

Special Relativity

- 1) Speed of light is constant in all inertial frames of reference
- 2) Physical laws must look the same in all inertial frames of reference - there is no experiment that can determine the "absolute" velocity of any inertial frame

⇒ If a flash of light goes off at the origin of some coord system, the outgoing wavefronts look spherical in all inertial frames.

Equation of wavefront is $r^2 - c^2t^2 = 0$

⇒ (x, y, z, t) coords in one inertial frame K
 (x', y', z', t') coords in another inertial frame K' that moves with velocity $\vec{v} = v\hat{x}$ with respect to K .

What is the transformation that relates coords in K' to coords in K ?

$$y = y', \quad z = z'$$

$$\Rightarrow c^2t^2 - x^2 = c^2t'^2 - x'^2$$

$$\Rightarrow \frac{(ct+x)(ct-x)}{(ct'+x')(ct'-x')} = 1$$

Expect transformation to be linear

$$\begin{aligned}\Rightarrow ct' + x' &= (ct+x) f \\ ct' - x' &= (ct-x) f^{-1}\end{aligned}$$

for some constant f . Write $f = e^{-y}$ y is rapidity

Solve for ct' and x' in terms of ct and x

$$ct' = ct \left(\frac{e^y + e^{-y}}{2} \right) - x \left(\frac{e^y - e^{-y}}{2} \right)$$

$$x' = -ct \left(\frac{e^y - e^{-y}}{2} \right) + x \left(\frac{e^y + e^{-y}}{2} \right)$$

$$ct' = ct \cosh y - x \sinh y$$

$$x' = -ct \sinh y + x \cosh y$$

meaning of parameter y

(at $x=0$)

the origin of K has trajectory $x' = -vt'$ in K'

$$\Rightarrow \frac{x'}{t'} = -v$$

from transformation above, with $x=0$, we get

$$\frac{x'}{ct'} = \frac{-ct \sinh y}{ct \cosh y} = -\tanh y$$

$$\text{so } \frac{v}{c} = \tanh y$$

$$\Rightarrow \cosh y = \frac{1}{\sqrt{1 - \left(\frac{v}{c}\right)^2}} \equiv \gamma$$

$$\sinh y = \left(\frac{v}{c}\right) \gamma$$

Lorentz Transformation

$$\begin{cases} ct' = \gamma ct - \gamma \left(\frac{v}{c}\right) x \\ x' = -\gamma \left(\frac{v}{c}\right) ct + \gamma x \end{cases}$$

Inverse transform obtained by taking $v \rightarrow -v$ in above

$$\begin{cases} ct = \gamma ct' + \gamma \left(\frac{v}{c}\right) x' \\ x = \gamma \left(\frac{v}{c}\right) ct' + \gamma x' \end{cases}$$

4-vectors

4-position: $X_\mu = (x_1, x_2, x_3, ict)$ $x_4 \equiv ict$
 $X_\mu X_\mu \equiv \sum_{\mu=1}^4 X_\mu^2 = r^2 - c^2 t^2$ Lorentz invariant scalar
 - has same value in all inertial frames

Lorentz transf is

$$\left. \begin{aligned} x_1' &= \gamma \left(x_1 + i \left(\frac{v}{c}\right) x_4 \right) \\ x_2' &= x_2 \\ x_3' &= x_3 \\ x_4' &= \gamma \left(x_4 - i \left(\frac{v}{c}\right) x_1 \right) \end{aligned} \right\} \text{linear transf, can be represented by a matrix}$$

or $x_\mu' = a_{\mu\nu}(L) x_\nu$

\mathbb{L} matrix of Lorentz transformation L

$$a(L) = \begin{pmatrix} \gamma & 0 & 0 & i \frac{v}{c} \gamma \\ 0 & 1 & 0 & 0 \\ 0 & 0 & 1 & 0 \\ -i \frac{v}{c} \gamma & 0 & 0 & \gamma \end{pmatrix}$$

inverse: $x_\mu = a_{\mu\nu}(L^{-1}) x_\nu'$

$a_{\mu\nu}(L^{-1})$ is given by taking $v \rightarrow -v$ in $a_{\mu\nu}(L)$

we see $a_{\mu\nu}(L^{-1}) = a_{\nu\mu}(L)$

inverse = transpose

More generally

Since x_μ^2 is Lorentz invariant scalar,

$$x_\mu'^2 = a_{\mu\nu}(L) a_{\mu\lambda}(L) x_\nu x_\lambda = x_\lambda^2$$

$$\Rightarrow a_{\mu\nu}(L) a_{\mu\lambda}(L) = \delta_{\nu\lambda}$$

$$\Rightarrow a_{\nu\mu}^t(L) a_{\mu\lambda}(L) = \delta_{\nu\lambda}$$

$$\Rightarrow a_{\mu\nu}^t = a_{\mu\nu}^{-1}(L) \quad \text{transpose} = \text{inverse}$$

$a_{\mu\nu}$ is 4x4 orthogonal matrix

If L_1 is a Lorentz transf from K to K'

L_2 is a Lorentz transf from K' to K''

Then the Lorentz transf from K to K'' is given by the matrix

$$a(L_2 L_1) = a(L_2) a(L_1)$$

$$\Rightarrow a^{-1}(L) = a(L^{-1})$$

$$dx_\mu = (dx_1, dx_2, dx_3, icdt)$$

$$-(dx_\mu)^2 \equiv c^2 ds^2 = c^2 dt^2 - dr^2 \quad \text{Lorentz invariant scalar}$$

$$ds^2 = dt^2 \left[1 - \frac{1}{c^2} \left(\frac{dx_1}{dt} \right)^2 - \frac{1}{c^2} \left(\frac{dx_2}{dt} \right)^2 - \frac{1}{c^2} \left(\frac{dx_3}{dt} \right)^2 \right]$$

$$ds^2 = \frac{dt^2}{\gamma^2}$$

$$\boxed{ds = \frac{dt}{\gamma}} \quad \text{proper time interval}$$

A 4-vector is any 4 numbers that transform under a Lorentz transformation the same way as does x_μ

4-velocity $u_\mu \equiv \frac{dx_\mu}{ds} \equiv \dot{x}_\mu$

$$= \gamma \frac{dx_\mu}{dt}$$

space components $\vec{u} = \gamma \vec{v}$

$$u_4 = ic\gamma$$

$$u_\mu u_\mu = \gamma^2 v^2 - c^2 \gamma^2 = \gamma^2 (v^2 - c^2)$$

$$= \frac{v^2 - c^2}{1 - \frac{v^2}{c^2}} = -c^2$$

4-acceleration $a_\mu \equiv \frac{du_\mu}{ds} = \gamma \frac{du_\mu}{dt}$

4-gradient $\frac{\partial}{\partial x_\mu} \equiv \left(\vec{\nabla}, -\frac{i}{c} \frac{\partial}{\partial t} \right)$

proof $\frac{\partial}{\partial x_\mu}$ is a 4-vector

$$\frac{\partial}{\partial x'_\mu} = \frac{\partial x_\lambda}{\partial x'_\mu} \frac{\partial}{\partial x_\lambda}$$

but $\frac{\partial x_\lambda}{\partial x'_\mu} = a_{\mu\lambda}(L^{-1})$

$$= a_{\mu\lambda}(L) \frac{\partial}{\partial x_\lambda}$$

so transforms same as x_μ

$$\left(\frac{\partial}{\partial x_\mu} \right)^2 = \nabla^2 - \frac{1}{c^2} \frac{\partial^2}{\partial t^2}$$

wave equation operator!

inner products

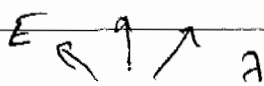
If u_μ and v_μ are 4-vectors, then $u_\mu v_\mu$ is Lorentz invariant scalar

Electromagnetism

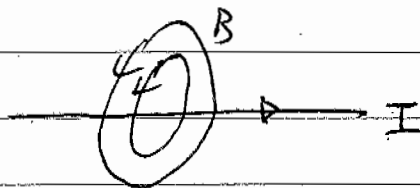
Clearly $\vec{E} + \vec{B}$ must transform into each other under Lorentz trans.

in inertial frame K
stationary line charge λ

$$\vec{E} \uparrow \lambda$$


cylindrical outward
electric field
no B-field

in frame K' moving with $\vec{v} \parallel$ to wire



moving line charge gives current
 \Rightarrow B circulating around wire
as well as outward radial E

Lorentz force

$$\vec{F} = q\vec{E} + q\frac{\vec{v}}{c} \times \vec{B}$$

What is the velocity \vec{v} here? velocity with respect to what inertial frame? Clearly \vec{E} and \vec{B} must change from one inertial frame to another if this force law can make sense.

Charge density

Consider charge ΔQ contained in a vol ΔV .
 ΔQ is a Lorentz invariant scalar.

Consider the reference frame in which the charge is instantaneously at rest. In this frame

$$\Delta Q = \rho^{\circ} \Delta V^{\circ}$$

ρ° is charge density in the rest frame
 ΔV° is volume in the rest frame

ρ° is Lorentz invariant by definition

Now transform to another frame moving with \vec{v} with respect to rest frame

ΔQ remains the same

$$\Delta V = \frac{\Delta V^{\circ}}{\gamma} \quad \text{volume contracts in direction || to } \vec{v}$$

$$\rho = \frac{\Delta Q}{\Delta V} = \frac{\Delta Q}{\Delta V^{\circ}} \gamma = \rho^{\circ} \gamma$$

Current density is $\vec{j} = \rho \vec{v} = \gamma \vec{v} \cdot \rho = \rho^{\circ} \vec{u}$

Define 4-current $j_{\mu} = (\vec{j}, ic\rho) = \rho^{\circ}(\vec{u}, ic\gamma)$
 $= \rho^{\circ} u_{\mu}$

it is 4-vector since u_{μ} is 4-vector and ρ° is Lorentz invariant scalar.

charge conservation

$$\vec{\nabla} \cdot \vec{j} + \frac{\partial \rho}{\partial t} = \boxed{\frac{\partial j_{\mu}}{\partial x_{\mu}} = 0}$$

Equation for potentials in Lorentz gauge

$$\left(\nabla^2 - \frac{1}{c^2} \frac{\partial^2}{\partial t^2}\right) \vec{A} = -\frac{4\pi}{c} \vec{j}$$

$$\left(\nabla^2 - \frac{1}{c^2} \frac{\partial^2}{\partial t^2}\right) \phi = -4\pi \rho$$

$$\frac{\partial^2}{\partial x_\mu^2} = \left(\nabla^2 - \frac{1}{c^2} \frac{\partial^2}{\partial t^2}\right) \text{ is Lorentz invariant operator}$$

4-potential

$$A_\mu = (\vec{A}, i\phi)$$

$$\left(\nabla^2 - \frac{1}{c^2} \frac{\partial^2}{\partial t^2}\right) A_\mu = -\frac{4\pi}{c} j_\mu = \frac{\partial^2 A_\mu}{\partial x_\mu^2}$$

Lorentz gauge condition is

$$\vec{\nabla} \cdot \vec{A} + \frac{\partial \phi}{c \partial t} = \frac{\partial A_\mu}{\partial x_\mu} = 0$$

Electric and magnetic fields

$$B_i = \frac{\partial A_k}{\partial x_j} - \frac{\partial A_j}{\partial x_k} \quad \text{E, j, k cyclic permutation of 1, 2, 3}$$

$$E_i = -\frac{\partial \phi}{\partial x_i} - \frac{\partial A_i}{c \partial t} = -i \left(\frac{\partial A_4}{\partial x_i} - \frac{\partial A_i}{\partial x_4} \right)$$

Define field stress tensor

$$F_{\mu\nu} = \frac{\partial A_\nu}{\partial x_\mu} - \frac{\partial A_\mu}{\partial x_\nu} = -F_{\nu\mu}$$

$$= \begin{pmatrix} 0 & B_3 & -B_2 & -iE_1 \\ -B_3 & 0 & B_1 & -iE_2 \\ B_2 & -B_1 & 0 & -iE_3 \\ iE_1 & iE_2 & iE_3 & 0 \end{pmatrix}$$

"curl" of a 4-vector
is a 4x4 anti
symmetric 2nd rank tensor

Inhomogeneous Maxwell's equations can be written in the form

$$\boxed{\frac{\partial F_{\mu\nu}}{\partial x_\nu} = \frac{4\pi}{c} j_\mu} \Rightarrow \left[\begin{array}{l} \vec{\nabla} \cdot \vec{E} = 4\pi \rho \\ \vec{\nabla} \times \vec{B} - \frac{1}{c} \frac{\partial \vec{E}}{\partial t} = \frac{4\pi}{c} \vec{j} \end{array} \right]$$

$$= \frac{\partial}{\partial x_\nu} \left(\frac{\partial A_\nu}{\partial x_\mu} - \frac{\partial A_\mu}{\partial x_\nu} \right) = \frac{\partial}{\partial x_\mu} \left(\frac{\partial A_\nu}{\partial x_\nu} \right) - \frac{\partial^2 A_\mu}{\partial x_\nu^2}$$

"0"

$$\Rightarrow - \frac{\partial^2 A_\mu}{\partial x_\nu^2} = \frac{4\pi}{c} j_\mu \quad \text{agrees with previous equation for } A_\mu$$

transformation law for 2nd rank tensor $F_{\mu\nu}$

$$F'_{\mu\nu} = \frac{\partial A'_\nu}{\partial x'^\mu} - \frac{\partial A'_\mu}{\partial x'^\nu} \\ = a_{\nu\lambda} a_{\mu\sigma} \frac{\partial A_\lambda}{\partial x^\sigma} - a_{\mu\sigma} a_{\nu\lambda} \frac{\partial A_\sigma}{\partial x^\lambda}$$

$$\text{use } A'_\mu = a_{\mu\sigma} A_\sigma \\ \frac{\partial}{\partial x'^\mu} = a_{\mu\lambda} \frac{\partial}{\partial x^\lambda}$$

$$F'_{\mu\nu} = a_{\mu\sigma} a_{\nu\lambda} F_{\sigma\lambda} \leftarrow$$

For n^{th} rank tensor

lets one find \vec{E}' and \vec{B}'
if one knows \vec{E} and \vec{B}

$$T'_{\mu_1 \mu_2 \dots \mu_n} = a_{\mu_1 \nu_1} a_{\mu_2 \nu_2} \dots a_{\mu_n \nu_n} T_{\nu_1 \nu_2 \dots \nu_n}$$

$\frac{\partial F_{\mu\nu}}{\partial x_\nu}$ is a 4-vector: proof:

$$\frac{\partial F'_{\mu\nu}}{\partial x'_\nu} = a_{\mu\sigma} a_{\nu\lambda} a_{\nu\gamma} \frac{\partial F_{\sigma\lambda}}{\partial x_\gamma}$$

but $a_{\nu\lambda} = a_{\lambda\nu}^{-1}$ since inverse = transpose
 $a_{\nu\lambda} a_{\nu\gamma} = a_{\lambda\nu}^{-1} a_{\nu\gamma} = \delta_{\lambda\gamma}$

$$\frac{\partial F'_{\mu\nu}}{\partial x'_\nu} = a_{\mu\sigma} \frac{\partial F_{\sigma\lambda}}{\partial x_\lambda} \delta_{\lambda\gamma} = a_{\mu\sigma} \frac{\partial F_{\sigma\lambda}}{\partial x_\lambda}$$
 transforms like 4-vector

To write the homogeneous Maxwell Equations

Construct 3rd rank co-variant tensor

$$G_{\mu\nu\lambda} = \frac{\partial F_{\mu\nu}}{\partial x_\lambda} + \frac{\partial F_{\lambda\mu}}{\partial x_\nu} + \frac{\partial F_{\nu\lambda}}{\partial x_\mu}$$

transforms as $G'_{\mu\nu\lambda} = a_{\mu\alpha} a_{\nu\beta} a_{\lambda\gamma} G_{\alpha\beta\gamma}$

in principle G has $4^3 = 64$ components

But can show that G is antisymmetric in exchange of any two indices

$$G_{\nu\mu\lambda} = \frac{\partial F_{\nu\mu}}{\partial x_\lambda} + \frac{\partial F_{\lambda\nu}}{\partial x_\mu} + \frac{\partial F_{\mu\lambda}}{\partial x_\nu}$$

$$= -\frac{\partial F_{\mu\nu}}{\partial x_\lambda} - \frac{\partial F_{\nu\lambda}}{\partial x_\mu} - \frac{\partial F_{\lambda\mu}}{\partial x_\nu} \quad \text{as } F \text{ antisymmetric}$$

$$= -G_{\mu\lambda\nu}$$

also $G_{\mu\nu} = 0$ if any two indices are equal

\Rightarrow only 4 independent components

$$G_{012}, G_{013}, G_{023}, G_{123}$$

all other components either vanish or are \pm one of the above.

The 4 homogeneous Maxwell Equations:

$$\vec{\nabla} \cdot \vec{B} = 0, \quad \vec{\nabla} \times \vec{E} + \frac{1}{c} \frac{\partial \vec{B}}{\partial t} = 0$$

can be written as

$$\boxed{G_{\mu\nu} = 0}$$

to see, substitute in definition of G the definition of F

$$G_{\mu\nu} = \frac{\partial^2 A_\nu}{\partial x_\lambda \partial x_\mu} - \frac{\partial^2 A_\mu}{\partial x_\lambda \partial x_\nu} + \frac{\partial^2 A_\mu}{\partial x_\nu \partial x_\lambda} - \frac{\partial^2 A_\lambda}{\partial x_\nu \partial x_\mu} + \frac{\partial^2 A_\lambda}{\partial x_\mu \partial x_\nu} - \frac{\partial^2 A_\nu}{\partial x_\mu \partial x_\lambda}$$

all terms cancel in pairs

$$= 0$$

$$G_{123} = 0 \Rightarrow \vec{\nabla} \cdot \vec{B} = 0$$

$$G_{012} = -i \left[\vec{\nabla} \times \vec{E} + \frac{\partial \vec{B}}{\partial t} \right]_z = 0 \quad \text{3 component Faraday's law}$$

Another way to write homogeneous Maxwell Equations

Define $\epsilon_{\mu\nu\lambda\sigma}$ = 4-d Levi-Civita symbol

$$\epsilon_{\mu\nu\lambda\sigma} = \begin{cases} +1 & \text{if } \mu\nu\lambda\sigma \text{ is even permutation of } 1234 \\ -1 & \text{if } \mu\nu\lambda\sigma \text{ is odd permutation of } 1234 \\ 0 & \text{otherwise} \end{cases}$$

Define $\tilde{F}_{\mu\nu} = \frac{1}{2i} \epsilon_{\mu\nu\lambda\sigma} F_{\lambda\sigma}$ pseudo-tensor

$$= \begin{pmatrix} 0 & -E_3 & E_2 & -iB_1 \\ E_3 & 0 & -E_1 & -iB_2 \\ -E_2 & E_1 & 0 & -iB_3 \\ iB_1 & iB_2 & iB_3 & 0 \end{pmatrix}$$

has wrong sign under parity transf

$\frac{\partial \tilde{F}_{\mu\nu}}{\partial x_\nu} = 0$ gives homogeneous Maxwell equations

$$\left. \begin{aligned} \frac{1}{2} F_{\mu\nu} F_{\mu\nu} &= B^2 - E^2 \\ -\frac{1}{4} F_{\mu\nu} \tilde{F}_{\mu\nu} &= \vec{B} \cdot \vec{E} \end{aligned} \right\} \text{Lorentz invariant scalars}$$

From $F_{\mu\nu} = a_{\mu\alpha} a_{\nu\lambda} F_{\alpha\lambda}$ we can get
Lorentz transf for \vec{E} and \vec{B}

For a transformation from K to K' with K' moving
with v along x_1 , with respect to K ,

$$E'_1 = E_1$$

$$E'_2 = \gamma \left(E_2 - \frac{v}{c} B_3 \right)$$

$$E'_3 = \gamma \left(E_3 + \frac{v}{c} B_2 \right)$$

$$B'_1 = B_1$$

$$B'_2 = \gamma \left(B_2 + \frac{v}{c} E_3 \right)$$

$$B'_3 = \gamma \left(B_3 - \frac{v}{c} E_2 \right)$$

Kinematics

"dot" is $\frac{d}{ds}$

4-momentum

$$p_\mu = m \dot{x}_\mu = m u_\mu = (m \gamma \vec{v}, i m c \gamma)$$

$$p_\mu^2 = m^2 \dot{x}_\mu^2 = -m^2 c^2$$

4-force

$$K_\mu = (\vec{K}, i K_0) \quad \text{"Minkowski force"}$$

Newton's 2nd law

$$m \frac{d^2 x_\mu}{ds^2} = K_\mu$$

$$\Rightarrow m \frac{d u_\mu}{ds} = \frac{d p_\mu}{ds} = K_\mu$$

$$p_\mu^2 = -m^2 c^2 \Rightarrow \frac{d}{ds} (p_\mu^2) = p_\mu \frac{d p_\mu}{ds} = p_\mu K_\mu = 0$$

$$\Rightarrow m \gamma \vec{v} \cdot \vec{K} - m c \gamma K_0 = 0 \quad \text{or}$$

$$K_0 = \frac{\vec{v} \cdot \vec{K}}{c}$$

Define the usual 3-force by

$$\frac{d\vec{p}}{dt} = \vec{F}$$

$$\frac{d\vec{p}}{ds} = \vec{K} \quad \text{and} \quad \frac{d\vec{p}}{ds} = \gamma \frac{d\vec{p}}{dt} = \gamma \vec{F} \quad \Rightarrow \quad \begin{aligned} K &= \gamma \vec{F} \\ K_0 &= \gamma \frac{d}{dt} \cdot \vec{F} \end{aligned}$$

Consider 4th component of Newton's eqn

$$m \frac{d u_4}{ds} = m \frac{d (ic\gamma)}{ds} = i K_0 = i \gamma \vec{v} \cdot \vec{F}$$

$$d(m\gamma) = \gamma \frac{\vec{v} \cdot \vec{F}}{c^2} ds = \frac{dt}{c^2} \vec{v} \cdot \vec{F} = \frac{d\vec{r} \cdot \vec{F}}{c^2}$$

Work-energy theorem: $d(m\gamma c^2) = d\vec{r} \cdot \vec{F} = \text{work done}$

$\Rightarrow d(m\gamma c^2)$ is change in ^{kinetic} energy

$E = m\gamma c^2$ is relativistic ^{kinetic} energy

$$\boxed{\begin{aligned} \mathcal{P}_\mu &= \left(\vec{p}, \frac{iE}{c} \right) & \begin{aligned} \vec{p} &= m\gamma \vec{v} \\ E &= m\gamma c^2 \end{aligned} \end{aligned}}$$

$$E = \frac{mc^2}{\sqrt{1-\frac{v^2}{c^2}}} \approx mc^2 \left(1 + \frac{1}{2} \frac{v^2}{c^2} \right) = mc^2 + \frac{1}{2} m v^2$$

↑
↑
↑

small $\frac{v}{c}$
rest mass energy
non-rel kinetic energy

$$\frac{d\mathcal{P}_\mu}{ds} = K_\mu$$

is therefore
relativistic analog of Newton's 3rd law
as well as law of conservation of energy

Lorentz force

$$\frac{dp_\mu}{ds} = K_\mu$$

what is the K_μ that represents the Lorentz force and how can we write it in ~~relativistic~~ Lorentz covariant way?

K_μ should depend on the fields $F_{\mu\nu}$ and the particles trajectory x_μ

$$\text{as } \vec{v} \rightarrow 0 \quad \vec{K} = q \vec{E}$$

K_μ can't depend directly on x_μ as should be indep of origin of coords. So can depend only on $\overset{\circ}{x}_\mu, \overset{\circ\circ}{x}_\mu$, etc.

as $v \rightarrow 0$, K does not depend on the acceleration, so K does not depend on $\overset{\circ\circ}{x}_\mu$

K_μ only depends on $F_{\mu\nu}$ and $\overset{\circ}{x}_\mu$
we need to form a μ -vector out of $F_{\mu\nu}$ and $\overset{\circ}{x}_\mu$ that is linear in the fields $F_{\mu\nu}$ and proportional to the charge q .

The only possibility is

$$q f(\overset{\circ\circ}{x}_\mu) F_{\mu\nu} \overset{\circ}{x}_\nu$$

But $\dot{x}_\mu^2 = c^2$ is a constant, choose $f(x_\mu^2) = \frac{1}{c}$

$$K_\mu = \frac{q}{c} F_{\mu\nu} \dot{x}_\nu \text{ is only possibility}$$

This gives force

$$\vec{F} = \frac{1}{\gamma} \vec{K}$$

$$F_i = \frac{1}{\gamma} K_i = \frac{q}{\gamma c} (F_{ij} \dot{x}_j + F_{i4} \dot{x}_4)$$

$$= \frac{q}{\gamma c} \left(\frac{\partial A_j}{\partial x_i} - \frac{\partial A_i}{\partial x_j} \right) \dot{x}_j + \frac{q}{\gamma c} (-iE_i)(ic\gamma)$$

$$= \frac{q}{\gamma c} [\epsilon_{ijk} B_k \gamma v_j] + \frac{q}{\gamma c} E_i c \gamma$$

$$= q E_i + q \epsilon_{ijk} \frac{v_j}{c} B_k$$

$$\vec{F} = q \vec{E} + q \frac{\vec{v}}{c} \times \vec{B}$$

Lorentz force is the same form in all inertial frames.
No relativistic modification is needed.

Relativistic Larmor's formula

non-relativistic $P = \frac{2}{3} \frac{q^2 [a(t_0)]^2}{c^3}$

Consider inertial frame $\overset{\circ}{K}$ in which charge is instantaneously at rest. Call the rest frame K .

power radiated in $\overset{\circ}{K}$ is $\overset{\circ}{P} = \frac{d\overset{\circ}{E}(t)}{dt}$

where $\overset{\circ}{E}$ is energy radiated. In $\overset{\circ}{K}$, the momentum density $\overset{\circ}{\Pi} = \frac{1}{4\pi c} \overset{\circ}{E} \times \overset{\circ}{B} \sim \hat{r}$ is in outward radial direction. Integrating over all directions, the radiated momentum vanishes $\overset{\circ}{P} = 0$

energy-momentum is a 4-vector $(\overset{\circ}{P}, i\overset{\circ}{E})$

To get radiated energy in original frame K we can use Lorentz transf

$$\frac{\mathcal{E}}{c} = \gamma \left(\frac{\overset{\circ}{E}}{c} - \vec{v} \cdot \overset{\circ}{P} \right) \Rightarrow \mathcal{E} = \gamma \overset{\circ}{E} \text{ as } \overset{\circ}{P} = 0$$

and $dt = \gamma dt^{\circ}$ is time interval in K

($d\vec{r}^{\circ} = 0$ as charge stays at origin in $\overset{\circ}{K}$)

$$\text{So } \frac{d\mathcal{E}}{dt} = \frac{\gamma d\overset{\circ}{E}}{\gamma dt^{\circ}} = \frac{d\overset{\circ}{E}}{dt^{\circ}} \Rightarrow P = \overset{\circ}{P}$$

radiated power is Lorentz invariant!

in K^0 we can use non-relativistic Larmor's formula since $v=0$. So

$$P = \frac{2}{3} \frac{q \dot{a}^2}{c^3} \quad \dot{a} \text{ is acceleration in } K^0$$

To write an expression without explicitly making mention of frame K^0 , we need to find a Lorentz invariant scalar that reduces to a^2 as $v \rightarrow 0$. Only choice is α_μ^2 the 4-acceleration $\alpha_\mu = \frac{dU_\mu}{ds}$

$$\alpha_\mu = \frac{dU_\mu}{ds} = \gamma \frac{dU_\mu}{dt} = \gamma \frac{d}{dt} (\gamma \vec{v}, c\gamma)$$

$$\vec{\alpha} = \gamma^2 \frac{d\vec{v}}{dt} + \gamma \vec{v} \frac{d\gamma}{dt}$$

$$\alpha_4 = ic \gamma \frac{d\gamma}{dt}$$

$$\frac{d\gamma}{dt} = \frac{d}{dt} \left(\frac{1}{\sqrt{1-v^2/c^2}} \right) = \frac{\frac{\vec{v} \cdot d\vec{v}}{c^2}}{(1-v^2/c^2)^{3/2}} = \frac{1}{c^2} \gamma^3 \vec{v} \cdot \vec{a}$$

$$\text{as } \vec{v} \rightarrow 0, \quad \gamma \rightarrow 1, \quad \frac{d\gamma}{dt} \rightarrow 0, \quad \text{so } \begin{cases} \vec{\alpha} \rightarrow \frac{d\vec{v}}{dt} = \vec{a} \\ \alpha_4 \rightarrow 0 \end{cases}$$

$$\alpha_\mu^2 \rightarrow |\vec{a}|^2 \text{ as desired}$$

Relativistic Larmor's formula

$$P = \frac{2}{3} \frac{q^2}{c^3} \alpha_\mu^2 = \frac{2}{3} \frac{q^2}{c^3} (\dot{U}_\mu)^2$$

$$\alpha_\mu = \left(\gamma^2 \frac{d\vec{v}}{dt} + \gamma \vec{v} \frac{d\gamma}{dt}, \quad c \gamma \frac{d\gamma}{dt} \right)$$

$$\frac{d\gamma}{dt} = \frac{1}{c^2} \gamma^3 \vec{v} \cdot \vec{a}$$

$$\alpha_\mu = \left(\gamma^2 \vec{a} + \gamma^4 \frac{1}{c^2} (\vec{v} \cdot \vec{a}) \vec{v}, \quad \frac{c \gamma^4 \vec{v} \cdot \vec{a}}{c^2} \right)$$

$$\alpha_\mu^2 = \gamma^4 a^2 + \gamma^8 \frac{(\vec{v} \cdot \vec{a})^2 v^2}{c^4} + 2 \gamma^6 \frac{(\vec{v} \cdot \vec{a})^2}{c^2} - \gamma^8 \frac{(\vec{v} \cdot \vec{a})^2}{c^2}$$

$$= \gamma^4 \left[a^2 + \gamma^4 \frac{(\vec{v} \cdot \vec{a})^2}{c^2} \left(\frac{v^2}{c^2} - 1 \right) + \frac{2\gamma}{c^2} (\vec{v} \cdot \vec{a})^2 \right]$$

$$= \gamma^4 \left[a^2 - \gamma^2 \frac{(\vec{v} \cdot \vec{a})^2}{c^2} + \frac{2\gamma^2 (\vec{v} \cdot \vec{a})^2}{c^2} \right]$$

$$\alpha_\mu^2 = \gamma^4 \left[a^2 + \gamma^2 \frac{(\vec{v} \cdot \vec{a})^2}{c^2} \right]$$

as $\vec{v} \rightarrow 0$, $\alpha_\mu^2 \rightarrow a^2$

$$\alpha_\mu^2 = \dot{a}^2 \quad \text{Lorentz invariant}$$

\dot{a} = acceleration in instantaneous rest

For a charge accelerating in linear motion, $(\vec{v} \cdot \vec{a})^2 = v^2 a^2$ frame

$$\alpha_\mu^2 = \gamma^4 a^2 \left(1 + \gamma^2 \frac{v^2}{c^2} \right) = \gamma^6 a^2$$

$$P = \frac{2}{3} \frac{a^2}{c^3} \gamma^6 = \frac{2}{3} \frac{a^2}{c^3} \gamma^4$$

For a charge in circular motion $(\vec{v} \cdot \vec{a}) = 0$

$$\alpha_\mu^2 = \gamma^4 a^2$$

$$P = \frac{2}{3} \frac{a^2}{c^3} \gamma^4$$