) - \vec{C}(\vec{A} \cdot \vec{B}) \quad \text{with} \quad \vec{A} \equiv \vec{R}, \quad \vec{B} = \vec{c}\vec{R} - R\vec{v}, \quad \vec{C} = \vec{a}$$

≡ substitute for D

$$E = \frac{1}{4\pi\epsilon_0} \frac{q}{\gamma^3 (\vec{c}\vec{R} - R\vec{v})^3} \left\{ \gamma c^2 (\vec{c}\vec{R} - R\vec{v}) + \gamma^3 \vec{R} \times [(\vec{c}\vec{R} - R\vec{v}) \times \vec{a}] \right\}$$

write $\begin{cases} \vec{c}\vec{R} - R\vec{v} = R(\vec{c}\hat{R} - \vec{v}) & \text{since } \vec{R} = R\hat{R} \\ \vec{c}\vec{R} - \vec{v} \cdot \vec{R} = \vec{R} \cdot (\vec{c}\hat{R} - \vec{v}) \end{cases}$

$$E = \frac{1}{4\pi\epsilon_0} \frac{qR}{[\vec{R} \cdot (\vec{c}\hat{R} - \vec{v})]^3} \left\{ \frac{1}{\gamma^2} c^2 (\vec{c}\hat{R} - \vec{v}) + \vec{R} \times [(\vec{c}\hat{R} - \vec{v}) \times \vec{a}] \right\}$$

use $\frac{c^2}{\gamma^2} = c^2 (1 - v^2/c^2) = c^2 - v^2$

$$E = \frac{1}{4\pi\epsilon_0} \frac{qR}{[\vec{R} \cdot (\vec{c}\hat{R} - \vec{v})]^3} \left\{ (\vec{c}\hat{R} - \vec{v})(c^2 - v^2) + \vec{R} \times [(\vec{c}\hat{R} - \vec{v}) \times \vec{a}] \right\}$$

taking $\vec{R} = \vec{r} - \vec{r}_0(t')$, $\hat{R} = \hat{m}(t')$, $\vec{v} = \vec{v}(t')$, $\vec{a} = \vec{a}(t')$, t' the retarded time
then the above is the same as the expression written at end of lecture 21.

If one defines $\vec{w} = c\hat{R} - \vec{v}$, then

$$\vec{E} = \frac{1}{4\pi\epsilon_0} \frac{qR}{(\vec{R} \cdot \vec{w})^3} \left\{ \vec{w} (c^2 - v^2) + \vec{R} \times (\vec{w} \times \vec{a}) \right\}$$

this is the same as Griffiths Eqn (10.72) if we use his notation $\vec{R} \rightarrow \vec{r}$, $\vec{w} \rightarrow \vec{u}$

Similarly we can find \vec{B}

$$B_i = F_{jk} \quad \text{with } i, j, k \text{ a cyclic permutation of } 1, 2, 3$$

$$B_i = \frac{\mu_0 c}{4\pi} \frac{q}{D^2} \left\{ \dot{u}_j R_k - \dot{u}_k R_j + \frac{c^2}{D} (u_j R_k - u_k R_j) \left(1 + \frac{\dot{u}_\lambda R_\lambda}{c^2}\right) \right\}$$

$$\text{use } \dot{u}_j R_k - \dot{u}_k R_j = (\dot{\vec{u}} \times \vec{R})_i = -(\vec{R} \times \dot{\vec{u}})_i$$

$$u_j R_k - u_k R_j = (\vec{u} \times \vec{R})_i = -(\vec{R} \times \vec{u})_i$$

$$\vec{R} = R \hat{R}$$

$$\vec{B} = \frac{\hat{R}}{c} \times \left[-\frac{\mu_0 c^2}{4\pi} \frac{q}{D^2} \left\{ R \dot{\vec{u}} + \frac{c^2}{D} R \vec{u} \left(1 + \frac{\dot{u}_\lambda R_\lambda}{c^2}\right) \right\} \right]$$

compare this to

$$\frac{\hat{R}}{c} \times \vec{E} = \frac{\hat{R}}{c} \times \left[-\frac{i\mu_0 c^2}{4\pi} \frac{q}{D^2} \left\{ \dot{u}_4 \vec{R} - \dot{u} R_4 + \frac{c^2}{D} (u_4 \vec{R} - \vec{u} R_4) \left(1 + \frac{\dot{u}_\lambda R_\lambda}{c^2}\right) \right\} \right]$$

gives zero as $\hat{R} \times \vec{R} = 0$

$$\text{use } R_4 = iR$$

$$\frac{\hat{R}}{c} \times \vec{E} = \frac{\hat{R}}{c} \times \left[-\frac{i\mu_0 c^2}{4\pi} \frac{q}{D^2} \left\{ -iR \dot{\vec{u}} + \frac{c^2}{D} (-iR \vec{u}) \left(1 + \frac{\dot{u}_\lambda R_\lambda}{c^2}\right) \right\} \right]$$

$$= \frac{\hat{R}}{c} \times \left[-\frac{\mu_0 c^2}{4\pi} \frac{q}{D^2} \left\{ R \dot{\vec{u}} + \frac{c^2}{D} R \vec{u} \left(1 + \frac{\dot{u}_\lambda R_\lambda}{c^2}\right) \right\} \right]$$

$$= \vec{B}$$

so
$$\boxed{\vec{B} = \frac{\hat{R}}{c} \times \vec{E}}$$