

when atoms have intrinsic magnetic moments due to electron spin, we can add these to $\vec{M}$ in obvious way

when molecules are neutral, $q_n = 0$, the "bound current" is given by

$$\vec{j}_{\text{bound}} = \sum_n \langle \vec{j}_n \rangle = c \vec{\nabla} \times \vec{M} + \frac{\partial \vec{P}}{\partial t}$$

Note that the $\frac{\partial \vec{P}}{\partial t}$ term is crucial to give conservation of bound charge

$$\begin{aligned} \vec{\nabla} \cdot \vec{j}_{\text{bound}} &= c \vec{\nabla} \cdot (\vec{\nabla} \times \vec{M}) + \vec{\nabla} \cdot \frac{\partial \vec{P}}{\partial t} \\ &= 0 + \frac{\partial}{\partial t} (\vec{\nabla} \cdot \vec{P}) \end{aligned}$$

$$= -\frac{\partial \rho_{\text{bound}}}{\partial t} \quad \text{where } \rho_{\text{bound}} = -\vec{\nabla} \cdot \vec{P} \text{ is bound charge density}$$

$$\text{so } \boxed{\vec{\nabla} \cdot \vec{j}_{\text{bound}} + \frac{\partial \rho_{\text{bound}}}{\partial t} = 0}$$

ad. bound charge is conserved.

Since total average charge must be conserved, i.e.

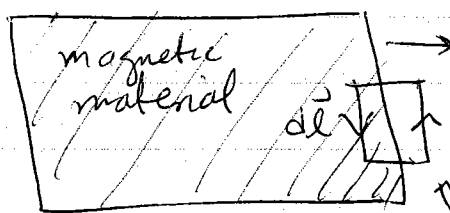
$$\vec{\nabla} \cdot \langle \vec{j}_0 \rangle - \frac{\partial \langle \rho_0 \rangle}{\partial t} = 0, \quad \text{and } \langle \vec{j}_0 \rangle = \vec{j} + \vec{j}_{\text{bound}}$$

$$\begin{aligned} \uparrow & \text{free current} \\ \langle \rho_0 \rangle &= \rho + \rho_{\text{bound}} \\ \uparrow & \text{free charge} \end{aligned}$$

$$\Rightarrow \boxed{\vec{\nabla} \cdot \vec{j} + \frac{\partial \rho}{\partial t} = 0}$$

free charge is also conserved

At a surface of a magnetic material



$\hat{n}$ outward normal to surface

take $\hat{z} = \hat{d}\vec{l} \times \hat{n}$ out of page

Amperean loop C bounding surface S of area da

$$\begin{aligned} c \int_S da \hat{z} \cdot (\vec{\nabla} \times \vec{M}) &= \int_S da \hat{z} \cdot \vec{j}_{\text{bound}} = da \hat{z} \cdot \vec{j}_{\text{bound}} \\ &= (\vec{d}\vec{l} \times \hat{n}) \cdot \vec{K}_{\text{bound}} \quad \text{as width of loop} \\ &\quad \rightarrow 0 \\ &= (\hat{n} \times \vec{K}_{\text{bound}}) \cdot \vec{d}\vec{l} \end{aligned}$$

But by Stokes theorem

$$c \int_S da \hat{z} \cdot (\vec{\nabla} \times \vec{M}) = c \int_C \vec{d}\vec{l} \cdot \vec{M} = c \vec{d}\vec{l} \cdot \vec{M} \quad \text{since width} \rightarrow 0$$

and $\vec{M} = 0$ outside

$$\Rightarrow c \vec{d}\vec{l} \cdot \vec{M} = (\hat{n} \times \vec{K}_{\text{bound}}) \cdot \vec{d}\vec{l} \quad \text{for any } \vec{d}\vec{l} \text{ in plane of surface}$$

$$\Rightarrow c \vec{M}_t = \hat{n} \times \vec{K}_{\text{bound}}$$

where $\vec{M}_t$ is component of $\vec{M}$ tangential to the surface (since $\vec{K}_b$ is in plane of surface, $\hat{n} \times \vec{K}$ is also entirely in the plane of the surface)

$$\begin{aligned} \Rightarrow c \hat{n} \times \vec{M}_t &= c \hat{n} \times \vec{M} = \hat{n} \times (\hat{n} \times \vec{K}_{\text{bound}}) \\ &= -\vec{K}_{\text{bound}} \end{aligned}$$

$$\Rightarrow \begin{cases} \vec{K}_{\text{bound}} = c \vec{M} \times \hat{n} \\ \vec{j}_{\text{bound}} = c \vec{\nabla} \times \vec{M} \end{cases}$$

Total bound charge vanishes

$$Q_{\text{bound}} = \int_V d^3r \rho_{\text{bound}} + \int_S da \sigma_{\text{bound}}$$

$\uparrow$ vol of dielectric $\uparrow$ surface of dielectric

$$= \int_V d^3r -\vec{\nabla} \cdot \vec{P} + \int da \hat{n} \cdot \vec{P}$$

but by Gauss theorem $\int_V d^3r \vec{\nabla} \cdot \vec{P} = \int da \hat{n} \cdot \vec{P}$

so $Q_{\text{bound}} = -\int da \hat{n} \cdot \vec{P} + \int da \hat{n} \cdot \vec{P} = 0$

Macroscopic Maxwell Equations

$$\vec{\nabla} \cdot \vec{B} = 0$$

$$\vec{\nabla} \times \vec{E} + \frac{1}{c} \frac{\partial \vec{B}}{\partial t} = 0$$

$$\vec{\nabla} \times \vec{H} = \frac{4\pi}{c} \vec{j} + \frac{1}{c} \frac{\partial \vec{D}}{\partial t}$$

$$\vec{\nabla} \cdot \vec{D} = 4\pi \rho$$

where ρ and $\vec{j}$ are macroscopic charge + current densities
do not include bound charges or currents

$$\vec{D} = \vec{E} + 4\pi \vec{P}$$

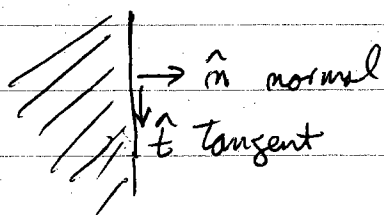
, $\vec{P}$ is polarization density

$$\vec{H} = \vec{B} - 4\pi \vec{M}$$

, $\vec{M}$ is magnetization density

Boundary conditions for statics

electrostatics: at surface of a dielectric, or at interface between two different dielectrics



$$\vec{\nabla} \times \vec{E} = 0 \Rightarrow \hat{t} \cdot \vec{E}_{\text{above}} = \hat{t} \cdot \vec{E}_{\text{below}}$$

tangential component $\vec{E}$ is continuous

$$\vec{\nabla} \cdot \vec{D} = 4\pi \rho \Rightarrow \hat{n} \cdot (\vec{D}_{\text{above}} - \vec{D}_{\text{below}}) = 4\pi \sigma$$

normal component of $\vec{D}$ jumps by $4\pi \sigma$

magnetostatics: at surface or interface of magnetic materials

$$\vec{\nabla} \cdot \vec{B} = 0 \Rightarrow \hat{n} \cdot \vec{B}_{\text{above}} - \hat{n} \cdot \vec{B}_{\text{below}}$$

normal component of $\vec{B}$ is continuous

$$\vec{\nabla} \times \vec{H} = \frac{4\pi}{c} \vec{j} \Rightarrow \hat{t} \cdot (\vec{H}_{\text{above}} - \vec{H}_{\text{below}}) = \frac{4\pi}{c} K$$

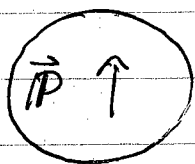
tangential component of $\vec{H}$ jumps by $\frac{4\pi}{c} K$

if $\sigma = 0$, i.e. no free surface charge, then $\hat{n} \cdot \vec{D}$ continuous

if $K = 0$, i.e. no free surface current, then $\hat{t} \cdot \vec{H}$ continuous

Examples

① Uniformly polarized sphere of radius R $\vec{P} = P \hat{z}$



bound charge $\rho_b = -\vec{\nabla} \cdot \vec{P} = 0$ as $\vec{P}$ constant

$$\sigma_b = \hat{n} \cdot \vec{P} = \hat{r} \cdot \vec{P} = P \cos \theta$$

we saw earlier that a sphere with surface charge $\sigma(\theta) = \sigma_0 \cos \theta$ gives an electric field like a pure dipole for $r > R$, and is constant for $r < R$.

$$\vec{E}(\vec{r}) = \begin{cases} \left(\frac{4}{3} \pi R^3 P \right) \left[\frac{2 \cos \theta \hat{r} + \sin \theta \hat{\theta}}{r^3} \right] & r > R \\ -\frac{4\pi P}{3} \hat{z} & r < R \end{cases}$$

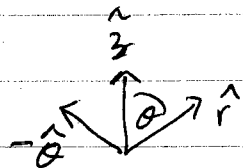
total dipole moment is $\vec{p} = \frac{4}{3} \pi R^3 \vec{P}$

check behavior at boundary

Tangential component $\vec{E}$

$$\vec{E}_{\text{above}}^{\perp} = \left(\frac{4}{3} \pi R^3 P \right) \frac{\sin \theta \hat{\theta}}{R^3} = \frac{4}{3} \pi P \sin \theta \hat{\theta}$$

$$\vec{E}_{\text{below}}^{\perp} = -\frac{4\pi P}{3} (\hat{z} \cdot \hat{\theta}) \hat{\theta} = \frac{4}{3} \pi P \sin \theta \hat{\theta}$$



$\Rightarrow$ Tangential component $\vec{E}$ is continuous

normal component of $\vec{D}$

outside: $\vec{P} = 0 \Rightarrow \vec{D} = \vec{E}$

$$\Rightarrow \hat{n} \cdot \vec{D} = \hat{r} \cdot \vec{E} = \left(\frac{4}{3} \pi R^3 P \right) \frac{2 \cos \theta}{R^3} = \frac{8}{3} \pi P \cos \theta$$

inside: $\vec{E} = -\frac{4\pi\vec{P}}{3} \Rightarrow \vec{P} = -\frac{3}{4\pi}\vec{E}$

$$\vec{D} = \vec{E} + 4\pi\vec{P} = \vec{E} - 3\vec{E} = -2\vec{E} = \frac{8\pi P}{3}\hat{z}$$

$$\hat{n} \cdot \vec{D} = \hat{r} \cdot \left(\frac{8\pi P}{3} \hat{z} \right) = \frac{8\pi P}{3} \cos \theta$$

$\Rightarrow$ normal component $\vec{D}$ is continuous

Note: normal component of $\vec{E}$ should jump by $4\pi\sigma_b = 4\pi P \cos \theta$
inside

to check this: $\hat{n} \cdot \vec{E} = \hat{r} \cdot \left(-\frac{4}{3}\pi P \hat{z} \right) = -\frac{4}{3}\pi P \cos \theta$

$$\hat{n} \cdot (\vec{E}^{\text{above}} - \vec{E}^{\text{below}}) = \frac{8\pi P}{3} \cos \theta + \frac{4\pi P}{3} \cos \theta$$

$$= \frac{12\pi P}{3} \cos \theta = 4\pi P \cos \theta = \overset{4\pi}{\sigma_b}(\theta)$$

② Uniformly magnetized sphere of radius R $\vec{M} = M \hat{z}$



bound current $\vec{j}_b = c \vec{\nabla} \times \vec{M} = 0$ as $\vec{M}$ constant
 $\vec{K}_b = c \vec{M} \times \hat{r} = cM (\hat{z} \times \hat{r})$
 $= cM \sin \theta \hat{\phi}$

we saw earlier that a sphere with surface current $\vec{K}_b = K_0 \sin \theta \hat{\phi}$ gives a magnetic field that is pure dipole for $r > R$, and is constant for $r < R$.

$$\vec{B}(\vec{r}) = \begin{cases} \left(\frac{4}{3} \pi R^3 M \right) \left[\frac{2 \cos \theta \hat{r} + \sin \theta \hat{\theta}}{r^3} \right] & r > R \\ \frac{8}{3} \pi M \hat{z} & r < R \end{cases}$$

total dipole moment is $\vec{m} = \frac{4}{3} \pi R^3 \vec{M}$

check behavior at boundary

normal component of $\vec{B}$

$$\hat{n} \cdot \vec{B}_{\text{above}} = \hat{r} \cdot \vec{B}_{\text{above}} = \frac{8}{3}\pi M \cos\theta$$

$$\hat{n} \cdot \vec{B}_{\text{below}} = \hat{r} \cdot \vec{B}_{\text{below}} = \frac{8}{3}\pi M (\hat{r} \cdot \hat{z}) = \frac{8}{3}\pi M \cos\theta$$

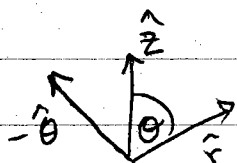
$\Rightarrow$ normal component of $\vec{B}$ is continuous

tangential component of $\vec{H}$

outside: $\vec{M} = 0 \Rightarrow \vec{H} = \vec{B}$

$$\vec{H}_{\text{above}}^t = \left(\frac{4}{3}\pi M\right) \sin\theta \hat{\theta}$$

inside: $\vec{H} = \vec{B} - 4\pi\vec{M} = \vec{B} - 4\pi\left(\frac{3}{8\pi}\vec{B}\right) = \vec{B} - \frac{3}{2}\vec{B} = -\frac{1}{2}\vec{B}$
 $= -\frac{4\pi}{3}M\hat{z}$



$$\text{so } \vec{H}_{\text{below}}^t = -\frac{4\pi}{3}M(\hat{z} \cdot \hat{\theta}) = \frac{4\pi}{3}M \sin\theta \hat{\theta}$$

$\Rightarrow$ tangential component $\vec{H}$ is continuous

Note: tangential component $\vec{B}$ should jump by $\frac{4\pi}{c}\vec{K}_b = 4\pi M \sin\theta \hat{\theta}$

inside:

to check: $\vec{B}_{\text{below}}^t = \frac{8}{3}\pi M(\hat{z} \cdot \hat{\theta})\hat{\theta} = -\frac{8}{3}\pi M \sin\theta \hat{\theta}$

$$\vec{H}_{\text{above}}^t = \vec{B}_{\text{above}}^t \Rightarrow \vec{B}_{\text{above}}^t - \vec{B}_{\text{below}}^t = \frac{4}{3}\pi M \sin\theta \hat{\theta} + \frac{8}{3}\pi M \sin\theta \hat{\theta}$$

$$= 4\pi M \sin\theta \hat{\theta} = \frac{4\pi}{c}\vec{K}_b$$

Linear Materials

Macroscopic Maxwell Equations

$$\vec{\nabla} \cdot \vec{B} = 0 \quad \vec{\nabla} \times \vec{E} + \frac{1}{c} \frac{\partial \vec{B}}{\partial t} = 0$$

$$\vec{\nabla} \cdot \vec{D} = 4\pi\rho \quad \vec{\nabla} \times \vec{H} = \frac{4\pi}{c} \vec{j} + \frac{1}{c} \frac{\partial \vec{D}}{\partial t}$$

where ρ and $\vec{j}$ are macroscopic charge + current densities
and

$$\vec{D} = \vec{E} + 4\pi\vec{P}$$

$\vec{P}$ is polarization density

$$\vec{H} = \vec{B} - 4\pi\vec{M}$$

$\vec{M}$ is magnetization density

To close these equations, we will in general need to know how $\vec{P}$ and $\vec{M}$ are related to the $\vec{E}$ and $\vec{B}$ in the material.

In some materials, there can be a finite $\vec{P}$ or $\vec{M}$ even if $\vec{E}$ and $\vec{B}$ are zero:

Ferro magnet: $\vec{M}$ can be non zero even if $\vec{B} = 0$

Ferroelectric: $\vec{P}$ can be non zero even if $\vec{E} = 0$

But more common are linear materials in which, for small $\vec{E}$ and $\vec{B}$, one has $\vec{P} \propto \vec{E}$ and $\vec{M} \propto \vec{B}$.

linear dielectric

$$\vec{P} = \chi_e \vec{E}$$

χ_e is "electric susceptibility"
 $\chi_e > 0$ for statics

$$\vec{D} = \vec{E} + 4\pi \vec{P} = (1 + 4\pi \chi_e) \vec{E}$$

$$\vec{D} = \epsilon \vec{E} \quad \text{with} \quad \epsilon = 1 + 4\pi \chi_e$$

ϵ is the dielectric constant

linear magnetic materials

$$\vec{M} = \chi_m \vec{H}$$

χ_m is "magnetic susceptibility"

$\chi_m > 0 \Rightarrow$ paramagnetic

$\chi_m < 0 \Rightarrow$ diamagnetic

$$\vec{H} = \vec{B} - 4\pi \vec{M} = \vec{B} - 4\pi \chi_m \vec{H}$$

$$\vec{B} = (1 + 4\pi \chi_m) \vec{H}$$

$$\vec{B} = \mu \vec{H}$$

with $\mu = 1 + 4\pi \chi_m$

μ is magnetic permeability

For statics, $\chi_e > 0$ and χ_m (or alternatively ϵ and μ) are constants depending on the material.

When we consider dynamics we will see that ϵ becomes a function of frequency.