

Equation for potentials in Lorentz gauge

$$\left(\nabla^2 - \frac{1}{c^2} \frac{\partial^2}{\partial t^2}\right) \vec{A} = -\frac{4\pi}{c} \vec{j}$$

$$\left(\nabla^2 - \frac{1}{c^2} \frac{\partial^2}{\partial t^2}\right) \phi = -4\pi \rho$$

$$\frac{\partial^2}{\partial x_\mu^2} = \left(\nabla^2 - \frac{1}{c^2} \frac{\partial^2}{\partial t^2}\right) \text{ is Lorentz invariant operator}$$

4-potential

$$A_\mu = (\vec{A}, i\phi)$$

$$\left(\nabla^2 - \frac{1}{c^2} \frac{\partial^2}{\partial t^2}\right) A_\mu = -\frac{4\pi}{c} j_\mu = \frac{\partial^2 A_\mu}{\partial x_\mu^2}$$

Lorentz gauge condition is

$$\vec{\nabla} \cdot \vec{A} + \frac{\partial \phi}{c \partial t} = \frac{\partial A_\mu}{\partial x_\mu} = 0$$

Electric and magnetic fields

$$B_i = \frac{\partial A_k}{\partial x_j} - \frac{\partial A_j}{\partial x_k} \quad \text{E, j, k cyclic permutation of 1, 2, 3}$$

$$E_i = -\frac{\partial \phi}{\partial x_i} - \frac{\partial A_i}{c \partial t} = c \left(\frac{\partial A_4}{\partial x_i} - \frac{\partial A_i}{\partial x_4} \right)$$

Define field stress tensor

$$F_{\mu\nu} = \frac{\partial A_\nu}{\partial x_\mu} - \frac{\partial A_\mu}{\partial x_\nu} = -F_{\nu\mu}$$

$$= \begin{pmatrix} 0 & B_3 & -B_2 & -iE_1 \\ -B_3 & 0 & B_1 & -iE_2 \\ B_2 & -B_1 & 0 & -iE_3 \\ iE_1 & iE_2 & iE_3 & 0 \end{pmatrix}$$

"curl" of a 4-vector
is a 4x4 anti
symmetric 2nd rank tensor

Inhomogeneous Maxwell's equations can be written in the form

$$\boxed{\frac{\partial F_{\mu\nu}}{\partial x_\nu} = \frac{4\pi}{c} j_\mu} \Rightarrow \left[\begin{array}{l} \vec{\nabla} \cdot \vec{E} = 4\pi \rho \\ \vec{\nabla} \times \vec{B} - \frac{1}{c} \frac{\partial \vec{E}}{\partial t} = \frac{4\pi}{c} \vec{j} \end{array} \right]$$

$$= \frac{\partial}{\partial x_\nu} \left(\frac{\partial A_\nu}{\partial x_\mu} - \frac{\partial A_\mu}{\partial x_\nu} \right) = \frac{\partial}{\partial x_\mu} \left(\frac{\partial A_\nu}{\partial x_\nu} \right) - \frac{\partial^2 A_\mu}{\partial x_\nu^2}$$

"0"

$$\Rightarrow - \frac{\partial^2 A_\mu}{\partial x_\nu^2} = \frac{4\pi}{c} j_\mu \quad \text{agrees with previous equation for } A_\mu$$

transformation law for 2nd rank tensor $F_{\mu\nu}$

$$\begin{aligned} F'_{\mu\nu} &= \frac{\partial A'_\nu}{\partial x'^\mu} - \frac{\partial A'_\mu}{\partial x'^\nu} && \text{use } A'_\mu = a_{\mu\sigma} A_\sigma \\ &= a_{\nu\lambda} a_{\mu\sigma} \frac{\partial A_\lambda}{\partial x^\sigma} && \frac{\partial}{\partial x'^\mu} = a_{\mu\lambda} \frac{\partial}{\partial x^\lambda} \\ &\quad - a_{\mu\sigma} a_{\nu\lambda} \frac{\partial A_\sigma}{\partial x^\lambda} \end{aligned}$$

$$F'_{\mu\nu} = a_{\mu\sigma} a_{\nu\lambda} F_{\sigma\lambda}$$

For n^{th} rank tensor

lets one find \vec{E}' and \vec{B}'
if one knows \vec{E} and \vec{B}

$$T'_{\mu_1 \mu_2 \dots \mu_n} = a_{\mu_1 \nu_1} a_{\mu_2 \nu_2} \dots a_{\mu_n \nu_n} T_{\nu_1 \nu_2 \dots \nu_n}$$

$\frac{\partial F_{\mu\nu}}{\partial x_\nu}$ is a 4-vector: proof:

$$\frac{\partial F'_{\mu\nu}}{\partial x'_\nu} = a_{\mu\sigma} a_{\nu\lambda} a_{\nu\gamma} \frac{\partial F_{\sigma\lambda}}{\partial x_\gamma}$$

but $a_{\nu\lambda} = a_{\lambda\nu}^{-1}$ since inverse = transpose
 $a_{\nu\lambda} a_{\nu\gamma} = a_{\lambda\nu}^{-1} a_{\nu\gamma} = \delta_{\lambda\gamma}$

$$\frac{\partial F'_{\mu\nu}}{\partial x'_\nu} = a_{\mu\sigma} \frac{\partial F_{\sigma\lambda}}{\partial x_\lambda} \delta_{\lambda\gamma} = a_{\mu\sigma} \frac{\partial F_{\sigma\lambda}}{\partial x_\lambda}$$

transforms like 4-vector

To write the homogeneous Maxwell Equations

Construct 3rd rank co-variant tensor

$$G_{\mu\nu\lambda} = \frac{\partial F_{\mu\nu}}{\partial x_\lambda} + \frac{\partial F_{\lambda\mu}}{\partial x_\nu} + \frac{\partial F_{\nu\lambda}}{\partial x_\mu}$$

transforms as $G'_{\mu\nu\lambda} = a_{\mu\alpha} a_{\nu\beta} a_{\lambda\gamma} G_{\alpha\beta\gamma}$

in principle G has $4^3 = 64$ components

But can show that G is antisymmetric in exchange of any two indices

$$\begin{aligned} G_{\nu\mu\lambda} &= \frac{\partial F_{\nu\mu}}{\partial x_\lambda} + \frac{\partial F_{\lambda\nu}}{\partial x_\mu} + \frac{\partial F_{\mu\lambda}}{\partial x_\nu} \\ &= -\frac{\partial F_{\mu\nu}}{\partial x_\lambda} - \frac{\partial F_{\nu\lambda}}{\partial x_\mu} - \frac{\partial F_{\lambda\mu}}{\partial x_\nu} \quad \text{as } F \text{ antisymmetric} \\ &= -G_{\mu\nu\lambda} \end{aligned}$$

also $G_{\mu\nu\lambda} = 0$ if any two indices are equal

\Rightarrow only 4 independent components

$$G_{012}, G_{013}, G_{023}, G_{123}$$

all other components either vanish or are \pm one of the above.

The 4 homogeneous Maxwell Equations:

$$\vec{\nabla} \cdot \vec{B} = 0, \quad \vec{\nabla} \times \vec{E} + \frac{1}{c} \frac{\partial \vec{B}}{\partial t} = 0$$

can be written as

$$\boxed{G_{\mu\nu\lambda} = 0}$$

to see, substitute in definition of G the definition of F

$$G_{\mu\nu\lambda} = \frac{\partial^2 A_\nu}{\partial x_\lambda \partial x_\mu} - \frac{\partial^2 A_\mu}{\partial x_\lambda \partial x_\nu} + \frac{\partial^2 A_\mu}{\partial x_\nu \partial x_\lambda} - \frac{\partial^2 A_\lambda}{\partial x_\nu \partial x_\mu} + \frac{\partial^2 A_\lambda}{\partial x_\mu \partial x_\nu} - \frac{\partial^2 A_\nu}{\partial x_\mu \partial x_\lambda}$$

all terms cancel in pairs

$$= 0$$

$$G_{123} = 0 \Rightarrow \vec{\nabla} \cdot \vec{B} = 0$$

$$G_{012} = -i \left[\vec{\nabla} \times \vec{E} + \frac{\partial \vec{B}}{c \partial t} \right]_3 = 0 \quad \text{3 component Faraday's law}$$

Another way to write homogeneous Maxwell Equations

Define $\epsilon_{\mu\nu\lambda\sigma}$ = $\left\{ \begin{array}{ll} +1 & \text{if } \mu\nu\lambda\sigma \text{ is even permutation} \\ & \text{of } 1234 \\ -1 & \text{if } \mu\nu\lambda\sigma \text{ is odd permutation} \\ & \text{of } 1234 \\ 0 & \text{otherwise} \end{array} \right.$

4-d Levi-Civita symbol

Define $\tilde{F}_{\mu\nu} = \frac{1}{2i} \epsilon_{\mu\nu\lambda\sigma} F_{\lambda\sigma}$ pseudo-tensor

has wrong sign
under parity
transf

$$= \begin{pmatrix} 0 & -E_3 & E_2 & -iB_1 \\ E_3 & 0 & -E_1 & -iB_2 \\ -E_2 & E_1 & 0 & -iB_3 \\ iB_1 & iB_2 & iB_3 & 0 \end{pmatrix}$$

$\frac{\partial \tilde{F}_{\mu\nu}}{\partial x_\nu} = 0$ gives homogeneous Maxwell equations

$\left. \begin{array}{l} \frac{1}{2} F_{\mu\nu} F_{\mu\nu} = B^2 - E^2 \\ -\frac{1}{4} F_{\mu\nu} \tilde{F}_{\mu\nu} = \vec{B} \cdot \vec{E} \end{array} \right\}$ Lorentz invariant scalars

From $F_{\mu\nu} = a_{\mu\sigma} a_{\nu\lambda} F_{\sigma\lambda}$ we can get
Lorentz transf for \vec{E} and \vec{B}

For a transformation from K to K' with K' moving
with v along x , with respect to K ,

$$\begin{aligned} E'_1 &= E_1 & B'_1 &= B_1 \\ E'_2 &= \gamma (E_2 - \frac{v}{c} B_3) & B'_2 &= \gamma (B_2 + \frac{v}{c} E_3) \\ E'_3 &= \gamma (E_3 + \frac{v}{c} B_2) & B'_3 &= \gamma (B_3 - \frac{v}{c} E_2) \end{aligned}$$

Kinematics

"dot" is $\frac{d}{ds}$

4-momentum $p_\mu = m \dot{x}_\mu = m u_\mu = (m\gamma \vec{v}, i m c \gamma)$

$$p_\mu^2 = m^2 u_\mu^2 = -m^2 c^2$$

4-force $K_\mu = (\vec{K}, i K_0)$ "Minkowski force"

Newton's 2nd law:

$$m \frac{d^2 x_\mu}{ds^2} = K_\mu$$

$$\Rightarrow m \frac{d u_\mu}{ds} = \frac{d p_\mu}{ds} = K_\mu$$

$$p_\mu^2 = -m^2 c^2 \Rightarrow \frac{d}{ds} (p_\mu^2) = p_\mu \frac{d p_\mu}{ds} = p_\mu K_\mu = 0$$

$$\Rightarrow m\gamma \vec{v} \cdot \vec{K} - m c \gamma K_0 = 0 \quad \text{or}$$

$$K_0 = \frac{\vec{v}}{c} \cdot \vec{K}$$

Define the usual 3-force by

$$\frac{d\vec{p}}{dt} = \vec{F}$$

(we identify Newtonian momentum \vec{p} with the space components of \vec{p}_μ)

$$\frac{d\vec{p}}{ds} = \vec{K} \quad \text{and} \quad \frac{d\vec{p}}{ds} = \gamma \frac{d\vec{p}}{dt} = \gamma \vec{F} \quad \Rightarrow \quad \vec{K} = \gamma \vec{F}$$

$$K_0 = \gamma \frac{\vec{v}}{c} \cdot \vec{F}$$

Consider 4th component of Newton's eqn

$$m \frac{d}{ds} u_4 = m \frac{d}{ds} (ic\gamma) = iK_0 = i\gamma \frac{\vec{v}}{c} \cdot \vec{F}$$

$$d(m\gamma) = \gamma \frac{\vec{v}}{c^2} \cdot \vec{F} ds = \frac{dt}{c^2} \vec{v} \cdot \vec{F} = \frac{d\vec{r} \cdot \vec{F}}{c^2}$$

Work-energy theorem: $d(m\gamma c^2) = d\vec{r} \cdot \vec{F} = \text{work done}$

$\Rightarrow d(m\gamma c^2)$ is change in kinetic energy

$E = m\gamma c^2$ is relativistic kinetic energy

$$\boxed{\vec{p}_\mu = \left(\vec{p}, \frac{iE}{c} \right) \quad \begin{array}{l} \vec{p} = m\gamma \vec{v} \\ E = m\gamma c^2 \end{array}}$$

$$E = \frac{mc^2}{\sqrt{1 - \frac{v^2}{c^2}}} \approx mc^2 \left(1 + \frac{1}{2} \frac{v^2}{c^2} \right) = mc^2 + \frac{1}{2} m v^2$$

\uparrow small $\frac{v}{c}$
 \uparrow rest mass energy
 \uparrow non-rel kinetic energy

$\frac{d\vec{p}_\mu}{ds} = K_\mu$ is therefore relativistic analog of Newton's 3rd law as well as law of conservation of energy

Lorentz force

$$\frac{dp_\mu}{ds} = K_\mu$$

What is the K_μ that represents the Lorentz force and how can we write it in ~~relativistic~~ Lorentz covariant way?

K_μ should depend on the fields $F_{\mu\nu}$ and the particles trajectory x_μ

$$\text{as } \vec{v} \rightarrow 0 \quad \vec{K} = q \vec{E}$$

K_μ can't depend directly on x_μ as should be indep of origin of coords. So can depend only on $\dot{x}_\mu, \ddot{x}_\mu, \dots$, etc.

as $v \rightarrow 0$, K does not depend on the acceleration, so K does not depend on \ddot{x}_μ

K_μ only depends on $F_{\mu\nu}$ and \dot{x}_μ
we need to form a 4-vector out of $F_{\mu\nu}$ and \dot{x}_μ that is linear in the fields $F_{\mu\nu}$ and proportional to the charge q .

The only possibility is

$$q f(x_\mu^2) F_{\mu\nu} \dot{x}_\nu$$

But $\dot{x}_\mu^2 = -c^2$ is a constant. Choose $f(x_\mu^2) = \frac{1}{c}$

$K_\mu = \frac{q}{c} F_{\mu\nu} \dot{x}_\nu$ is only possibility

This gives force

$$\vec{F} = \frac{1}{\gamma} \vec{K}$$

$$F_i = \frac{1}{\gamma} K_i = \frac{q}{\gamma c} (F_{ij} \dot{x}_j + F_{i4} \dot{x}_4)$$

$$= \frac{q}{\gamma c} \left(\frac{\partial A_j}{\partial x_i} - \frac{\partial A_i}{\partial x_j} \right) \dot{x}_j + \frac{q}{\gamma c} (-iE_i)(ic\gamma)$$

$$= \frac{q}{\gamma c} \left[\epsilon_{ijk} B_k \gamma v_j \right] + \frac{q}{\gamma c} E_i c \gamma$$

$$= q E_i + q \epsilon_{ijk} \frac{v_j}{c} B_k$$

$$\vec{F} = q \vec{E} + q \frac{\vec{v}}{c} \times \vec{B}$$

Lorentz force is the same form in all inertial frames.
No relativistic modification is needed.

Relativistic Larmor's formula

non-relativistic $\mathcal{P} = \frac{2}{3} \frac{q^2 [a(t_0)]^2}{c^3}$

Consider inertial frame in which charge is instantaneously at rest. Call the rest frame K' .

power radiated in K' is $\mathcal{P}' = \frac{d\mathcal{E}'(t')}{dt'}$

where \mathcal{E}' is energy radiated. In K' , the momentum density $\vec{\Pi}' = \frac{1}{4\pi c} \vec{E}' \times \vec{B}' \sim \hat{r}'$ is in outward radial direction. Integrating over all directions, the radiated momentum vanishes $\vec{P}' = 0$

energy-momentum is a 4-vector $(\vec{P}', \frac{i\mathcal{E}'}{c})$

To get radiated energy in original frame K we can use Lorentz transf

$$\frac{\mathcal{E}}{c} = \gamma \left(\frac{\mathcal{E}'}{c} - \vec{v} \cdot \vec{P}' \right) \Rightarrow \mathcal{E} = \gamma \mathcal{E}' \text{ as } \vec{P}' = 0$$

and $dt = \gamma dt'$ is time interval in K
($d\vec{r}' = 0$ as charge stays at origin in K')

$$\text{So } \frac{d\mathcal{E}}{dt} = \frac{\gamma d\mathcal{E}'}{\gamma dt'} = \frac{d\mathcal{E}'}{dt'} \Rightarrow \mathcal{P} = \mathcal{P}'$$

radiated power is Lorentz invariant!

in K^0 we can use non-relativistic Larmor's formula since $v=0$. So

$$P = \frac{2}{3} \frac{q^2 a^2}{c^3} \quad \text{a is acceleration in } K^0$$

To write an expression without explicitly making mention of frame K^0 , we need to find a Lorentz invariant scalar that reduces to a^2 as $v \rightarrow 0$.

Only choice is α_μ^2 the 4-acceleration $\alpha_\mu = \frac{d u_\mu}{ds}$

$$\alpha_\mu = \frac{d u_\mu}{ds} = \gamma \frac{d u_\mu}{dt} = \gamma \frac{d}{dt} (\gamma \vec{v}, c\gamma)$$

$$\vec{\alpha} = \gamma^2 \frac{d\vec{v}}{dt} + \gamma \vec{v} \frac{d\gamma}{dt}$$

$$\alpha_4 = ic \gamma \frac{d\gamma}{dt}$$

$$\frac{d\gamma}{dt} = \frac{d}{dt} \left(\frac{1}{\sqrt{1-v^2/c^2}} \right) = \frac{\frac{v \cdot d\vec{v}}{c^2} \frac{d\vec{v}}{dt}}{(1-v^2/c^2)^{3/2}} = \frac{1}{c^2} \gamma^3 \vec{v} \cdot \vec{a}$$

$$\text{as } \vec{v} \rightarrow 0, \quad \gamma \rightarrow 1, \quad \frac{d\gamma}{dt} \rightarrow 0, \quad \text{so } \begin{cases} \vec{\alpha} \rightarrow \frac{d\vec{v}}{dt} = \vec{a} \\ \alpha_4 \rightarrow 0 \end{cases}$$

$$\alpha_\mu^2 \rightarrow |\vec{a}|^2 \quad \text{as desired}$$

Relativistic Larmor's formula

$$P = \frac{2}{3} \frac{q^2}{c^3} \alpha_\mu^2 = \frac{2}{3} \frac{q^2}{c^3} (\dot{u}_\mu)^2$$

$$\alpha_\mu = \left(\gamma^2 \frac{d\vec{v}}{dt} + \gamma \vec{v} \frac{d\gamma}{dt}, \quad i c \gamma \frac{d\gamma}{dt} \right)$$

$$\frac{d\gamma}{dt} = \frac{1}{c^2} \gamma^3 \vec{v} \cdot \vec{a}$$

$$\alpha_\mu = \left(\gamma^2 \vec{a} + \gamma^4 \frac{1}{c^2} (\vec{v} \cdot \vec{a}) \vec{v}, \quad i c \frac{\gamma^4}{c^2} \vec{v} \cdot \vec{a} \right)$$

$$\alpha_\mu^2 = \gamma^4 a^2 + \gamma^8 \frac{(\vec{v} \cdot \vec{a})^2}{c^4} v^2 + \frac{2\gamma^6}{c^2} (\vec{v} \cdot \vec{a})^2 - \frac{\gamma^8}{c^2} (\vec{v} \cdot \vec{a})^2$$

$$= \gamma^4 \left[a^2 + \gamma^4 \frac{(\vec{v} \cdot \vec{a})^2}{c^2} \left(\frac{v^2}{c^2} - 1 \right) + \frac{2\gamma}{c^2} (\vec{v} \cdot \vec{a})^2 \right]$$

$$= \gamma^4 \left[a^2 - \gamma^2 \frac{(\vec{v} \cdot \vec{a})^2}{c^2} + \frac{2\gamma^2 (\vec{v} \cdot \vec{a})^2}{c^2} \right]$$

$$\alpha_\mu^2 = \gamma^4 \left[a^2 + \gamma^2 \frac{(\vec{v} \cdot \vec{a})^2}{c^2} \right]$$

as $\vec{v} \rightarrow 0$, $\alpha_\mu^2 \rightarrow a^2$

$$\alpha_\mu^2 = \dot{a}^2 \quad \text{Lorentz invariant}$$

\dot{a} = acceleration in instantaneous rest frame

For a charge accelerating in linear motion, $(\vec{v} \cdot \vec{a})^2 = v^2 a^2$

$$\alpha_\mu^2 = \gamma^4 a^2 \left(1 + \gamma^2 \frac{v^2}{c^2} \right) = \gamma^6 a^2$$

$$P = \frac{2}{3} \frac{a^2}{c^3} \gamma^6 = \frac{2}{3} \frac{a^2}{c^3} \gamma^2$$

For a charge in circular motion $(\vec{v} \cdot \vec{a}) = 0$

$$\alpha_\mu^2 = \gamma^4 a^2$$

$$P = \frac{2}{3} \frac{a^2}{c^3} \gamma^4$$