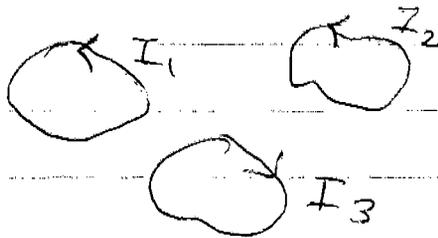


Inductance

Consider a set of current carrying loops C_i with currents I_i .



In Coulomb gauge, we can write the magnetic vector potential \vec{A} from these current loops as

$$\vec{A}(\vec{r}) = \frac{1}{c} \int d^3r' \frac{\vec{j}(\vec{r}')}{|\vec{r}-\vec{r}'|} = \sum_i \frac{I_i}{c} \oint_{C_i} \frac{d\vec{l}'}{|\vec{r}-\vec{r}'|}$$

↑ integrate over loop C_i
integration variable is \vec{r}'

The magnetic flux through loop i is

$$\Phi_i = \int_{S_i} da \hat{n} \cdot \vec{B} = \int_{S_i} da \hat{n} \cdot \vec{\nabla} \times \vec{A} = \oint_{C_i} d\vec{l} \cdot \vec{A}$$

↑ surface bounded
by loop C_i

$$\Phi_i = \sum_j \frac{I_j}{c} \oint_{C_i} \oint_{C_j} \frac{d\vec{l}_i \cdot d\vec{l}_j}{|\vec{r}_i - \vec{r}_j|}$$

pure geometrical
quantity

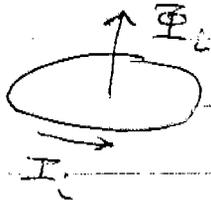
$$\boxed{\Phi_i \equiv c \sum_j M_{ij} I_j}$$

$$\text{where } M_{ij} = \oint_{C_i} \oint_{C_j} \frac{d\vec{l}_i \cdot d\vec{l}_j}{c^2 |\vec{r}_i - \vec{r}_j|}$$

is the mutual inductance of
loops (i) and (j). $M_{ij} = M_{ji}$

$L_i \equiv M_{ii}$ is self-inductance of loop (i)

The sign convention in the above is that, Φ_i is computed in direction given by right hand rule, according to the direction taken for current in loop (i)



Magnetostatic energy

$$\begin{aligned} \mathcal{E} &= \frac{1}{2c} \int d^3r \vec{j} \cdot \vec{A} = \frac{1}{2c} \sum_i \oint_{C_i} d\vec{l} \cdot \vec{A} I_i \\ &= \frac{1}{2c} \sum_i \Phi_i I_i \end{aligned}$$

$$\mathcal{E} = \frac{1}{2} \sum_{i,j} M_{ij} I_i I_j$$

Force and torque on electric dipoles

localized charge distribution $\rho(\vec{r})$ with net charge $\int d^3r \rho = 0$

force on ρ in slowly varying electric field \vec{E} is

$$\vec{F} = \int d^3r \rho(\vec{r}) \vec{E}(\vec{r})$$

define $\vec{r} = \vec{r}_0 + \vec{r}'$ where \vec{r}_0 is some fixed reference point in center of charge distrib ρ , and \vec{r}' is distance relative to \vec{r}_0 .

$$\vec{F} = \int d^3r' \rho(\vec{r}') \vec{E}(\vec{r}_0 + \vec{r}')$$

since \vec{E} is slowly varying on length scale where $\rho \neq 0$, we expand

$$\begin{aligned} \vec{F} &\approx \int d^3r' \rho(\vec{r}') \left[\vec{E}(\vec{r}_0) + (\vec{r}' \cdot \vec{\nabla}) \vec{E}(\vec{r}_0) \right] + \dots \\ &= \vec{E}(\vec{r}_0) \int d^3r' \rho(\vec{r}') + \left(\int d^3r' \rho(\vec{r}') \vec{r}' \cdot \vec{\nabla} \right) \vec{E}(\vec{r}_0) \\ &= 0 + (\vec{p} \cdot \vec{\nabla}) \vec{E}(\vec{r}_0) \end{aligned}$$

$$\boxed{\vec{F} = (\vec{p} \cdot \vec{\nabla}) \vec{E} = \sum_{\alpha=1}^3 p_{\alpha} \frac{\partial \vec{E}}{\partial r_{\alpha}}}$$

For $\vec{E} = \text{constant}$, $\vec{F} = 0$

Torque on p is ~~integrated over volume~~

$$\vec{N} = \int d^3r \rho(\vec{r}) \vec{r} \times \vec{E}(\vec{r}) \cong \int d^3r \rho(\vec{r}) \vec{r} \times [\vec{E}(\vec{r}_0) + \dots]$$

to lowest order $\boxed{\vec{N} = \vec{p} \times \vec{E}}$

Force and torque on magnetic dipoles

localized magnetostatic current distribution $\vec{j}(\vec{r})$

$$\vec{F} = \frac{1}{c} \int d^3r \vec{j} \times \vec{B}$$

expand about center of current \vec{r}_0

$$\vec{B}(\vec{r}) \cong \vec{B}(\vec{r}_0) + (\vec{r}' \cdot \vec{\nabla}) \vec{B}(\vec{r}_0) + \dots$$

$$\vec{F} = \frac{1}{c} \left[\int d^3r' \vec{j}(\vec{r}') \times \vec{B}(\vec{r}_0) + \frac{1}{c} \int d^3r' \vec{j}(\vec{r}') \times (\vec{r}' \cdot \vec{\nabla}) \vec{B}(\vec{r}_0) \right]$$

from discussion of magnetic dipole approx we had $\int d^3r \vec{j} = 0$
for magnetostatics where $\vec{\nabla} \cdot \vec{j} = 0$. So 1st term vanishes.
The 2nd term can be written as

$$\vec{F}_\alpha = \frac{\epsilon_{\alpha\beta\gamma}}{c} \int d^3r' j_\beta r'_\gamma \partial_\delta B_\gamma$$

for magnetostatics see magnetic dipole derivation

we need the tensor $\frac{1}{c} \int d^3r' j_\beta r'_\gamma = -\frac{1}{c} \int d^3r' r'_\beta j_\gamma$

$$= \frac{1}{2c} \int d^3r' [j_\beta r'_\gamma - r'_\beta j_\gamma]$$

$$= -m_\sigma \epsilon_{\sigma\beta\gamma}$$

↑ magnetic dipole $\vec{m} = \frac{1}{2c} \int d^3r \vec{r} \times \vec{j}$

$$\begin{aligned}
 F_\alpha &= \epsilon_{\alpha\beta\gamma} \epsilon_{\sigma\beta\delta} (-m_\sigma) \partial_\delta B_\gamma \\
 &= -(\delta_{\alpha\sigma} \delta_{\gamma\delta} - \delta_{\alpha\delta} \delta_{\sigma\gamma}) m_\sigma \partial_\delta B_\gamma \\
 &= \text{div} \cdot \vec{\nabla} (\vec{m} \cdot \vec{B}) - \vec{m}_\alpha \vec{\nabla} \cdot \vec{B}
 \end{aligned}$$

$$\boxed{\vec{F} = \vec{\nabla} (\vec{m} \cdot \vec{B})} \quad \text{as } \vec{\nabla} \cdot \vec{B} = 0$$

torque on \vec{j} is

$$\begin{aligned}
 \vec{N} &= \frac{1}{c} \int d^3r \vec{r} \times (\vec{j} \times \vec{B}) \quad \text{to lowest order, } \vec{B} = \vec{B}(\vec{r}_0) \\
 & \quad \text{is const over region where } \vec{j} \neq 0 \\
 &= \frac{1}{c} \int d^3r [\vec{j} (\vec{r} \cdot \vec{B}) - \vec{B} (\vec{r} \cdot \vec{j})]
 \end{aligned}$$

2nd term = 0 as follows

$$\begin{aligned}
 \int d^3r \vec{r} \cdot \vec{j} &= \int d^3r \vec{j} \cdot \vec{\nabla} \left(\frac{r^2}{2} \right) \quad \text{as } \vec{\nabla} \left(\frac{r^2}{2} \right) = \vec{r} \\
 &= - \int d^3r (\vec{\nabla} \cdot \vec{j}) \left(\frac{r^2}{2} \right) \quad \text{integrate by parts.} \\
 & \quad \text{surface term } \rightarrow 0 \text{ as } \vec{j} \text{ is localized} \\
 &= 0 \quad \text{as } \vec{\nabla} \cdot \vec{j} = 0 \text{ in magnetostatics}
 \end{aligned}$$

1st term involves

see derivation of magnetic dipole approx

$$\int d^3r \vec{j} \vec{r} = - \int d^3r \vec{r} \vec{j} = \frac{1}{2} \int d^3r [\vec{j} \vec{r} - \vec{r} \vec{j}]$$

So

$$\vec{N} = \frac{1}{2c} \int d^3r [\vec{j} (\vec{r} \cdot \vec{B}) - \vec{r} (\vec{j} \cdot \vec{B})]$$

$$\vec{N} = \frac{1}{2c} \int d^3r \left[\vec{j} (\vec{r} \cdot \vec{B}) - \vec{r} (\vec{j} \cdot \vec{B}) \right]$$

$$\approx \vec{m} \times \vec{B}$$

$$= \frac{1}{2c} \int d^3r (\vec{r} \times \vec{j}) \times \vec{B}$$

$$\boxed{\vec{N} = \vec{m} \times \vec{B}}$$

Electrostatic energy of interaction

$$E = \frac{1}{8\pi} \int d^3r E^2$$

Suppose the charge density ρ that produces \vec{E} can be broken into two pieces, $\rho = \rho_1 + \rho_2$ with $\vec{E} = \vec{E}_1 + \vec{E}_2$ where $\vec{\nabla} \cdot \vec{E}_1 = 4\pi\rho_1$ and $\vec{\nabla} \cdot \vec{E}_2 = 4\pi\rho_2$. Then

$$E = \frac{1}{8\pi} \int d^3r \left[E_1^2 + E_2^2 + 2\vec{E}_1 \cdot \vec{E}_2 \right]$$

↑ ↑ ↑
"self-energy" "self-energy" "interaction" energy
of ρ_1 of ρ_2 of ρ_1 with ρ_2

$$\begin{aligned} E_{\text{int}} &= \frac{1}{4\pi} \int d^3r \vec{E}_1 \cdot \vec{E}_2 \\ &= \int d^3r \rho_1 \phi_2 = \int d^3r \rho_2 \phi_1 \end{aligned}$$

where $\vec{E}_1 = -\vec{\nabla}\phi_1$, $\vec{E}_2 = -\vec{\nabla}\phi_2$, by similar manipulations as earlier
integrals are over all space.

Apply to the interaction energy of a dipole in an external \vec{E} field

$$E_{\text{int}} = \int d^3r \rho_1 \phi_2$$

↑ ↑
charge distribution of dipole potential of external \vec{E} field

Assuming ϕ_2 varies ^{slowly} on length scale of ρ_1 , then we can expand $\phi_2(\vec{r}) = \phi_2(\vec{r}_0) + (\vec{r} - \vec{r}_0) \cdot \vec{\nabla} \phi_2(\vec{r}_0)$ where \vec{r}_0 is the center of mass or any other convenient reference position within ρ_1 .

$$\begin{aligned} E_{\text{int}} &= \int d^3r \rho_1(\vec{r}) \left[\phi_2(\vec{r}_0) + (\vec{r} - \vec{r}_0) \cdot \vec{\nabla} \phi_2(\vec{r}_0) \right] \\ &= q \phi_2(\vec{r}_0) + \left[\int d^3r \rho_1(\vec{r}) (\vec{r} - \vec{r}_0) \right] \cdot \vec{\nabla} \phi_2(\vec{r}_0) \\ &= q \phi_2(\vec{r}_0) + \vec{p} \cdot \vec{E} \end{aligned}$$

Where q is total charge in ρ_1 , and \vec{p} is dipole moment with respect to \vec{r}_0 . $\vec{E} = -\vec{\nabla} \phi_2$ is external \vec{E} -field

For a neutral charge distribution $q=0$, and \vec{p} is independent of the origin about which it is computed, so

$$E_{\text{int}} = -\vec{p} \cdot \vec{E}$$

← does not include the energy needed to make the dipole or to make \vec{E} .

E_{int} is lowest when $\vec{p} \parallel \vec{E}$

⇒ in thermal ensemble, dipoles tend to align parallel to an applied \vec{E} .

Energy of magnetic dipole in external field

We had that the force on the dipole was

$$\vec{F} = \vec{\nabla}(\vec{m} \cdot \vec{B})$$

If we regard the force as coming from the gradient of a potential energy U then $\vec{F} = -\vec{\nabla}U \Rightarrow$

$$U = -\vec{m} \cdot \vec{B}$$

or equivalently, energy = work done to move dipole into position from ∞

$$W = -\int_{\infty}^{\vec{r}} \vec{F} \cdot d\vec{l} = -\int_{\infty}^{\vec{r}} \vec{\nabla}(\vec{m} \cdot \vec{B}) \cdot d\vec{l} = -\vec{m} \cdot \vec{B}(\vec{r})$$

This is the correct energy to use in cases where \vec{m} is due to intrinsic magnetic moments of atom or molecule - say from electron or nuclear spin. For a thermal ensemble magnetic moments tend to align \parallel to \vec{B} .

The answer comes out quite differently if we are talking about a magnetic moment produced by a classical current loop. To see flux, consider what we would get if we tried to do the calculation in a similar way to how we did it for the energy of an electric dipole in an electric field...

Magnetostatic energy of interaction

$$\mathcal{E} = \frac{1}{8\pi} \int d^3r B^2$$

Suppose current \vec{j} that produces \vec{B} can be divided

$$\vec{j} = \vec{j}_1 + \vec{j}_2 \quad \text{with} \quad \vec{B} = \vec{B}_1 + \vec{B}_2 \quad \text{where} \quad \vec{\nabla} \times \vec{B}_1 = \frac{4\pi}{c} \vec{j}_1$$

$$\text{and} \quad \vec{\nabla} \times \vec{B}_2 = \frac{4\pi}{c} \vec{j}_2 \quad \text{then}$$

$$\mathcal{E} = \frac{1}{8\pi} \int d^3r \left[\underbrace{B_1^2}_{\substack{\uparrow \\ \text{self energy} \\ \text{of } \vec{j}_1}} + \underbrace{B_2^2}_{\substack{\uparrow \\ \text{self energy} \\ \text{of } \vec{j}_2}} + 2 \underbrace{\vec{B}_1 \cdot \vec{B}_2}_{\substack{\uparrow \\ \text{interaction energy} \\ \text{of } \vec{j}_1 \text{ with } \vec{j}_2}} \right]$$

$$\begin{aligned} \mathcal{E}_{\text{int}} &= \frac{1}{4\pi} \int d^3r \vec{B}_1 \cdot \vec{B}_2 \\ &= \frac{1}{c} \int d^3r \vec{j}_1 \cdot \vec{A}_2 = \frac{1}{c} \int d^3r \vec{j}_2 \cdot \vec{A}_1 \end{aligned}$$

where $\vec{B}_1 = \vec{\nabla} \times \vec{A}_1$, $\vec{B}_2 = \vec{\nabla} \times \vec{A}_2$, by similar manipulations as earlier

integrals are over all space

Apply to the interaction energy of a magnetic dipole in an external \vec{B} field.

$$\mathcal{E}_{\text{int}} = \frac{1}{c} \int d^3r \underbrace{\vec{j}_1}_{\substack{\uparrow \\ \text{current distribution of dipole}}} \cdot \underbrace{\vec{A}_2}_{\substack{\uparrow \\ \text{vector potential of external } \vec{B} \text{ field}}}$$

Assuming \vec{A} varies slowly on length scale of \vec{j} , then expand $A_i(\vec{r}) = A_i(\vec{r}_0) + (\vec{r} - \vec{r}_0) \cdot \vec{\nabla} A_i(\vec{r}_0)$

$$\begin{aligned} \epsilon_{int} &= \frac{1}{c} \int d^3r \vec{j}_i \cdot \vec{A}(\vec{r}_0) \\ &+ \frac{1}{c} \int d^3r \sum_{i,j} j_{i,j} (r - r_0)_j \partial_j A_i(\vec{r}_0) \end{aligned}$$

Shift origin so origin at \vec{r}_0 \vec{r} now measures distance

From magnetostatic computation of magnetic dipole moment we had $\int d^3r \vec{j} = 0$ for magnetostatics

\Rightarrow 1st term above vanishes. So does the piece of 2nd term $\left(\int d^3r j_{i,j} \right) r_{0,j} \partial_j A_i(\vec{r}_0)$

We are left with

$$\epsilon_{int} = \left[\frac{1}{c} \int d^3r j_{i,j} r_j \right] \partial_j A_i(\vec{r}_0) \quad \begin{array}{l} \text{summation over} \\ \text{repeated indices} \\ \text{is implied} \end{array}$$

From computation of magnetic dipole approx we had

$$\int d^3r j_{i,j} r_j = - \int d^3r j_{i,j} r_i$$

Recall:

$$\vec{m} = \frac{1}{2c} \int d^3r \vec{r} \times \vec{j}$$

$$= \frac{1}{2} \int d^3r [j_{i,j} r_j - j_{i,j} r_i]$$

$$= \frac{1}{2} \epsilon_{kij} \int d^3r (\vec{j} \times \vec{r})_k$$

$$\Rightarrow \frac{1}{c} \int d^3r j_{i,j} r_i = - \epsilon_{kij} m_k \leftarrow \text{mag dipole moment}$$

$$\begin{aligned}
 E_{\text{int}} &= -m_k \varepsilon_{kij} \partial_j A_i = m_k \varepsilon_{kji} \partial_j A_i \\
 &= \vec{m} \cdot (\vec{\nabla} \times \vec{A}) = \vec{m} \cdot \vec{B} = E_{\text{int}}
 \end{aligned}$$

This is opposite in sign to what we found earlier!

Why the difference?

① When we integrate the work done against the magnetostatic force to move \vec{m} into position from infinity, we found the energy

$$U = -\vec{m} \cdot \vec{B}$$

② When we compute the interaction energy from

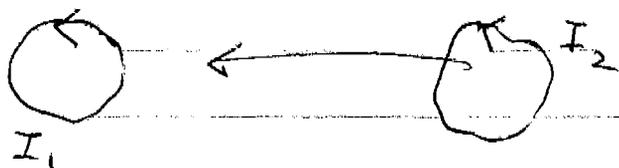
$$E_{\text{int}} = \frac{1}{c} \int d^3r \vec{j}_1 \cdot \vec{A}_2 = \frac{1}{c^2} \int d^3r \int d^3r' \frac{\vec{j}_1(\vec{r}) \cdot \vec{j}_2(\vec{r}')}{|\vec{r} - \vec{r}'|}$$

we find the energy $E_{\text{int}} = +\vec{m} \cdot \vec{B}$

To see which is correct, let us consider computing the interaction energy ② directly via method ①.

Consider two loops with currents I_1 and I_2

What is the work done to move loop 2 in from infinity to its final position with respect to loop 1?



Magnetostatic force on loop 2 due to loop 1 is

$$\vec{F} = \frac{I_2}{c} \oint_2 d\vec{l}_2 \times \vec{B}_1 \quad \begin{array}{l} \text{Lorentz force} \\ \vec{B}_1 \text{ is magnetic field from loop 1} \end{array}$$

$$\vec{B}_1(\vec{r}) = \frac{I_1}{c} \oint_1 \frac{d\vec{l}_1 \times (\vec{r} - \vec{r}_1)}{|\vec{r} - \vec{r}_1|^3} \quad \text{Biot-Savart law}$$

$$F = \frac{I_1 I_2}{c^2} \oint_2 \oint_1 d\vec{l}_2 \times \frac{d\vec{l}_1 \times (\vec{r}_2 - \vec{r}_1)}{|\vec{r}_2 - \vec{r}_1|^3}$$

Use triple product rule

$$\begin{aligned} d\vec{l}_2 \times [d\vec{l}_1 \times (\vec{r}_2 - \vec{r}_1)] \\ = d\vec{l}_1 [d\vec{l}_2 \cdot (\vec{r}_2 - \vec{r}_1)] - (\vec{r}_2 - \vec{r}_1) (d\vec{l}_1 \cdot d\vec{l}_2) \end{aligned}$$

from the 1st term

$$\oint_2 d\vec{l}_2 \cdot \frac{(\vec{r}_2 - \vec{r}_1)}{|\vec{r}_2 - \vec{r}_1|^3} = - \oint_2 d\vec{l}_2 \cdot \vec{\nabla}_2 \left(\frac{1}{|\vec{r}_2 - \vec{r}_1|} \right) = 0$$

as integral of gradient around closed loop always vanishes!

So

$$\vec{F} = -\frac{I_1 I_2}{c^2} \oint_1 \oint_2 d\vec{l}_1 \cdot d\vec{l}_2 \frac{(\vec{r}_2 - \vec{r}_1)}{|\vec{r}_2 - \vec{r}_1|^3}$$

write $\vec{r}_2 = \vec{R} + \delta\vec{r}_2$ where \vec{R} is center of loop 2

$$\text{use } \frac{\vec{R} + \delta\vec{r}_2 - \vec{r}_1}{|\vec{R} + \delta\vec{r}_2 - \vec{r}_1|^3} = -\vec{\nabla}_R \left(\frac{1}{|\vec{R} + \delta\vec{r}_2 - \vec{r}_1|} \right)$$

$$\vec{F} = \frac{I_1 I_2}{c^2} \oint_1 \oint_2 d\vec{l}_1 \cdot d\vec{l}_2 \vec{\nabla}_R \left(\frac{1}{|\vec{R} + \delta\vec{r}_2 - \vec{r}_1|} \right)$$

to move loop 2 we need to apply a ^{mechanical} force equal and opposite to the above magnetostatic force.

Therefore the work we do in moving loop 2 from infinity to its final position at \vec{R}_0 is

$$W_{\text{mech}} = - \int_{\infty}^{\vec{R}_0} \vec{F} \cdot d\vec{R} = - \frac{I_1 I_2}{c^2} \oint_1 \oint_2 d\vec{l}_1 \cdot d\vec{l}_2 \int_{\infty}^{\vec{R}_0} d\vec{R} \cdot \vec{\nabla}_R \left(\frac{1}{|\vec{R} + \delta\vec{r}_2 - \vec{r}_1|} \right)$$

$$= - \frac{I_1 I_2}{c^2} \oint_1 \oint_2 \frac{d\vec{l}_1 \cdot d\vec{l}_2}{|\vec{r}_2 - \vec{r}_1|} \quad \text{where } \vec{r}_2 = \vec{R}_0 + \delta\vec{r}_2$$

$$= - \frac{1}{c^2} \int d^3 r_1 \int d^3 r_2 \frac{\vec{j}_1(\vec{r}_1) \cdot \vec{j}_2(\vec{r}_2)}{|\vec{r}_2 - \vec{r}_1|}$$

Note the minus sign!

$$= -M_{12} I_1 I_2$$

↑ mutual inductance

why the minus sign!

this is just the negative of the interaction energy!!

The minus sign we have here is the same minus sign we got when we found $U = -\vec{m} \cdot \vec{B}$ by integrating the force on the magnetic dipoles.

Why don't we get
$$+ \frac{1}{c^2} \int d^3r_1 d^3r_2 \frac{\vec{J}_1(\vec{r}_1) \cdot \vec{J}_2(\vec{r}_2)}{|\vec{r}_2 - \vec{r}_1|}$$

with the plus sign we expect from $E = \frac{1}{8\pi} \int d^3r B^2$?

Answer: we have left something out!

Faraday's law - when we move loop 2, the magnetic flux through loop 2 changes. This $\frac{d\Phi}{dt}$ creates an emf $= \oint d\vec{l} \cdot \vec{E}$ around the loop that would tend to change the current in the loop. If we are to keep the current fixed at constant I_2 then there must be a battery in the loop that does work to counter this induced emf ("electromotive force"). Similarly, the flux through loop 1 is changing and a battery does work to keep I_1 constant. We need to add this work done by the batteries to the mechanical work computed above.

$$\begin{array}{l} \text{emf induced in loop 1} \\ \text{emf induced in loop 2} \end{array} \quad \begin{array}{l} \mathcal{E}_1 = \oint_1 d\vec{l}_1 \cdot \vec{E}_2 \\ \mathcal{E}_2 = \oint_2 d\vec{l}_2 \cdot \vec{E}_1 \end{array} \quad \left. \begin{array}{l} \text{integrations} \\ \text{in direction} \\ \text{of current} \end{array} \right\}$$

Faraday $\mathcal{E}_1 = -\frac{d\Phi_1}{c dt}$ $\Phi_1 = \text{flux through loop 1}$

$\mathcal{E}_2 = -\frac{d\Phi_2}{c dt}$ $\Phi_2 = \text{flux through loop 2}$

To keep the current constant, the batteries need to provide an emf that counters these Faraday induced emf's. The work done by the batteries per unit time is therefore

$$\frac{dW_{\text{battery}}}{dt} = -\mathcal{E}_1 I_1 - \mathcal{E}_2 I_2$$

(check units: $\mathcal{E}I$ is $[\text{length}] \cdot [E] \cdot [I/s]$
 $= [\text{length}] \cdot [\text{force}/s]$
 $= \text{energy}/s$)

$$\frac{dW_{\text{battery}}}{dt} = \frac{d\Phi_1}{cdt} I_1 + \frac{d\Phi_2}{cdt} I_2$$

$$W_{\text{battery}} = \int_0^T dt \left(\frac{d\Phi_1}{cdt} I_1 + \frac{d\Phi_2}{cdt} I_2 \right)$$

where $t=0$ loop 2 is at infinity
 $t=T$ loop 2 is at final position
 I_1, I_2 kept constant as loop moves

$$W_{\text{battery}} = \frac{1}{c} \Phi_1 I_1 + \frac{1}{c} \Phi_2 I_2 \quad \text{where } \Phi_1 \text{ and } \Phi_2$$

are fluxes in final position, and are assumed that fluxes = 0 at infinity

$$\Phi_1 = c M_{12} I_2$$

$$\Phi_2 = c M_{21} I_1 = c M_{12} I_1 \quad \text{as } M_{12} = M_{21}$$

$$\Rightarrow W_{\text{battery}} = 2 M_{12} I_1 I_2$$

add this to the mechanical work

$$W_{\text{total}} = W_{\text{mech}} + W_{\text{battery}} = -M_{12} I_1 I_2 + 2 M_{12} I_1 I_2$$
$$= M_{12} I_1 I_2 = + \frac{1}{c^2} \int d^3 r_1 d^3 r_2 \frac{\vec{j}_1(\vec{r}_1) \cdot \vec{j}_2(\vec{r}_2)}{|\vec{r}_1 - \vec{r}_2|}$$

we get back the correct interaction energy!

Conclusion : The magnetostatic interaction

energy $\frac{1}{c^2} \int d^3 r_1 d^3 r_2 \frac{\vec{j}_1(\vec{r}_1) \cdot \vec{j}_2(\vec{r}_2)}{|\vec{r}_1 - \vec{r}_2|}$

includes the work done to maintain the currents stationary as the current distributions move.

When we computed the interaction energy of a current loop dipole \vec{m} and find

$$E_{\text{int}} = +\vec{m} \cdot \vec{B}$$

this includes the energy needed to maintain the constant current producing the constant \vec{m}

When we integrated the force on the dipole to find the potential energy

$$U = -\vec{m} \cdot \vec{B}$$

this did not include the energy needed to maintain the constant current that creates \vec{m} .

This is the correct energy expression to use when \vec{m} comes from intrinsic magnetic moments due to particles intrinsic spin, which cannot be viewed as arising from a current loop!

Electromagnetic waves in a vacuum

No sources $\vec{j} = 0$, $\rho = 0$

$$\begin{array}{ll} 1) \quad \vec{\nabla} \cdot \vec{E} = 0 & 3) \quad \vec{\nabla} \cdot \vec{B} = 0 \\ 2) \quad \vec{\nabla} \times \vec{E} = -\frac{\partial \vec{B}}{\partial t} & 4) \quad \vec{\nabla} \times \vec{B} = \frac{1}{c} \frac{\partial \vec{E}}{\partial t} \end{array}$$

$$\vec{\nabla} \times (\vec{B}) \Rightarrow \vec{\nabla} \times (\vec{\nabla} \times \vec{E}) = \vec{\nabla} (\vec{\nabla} \cdot \vec{E}) - \nabla^2 \vec{E} = -\frac{\partial}{\partial t} (\vec{\nabla} \times \vec{B})$$

0'' by (1)

$$-\nabla^2 \vec{E} = -\frac{\partial}{\partial t} (\vec{\nabla} \times \vec{B}) = -\frac{\partial}{\partial t} \left(\frac{1}{c} \frac{\partial \vec{E}}{\partial t} \right)$$

$$\nabla^2 \vec{E} - \frac{1}{c^2} \frac{\partial^2 \vec{E}}{\partial t^2} = 0$$

Similarly

$$\nabla^2 \vec{B} - \frac{1}{c^2} \frac{\partial^2 \vec{B}}{\partial t^2} = 0$$

} wave equation
wave speed is c .

Note: in MKS units, above wave equation looks like

$$\nabla^2 \vec{E} - \epsilon_0 \mu_0 \frac{\partial^2 \vec{E}}{\partial t^2} = 0$$

It was noticed that the speed of electromagnetic wave,

$$\frac{1}{\sqrt{\epsilon_0 \mu_0}} = 3 \times 10^8 \text{ m/s} \text{ was the same as the speed of}$$

light! This observation was a key element in showing that light was in fact electromagnetic waves

Harmonic

Plane waves

$$\begin{aligned}\vec{E}(\vec{r}, t) &= \text{Re} \left[\vec{E}_k e^{i(\vec{k} \cdot \vec{r} - \omega t)} \right] \\ \vec{B}(\vec{r}, t) &= \text{Re} \left[\vec{B}_k e^{i(\vec{k} \cdot \vec{r} - \omega t)} \right]\end{aligned} \quad \left. \vphantom{\begin{aligned}\vec{E}(\vec{r}, t) \\ \vec{B}(\vec{r}, t)\end{aligned}} \right\} \text{complex exponential form}$$

\vec{k} is wave vector

ω is angular frequency

$\nu = \omega/2\pi$ is frequency

$T = 1/\nu$ is period

$\lambda = \frac{2\pi}{|\vec{k}|}$ is wavelength

$\left. \begin{aligned} |\vec{E}_k| \\ |\vec{B}_k| \end{aligned} \right\}$ is amplitude

$$\vec{E}(\vec{r} + \lambda \hat{k}, t) = \vec{E}(\vec{r}, t) \quad \text{periodic in space with period } \lambda$$

$$\vec{E}(\vec{r}, t + T) = \vec{E}(\vec{r}, t) \quad \text{periodic in time with period } T$$

"plane wave" $\Rightarrow \vec{E}(\vec{r}, t)$ is constant in space on planes with normal $\hat{m} \parallel \vec{k}$.

properties of EM plane waves

$$\begin{aligned}\vec{\nabla} \cdot \vec{E} = 0 &\Rightarrow \text{Re} \left[\vec{E}_k \cdot \vec{\nabla} e^{i(\vec{k} \cdot \vec{r} - \omega t)} \right] \\ &= \text{Re} \left[i \vec{E}_k \cdot \vec{k} e^{i(\vec{k} \cdot \vec{r} - \omega t)} \right] = 0 \\ &\Rightarrow \vec{E}_k \cdot \vec{k} = 0\end{aligned}$$

amplitude is orthogonal to \vec{k}

$$\vec{\nabla} \cdot \vec{B} = 0 \Rightarrow \vec{B}_k \cdot \vec{k} = 0$$

amplitude orthogonal to \vec{k}

$$\vec{\nabla} \times \vec{B} = \frac{1}{c} \frac{\partial \vec{E}}{\partial t}$$

$$\Rightarrow \operatorname{Re} \left[\vec{\nabla} \times \vec{B}_k e^{i(\vec{k} \cdot \vec{r} - \omega t)} \right] = \operatorname{Re} \left[\frac{1}{c} \vec{E}_k \frac{\partial}{\partial t} e^{i(\vec{k} \cdot \vec{r} - \omega t)} \right]$$

$$\Rightarrow \operatorname{Re} \left[-\vec{B}_k \times \vec{\nabla} e^{i(\vec{k} \cdot \vec{r} - \omega t)} \right] = \operatorname{Re} \left[-\frac{i\omega}{c} \vec{E}_k e^{i(\vec{k} \cdot \vec{r} - \omega t)} \right]$$

$$\Rightarrow \operatorname{Re} \left[i\vec{k} \times \vec{B}_k e^{i(\vec{k} \cdot \vec{r} - \omega t)} \right] = \operatorname{Re} \left[-\frac{i\omega}{c} \vec{E}_k e^{i(\vec{k} \cdot \vec{r} - \omega t)} \right]$$

$$\Rightarrow \vec{k} \times \vec{B}_k = -\frac{\omega}{c} \vec{E}_k$$

$$\vec{k} \times \vec{k} \times \vec{B}_k = -k^2 \vec{B}_k = -\frac{\omega}{c} \vec{k} \times \vec{E}_k$$

$$\underline{\underline{\vec{B}_k = \frac{\omega}{ck^2} \vec{k} \times \vec{E}_k}}$$

Finally

$$\nabla^2 E - \frac{1}{c^2} \frac{\partial^2 E}{\partial t^2} = 0$$

$$\Rightarrow \operatorname{Re} \left[\vec{E}_k \nabla^2 e^{i(\vec{k} \cdot \vec{r} - \omega t)} - \frac{\vec{E}_k}{c^2} \frac{\partial^2}{\partial t^2} e^{i(\vec{k} \cdot \vec{r} - \omega t)} \right] = 0$$

$$\Rightarrow \operatorname{Re} \left[\vec{E}_k (-k^2) e^{i(\vec{k} \cdot \vec{r} - \omega t)} + \frac{\omega^2}{c^2} \vec{E}_k e^{i(\vec{k} \cdot \vec{r} - \omega t)} \right] = 0$$

$$\Rightarrow k^2 = \frac{\omega^2}{c^2}$$

$$\boxed{\omega = \pm kc} \quad \underline{\underline{\text{dispersion relation}}}$$

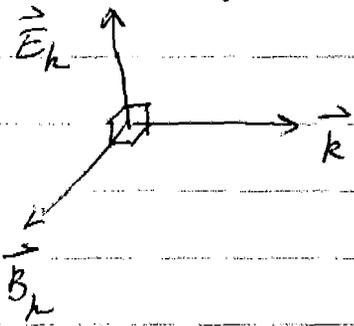
insert in above

$$\vec{B}_k = \hat{k} \times \vec{E}_k$$

$$\hat{k} = \frac{\vec{k}}{|\vec{k}|}$$

$$\Rightarrow |\vec{B}_k| = |\vec{E}_k|$$

Summary



$$\left. \begin{aligned} \vec{E}_k &\perp \vec{k} \\ \vec{B}_k &\perp \vec{k} \end{aligned} \right\} \text{"transverse" polarization}$$

$$\vec{B}_k = \hat{k} \times \vec{E}_k$$

$$\omega^2 = c^2 k^2$$

$|\vec{B}_k| = |\vec{E}_k| \Rightarrow$ Lorentz force from plane EM wave on charge q is

$$q \left(\vec{E} + \vec{v} \times \vec{B} \right)$$

magnetic force is smaller factor $\left(\frac{v}{c}\right)$ as compared to electric force - can usually be ignored

Most general solution is a linear superposition of the above ^{harmonic} plane waves

$$\vec{E}(\vec{r}, t) = \int \frac{d^3k}{(2\pi)^3} \vec{E}_k e^{i(\vec{k} \cdot \vec{r} - \omega t)} \quad \text{Fourier transform}$$

$$\vec{E}(\vec{r}, t) \text{ is real} \Rightarrow \vec{E}_k^* = \vec{E}_{-k}$$

For dispersion relation $\omega^2 = c^2 k^2$ we can write

$$\vec{k} \cdot \vec{r} - \omega t = \vec{k} \cdot (\vec{r} - \vec{v} t)$$

where $\vec{v} = c \hat{k}$ is velocity of wave. If we only combine waves traveling in same direction \hat{k} , then

$$\vec{E}(\vec{r}, t) = \int \frac{d^3k}{(2\pi)^3} \vec{E}_k e^{i\vec{k} \cdot (\vec{r} - \vec{v} t)} = \vec{E}(\vec{r} - \vec{v} t, 0)$$

The general ^{plane wave} solution of wave equation always has this property

$$\vec{E}(\vec{r}, t) = \vec{E}(\vec{r} - \vec{v} t, 0) \quad \text{If know } \vec{E} \text{ at } t=0, \text{ then know } \vec{E} \text{ at all times } t$$

Energy & momentum in EM wave

$$\begin{aligned}\vec{E} &= \text{Re} [\vec{E}_k e^{i(\vec{k}\cdot\vec{r}-\omega t)}] = \vec{E}_k \cos(\vec{k}\cdot\vec{r}-\omega t) \\ \vec{B} &= \text{Re} [\vec{B}_k e^{i(\vec{k}\cdot\vec{r}-\omega t)}] = \hat{k} \times \vec{E}_k \cos(\vec{k}\cdot\vec{r}-\omega t)\end{aligned} \left. \vphantom{\begin{aligned}\vec{E} \\ \vec{B}\end{aligned}} \right\} \begin{array}{l} \text{for} \\ \text{real} \\ \vec{E}_k \end{array}$$

energy density $u = \frac{1}{8\pi} (E^2 + B^2)$

$$= \frac{1}{8\pi} [E_k^2 + E_k^2] \cos^2(\vec{k}\cdot\vec{r}-\omega t)$$

$$= \frac{1}{4\pi} E_k^2 \cos^2(\vec{k}\cdot\vec{r}-\omega t)$$

Poynting vector

energy current

$$\vec{S} = \frac{c}{4\pi} \vec{E} \times \vec{B}$$

$$= \frac{c}{4\pi} [\vec{E}_k \times (\hat{k} \times \vec{E}_k)] \cos^2(\vec{k}\cdot\vec{r}-\omega t)$$

$$= \frac{c}{4\pi} \hat{k} E_k^2 \cos^2(\vec{k}\cdot\vec{r}-\omega t)$$

$$\vec{S} = c u \hat{k}$$

momentum density $\vec{\pi} = \frac{1}{c^2} \vec{S} = \frac{u}{c} \hat{k}$

$$u = c |\vec{\pi}| \quad - \text{energy momentum relation of photons!}$$

For visible light $\lambda \sim 5 \times 10^{-7} \text{ m} \sim 5000 \text{ \AA}$

$$T = \frac{\lambda}{c} = 1.6 \times 10^{-15} \text{ sec}$$

most classical measurements on microscopic scales $t \gg T$, $l \gg \lambda$

measure average quantities

$$\langle u \rangle = \frac{1}{T} \int_0^T dt u = \frac{1}{8\pi} E_k^2 \quad \text{as } \langle \cos^2 \theta \rangle = \frac{1}{2}$$

$$\langle \vec{S} \rangle = c \langle u \rangle \hat{k}$$

$$\langle \vec{\Pi} \rangle = \frac{1}{c} \langle u \rangle \hat{k}$$

intensity = average power per area transported by wave through surface with normal \hat{m}

$$I = \langle \vec{S} \rangle \cdot \hat{m}$$

Electromagnetic waves in matter

Macroscopic Maxwell equations with no sources
("free" charge and current vanishes)

$$\begin{aligned}\vec{\nabla} \cdot \vec{D} &= 0 & \vec{\nabla} \times \vec{H} &= \frac{1}{c} \frac{\partial \vec{D}}{\partial t} \\ \vec{\nabla} \cdot \vec{B} &= 0 & \vec{\nabla} \times \vec{E} &= -\frac{1}{c} \frac{\partial \vec{B}}{\partial t}\end{aligned}$$

linear materials

$$\begin{aligned}\vec{B} &= \mu \vec{H} \\ \vec{D} &= \epsilon \vec{E}\end{aligned}$$

if μ and ϵ were simply constants then the above would become

$$\begin{aligned}\vec{\nabla} \cdot \vec{E} &= 0 & \vec{\nabla} \times \vec{B} &= \frac{\mu \epsilon}{c} \frac{\partial \vec{E}}{\partial t} \\ \vec{\nabla} \cdot \vec{B} &= 0 & \vec{\nabla} \times \vec{E} &= -\frac{1}{c} \frac{\partial \vec{B}}{\partial t}\end{aligned}$$

Then

$$\begin{aligned}\vec{\nabla} \times (\vec{\nabla} \times \vec{E}) &= -\nabla^2 \vec{E} = -\frac{1}{c} \frac{\partial}{\partial t} (\vec{\nabla} \times \vec{B}) \\ &= -\frac{1}{c} \frac{\partial}{\partial t} \left(\frac{\mu \epsilon}{c} \frac{\partial \vec{E}}{\partial t} \right) \\ &= -\frac{\mu \epsilon}{c^2} \frac{\partial^2 \vec{E}}{\partial t^2}\end{aligned}$$

wave equation with wave speed $\frac{c}{\sqrt{\mu \epsilon}} < c$

This would be very much as for waves in a vacuum, except for the following minor

changes:

$$\omega^2 = \frac{c^2 k^2}{\mu \epsilon}$$

dispersion relation
changed by constant
factor

$$\begin{aligned}\vec{E}_k &\perp \vec{k} \\ \vec{B}_k &\perp \vec{k}\end{aligned}$$

$$i \vec{k} \times \vec{E}_k = i \omega \vec{B}_k$$

$$\frac{c |\vec{k}|}{\omega} \hat{k} \times \vec{E}_k = \vec{B}_k$$

$$\Rightarrow \sqrt{\mu \epsilon} \hat{k} \times \vec{E}_k = \vec{B}_k \quad |\vec{B}_k| > |\vec{E}_k|$$

wave speed $v = \frac{c}{\sqrt{\mu \epsilon}} < c$

In general however things are much more complicated
because ϵ cannot be viewed as a constant
when considering time varying behavior!