

Quadrupole term more generally

$$\phi_{\text{quad}} = \frac{\hat{r} \cdot \overleftrightarrow{Q} \cdot \hat{r}}{2r^3}$$

since \overleftrightarrow{Q} is a symmetric tensor, there is always some coordinate system in which it is diagonal. Let's work in that coordinate system. Then

$$\overleftrightarrow{Q} = \begin{pmatrix} Q_1 & 0 & 0 \\ 0 & Q_2 & 0 \\ 0 & 0 & Q_3 \end{pmatrix}$$

let us take \hat{z} axis as the axis with the largest Q_i

so $Q_3 \geq Q_1, Q_2$

in this coord system $\hat{r} = (\sin\theta\cos\varphi, \sin\theta\sin\varphi, \cos\theta)$

$$\hat{r} \cdot \overleftrightarrow{Q} \cdot \hat{r} = Q_1 \sin^2\theta \cos^2\varphi + Q_2 \sin^2\theta \sin^2\varphi + Q_3 \cos^2\theta$$

this gives the angular variation of ϕ_{quad} as the direction of the observer varies.

let us consider now averaging this over all directions

$$\frac{1}{4\pi} \int_0^\pi d\theta \sin\theta \int_0^{2\pi} d\varphi \left[Q_1 \sin^2\theta \cos^2\varphi + Q_2 \sin^2\theta \sin^2\varphi + Q_3 \cos^2\theta \right]$$

$$= \frac{1}{4\pi} \int_0^\pi d\theta \sin\theta \left[\pi Q_1 \sin^2\theta + \pi Q_2 \sin^2\theta + 2\pi Q_3 \cos^2\theta \right]$$

$$= \frac{1}{4} \int_0^\pi d\theta \sin\theta \left[(Q_1 + Q_2) \sin^2\theta + 2Q_3 \cos^2\theta \right]$$

$$= \frac{1}{4} (Q_1 + Q_2) \int_0^\pi d\theta \sin^3\theta + \frac{1}{2} Q_3 \int_0^\pi d\theta \sin\theta \cos^2\theta$$

$$\text{Now } \int_0^\pi d\theta \sin\theta \cos^2\theta = \left. \frac{-\cos^3\theta}{3} \right|_0^\pi = \frac{2}{3}$$

$$\int_0^\pi d\theta \sin^3\theta = \int_0^\pi d\theta \sin\theta (1 - \cos^2\theta)$$
$$= \int_0^\pi d\theta \sin\theta - \frac{2}{3} = \left. -\cos\theta \right|_0^\pi - \frac{2}{3}$$

$$= 2 - \frac{2}{3} = \frac{4}{3}$$

So angular average of $\vec{r} \cdot \vec{Q} \cdot \vec{r}$

$$= \frac{1}{4}(Q_1 + Q_2) \frac{4}{3} + \frac{1}{2} Q_3 \frac{2}{3} = \frac{1}{3}(Q_1 + Q_2 + Q_3)$$

$$= \frac{1}{3} \text{trace}[\vec{Q}]$$

But we know $\text{trace}[\vec{Q}] = 0$

\Rightarrow angular average of ϕ_{quad} always vanishes for any charge distribution!

$$\phi(\vec{r}) = \frac{q}{r} + \frac{\vec{p} \cdot \hat{r}}{r^2} + \frac{\hat{r} \cdot \vec{Q} \cdot \hat{r}}{2r^3} + \dots$$

Note, in each term the dependence on $r = |\vec{r}|$ is only in the denominator. The numerators depend on the orientation of \vec{r} via $\hat{r} = \frac{\vec{r}}{|\vec{r}|}$. So we can write

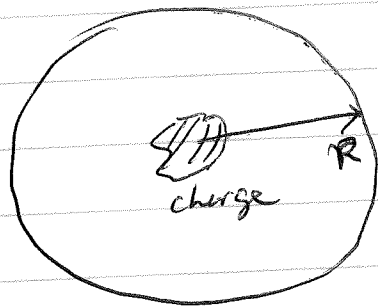
$$\phi(\vec{r}) = \frac{q}{r} + \sum_{n=2}^{\infty} \frac{f_n(\theta, \varphi)}{r^n}$$

where $f_n(\theta, \varphi)$ gives the dependence on the orientation of \vec{r}

Now we show that the angular average of $f_n(\theta, \varphi)$ must vanish, i.e. $\int_0^\pi d\theta \sin\theta \int_0^{2\pi} d\varphi f_n(\theta, \varphi) = 0$

Consider the corresponding electric field $\vec{E} = -\vec{\nabla}\phi$

$$\vec{E} = q \frac{\hat{r}}{r^2} + \sum_{n=2}^{\infty} \vec{\nabla} \left(\frac{f_n(\theta, \varphi)}{r^n} \right)$$



consider a sphere of radius R centered on the charge distribution. Let S be the surface of this sphere. We know that

$$\oint_S da \hat{n} \cdot \vec{E} = 4\pi Q_{\text{enclosed}} = 4\pi q R \quad \text{monopole moment}$$

$$\text{Since } \oint_S da \hat{n} \cdot q \frac{\hat{r}}{r^2} = \oint_S da \frac{q}{r^2}$$

$$= 4\pi R^2 \frac{q}{R^2} = 4\pi q$$

since $\hat{n} = \hat{r}$

So monopole term gives all the flux of \vec{E} through the surface, and the flux of the higher terms must give zero. Since this ~~can~~ must be true for any radius R , it can only be true if each term individually gives zero flux, i.e.

$$-\oint_S da \hat{r} \cdot \vec{\nabla} \left(\frac{f_n(\theta, \varphi)}{r^n} \right) = 0$$

but $\hat{r} \cdot \vec{\nabla} = \frac{\partial}{\partial r}$ radial directional derivative
 so above is

$$-\oint_S da \frac{\partial}{\partial r} \left(\frac{f_n(\theta, \varphi)}{r^n} \right) = n \oint_S da \frac{f_n(\theta, \varphi)}{r^{n+1}}$$

$$= \frac{n}{R^{n+1}} \oint_S da f_n(\theta, \varphi) \quad \text{since } r=R \text{ on } S$$

$$= \frac{n}{R^{n+1}} R^2 \int_0^\pi d\theta \sin\theta \int_0^{2\pi} d\varphi f_n(\theta, \varphi) = 0$$

$$\text{so } \int_0^\pi d\theta \sin\theta \int_0^{2\pi} d\varphi f_n(\theta, \varphi) = 0$$

So the n -th moment contribution to Φ

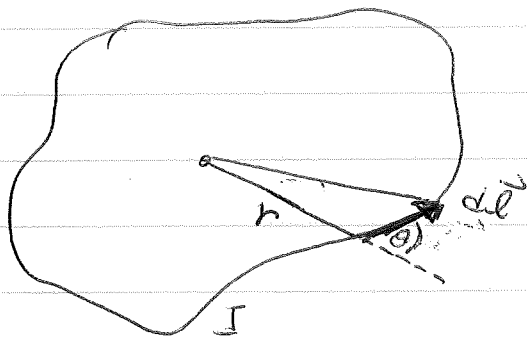
$$\Phi^{(n)} = \frac{f_n(\theta, \varphi)}{r^n} \quad \text{vanishes if we take an angular average.}$$

$$\vec{B} = \frac{3(\vec{m} \cdot \hat{r})\hat{r} - \vec{m}}{r^3}$$

same form as \vec{E} from electric dipole \vec{p}

For a current loop in a plane (any shape loop provided it is flat)

$$\vec{m} = \frac{1}{2c} \int d^3x \vec{r} \times \vec{j} = \frac{1}{2c} I \oint \vec{r} \times d\vec{l}$$



area of triangle is $\frac{1}{2} r dl \sin \theta$
 $= \frac{1}{2} |\vec{r} \times d\vec{l}|$



area of ~~rectangle~~ ^{parallelogram} is $r dl \sin \theta$

$$\Rightarrow \vec{m} = \frac{1}{2c} I (\text{area}) \hat{m}$$

\uparrow
area of loop

\nwarrow outward normal

(direction given by right hand rule with respect to direction of current)

magnetic dipole moment \vec{m} is independent of location of origin.

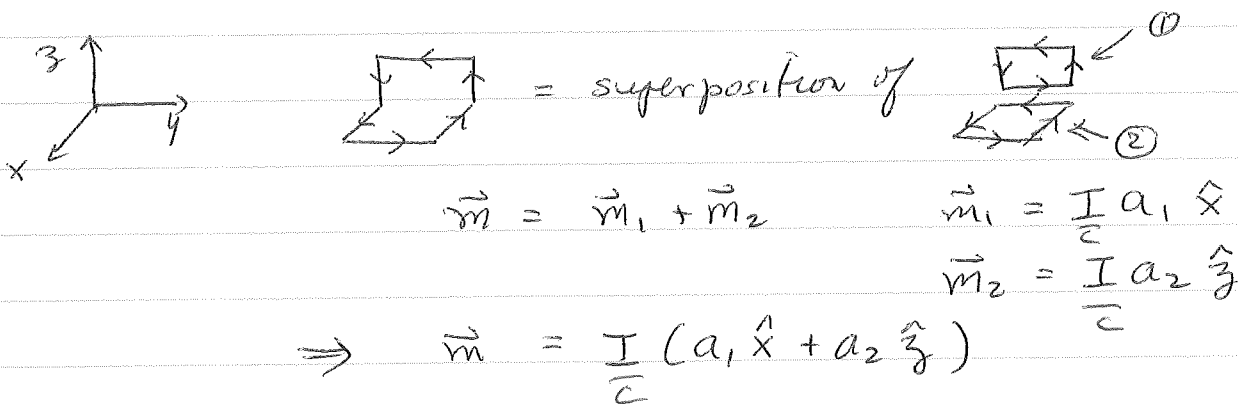
$$\vec{r}' = \vec{r} + \vec{d} \quad \text{new coord}$$

$$\begin{aligned} \vec{m}' &= \frac{1}{2c} \int d^3r' (\vec{r}' \times \vec{j}) = \frac{1}{2c} \int d^3r (\vec{r} + \vec{d}) \times \vec{j} \\ &= \frac{1}{2c} \int d^3r \vec{r} \times \vec{j} + \frac{1}{2c} \vec{d} \times \left[\int d^3r \vec{j} \right] \end{aligned}$$

$$\vec{m}' = \vec{m} + 0 \quad \text{as } \int d^3r \vec{j} = 0$$

for planar loop $\vec{m} = \frac{Ia}{c} \hat{n}$ where $a = \text{area}$
 $\hat{n} = \text{outward normal}$

can also apply to get \vec{m} for piecewise planar loops



Boundary value problems in magnetostatics

Scalar Magnetic Potential

Because of the vector character of the equation

$$-\nabla^2 \vec{A} = \frac{4\pi}{c} \vec{j}$$

and the fact that $\nabla^2 \vec{A}$ only has a convenient representation in Cartesian coordinates, many of the methods we used to solve the scalar $-\nabla^2 \phi = 4\pi\rho$ don't work so well for magnetostatics.

However, in situations where the current \vec{j} is confined to certain surfaces, we can make things much closer to the electrostatic case by using the trick of the scalar magnetic potential ϕ_M .

In regions where $\vec{j} = 0$, i.e. not on the certain surfaces, we have $\vec{\nabla} \cdot \vec{B} = 0$ and $\vec{\nabla} \times \vec{B} = 0$. Since $\vec{\nabla} \times \vec{B} = 0$ in these regions we can define a scalar potential ϕ_M such that

$$\vec{B} = -\vec{\nabla} \phi_M$$

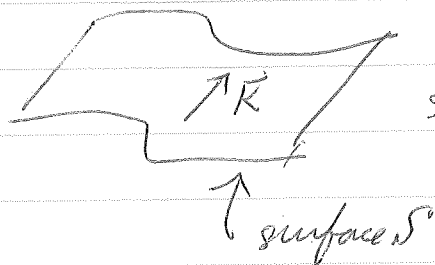
and then

$$\vec{\nabla} \cdot \vec{B} = -\nabla^2 \phi_M = 0$$

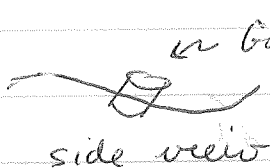
We can solve for ϕ_M as in electrostatics, and match solutions by applying appropriate boundary conditions on the current carrying surfaces.

Boundary Conditions at Sheet current

in magnetostatics $\vec{\nabla} \cdot \vec{B} = 0$, $\vec{\nabla} \times \vec{B} = \frac{4\pi}{c} \vec{j}$



surface current $\vec{K}(\vec{r})$ at pt \vec{r}
on surface S'



Gaussian pillbox vol V

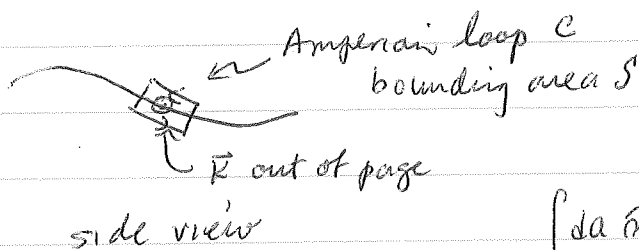
$$\int_V d^3r \vec{\nabla} \cdot \vec{B} = 0$$

side view

top + bottom area of pill box is da
width of pill box $\rightarrow 0$

$$\Rightarrow \int_V d^3r \vec{\nabla} \cdot \vec{B} = \oint_S da \hat{m} \cdot \vec{B} = da (\vec{B}_{\text{above}} - \vec{B}_{\text{below}}) \cdot \hat{m} = 0$$

normal component of \vec{B} is continuous $(\vec{B}_{\text{above}} - \vec{B}_{\text{below}}) \cdot \hat{m} = 0$



Amperian loop C
bounding area S

\vec{K} out of page

side view

$$\int_S da \hat{m} \cdot (\vec{\nabla} \times \vec{B}) = \oint_C \vec{B} \cdot d\vec{l} = \frac{4\pi}{c} I_{\text{enclosed}}$$

let width of loop $\rightarrow 0$, top + bottom sides $d\vec{l}$



$$(\vec{B}_{\text{above}} - \vec{B}_{\text{below}}) \cdot d\vec{l} = \frac{4\pi}{c} (\hat{m} \times d\vec{l}) \cdot \vec{K}$$

$$= \frac{4\pi}{c} (\vec{K} \times \hat{m}) \cdot d\vec{l}$$

\hat{m} is outward normal

tangential component of \vec{B} has discontinuous jump $\frac{4\pi}{c} \vec{K} \times \hat{m}$

Combine both results into

$$\vec{B}_{\text{above}} - \vec{B}_{\text{below}} = \frac{4\pi}{c} \vec{K} \times \hat{m}$$

magnetic analog of $\vec{E}_{\text{above}} - \vec{E}_{\text{below}} = 4\pi\sigma \hat{m}$

In terms of magnetic ~~vector~~^{scalar} potential ϕ_M

$$-\vec{\nabla}_{M \text{ above}} \phi_M + \vec{\nabla}_{M \text{ below}} \phi_M = \frac{4\pi}{c} \vec{K} \times \hat{m}$$

Note: ϕ_M is a calculational tool only
it does not have any direct physical
significance as does the electrostatic ϕ .

Electrostatic ϕ is related to work done
moving a charge $W_{12} = q [\phi(r_2) - \phi(r_1)]$

nothing similar for ϕ_M .

(in fact magnetostatic magnetic forces do no work!)

$$\vec{F} = q \vec{v} \times \vec{B}$$

$$\Rightarrow \vec{F} \cdot \vec{v} = \frac{dW}{dt} = 0$$

Note:

ϕ_M is not necessarily continuous at surface current
cannot do similar to electrostatics and use

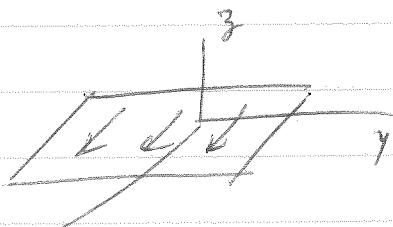
$$\phi_M(r_{\text{above}}) - \phi_M(r_{\text{below}}) = - \int_{r_{\text{below}}}^{r_{\text{above}}} \vec{B} \cdot d\vec{l}$$

since ϕ_M is not defined on the current sheet
itself, separating "above" from "below".

example

Flat infinite plane at $z=0$ with surface current

$$\vec{K} = K \hat{x}$$



$$z > 0, \nabla^2 \Phi_M^> = 0 \Rightarrow \Phi_M^> = a^> - b_x^> x - b_y^> y - b_z^> z$$

$$z < 0, \nabla^2 \Phi_M^< = 0 \Rightarrow \Phi_M^< = a^< - b_x^< x - b_y^< y - b_z^< z$$

$$z > 0, \vec{B}^> = -\vec{\nabla} \Phi_M^> = b_x^> \hat{x} + b_y^> \hat{y} + b_z^> \hat{z}$$

$$z < 0, \vec{B}^< = -\vec{\nabla} \Phi_M^< = b_x^< \hat{x} + b_y^< \hat{y} + b_z^< \hat{z}$$

$$\begin{aligned} \text{at } z=0 \quad \vec{B}^> - \vec{B}^< &= (b_x^> - b_x^<) \hat{x} + (b_y^> - b_y^<) \hat{y} + (b_z^> - b_z^<) \hat{z} \\ &= \frac{4\pi}{c} \vec{K} \times \hat{m} = \frac{4\pi}{c} K (\hat{x} \times \hat{z}) = -\frac{4\pi K}{c} \hat{y} \end{aligned}$$

$$\Rightarrow b_x^> = b_x^< \equiv b_{x0}, \quad b_z^> = b_z^< \equiv b_{z0}, \quad b_y^> - b_y^< = -\frac{4\pi K}{c}$$

$$\text{define } \left. \begin{aligned} b_y^> &= b_{y0} + \delta b_y \\ b_y^< &= b_{y0} - \delta b_y \end{aligned} \right\} \delta b_y = -\frac{2\pi K}{c}$$

$$\begin{aligned} \Rightarrow \vec{B}^> &= \vec{B}_0 - \frac{2\pi K}{c} \hat{y} & \vec{B}_0 &= b_{x0} \hat{x} + b_{y0} \hat{y} + b_{z0} \hat{z} \\ \vec{B}^< &= \vec{B}_0 + \frac{2\pi K}{c} \hat{y} \end{aligned}$$

if \vec{K} is the only source of magnetic field then $\vec{B}_0 = 0$

$$\vec{B} = \begin{cases} -\frac{2\pi K}{c} \hat{y} & z > 0 \\ \frac{2\pi K}{c} \hat{y} & z < 0 \end{cases}$$