

For arbitrary charge distributions - not pure harmonic

For $\vec{p}_\omega e^{-i\omega t}$ pure harmonic oscillation, we found the radiated fields in electric dipole approx are

$$\vec{E} = \vec{E}_\omega e^{-i\omega t}, \quad \vec{B} = \vec{B}_\omega e^{-i\omega t}$$

$$\vec{E}_\omega = -k^2 \frac{e^{ikr}}{r} \hat{r} \times (\hat{r} \times \vec{p}_\omega) = -\frac{\omega^2}{c^2} \frac{e^{i\omega r/c}}{r} \hat{r} \times (\hat{r} \times \vec{p}_\omega)$$

$$\vec{B}_\omega = k^2 \frac{e^{ikr}}{r} (\hat{r} \times \vec{p}_\omega) = \frac{\omega^2}{c^2} \frac{e^{i\omega r/c}}{r} (\hat{r} \times \vec{p}_\omega)$$

$$\text{as } k = \frac{\omega}{c}$$

For an arbitrarily time varying charge distribution with electric dipole moment

$$\vec{p}(t) = \int \frac{d\omega}{2\pi} \vec{p}_\omega e^{-i\omega t}$$

then solution for fields given by superposition

$$\vec{E}(\vec{r}, t) = \int \frac{d\omega}{2\pi} \vec{E}_\omega e^{-i\omega t}$$

$$= - \int \frac{d\omega}{2\pi} \frac{e^{-i\omega(t-r/c)}}{r} \left(\frac{\omega^2}{c^2} \right) \hat{r} \times (\hat{r} \times \vec{p}_\omega)$$

$$= \frac{-1}{c^2 r} \hat{r} \times \left[\hat{r} \times \int \frac{d\omega}{2\pi} e^{-i\omega(t-r/c)} \vec{p}_\omega \omega^2 \right]$$

$$= \frac{1}{c^2 r} \hat{r} \times \left[\hat{r} \times \frac{\partial^2}{\partial t^2} \int \frac{d\omega}{2\pi} e^{-i\omega(t-r/c)} \vec{p}_\omega \right]$$

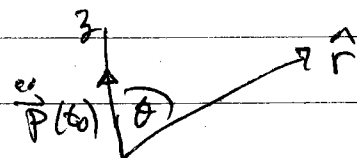
$$\boxed{\vec{E}(\vec{r}, t) = \frac{1}{c^2 r} \hat{r} \times \left[\hat{r} \times \ddot{\vec{p}}(t - r/c) \right]}$$

$$\ddot{\vec{p}} = \frac{d^2 \vec{p}}{dt^2}$$

define $t_0 \equiv t - r/c$ = "retarded time"

in spherical coords, if $\ddot{\vec{p}}(t_0)$ is along $\hat{z}$

$$\vec{E}(\vec{r}, t) = \frac{\ddot{p}(t_0)}{c^2 r} \sin \theta \hat{\theta}$$



Similarly

$$\vec{B}(\vec{r}, t) = \int \frac{d\omega}{2\pi} \vec{B}_\omega e^{-i\omega t}$$

$$= \int \frac{d\omega}{2\pi} \frac{e^{-i\omega(t-r/c)}}{r} \left(\frac{\omega^2}{c^2} \right) (\hat{r} \times \vec{p}_\omega)$$

$$= \frac{-1}{c^2 r} \hat{r} \times \frac{\partial^2}{\partial t^2} \int \frac{d\omega}{2\pi} e^{-i\omega(t-r/c)} \vec{p}_\omega$$

$$\boxed{\vec{B}(\vec{r}, t) = \frac{-1}{c^2 r} \hat{r} \times \ddot{\vec{p}}(t_0)}$$

$$\vec{B}(\vec{r}, t) = \frac{\ddot{p}(t_0)}{c^2 r} \sin \theta \hat{\phi} \quad \text{in spherical coords}$$

Poynting vector

$$\vec{S} = \frac{c}{4\pi} \vec{E} \times \vec{B} = \frac{c}{4\pi} \left(\frac{1}{c^2 r} \right)^2 [\ddot{p}(t_0)]^2 \sin^2 \theta \hat{r}$$

Total power radiated through a sphere of radius r is

$$\begin{aligned}
 P &= \oint da \hat{r} \cdot \vec{S} = 2\pi \int_0^\pi d\theta \sin\theta r^2 \hat{r} \cdot \vec{S} \\
 &= \frac{[\ddot{\vec{p}}(t_0)]^2}{2c^3} \underbrace{\int_0^\pi d\theta \sin^3\theta}_{4/3}
 \end{aligned}$$

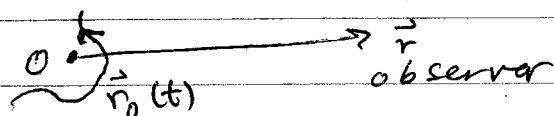
$$P = \frac{2 [\ddot{\vec{p}}(t_0)]^2}{3c^3}$$

For a point charge moving along a trajectory $\vec{r}_0(t)$

$$\vec{\Phi}(t) = q \vec{r}_0(t)$$

$$\ddot{\vec{\Phi}}(t) = q \ddot{\vec{r}}_0(t) = q \vec{a}(t)$$

↑ acceleration



$$P = \frac{2}{3} \frac{q^2 a^2(t_0)}{c^3}$$

Larmor's formula

← total power passing through a sphere of radius r at time t is due to acceleration at retarded time $t_0 = t - r/c$

power radiated $\propto (\text{acceleration})^2$

Larmor's formula above only holds in the non-relativistic limit since it is based on the electric dipole approx.

To go beyond non-relativistic limit, one can do the following:

- 1) transform to a new inertial frame of reference in which the charge is instantaneously at rest
- 2) apply non-relativistic Larmor formula in this frame
- 3) transform back to "lab" frame

Back to non-relativistic case

radiation fields from moving point charge

$$\vec{E}(\vec{r}, t) = \frac{q}{c^2 r} \hat{r} \times (\hat{r} \times \vec{a}(t_0))$$

$$\vec{B}(\vec{r}, t) = -\frac{q}{c^2 r} (\hat{r} \times \vec{a}(t_0))$$

Poynting vector

$$\begin{aligned} \vec{S} &= \frac{c}{4\pi} \vec{E} \times \vec{B} = -\frac{q}{4\pi} \left(\frac{q}{c^2 r} \right)^2 [\hat{r} \times (\hat{r} \times \vec{a})] \times [\hat{r} \times \vec{a}] \\ &= \frac{c}{4\pi} \left(\frac{q}{c^2 r} \right)^2 \left\{ \hat{r} (\hat{r} \times \vec{a})^2 - (\hat{r} \times \vec{a}) [\hat{r} \cdot (\hat{r} \times \vec{a})] \right\} \\ &= \frac{q^2}{4\pi c^3} \frac{[\hat{r} \times \vec{a}(t_0)]^2}{r^2} \hat{r} \end{aligned}$$

for $\vec{a} = a \hat{z}$

$$\begin{aligned} \vec{S} &= \frac{q^2}{4\pi c^3 r^2} (a^2 - (\hat{r} \cdot \vec{a})^2) \hat{r} \\ &= \frac{q^2}{4\pi c^3} \frac{a^2(t_0)}{r^2} \sin^2 \theta \hat{r} \end{aligned}$$

$\vec{a}$ evaluated at t_0

Special Relativity

- 1) Speed of light is constant in all inertial frames of reference
- 2) Physical laws must look the same in all inertial frames of reference - there is no experiment that can determine the "absolute" velocity of any inertial frame

⇒ If a flash of light goes off at the origin of some coord system, the outgoing wavefronts look spherical in all inertial frames.

Equation of wavefront is $r^2 - c^2 t^2 = 0$

⇒ (x, y, z, t) coords in one inertial frame K

(x', y', z', t') coords in another inertial frame K' that moves with velocity $\vec{v} = v\hat{x}$ with respect to K .

What is the transformation that relates coords in K' to coords in K ?

$$y = y', \quad z = z'$$

$$\Rightarrow c^2 t^2 - x^2 = c^2 t'^2 - x'^2$$

$$\Rightarrow \frac{(ct+x)}{(ct'+x')} \frac{(ct-x)}{(ct'-x')} = 1$$

Expect transformation to be linear

$$\Rightarrow ct' + x' = (ct + x) f$$

$$ct' - x' = (ct - x) f^{-1}$$

for some constant f . Write $f = e^{-y}$

y is rapidity

Solve for ct' and x' in terms of ct and x

$$ct' = ct \left(\frac{e^y + e^{-y}}{2} \right) - x \left(\frac{e^y - e^{-y}}{2} \right)$$

$$x' = -ct \left(\frac{e^y - e^{-y}}{2} \right) + x \left(\frac{e^y + e^{-y}}{2} \right)$$

$$ct' = ct \cosh y - x \sinh y$$

$$x' = -ct \sinh y + x \cosh y$$

meaning of parameter y

(at $x=0$)

the origin of K has trajectory $x' = -vt'$ in K'

$$\Rightarrow \frac{x'}{t'} = -v$$

from transformation above, with $x=0$, we get

$$\frac{x'}{ct'} = \frac{-ct \sinh y}{ct \cosh y} = -\tanh y$$

$$\text{so } \frac{v}{c} = \tanh y$$

$$\Rightarrow \cosh y = \frac{1}{\sqrt{1 - \left(\frac{v}{c}\right)^2}} \equiv \gamma$$

$$\sinh y = \left(\frac{v}{c}\right) \gamma$$

Lorentz Transformation

$$\begin{cases} ct' = \gamma ct - \gamma \left(\frac{v}{c}\right) x \\ x' = -\gamma \left(\frac{v}{c}\right) ct + \gamma x \end{cases}$$

Inverse transform obtained by taking $v \rightarrow -v$ in above

$$\begin{cases} ct = \gamma ct' + \gamma\left(\frac{v}{c}\right)x' \\ x = \gamma\left(\frac{v}{c}\right)ct' + \gamma x' \end{cases}$$

4-vectors

4-position: $x_\mu = (x_1, x_2, x_3, ict)$ $x_4 \equiv ict$

$$x_\mu x_\mu \equiv \sum_{\mu=1}^4 x_\mu^2 = r^2 - c^2 t^2$$

Lorentz invariant scalar
- has same value in all
inertial frames

Lorentz transf is

$$\left. \begin{aligned} x_1' &= \gamma \left(x_1 + i\left(\frac{v}{c}\right)x_4 \right) \\ x_2' &= x_2 \\ x_3' &= x_3 \\ x_4' &= \gamma \left(x_4 - i\left(\frac{v}{c}\right)x_1 \right) \end{aligned} \right\} \text{linear transf, can be represented by a matrix}$$

or $x_\mu' = a_{\mu\nu}(L) x_\nu$

$\uparrow$ matrix of Lorentz transformation L

$$a(L) = \begin{pmatrix} \gamma & 0 & 0 & i\frac{v}{c}\gamma \\ 0 & 1 & 0 & 0 \\ 0 & 0 & 1 & 0 \\ -i\frac{v}{c}\gamma & 0 & 0 & \gamma \end{pmatrix}$$

inverse: $x_\mu = a_{\mu\nu}(L^{-1}) x_\nu'$

$a_{\mu\nu}(L^{-1})$ is given by taking $v \rightarrow -v$ in $a_{\mu\nu}(L)$

we see $a_{\mu\nu}(L^{-1}) = a_{\nu\mu}(L)$

inverse = transpose

More generally

Since x_μ^2 is Lorentz invariant scalar,

$$x_\mu'^2 = a_{\mu\nu}(L) a_{\mu\lambda}(L) x_\nu x_\lambda = x_\lambda^2$$

$$\Rightarrow a_{\mu\nu}(L) a_{\mu\lambda}(L) = \delta_{\nu\lambda}$$

$$\Rightarrow a_{\nu\mu}^t(L) a_{\mu\lambda}(L) = \delta_{\nu\lambda}$$

$$\Rightarrow a_{\mu\nu}^t = a_{\mu\nu}^{-1}(L) \quad \text{transpose} = \text{inverse}$$

$a_{\mu\nu}$ is 4×4 orthogonal matrix

If L_1 is a Lorentz transf from K to K'

L_2 is a Lorentz transf from K' to K''

Then the Lorentz transf from K to K'' is given by the matrix

$$a(L_2 L_1) = a(L_2) a(L_1)$$

$$\Rightarrow a^{-1}(L) = a(L^{-1})$$

$$dx_\mu = (dx_1, dx_2, dx_3, icdt)$$

$$-(dx_\mu)^2 \equiv c^2 ds^2 = c^2 dt^2 - dr^2 \quad \text{Lorentz invariant scalar}$$

$$ds^2 = dt^2 \left[1 - \frac{1}{c^2} \left(\frac{dx_1}{dt} \right)^2 - \frac{1}{c^2} \left(\frac{dx_2}{dt} \right)^2 - \frac{1}{c^2} \left(\frac{dx_3}{dt} \right)^2 \right]$$

$$ds^2 = \frac{dt^2}{\gamma^2}$$

$$\boxed{ds = \frac{dt}{\gamma}} \quad \text{proper time interval}$$

A 4-vector is any 4 numbers that transform under a Lorentz transformation the same way as does x_μ

4-velocity $u_\mu \equiv \frac{dx_\mu}{ds} \equiv \dot{x}_\mu$

$$= \gamma \frac{dx_\mu}{dt}$$

space components $\vec{u} = \gamma \vec{v}$

$$u_4 = ic\gamma$$

$$u_\mu u_\mu = \gamma^2 v^2 - c^2 \gamma^2 = \gamma^2 (v^2 - c^2)$$

$$= \frac{v^2 - c^2}{1 - \frac{v^2}{c^2}} = -c^2$$

4-acceleration $a_\mu \equiv \frac{du_\mu}{ds} = \gamma \frac{du_\mu}{dt}$

4-gradient $\frac{\partial}{\partial x_\mu} \equiv \left(\vec{\nabla}, -\frac{i}{c} \frac{\partial}{\partial t} \right)$

proof $\frac{\partial}{\partial x_\mu}$ is a 4-vector

$$\frac{\partial}{\partial x'_\mu} = \frac{\partial x_\lambda}{\partial x'_\mu} \frac{\partial}{\partial x_\lambda}$$

but $\frac{\partial x_\lambda}{\partial x'_\mu} = a_{\mu\lambda} (L^{-1})$

$$= a_{\mu\lambda} (L) \frac{\partial}{\partial x_\lambda}$$

so transforms same as x_μ

$$\left(\frac{\partial}{\partial x_\mu} \right)^2 = \nabla^2 - \frac{1}{c^2} \frac{\partial^2}{\partial t^2}$$

wave equation operator!

inner products

If u_μ and v_μ are 4-vectors, then $u_\mu v_\mu$ is Lorentz invariant scalar