

Force and torque on electric dipoles

localized charge distribution $\rho(\vec{r})$ with net charge $\int d^3r \rho = 0$

force on ρ in slowly varying electric field \vec{E} is

$$\vec{F} = \int d^3r \rho(\vec{r}) \vec{E}(\vec{r})$$

define $\vec{r} = \vec{r}_0 + \vec{r}'$ where \vec{r}_0 is some fixed reference point in center of charge distn ρ , and \vec{r}' is distance relative to \vec{r}_0

$$\vec{F} = \int d^3r' \rho(\vec{r}') \vec{E}(\vec{r}_0 + \vec{r}')$$

since \vec{E} is slowly varying on length scale where $\rho \neq 0$, we expand

$$\vec{F} \approx \int d^3r' \rho(\vec{r}') \left[\vec{E}(\vec{r}_0) + (\vec{r}' \cdot \vec{\nabla}) \vec{E}(\vec{r}_0) \right] + \dots$$

$$= \vec{E}(\vec{r}_0) \int d^3r' \rho(\vec{r}') + \left(\int d^3r' \rho(\vec{r}') \vec{r}' \cdot \vec{\nabla} \right) \vec{E}(\vec{r}_0)$$

$$= 0 + (\vec{p} \cdot \vec{\nabla}) \vec{E}(\vec{r}_0)$$

$$\boxed{\vec{F} = (\vec{p} \cdot \vec{\nabla}) \vec{E} = \sum_{\alpha=1}^3 p_{\alpha} \frac{\partial \vec{E}}{\partial r_{\alpha}}}$$

For $\vec{E} = \text{constant}$, $\vec{F} = 0$

Torque on p is ~~integrated over volume~~

$$\vec{N} = \int d^3r \rho(\vec{r}) \vec{r} \times \vec{E}(\vec{r}) \cong \int d^3r \rho(\vec{r}) \vec{r} \times [\vec{E}(\vec{r}_0) + \dots]$$

to lowest order

$$\boxed{\vec{N} = \vec{p} \times \vec{E}}$$

Force and torque on magnetic dipoles

focalized magnetostatic current distribution $\vec{j}(\vec{r})$

$$\vec{F} = \frac{1}{c} \int d^3r \vec{j} \times \vec{B}$$

expand about center of current \vec{r}_0

$$\vec{B}(\vec{r}) \cong \vec{B}(\vec{r}_0) + (\vec{r}' \cdot \vec{\nabla}) \vec{B}(\vec{r}_0) + \dots$$

$$\vec{F} = \frac{1}{c} \left[\int d^3r' \vec{j}(\vec{r}') \times \vec{B}(\vec{r}_0) + \frac{1}{c} \int d^3r' \vec{j}(\vec{r}') \times (\vec{r}' \cdot \vec{\nabla}) \vec{B}(\vec{r}_0) \right]$$

from discussion of magnetic dipole approx we had $\int d^3r \vec{j} = 0$
for magnetostatics where $\vec{\nabla} \cdot \vec{j} = 0$. So 1st term vanishes.
The 2nd term can be written as

$$\vec{F}_d = \frac{\epsilon_{\alpha\beta\gamma}}{c} \int d^3r' j_\beta r'_\gamma \partial_\alpha B_\gamma$$

for magnetostatics
see magnetic dipole
derivation

$$\text{we need the tensor } \frac{1}{c} \int d^3r' j_\beta r'_\gamma = -\frac{1}{c} \int d^3r' r'_\beta j_\gamma$$

$$= \frac{1}{2c} \int d^3r' [j_\beta r'_\gamma - r'_\beta j_\gamma]$$

$$= -M_\alpha \epsilon_{\alpha\beta\gamma}$$

↑ magnetic dipole $\vec{m} = \pm \int d^3r \vec{r} \times \vec{j}$

$$\begin{aligned}
 F_\alpha &= \epsilon_{\alpha\beta\gamma} \epsilon_{\sigma\beta\delta} (-m_\sigma) \partial_\delta B_\gamma \\
 &= -(\delta_{\alpha\sigma} \delta_{\gamma\delta} - \delta_{\alpha\delta} \delta_{\sigma\gamma}) m_\sigma \partial_\delta B_\gamma \\
 &= \text{div} \cdot \vec{\nabla} (\vec{m} \cdot \vec{B}) - \vec{m} \cdot \vec{\nabla} \vec{B}
 \end{aligned}$$

$$\boxed{\vec{F} = \vec{\nabla} (\vec{m} \cdot \vec{B})} \quad \text{as } \vec{\nabla} \cdot \vec{B} = 0$$

torque on \vec{j} is

$$\begin{aligned}
 \vec{N} &= \frac{1}{c} \int d^3r \vec{r} \times (\vec{j} \times \vec{B}) \quad \text{to lowest order, } \vec{B} = \vec{B}(\vec{r}_0) \\
 & \quad \text{is const over region where } \vec{j} \neq 0 \\
 &= \frac{1}{c} \int d^3r [\vec{j} (\vec{r} \cdot \vec{B}) - \vec{B} (\vec{r} \cdot \vec{j})]
 \end{aligned}$$

2nd term = 0 as follows

$$\begin{aligned}
 \int d^3r \vec{r} \cdot \vec{j} &= \int d^3r \vec{j} \cdot \vec{\nabla} \left(\frac{r^2}{2} \right) \quad \text{as } \vec{\nabla} \left(\frac{r^2}{2} \right) = \vec{r} \\
 &= - \int d^3r (\vec{\nabla} \cdot \vec{j}) \left(\frac{r^2}{2} \right) \quad \text{integrate by parts.} \\
 & \quad \text{Surface term } \rightarrow 0 \text{ as } \vec{j} \text{ is localized} \\
 &= 0 \quad \text{as } \vec{\nabla} \cdot \vec{j} = 0 \text{ in magnetostatics}
 \end{aligned}$$

1st term involves

see derivation of magnetic dipole approx

$$\int d^3r \vec{j} \vec{r} = - \int d^3r \vec{r} \vec{j} = \frac{1}{2} \int d^3r [\vec{j} \vec{r} - \vec{r} \vec{j}]$$

So

$$\vec{N} = \frac{1}{2c} \int d^3r [\vec{j} (\vec{r} \cdot \vec{B}) - \vec{r} (\vec{j} \cdot \vec{B})]$$

$$\vec{N} = \frac{1}{2c} \int d^3r \left[\vec{j} (\vec{r} \cdot \vec{B}) - \vec{r} (\vec{j} \cdot \vec{B}) \right]$$

$$\approx \vec{r} \times \vec{B}$$

$$= \frac{1}{2c} \int d^3r (\vec{r} \times \vec{j}) \times \vec{B}$$

$$\boxed{\vec{N} = \vec{m} \times \vec{B}}$$

Electrostatic energy of interaction

$$\mathcal{E} = \frac{1}{8\pi} \int d^3r E^2$$

Suppose the charge density ρ that produces \vec{E} can be broken into two pieces, $\rho = \rho_1 + \rho_2$ with $\vec{E} = \vec{E}_1 + \vec{E}_2$ where $\vec{\nabla} \cdot \vec{E}_1 = 4\pi\rho_1$ and $\vec{\nabla} \cdot \vec{E}_2 = 4\pi\rho_2$.
Then

$$\mathcal{E} = \frac{1}{8\pi} \int d^3r [E_1^2 + E_2^2 + 2\vec{E}_1 \cdot \vec{E}_2]$$

↑ ↑ ↑
"self-energy" "self-energy" "interaction" energy
of ρ_1 of ρ_2 of ρ_1 with ρ_2

$$\begin{aligned} \mathcal{E}_{\text{int}} &= \frac{1}{4\pi} \int d^3r \vec{E}_1 \cdot \vec{E}_2 \\ &= \int d^3r \rho_1 \phi_2 = \int d^3r \rho_2 \phi_1 \end{aligned}$$

where $\vec{E}_1 = -\vec{\nabla}\phi_1$, $\vec{E}_2 = -\vec{\nabla}\phi_2$, by similar manipulations as earlier
integrals are over all space

Apply to the interaction energy of a dipole in an external \vec{E} field

$$\mathcal{E}_{\text{int}} = \int d^3r \rho_1 \phi_2$$

↑ ↖ potential of external \vec{E} field
charge distribution of dipole

Assuming ϕ_2 varies ^{slowly} on length scale of ρ_1 , then we can expand $\phi_2(\vec{r}) = \phi_2(\vec{r}_0) + (\vec{r} - \vec{r}_0) \cdot \vec{\nabla} \phi_2(\vec{r}_0)$ where \vec{r}_0 is the center of mass or any other convenient reference position within ρ_1 .

$$\begin{aligned} \epsilon_{\text{int}} &= \int d^3r \rho_1(\vec{r}) \left[\phi_2(\vec{r}_0) + (\vec{r} - \vec{r}_0) \cdot \vec{\nabla} \phi_2(\vec{r}_0) \right] \\ &= q \phi_2(\vec{r}_0) + \left[\int d^3r \rho_1(\vec{r}) (\vec{r} - \vec{r}_0) \right] \cdot \vec{\nabla} \phi_2(\vec{r}_0) \\ &= q \phi_2(\vec{r}_0) + \vec{p} \cdot \vec{E} \end{aligned}$$

Where q is total charge in ρ_1 , and \vec{p} is dipole moment with respect to \vec{r}_0 . $\vec{E} = -\vec{\nabla} \phi_2$ is external \vec{E} -field

For a neutral charge distribution $q=0$, and \vec{p} is independent of the origin about which it is computed, so

$$\boxed{\epsilon_{\text{int}} = -\vec{p} \cdot \vec{E}}$$

← does not include the energy needed to make the dipole or to make \vec{E} .

ϵ_{int} is lowest when $\vec{p} \parallel \vec{E}$

⇒ in thermal ensemble, dipoles tend to align parallel to an applied \vec{E} .

Energy of magnetic dipole in external field

We had that the force on the dipole was

$$\vec{F} = \vec{\nabla}(\vec{m} \cdot \vec{B})$$

if we regard this force as coming from the gradient of a potential energy U then $\vec{F} = -\vec{\nabla}U \Rightarrow$

$$U = -\vec{m} \cdot \vec{B}$$

or equivalently, energy = work done to move dipole into position from ∞

$$W = -\int_{\infty}^{\vec{r}} \vec{F} \cdot d\vec{\ell} = -\int_{\infty}^{\vec{r}} \vec{\nabla}(\vec{m} \cdot \vec{B}) \cdot d\vec{\ell} = -\vec{m} \cdot \vec{B}(\vec{r})$$

This is the correct energy to use in cases where \vec{m} is due to intrinsic magnetic moments of atom or molecule - say from electron or nuclear spin. For a thermal ensemble magnetic moments tend to align \parallel to \vec{B} .

The answer comes out quite differently if we are talking about a magnetic moment produced by a classical current loop. To see this, consider what we would get if we tried to do the calculation in a similar way to how we did it for the energy of an electric dipole in an electric field....

Magnetostatic energy of interaction

$$\mathcal{E} = \frac{1}{8\pi} \int d^3r B^2$$

Suppose current \vec{j} that produces \vec{B} can be divided
 $\vec{j} = \vec{j}_1 + \vec{j}_2$ with $\vec{B} = \vec{B}_1 + \vec{B}_2$ where $\vec{\nabla} \times \vec{B}_1 = \frac{4\pi}{c} \vec{j}_1$
and $\vec{\nabla} \times \vec{B}_2 = \frac{4\pi}{c} \vec{j}_2$. Then

$$\mathcal{E} = \frac{1}{8\pi} \int d^3r [\underset{\substack{\uparrow \\ \text{self energy} \\ \text{of } \vec{j}_1}}{B_1^2} + \underset{\substack{\uparrow \\ \text{self energy} \\ \text{of } \vec{j}_2}}{B_2^2} + 2 \underset{\substack{\uparrow \\ \text{interaction energy} \\ \text{of } \vec{j}_1 \text{ with } \vec{j}_2}}{\vec{B}_1 \cdot \vec{B}_2}]$$

$$\begin{aligned} \mathcal{E}_{\text{int}} &= \frac{1}{4\pi} \int d^3r \vec{B}_1 \cdot \vec{B}_2 \\ &= \frac{1}{c} \int d^3r \vec{j}_1 \cdot \vec{A}_2 = \frac{1}{c} \int d^3r \vec{j}_2 \cdot \vec{A}_1 \end{aligned}$$

where $\vec{B}_1 = \vec{\nabla} \times \vec{A}_1$, $\vec{B}_2 = \vec{\nabla} \times \vec{A}_2$, by similar manipulations
as earlier
integrals are over all space.

Apply to the interaction energy of a magnetic
dipole in an external \vec{B} field.

$$\mathcal{E}_{\text{int}} = \frac{1}{c} \int d^3r \underset{\substack{\uparrow \\ \text{current distribution of dipole}}}{\vec{j}_1} \cdot \underset{\substack{\uparrow \\ \text{vector potential of external } \vec{B} \text{ field}}}{\vec{A}_2}$$

Assuming \vec{A} varies slowly on length scale of \vec{j} , then expand $A_i(\vec{r}) = A_i(\vec{r}_0) + (\vec{r} - \vec{r}_0) \cdot \vec{\nabla} A_i(\vec{r}_0)$

$$\begin{aligned} \mathcal{E}_{int} &= \frac{1}{c} \int d^3r \vec{j}_i \cdot \vec{A}(\vec{r}_0) \\ &+ \frac{1}{c} \int d^3r \sum_{i,j} j_{ij} (r - r_0)_j \partial_j A_i(\vec{r}_0) \end{aligned}$$

Shift origin so origin at \vec{r}_0 \vec{r} now measures distance

From magnetostatic computation of magnetic dipole moment we had $\int d^3r \vec{j} = 0$ for magnetostatics

\Rightarrow 1st term above vanishes. So does the piece of 2nd term $\left(\int d^3r j_{ij} \right) r_{0j} \partial_j A_i(\vec{r}_0)$

We are left with

$$\mathcal{E}_{int} = \left[\frac{1}{c} \int d^3r j_{ij} r_j \right] \partial_j A_i(\vec{r}_0) \quad \begin{array}{l} \text{summation over} \\ \text{repeated indices} \\ \text{is implied} \end{array}$$

From computation of magnetic dipole approx we had

$$\int d^3r j_{ij} r_j = - \int d^3r j_{ij} r_i$$

Recall:

$$\vec{m} = \frac{1}{2c} \int d^3r \vec{r} \times \vec{j}$$

$$= \frac{1}{2} \int d^3r [j_{ik} r_j - j_{lj} r_i]$$

$$= \frac{1}{2} \epsilon_{kij} \int d^3r (\vec{j} \times \vec{r})_k$$

$$\Rightarrow \frac{1}{c} \int d^3r j_{ij} r_i = - \epsilon_{kij} m_k \leftarrow \text{mag dipole}$$

$$\begin{aligned} E_{\text{int}} &= -m_k \epsilon_{kij} \partial_j A_i = m_k \epsilon_{kji} \partial_j A_i \\ &= \vec{m} \cdot (\vec{\nabla} \times \vec{A}) = \vec{m} \cdot \vec{B} = E_{\text{int}} \end{aligned}$$

This is opposite in sign to what we found earlier!

Why the difference?

① When we integrate the work done against the magnetostatic force to move \vec{m} into position from infinity we found the energy

$$U = -\vec{m} \cdot \vec{B}$$

② When we compute the interaction energy from

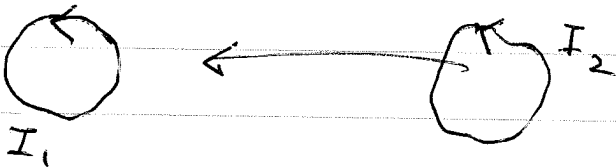
$$E_{\text{int}} = \frac{1}{c} \int d^3r \vec{j}_1 \cdot \vec{A}_2 = \frac{1}{c^2} \int d^3r \int d^3r' \frac{\vec{j}_1(\vec{r}) \cdot \vec{j}_2(\vec{r}')}{|\vec{r} - \vec{r}'|}$$

we found the energy $E_{\text{int}} = +\vec{m} \cdot \vec{B}$

To see which is correct, let us consider computing the interaction energy ② directly via method ①.

Consider two loops with currents I_1 and I_2

What is the work done to move loop 2 in from infinity to its final position with respect to loop 1?



Magnetostatic force on loop 2 due to loop 1 is

$$\vec{F} = \frac{I_2}{c} \oint_2 d\vec{l}_2 \times \vec{B}_1 \quad \begin{array}{l} \text{Lorentz force} \\ \vec{B}_1 \text{ is magnetic field from loop 1} \end{array}$$

$$\vec{B}_1(\vec{r}) = \frac{I_1}{c} \oint_1 d\vec{l}_1 \times \frac{(\vec{r} - \vec{r}_1)}{|\vec{r} - \vec{r}_1|^3} \quad \text{Biot-Savart law}$$

$$F = \frac{I_1 I_2}{c^2} \oint_2 \oint_1 d\vec{l}_2 \times \frac{(d\vec{l}_1 \times (\vec{r}_2 - \vec{r}_1))}{|\vec{r}_2 - \vec{r}_1|^3}$$

Use triple product rule

$$\begin{aligned} d\vec{l}_2 \times [d\vec{l}_1 \times (\vec{r}_2 - \vec{r}_1)] \\ = d\vec{l}_1 [d\vec{l}_2 \cdot (\vec{r}_2 - \vec{r}_1)] - (\vec{r}_2 - \vec{r}_1) (d\vec{l}_1 \cdot d\vec{l}_2) \end{aligned}$$

from the 1st term

$$\oint_2 d\vec{l}_2 \cdot \frac{(\vec{r}_2 - \vec{r}_1)}{|\vec{r}_2 - \vec{r}_1|^3} = - \oint_2 d\vec{l}_2 \cdot \vec{\nabla}_2 \left(\frac{1}{|\vec{r}_2 - \vec{r}_1|} \right) = 0$$

as integral of gradient around closed loop always vanishes!

So

$$\vec{F} = -\frac{I_1 I_2}{c^2} \oint_1 \oint_2 d\vec{l}_1 \cdot d\vec{l}_2 \frac{(\vec{r}_2 - \vec{r}_1)}{|\vec{r}_2 - \vec{r}_1|^3}$$

write $\vec{r}_2 = \vec{R} + \delta\vec{r}_2$ where \vec{R} is center of loop 2

$$\text{use } \frac{\vec{R} + \delta\vec{r}_2 - \vec{r}_1}{|\vec{R} + \delta\vec{r}_2 - \vec{r}_1|^3} = -\vec{\nabla}_R \left(\frac{1}{|\vec{R} + \delta\vec{r}_2 - \vec{r}_1|} \right)$$

$$\vec{F} = \frac{I_1 I_2}{c^2} \oint_1 \oint_2 d\vec{l}_1 \cdot d\vec{l}_2 \vec{\nabla}_R \left(\frac{1}{|\vec{R} + \delta\vec{r}_2 - \vec{r}_1|} \right)$$

to move loop 2 we need to apply a ^{mechanical} force equal and opposite to the above magnetostatic force.

Therefore the work we do in moving loop 2 from infinity to its final position at \vec{R}_0 is

$$W_{\text{mech}} = -\int_{\infty}^{\vec{R}_0} \vec{F} \cdot d\vec{R} = -\frac{I_1 I_2}{c^2} \oint_1 \oint_2 d\vec{l}_1 \cdot d\vec{l}_2 \int_{\infty}^{\vec{R}_0} d\vec{R} \cdot \vec{\nabla}_R \left(\frac{1}{|\vec{R} + \delta\vec{r}_2 - \vec{r}_1|} \right)$$

$$= -\frac{I_1 I_2}{c^2} \oint_1 \oint_2 \frac{d\vec{l}_1 \cdot d\vec{l}_2}{|\vec{r}_2 - \vec{r}_1|} \quad \text{where } \vec{r}_2 = \vec{R}_0 + \delta\vec{r}_2$$

$$= -\frac{1}{c^2} \int d^3r_1 \int d^3r_2 \frac{\vec{j}_1(\vec{r}_1) \cdot \vec{j}_2(\vec{r}_2)}{|\vec{r}_2 - \vec{r}_1|}$$

Note the minus sign!

$$= -M_{12} I_1 I_2$$

↑ mutual inductance

why the minus sign!

← This is just the negative of the interaction energy!!

The minus sign we have here is the same minus sign we got when we found $U = -\vec{m} \cdot \vec{B}$ by integrating the force on the magnetic dipole.

Why don't we get $+\frac{1}{c^2} \int d^3r_1 d^3r_2 \frac{\vec{f}_1(r_1) \cdot \vec{f}_2(r_2)}{|\vec{r}_2 - \vec{r}_1|}$

with the plus sign we expect from $E = \frac{1}{8\pi} \int d^3r B^2$?

Answer: we have left something out!

Faraday's Law - when we move loop 2, the magnetic flux through loop 2 changes. This $\frac{d\Phi}{dt}$ creates an emf $= \oint d\vec{l} \cdot \vec{E}$ around the loop that would tend to change the current in the loop. If we are to keep the current fixed at constant I_2 then there must be a battery in the loop that does work to counter this induced emf ("electromotive force"). Similarly, the flux through loop 1 is changing and a battery does work to keep I_1 constant. We need to add this work done by the batteries to the mechanical work computed above.

$$\begin{array}{l} \text{emf induced in loop 1} \\ \text{emf induced in loop 2} \end{array} \quad \begin{array}{l} \vec{E}_1 = \oint_1 d\vec{l}_1 \cdot \vec{E}_2 \\ \vec{E}_2 = \oint_2 d\vec{l}_2 \cdot \vec{E}_1 \end{array} \quad \left. \begin{array}{l} \int \text{integrations} \\ \int \text{in direction} \\ \int \text{of current} \end{array} \right\}$$

$$\text{Faraday} \quad \vec{E}_1 = -\frac{d\Phi_1}{c dt} \quad \Phi_1 = \text{flux through loop 1}$$

$$\vec{E}_2 = -\frac{d\Phi_2}{c dt} \quad \Phi_2 = \text{flux through loop 2}$$

To keep the current constant, the batteries need to provide an emf that counters these Faraday induced emf's. The work done by the batteries per unit time is therefore

$$\frac{dW_{\text{battery}}}{dt} = -\mathcal{E}_1 I_1 - \mathcal{E}_2 I_2$$

(check units: $\mathcal{E}I$ is $[\text{length}] \cdot [E] \cdot [I/s]$
 $= [\text{length}] \cdot [\text{force}/s]$
 $= \text{energy}/s$)

$$\frac{dW_{\text{battery}}}{dt} = \frac{d\Phi_1}{cdt} I_1 + \frac{d\Phi_2}{cdt} I_2$$

$$W_{\text{battery}} = \int_0^T dt \left(\frac{d\Phi_1}{cdt} I_1 + \frac{d\Phi_2}{cdt} I_2 \right)$$

where $t=0$ loop 2 is at infinity
 $t=T$ loop 2 is at final position
 I_1, I_2 kept constant as loop moves

$$W_{\text{battery}} = \frac{1}{c} \Phi_1 I_1 + \frac{1}{c} \Phi_2 I_2 \quad \text{where } \Phi_1 \text{ and } \Phi_2$$

are fluxes in final position, and we assumed that fluxes = 0 at infinity

$$\Phi_1 = c M_{12} I_2$$

$$\Phi_2 = c M_{21} I_1 = c M_{12} I_1 \quad \text{as } M_{12} = M_{21}$$

$$\Rightarrow W_{\text{battery}} = 2 M_{12} I_1 I_2$$

add this to the mechanical work

$$W_{\text{total}} = W_{\text{mech}} + W_{\text{battery}} = -M_{12} I_1 I_2 + 2 M_{12} I_1 I_2 \\ = M_{12} I_1 I_2 = + \frac{1}{c^2} \int d^3 r_1 d^3 r_2 \frac{\vec{j}_1(\vec{r}_1) \cdot \vec{j}_2(\vec{r}_2)}{|\vec{r}_1 - \vec{r}_2|}$$

we get back the correct interaction energy!

Conclusion : The magnetostatic interaction energy $\frac{1}{c^2} \int d^3 r_1 d^3 r_2 \frac{\vec{j}_1(\vec{r}_1) \cdot \vec{j}_2(\vec{r}_2)}{|\vec{r}_1 - \vec{r}_2|}$

includes the work done to maintain the currents stationary as the current distributions move.

When we computed the interaction energy of a current loop dipole \vec{m} and find

$$E_{\text{int}} = +\vec{m} \cdot \vec{B}$$

this includes the energy needed to maintain the constant current producing the constant \vec{m}

When we integrated the force on the dipole to find the potential energy

$$U = -\vec{m} \cdot \vec{B}$$

this did not include the energy needed to maintain the constant current that creates \vec{m} .

This is the correct energy expression to use when \vec{m} comes from intrinsic magnetic moments (due to particles intrinsic spin, which cannot be viewed as arising from a current loop)