

Magnetostatics

$$\vec{B} = \vec{\nabla} \times \vec{A} \quad , \quad \begin{cases} \vec{\nabla} \cdot \vec{B} = 0 \\ \vec{\nabla} \times \vec{B} = \frac{4\pi}{c} \vec{j} \end{cases} \quad \text{Ampere's law (statics only!)} \\ \Rightarrow \vec{\nabla} \times (\vec{\nabla} \times \vec{A}) = \frac{4\pi}{c} \vec{j}$$

can write $\vec{\nabla} \times (\vec{\nabla} \times \vec{A}) = \vec{\nabla}(\vec{\nabla} \cdot \vec{A}) - \nabla^2 \vec{A}$

where by $\nabla^2 \vec{A}$ we mean $(\nabla^2 A_x) \hat{x} + (\nabla^2 A_y) \hat{y} + (\nabla^2 A_z) \hat{z}$
 $\nabla^2 \vec{A}$ only has a single expression in Cartesian coords

If tried to write it in spherical coords, for example,
 one has

$$\begin{aligned} \nabla^2 \vec{A} &= \nabla^2 (A_r \hat{r} + A_\theta \hat{\theta} + A_\phi \hat{\phi}) \\ &= (\nabla^2 A_r) \hat{r} + A_r (\nabla^2 \hat{r}) + (A_\theta \nabla^2 \hat{\theta}) \hat{\theta} + (A_\phi \nabla^2 \hat{\phi}) \hat{\phi} \\ &\quad + (A_\theta \nabla^2 \hat{\phi}) \hat{\theta} + A_\phi (\nabla^2 \hat{\phi}) \end{aligned}$$

one must not forget to take the derivates of $\hat{r}, \hat{\theta}, \hat{\phi}$
 since they vary with position!

for example, $\hat{r} = \sin\theta \cos\phi \hat{x} + \sin\theta \sin\phi \hat{y} + \cos\theta \hat{z}$

one could compute $\nabla^2 \hat{r}$ by applying ∇^2 in spherical coords
 to each piece and summing up... Get a mess!

If work in Coulomb gauge, with $\vec{\nabla} \cdot \vec{A} = 0$, then

$$\vec{\nabla} \times (\vec{\nabla} \times \vec{A}) = \boxed{-\nabla^2 \vec{A} = \frac{4\pi}{c} \vec{j}}$$

Poisson's equation,

Many of the same methods used to solve for electrostatic ϕ can therefore be applied to solve for magnetostatic \vec{A} . But vector nature of \vec{B} makes for complications!

For simple geometries, one can do the Coulomb-like integral

$$\vec{A}(\vec{r}) = \frac{1}{4\pi} \int d^3 r' \frac{\vec{f}(\vec{r}')}{|\vec{r}-\vec{r}'|} \quad \text{three equations for } A_x, A_y, A_z !$$

for localized current sources $f(r) \rightarrow 0$ as $r \rightarrow \infty$

Multipole expansion - magnetic dipole moment

For a general treatment, analogous to how we did multipole expansion for electrostatics, one can use vector spherical harmonics - see Jackson Chpt 9.

Here we do a more straight forward approach, but only up to magnetic dipole term.

For $r \gg r'$ approx

$$\frac{1}{|\vec{r}-\vec{r}'|} = \frac{1}{(r^2 - 2\vec{r} \cdot \vec{r}' + r'^2)^{1/2}} = \frac{1}{r} \sqrt{\left[1 - 2\frac{\vec{r} \cdot \vec{r}'}{r^2} + \left(\frac{r'}{r}\right)^2\right]^{1/2}}$$

do Taylor series to 1st order in $(\frac{r'}{r})$ to get

$$\frac{1}{|\vec{r}-\vec{r}'|} \approx \frac{1}{r} \left\{ 1 + \frac{\vec{r} \cdot \vec{r}'}{r^2} + \dots \right\} = \frac{1}{r} + \frac{\vec{r} \cdot \vec{r}'}{r^3} + \dots$$

$$\vec{A}(\vec{r}) = \sum_{\vec{r}'} \int \frac{d^3r'}{r} \vec{f}(\vec{r}') + \int \frac{d^3r' \cdot \vec{f}(\vec{r}')}{c} \frac{(\vec{r} \cdot \vec{r}')}{r^3} + \dots$$

Consider term ①

$$\int d^3r \vec{f}(\vec{r}) \quad \text{if } \int d^3r (\vec{f} \cdot \vec{r}) \vec{r} = \frac{\partial r_i}{\partial r_j} f_{ij}$$

write $\int d^3r f_i(r) = \sum_{j=1}^3 \int d^3r f_j \frac{\partial r_i}{\partial r_j}$ integrate by parts

$$= \sum_j \left\{ \int_S d\alpha f_j r_i - \int d^3r \frac{\partial f_j}{\partial r_i} r_i \right\}$$

↑ vanishes as $S \rightarrow \infty$ if

\vec{f} sufficiently localized

i.e. $\vec{f}(\vec{r}) \rightarrow 0$ sufficiently fast as $r \rightarrow \infty$

vanishes in magneto statics where $\vec{B} \cdot \vec{f} = 0$

So. $\int d^3r \vec{f}(\vec{r}) = 0$ in magneto statics
monopole term vanishes

term (2)

$$\int d^3r \vec{f}(\vec{r}) \vec{r} \quad \text{tensor}$$

Consider $\int d^3r j_i r_j = \sum_k \int d^3r j_k r_j \frac{\partial r_i}{\partial r_k}$ integrate by parts

$$= \sum_k \left\{ \int d\sigma j_k r_j r_i - \int d^3r \frac{\partial}{\partial r_k} (j_k r_j) r_i \right\}$$

↑
vanishes as $S \rightarrow \infty$ if \vec{f} sufficiently localized

$$= - \sum_k \int d^3r \left(\frac{\partial j_k}{\partial r_k} r_j r_i + j_k \frac{\partial r_j}{\partial r_k} r_i \right)$$

↑
vanishes as $\nabla \cdot \vec{f} = 0$ $= \delta_{jk}$
in magnetostatics

$$= - \int d^3r j_j r_i$$

$$\text{So } \int d^3r j_i r_j = - \int d^3r j_j r_i$$

$$= \frac{1}{2} \int d^3r (j_i r_j - j_j r_i)$$

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$$\int d^3r' j_i(\vec{r}') (\vec{r} \cdot \vec{r}') = \sum_j r_j \int d^3r' j_i(\vec{r}') r'_j$$

$$= \sum_j \frac{1}{2} \int d^3r' (j_i r_j r'_j - r'_j j_i r'_j)$$

$$= \frac{1}{2} \int d^3r' (j_i (\vec{r} \cdot \vec{r}') - r'_i (\vec{r} \cdot \vec{f}))$$

use triple product rule

$$\vec{r} \times (\vec{r}' \times \vec{f}) = \vec{r}'(\vec{r} \cdot \vec{f}) - \vec{f}(\vec{r} \cdot \vec{r}')$$

to rewrite as

$$\int d^3r' \vec{f}(\vec{r}, \vec{r}') = -\frac{1}{2} \vec{r} \times \left[\int d^3r' \vec{r}' \times \vec{f}(\vec{r}') \right]$$

define the magnetic dipole moment as

$$\boxed{\vec{m} = \frac{1}{2c} \int d^3r' \vec{r}' \times \vec{f}(\vec{r}')}}$$

In magnetic dipole approx (this is the lowest non-vanishing term)

$$\vec{A}(\vec{r}) = -\frac{\vec{r} \times \vec{m}}{r^3} = \frac{\vec{m} \times \vec{r}}{r^3} = \frac{\vec{m} \times \hat{r}}{r^2}$$

$$\vec{B} = \vec{\nabla} \times \vec{A} = \vec{\nabla} \times \left(\vec{m} \times \frac{\vec{r}}{r^3} \right)$$

Levi-Civita symbol

$$B_i = \epsilon_{ijk} \partial_j \epsilon_{klm} m_l \frac{r_m}{r^3}$$

$$= (\delta_{il} \delta_{jm} - \delta_{im} \delta_{je}) \partial_j m_l \frac{r_m}{r^3}$$

$$= m_i \partial_j \left(\frac{r_j}{r^3} \right) - m_j \partial_i \left(\frac{r_i}{r^3} \right)$$

$$= m_i \left[-4\pi \delta(\vec{r}) \right] - m_j \left[\frac{\delta_{ij}}{r^3} - \frac{3r_i}{r^4} \partial_j r \right]$$

$$= \underset{\text{for point source}}{\overset{O}{\nwarrow}} - \frac{m_i}{r^3} + \frac{3r_i}{r^4} \frac{r_j}{r} m_j$$

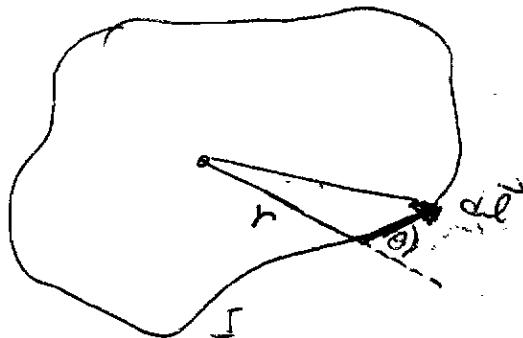
$\epsilon_{ijk} = \begin{cases} 0, & \text{any two indices equal} \\ +1, & ijk \text{ even perm of } 123 \\ -1, & ijk \text{ odd perm of } 123 \end{cases}$

$$\vec{B} = \frac{3(\vec{m} \cdot \hat{r})\hat{r} - \vec{m}}{r^3}$$

same form as \vec{E} from electric dipole \vec{p}

For a current loop in a plane (any shape loop provided it is flat)

$$\vec{m} = \frac{1}{2c} \int d^3x \ \vec{r} \times \vec{j} = \frac{1}{2c} I \oint \vec{r} \times d\vec{l}$$



$$\text{area of triangle is } \frac{1}{2} r dl \sin \theta \\ = \frac{1}{2} I \vec{r} \times d\vec{l}$$



$$\text{area of rectangle is } r dl \sin \theta$$

$$\Rightarrow \vec{m} = \frac{1}{2} I (\text{area}) \hat{m}$$

\hat{m} → outward normal
area of loop (direction given by right hand rule with respect to direction of current)

Magnetic dipole moment \vec{m} is independent of location of origin.

$$\vec{r}' = \vec{r} + \vec{d} \quad \text{new coord}$$

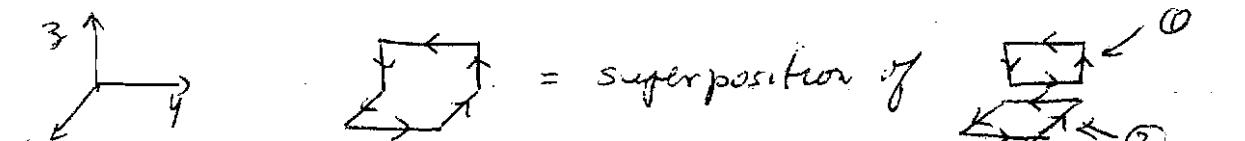
$$\begin{aligned}\vec{m}' &= \frac{1}{2\mu_0} \int d^3r' (\vec{r}' \times \vec{f}) = \frac{1}{2\mu_0} \int d^3r (\vec{r} + \vec{d}) \times \vec{f} \\ &= \frac{1}{2\mu_0} \int d^3r \vec{r} \times \vec{f} + \frac{1}{2\mu_0} \vec{d} \times \left[\int d^3r \vec{f} \right]\end{aligned}$$

$$\vec{m}' = \vec{m} + 0 \quad \text{as } \int d^3r \vec{f} = 0$$

for planar loop $\vec{m} = \frac{Ia}{c} \hat{n}$ where a = area

\hat{n} = outward normal

Can also apply to get \vec{m} for piecewise planar loops



$$\vec{m} = \vec{m}_1 + \vec{m}_2 \quad \vec{m}_1 = \frac{Ia_1}{c} \hat{x} \quad \vec{m}_2 = \frac{Ia_2}{c} \hat{z}$$

$$\Rightarrow \vec{m} = \frac{I}{c} (a_1 \hat{x} + a_2 \hat{z})$$