

Linearity and Superposition

We can write the differential operator that appears in the driven harmonic oscillator problem as

$$L[x] = \ddot{x} + 2\beta \dot{x} + \omega_0^2 x$$

$L[x]$ is a linear ~~aff~~ operator

$$\Rightarrow L[x_1 + x_2] = L[x_1] + L[x_2]$$

$$\frac{d^2}{dt^2}(x_1 + x_2) = \frac{d^2x_1}{dt^2} + \frac{d^2x_2}{dt^2} = \ddot{x}_1 + \ddot{x}_2 \text{ etc.}$$

If x_1 is a particular solution to

$$L[x] = F_1(t) \quad , \quad \text{ie } L[x_1] = F_1(t)$$

and x_2 is a particular solution to

$$L[x] = F_2(t) \quad , \quad \text{ie } L[x_2] = F_2(t)$$

then $x_1 + x_2$ is a particular solution to

$$L[x] = F_1(t) + F_2(t)$$

Since $L[x_1 + x_2] = L[x_1] + L[x_2] = F_1 + F_2$

In general, if x_p is a particular solution to

$$L[x] = F_n(t)$$

then $x = \sum_{n=1}^{\infty} x_n + x_c$ is the general solution

to

$$L[x] = \sum_{n=1}^{\infty} \alpha_n F_n(t), \text{ where}$$

x_c is the general solution to $L[x] = 0$.

For $F_n(t) = \operatorname{Re}[F_n e^{i\omega_n t}]$ where $F_n = |F_n| e^{-i\phi_n}$ may be complex

then a particular solution to $L[x] = F_n(t)$ is

$$x_n(t) = \operatorname{Re} [D_n e^{i\omega_n t}] \text{ where } D_n = \frac{F_n/m}{\omega_0^2 - \omega_n^2 + 2i\beta\omega_n}$$

\Rightarrow for $F_n = |F_n| \cos(\omega_n t - \phi_n)$, a solution is

$$x_n(t) = |D_n| \cos(\omega_n t - \phi_n - \delta_n)$$

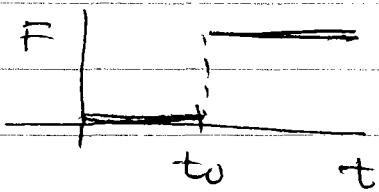
$$\text{where } |D_n| = \frac{|F_n|/m}{\sqrt{(\omega_0^2 - \omega_n^2)^2 + 4\beta^2\omega_n^2}}$$

$$\tan \delta_n = \frac{2\beta\omega_n}{\omega_0^2 - \omega_n^2}$$

This is important because any periodic $F(t)$ can always be written as a sum of harmonic functions

Response to a step function

$$F(t) = \begin{cases} 0 & t < t_0 \\ F_0 & t \geq t_0 \end{cases}$$



a particular solution to $L[x] = \frac{F(t)}{m}$

$$x_p(t) = 0 \quad t < t_0$$

$$x_p(t) = \frac{F_0}{\omega_0^2 m} \quad t \geq t_0$$

general solution is :

$$t < t_0 : \quad x_1(t) = x_p(t) + x_c(t)$$

$$= 0 + e^{-\beta t} (A_1 \cos \omega_1 t + B_1 \sin \omega_1 t)$$

$$\text{where } \omega_1 = \sqrt{\omega_0^2 - \beta^2}$$

$$t > t_0 : \quad x_2(t) = x_p(t) + x_c(t)$$

$$= \frac{F_0}{\omega_0^2 m} + e^{-\beta t} (A_2 \cos \omega_1 t + B_2 \sin \omega_1 t)$$

Assume initial condition $x_1(0) = \dot{x}_1(0) = 0$

$$x_1(0) = 0 \Rightarrow A_1 = 0 \quad , \quad \dot{x}_1 = -\beta e^{-\beta t} (A_1 \cos \omega_1 t + B_1 \sin \omega_1 t) + e^{-\beta t} (-\omega_1 A_1 \sin \omega_1 t + \omega_1 B_1 \cos \omega_1 t)$$

$$\dot{x}_1(0) = 0 \Rightarrow -\beta A_1 + \omega_1 B_1 = 0 \Rightarrow B_1 = 0$$

$$\Rightarrow \frac{e^{-\beta t_0} w_1}{\beta \cos \omega_1 t_0 + w_1 \sin \omega_1 t_0} B_2 = -\frac{F_0}{\omega_0^2 m}$$

$$\Rightarrow \begin{cases} B_2 = -\frac{F_0}{\omega_0^2 m} \frac{e^{\beta t_0}}{w_1} (\beta \cos \omega_1 t_0 + w_1 \sin \omega_1 t_0) \\ A_2 = -\frac{F_0}{\omega_0^2 m} \frac{e^{\beta t_0}}{w_1} (-\beta \sin \omega_1 t_0 + w_1 \cos \omega_1 t_0) \end{cases}$$

Substitute into $x_2(t) = \frac{F_0}{\omega_0^2 m} + e^{-\beta t} (A_2 \cos \omega_1 t + B_2 \sin \omega_1 t)$

to get

$$x_2(t) = \frac{F_0}{\omega_0^2 m} \left[1 - \frac{e^{-\beta(t-t_0)}}{w_1} \left(-\beta \sin \omega_1 t_0 \cos \omega_1 t + w_1 \cos \omega_1 t_0 \cos \omega_1 t + \beta \cos \omega_1 t_0 \sin \omega_1 t + w_1 \sin \omega_1 t_0 \sin \omega_1 t \right) \right]$$

using trig formulae for $\cos(A+B)$ and $\sin(A+B)$

$$x_2(t) = \frac{F_0}{\omega_0^2 m} \left[1 - \frac{e^{-\beta(t-t_0)}}{w_1} \left(w_1 \cos \omega_1 (t-t_0) + \beta \sin \omega_1 (t-t_0) \right) \right]$$

$$x_2(t) = \frac{F_0}{\omega_0^2 m} \left[1 - e^{-\beta(t-t_0)} \left(\cos \omega_1 (t-t_0) + \frac{\beta}{w_1} \sin \omega_1 (t-t_0) \right) \right]$$

note: we could have gotten this result in a smarter and simpler way as follows:

Define $t' = t - t_0$

Solution to $t > t_0$, or $t' > 0$, could have been written as

$$x_2(t') = \frac{F_0}{\omega_0^2 m} + e^{-\beta t'} \left[A \cos(\omega_1 t') + B \sin(\omega_1 t') \right]$$

initial conditions are $x(t_0) = x(t'=0) = 0$
 $\dot{x}(t_0) = \dot{x}(t'=0) = 0$

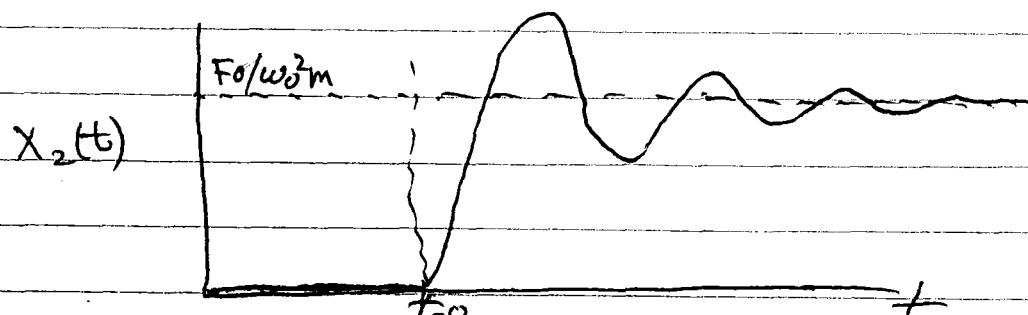
$$x_2(t'=0) = 0 \Rightarrow \frac{F_0}{\omega_0^2 m} + A = 0 \Rightarrow A = -\frac{F_0}{\omega_0^2 m}$$

$$\dot{x}_2(t'=0) = 0 \Rightarrow -\beta A + \omega_1 B = 0 \Rightarrow B = \frac{\beta A}{\omega_1} = \frac{-F_0}{\omega_0^2 m} \frac{\beta}{\omega_1}$$

$$\Rightarrow x_2(t') = \frac{F_0}{\omega_0^2 m} \left[1 - e^{-\beta t'} \left(\cos \omega_1 t' + \frac{\beta}{\omega_1} \sin \omega_1 t' \right) \right]$$

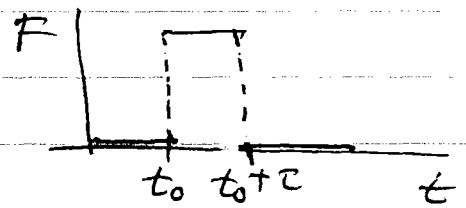
$$x_2(t) = \frac{F_0}{\omega_0^2 m} \left[1 - e^{-\beta(t-t_0)} \left(\cos \omega_1(t-t_0) + \frac{\beta}{\omega_1} \sin \omega_1(t-t_0) \right) \right]$$

\Rightarrow same result as before

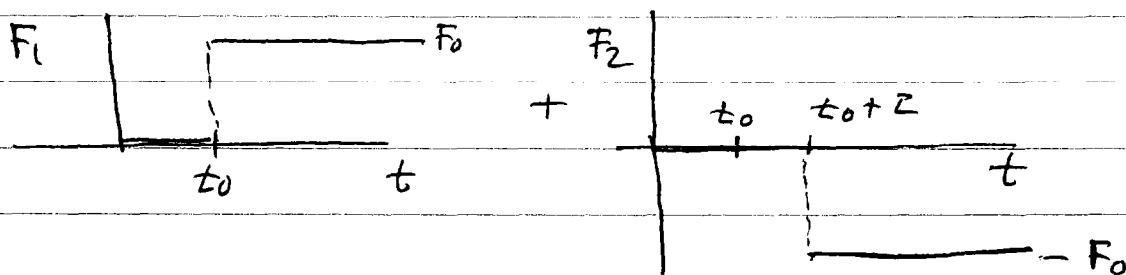


Response to an impulse

$$F(t) = \begin{cases} 0 & t < t_0 \\ F_0 & t_0 < t < t_0 + \tau \\ 0 & t_0 + \tau < t \end{cases}$$



Regard $F(t)$ as superposition of



By linearity, we know that solution to $F_1 + F_2$ is just solution to F_1 , plus solution to F_2

$$x_1(t) = \begin{cases} 0 & t < t_0 \\ \frac{F_0}{\omega_0^2 m} \left[1 - e^{-\beta(t-t_0)} \left(\cos \omega_1(t-t_0) + \frac{\beta}{\omega_1} \sin \omega_1(t-t_0) \right) \right] & t > t_0 \end{cases}$$

$$x_2(t) = \begin{cases} 0 & t < t_0 + \tau \\ -\frac{F_0}{\omega_0^2 m} \left[1 - e^{-\beta(t-t_0-\tau)} \left(\cos \omega_1(t-t_0-\tau) + \frac{\beta}{\omega_1} \sin \omega_1(t-t_0-\tau) \right) \right] & t > t_0 + \tau \end{cases}$$

Solution to $F = F_1 + F_2$ is $x = x_1 + x_2$

Note $x(t)$ has correct initial conditions $x(0) = \dot{x}(0) = 0$ and ~~is continuous~~ $x(t)$ and $\dot{x}(t)$ are continuous at $t = t_0$ and $t = t_0 + \tau$. So $x(t)$ is solution to our problem.

Suppose now that ϵ is very small.

We can write to first order in ϵ

$$e^{-\beta(t-t_0-\epsilon)} = e^{-\beta(t-t_0)} e^{-\beta\epsilon} = e^{-\beta(t-t_0)} (1 + \beta\epsilon)$$

$$\cos \omega_1(t-t_0-\epsilon) = \cos \omega_1(t-t_0) \cos \omega_1 \epsilon + \sin \omega_1(t-t_0) \sin \omega_1 \epsilon \\ \cos \omega_1(t-t_0) + \omega_1 \epsilon \sin \omega_1(t-t_0)$$

$$\sin \omega_1(t-t_0-\epsilon) = \sin \omega_1(t-t_0) \cos \omega_1 \epsilon - \cos \omega_1(t-t_0) \sin \omega_1 \epsilon \\ \approx \sin \omega_1(t-t_0) - \omega_1 \epsilon \cos \omega_1(t-t_0)$$

So, to $O(\epsilon)$

$$x_2(t) \approx \frac{-F_0}{\omega_0^2 m} \left[1 - e^{-\beta(t-t_0)} \left[(\cos \omega_1(t-t_0) + \frac{\beta}{\omega_1} \sin \omega_1(t-t_0)) \right. \right. \\ \left. \left. + \beta \epsilon (\cos \omega_1(t-t_0) + \frac{\beta}{\omega_1} \sin \omega_1(t-t_0)) \right] \right. \\ \left. + \omega_1 \epsilon \left(\sin \omega_1(t-t_0) - \frac{\beta}{\omega_1} \cos \omega_1(t-t_0) \right) \right]$$

For $t > t_0 + \epsilon$,

$$x(t) = x_1 + x_2 \quad \leftarrow \text{when add, the } O(1) \text{ term in } x_2 \\ \text{exactly cancels the contribution from } x_1, \text{ leaving only the } O(\epsilon) \text{ terms left}$$

$$= +\frac{F_0}{\omega_0^2 m} e^{-\beta(t-t_0)} \left[+\beta \epsilon \cos \omega_1(t-t_0) + \frac{\beta^2 \epsilon}{\omega_1} \sin \omega_1(t-t_0) \right. \\ \left. + \omega_1 \epsilon \sin \omega_1(t-t_0) - \beta \epsilon \cos \omega_1(t-t_0) \right]$$

$$x(t) = \frac{F_0}{\omega_0^2 m} \left(\omega_1 \epsilon + \frac{\beta^2 \epsilon}{\omega_1} \right) e^{-\beta(t-t_0)} \sin \omega_1(t-t_0) \quad \text{for } t > t_0 + \epsilon$$

Now as $\tau \rightarrow 0$, the region $t_0 < t < t_0 + \tau$ becomes vanishingly small. So the solution becomes

$$x(t) = \begin{cases} 0 & t < t_0 \\ \frac{F_0 \tau}{m \omega_0^2} \left(\omega_1 + \frac{\beta^2}{\omega_1} \right) e^{-\beta(t-t_0)} \sin \omega_1(t-t_0) & t > t_0 \end{cases}$$

For this solution to make sense, we need that $F_0 \tau \rightarrow \text{constant}$ as $\tau \rightarrow 0$, i.e. F_0 diverges as $\tau \rightarrow 0$ in such a way that $F_0 \tau$ stays constant

Note: $F_0 \tau = \int_{-\infty}^{\infty} F(t) dt = \int \frac{dp}{dt} dt = p_{\text{final}} - p_{\text{initial}}$

gives change in momentum of particle as result of the impulse force $F(t)$.

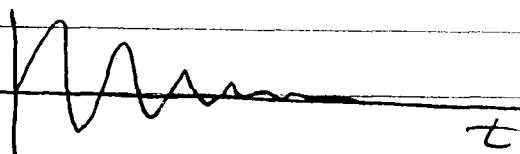
Note, using $\omega_1^2 = \omega_0^2 - \beta^2$, we can write

$$\frac{1}{m \omega_0^2} \left(\omega_1 + \frac{\beta^2}{\omega_1} \right) = \frac{1}{m \omega_1^2} \left(\frac{\omega_1^2 + \beta^2}{\omega_1} \right) = \frac{1}{m \omega_1^2} \frac{\omega_0^2}{\omega_1} = \frac{1}{m \omega_1}$$

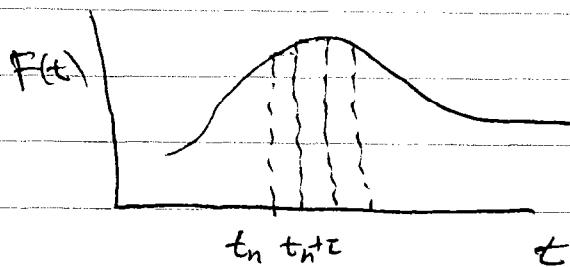
So

$$x(t) = \begin{cases} 0 & t < t_0 \\ \frac{F_0 \tau}{m \omega_1} e^{-\beta(t-t_0)} \sin \omega_1(t-t_0) & t > t_0 \end{cases}$$

$x(t)$



Now, any general force $F(t)$ can always be written as a sum of impulse forces



We set the solution for a particle initially at rest.

$$F(t) = \sum_n F_n(t) \quad \text{where } F_n(t) = \begin{cases} 0 & t < t_n \\ F(t) & t_n < t < t_n + \tau \\ 0 & t_n + \tau < t \end{cases}$$

Solution $x_n(t)$ for $F_n(t)$ alone is as $\tau \rightarrow 0$

$$x_n(t) = \begin{cases} 0 & t < t_n \\ \frac{F(t_n)\tau}{m\omega_1} e^{-\beta(t-t_n)} \sin \omega_1(t-t_n) & t > t_n \end{cases}$$

Solution for F is then

$$x(t) = \sum_n x_n(t) = \sum_{t_n < t} \frac{F(t_n)\tau}{m\omega_1} e^{-\beta(t-t_n)} \sin \omega_1(t-t_n)$$

as $\tau \rightarrow 0$

$$x(t) = \int_{-\infty}^t dt' \frac{F(t')}{m\omega_1} e^{-\beta(t-t')} \sin \omega_1(t-t')$$

has the form $x(t) = \int_{-\infty}^t dt' F(t') G(t-t')$

where $G(t-t') = \frac{1}{m\omega_1} e^{-\beta(t-t')} \sin \omega_1(t-t')$ is the Green's function for the harmonic oscillator.

Can derive the same result using
Fourier transforms

$$F(t) = \int_{-\infty}^{\infty} \frac{dw}{2\pi} e^{-iwt} F_w \quad , \quad F_w = \int_{-\infty}^{\infty} dt e^{-iwt} F(t)$$

$$\Rightarrow x(t) = \int_{-\infty}^{\infty} \frac{dw}{2\pi} e^{iwt} D_w \\ = \int_{-\infty}^{\infty} \frac{dw}{2\pi} e^{iwt} \frac{F_w}{m} \frac{1}{\omega_0^2 - w^2 + 2i\beta w}$$

$$= \int_{-\infty}^{\infty} \frac{dw}{2\pi} \frac{e^{iwt}}{m} \frac{1}{\omega_0^2 - w^2 + 2i\beta w} \int_{-\infty}^{\infty} dt' e^{-iwt'} F(t')$$

$$= \int_{-\infty}^{\infty} dt' \frac{F(t')}{m} \int_{-\infty}^{\infty} dw \frac{e^{-i\omega(t'-t)}}{2\pi} \frac{1}{\omega_0^2 - \omega^2 + 2i\beta\omega}$$

\uparrow
can do ω integration by
complex contour integration

to get

$$\frac{e^{-\beta(t-t')}}{\omega_0} \sin \omega(t-t')$$

we recover earlier result