

Adding all the pieces

$$\langle \vec{j}_n \rangle = \underbrace{\langle g_n \vec{v}_n \delta(\vec{r}-\vec{r}_n) \rangle}_{(1)} + c \vec{\nabla} \times \underbrace{\langle \vec{m}_n \delta(\vec{r}-\vec{r}_n) \rangle}_{(4)}$$

$$+ \underbrace{\frac{\partial}{\partial t} \langle \vec{p}_n \delta(\vec{r}-\vec{r}_n) \rangle}_{(2)} + \underbrace{(\vec{v}_n \cdot \vec{\nabla}) \langle \vec{p}_n \delta(\vec{r}-\vec{r}_n) \rangle}_{(2)}$$

$$- \underbrace{\vec{v}_n \cdot \vec{\nabla}_0 \langle \vec{p}_n \delta(\vec{r}-\vec{r}_n) \rangle}_{(3)}$$

Define $\vec{M}(\vec{r}) \equiv \sum_n \langle \vec{m}_n \delta(\vec{r}-\vec{r}_n) \rangle$ average magnetization density

$\vec{P}(\vec{r}) \equiv \sum_n \langle \vec{p}_n \delta(\vec{r}-\vec{r}_n) \rangle$ polarization density, as before

$$\sum_n \langle \vec{j}_n \rangle = \sum_n \langle g_n \vec{v}_n \delta(\vec{r}-\vec{r}_n) \rangle + c \vec{\nabla} \times \vec{M} + \frac{\partial \vec{P}}{\partial t}$$

$$+ \sum_n \left[(\vec{v}_n \cdot \vec{\nabla}) \langle \vec{p}_n \delta(\vec{r}-\vec{r}_n) \rangle - \vec{v}_n \cdot \vec{\nabla}_0 \langle \vec{p}_n \delta(\vec{r}-\vec{r}_n) \rangle \right]$$

see Jackson (6.96) for additional electric quadrupole terms

The last term on the right hand side is usually small and ignored. This is because the molecular velocities \vec{v}_n are usually small, and randomly oriented, so that they average to zero. (see Jackson (6.100) for case of net translation of dielectric, $\vec{v}_n = \text{const}$ all n)

Define macroscopic current density

$$\vec{j}(\vec{r}, t) = \left\langle \sum_{i \in \text{free}} q_i \vec{v}_i \delta(\vec{r} - \vec{r}_i) \right\rangle + \left\langle \sum_n q_n \vec{v}_n \delta(\vec{r} - \vec{r}_n) \right\rangle$$

↑
↑
 current of free charges current of molecular drifting
 if molecules are charged

Then $\langle \vec{j}_0 \rangle = \vec{j} + c \vec{\nabla} \times \vec{M} + \frac{\partial \vec{P}}{\partial t}$

Ampere's law becomes upon averaging

$$\vec{\nabla} \times \vec{B} = 4\pi \langle \vec{j}_0 \rangle + \frac{1}{c} \frac{\partial \vec{E}}{\partial t}$$

$$= \frac{4\pi}{c} \vec{j} + 4\pi \vec{\nabla} \times \vec{M} + \frac{4\pi}{c} \frac{\partial \vec{P}}{\partial t} + \frac{1}{c} \frac{\partial \vec{E}}{\partial t}$$

$$\vec{\nabla} \times (\vec{B} - 4\pi \vec{M}) = \frac{4\pi}{c} \vec{j} + \frac{1}{c} \frac{\partial}{\partial t} (\vec{E} + 4\pi \vec{P})$$

define $\vec{H} \equiv \vec{B} - 4\pi \vec{M}$ to get

$$\vec{\nabla} \times \vec{H} = \frac{4\pi}{c} \vec{j} + \frac{1}{c} \frac{\partial \vec{D}}{\partial t}$$

$$\vec{D} = \vec{E} + 4\pi \vec{P} \text{ as before}$$

official nomenclature: \vec{B} is the magnetic induction

\vec{H} is the magnetic field

common usage: both ~~H~~ and \vec{B} are called magnetic field

when atoms have intrinsic magnetic moments due to electron spin, we can add these to \vec{M} in obvious way

when molecules are neutral, $q_n = 0$, the "bound current" is given by

$$\vec{j}_{\text{bound}} = \sum_n \langle \vec{j}_n \rangle = c \vec{\nabla} \times \vec{M} + \frac{\partial \vec{P}}{\partial t}$$

Note that the $\frac{\partial \vec{P}}{\partial t}$ term is crucial to give conservation of bound charge

$$\begin{aligned} \vec{\nabla} \cdot \vec{j}_{\text{bound}} &= c \vec{\nabla} \cdot (\vec{\nabla} \times \vec{M}) + \vec{\nabla} \cdot \frac{\partial \vec{P}}{\partial t} \\ &= 0 + \frac{\partial}{\partial t} (\vec{\nabla} \cdot \vec{P}) \end{aligned}$$

$$= -\frac{\partial \rho_{\text{bound}}}{\partial t} \quad \text{where } \rho_{\text{bound}} = -\vec{\nabla} \cdot \vec{P} \text{ is bound charge density}$$

$$\text{So } \boxed{\vec{\nabla} \cdot \vec{j}_{\text{bound}} + \frac{\partial \rho_{\text{bound}}}{\partial t} = 0}$$

and bound charge is conserved.

Since total average charge must be conserved, i.e.

$$\vec{\nabla} \cdot \langle \vec{j}_0 \rangle - \frac{\partial \langle \rho_0 \rangle}{\partial t} = 0, \quad \text{and } \langle \vec{j}_0 \rangle = \vec{j} + \vec{j}_{\text{bound}}$$

↑
free current

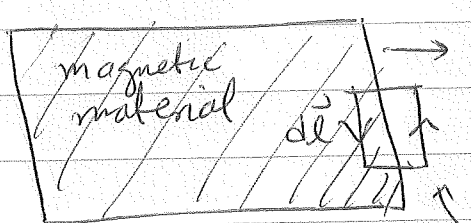
$$\langle \rho_0 \rangle = \rho + \rho_{\text{bound}}$$

↑
free charge

$$\Rightarrow \boxed{\vec{\nabla} \cdot \vec{j} + \frac{\partial \rho}{\partial t} = 0}$$

free charge is also conserved

At a surface of a magnetic material



\hat{m} outward normal to surface

take $\hat{z} \equiv d\vec{l} \times \hat{m}$ out of page

Amperian loop C bounding surface of area da

$$\begin{aligned} c \int_S da \hat{z} \cdot (\vec{\nabla} \times \vec{M}) &= \int_S da \hat{z} \cdot \left[\vec{j}_{\text{bound}} - \frac{\partial \vec{P}}{\partial t} \right] = da \hat{z} \cdot \left[\vec{j}_{\text{bound}} - \frac{\partial \vec{P}}{\partial t} \right] \\ &= (d\vec{l} \times \hat{m}) \cdot \vec{K}_{\text{bound}} \quad \text{as width of loop} \\ &= (\hat{m} \times \vec{K}_{\text{bound}}) \cdot d\vec{l} \quad \begin{array}{l} \rightarrow 0 \\ \frac{\partial \vec{P}}{\partial t} \text{ term} \\ \text{vanishes as } da \rightarrow 0 \end{array} \end{aligned}$$

But by Stokes theorem

$$c \int_S da \hat{z} \cdot (\vec{\nabla} \times \vec{M}) = c \oint_C d\vec{l} \cdot \vec{M} = c d\vec{l} \cdot \vec{M} \quad \begin{array}{l} \text{since width} \rightarrow 0 \\ \text{and } \vec{M} = 0 \text{ outside} \end{array}$$

$$\Rightarrow c d\vec{l} \cdot \vec{M} = (\hat{m} \times \vec{K}_{\text{bound}}) \cdot d\vec{l} \quad \text{for any } d\vec{l} \text{ in plane of surface}$$

$$\Rightarrow c \vec{M}_t = \hat{m} \times \vec{K}_{\text{bound}}$$

where \vec{M}_t is component of \vec{M} tangential to the surface (since \vec{K}_b is in plane of surface, $\hat{m} \times \vec{K}$ is also entirely in the plane of the surface)

$$\Rightarrow c \hat{m} \times \vec{M}_t = c \hat{m} \times \vec{M} = \hat{m} \times (\hat{m} \times \vec{K}_{\text{bound}}) = -\vec{K}_{\text{bound}}$$

$$\Rightarrow \boxed{\begin{aligned} \vec{K}_{\text{bound}} &= c \vec{M} \times \hat{m} \\ \vec{H} &= c \vec{\nabla} \times \vec{M} + \frac{\partial \vec{P}}{\partial t} \end{aligned}}$$

Total bound charge vanishes (for neutral molecules)

$$Q_{\text{bound}} = \int_V d^3r \rho_{\text{bound}} + \int_S da \sigma_{\text{bound}}$$

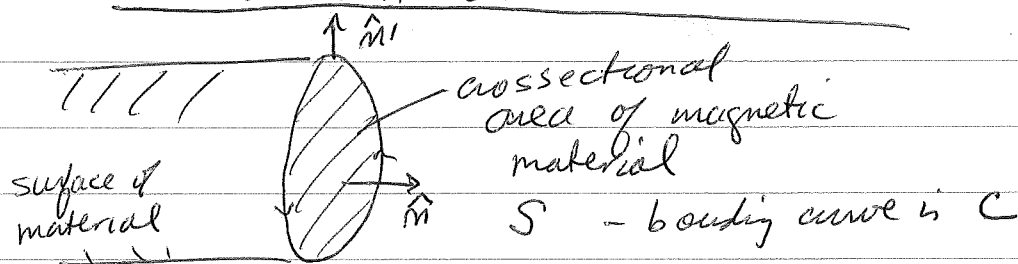
\uparrow vol of dielectric \leftarrow surface of dielectric

$$= \int_V d^3r (-\vec{\nabla} \cdot \vec{P}) + \int da \hat{n} \cdot \vec{P}$$

but by Gauss theorem $\int_V d^3r \vec{\nabla} \cdot \vec{P} = \int da \hat{n} \cdot \vec{P}$

$$\text{so } Q_{\text{bound}} = - \int da \hat{n} \cdot \vec{P} + \int da \hat{n} \cdot \vec{P} = 0$$

Total bound current vanishes



\hat{n} is normal to crosssection
 \hat{n}' is normal to surface

total current flowing through S is

$$\int_S da \hat{n} \cdot \vec{j}_{\text{bound}} + \int_C dl \vec{K}_{\text{bound}} \cdot \hat{n}$$

$$= c \int_S da \hat{n} \cdot (\vec{\nabla} \times \vec{M}) + c \int_C dl \hat{n} \cdot (\vec{M} \times \hat{n}')$$

$$= c \int_C d\vec{l} \cdot \vec{M} + c \int_C dl (\hat{n}' \times \hat{n}) \cdot \vec{M}$$

$= -\hat{t}$ mit tangent, $d\vec{l} = dl \hat{t}$

$$= c \int_C d\vec{l} \cdot \vec{M} - c \int_C dl \vec{l} \cdot \vec{M} = 0$$

Macroscopic Maxwell Equations

$$\vec{\nabla} \cdot \vec{B} = 0$$

$$\vec{\nabla} \times \vec{E} + \frac{1}{c} \frac{\partial \vec{B}}{\partial t} = 0$$

$$\vec{\nabla} \times \vec{H} = \frac{4\pi}{c} \vec{j} + \frac{1}{c} \frac{\partial \vec{D}}{\partial t}$$

$$\vec{\nabla} \cdot \vec{D} = 4\pi \rho$$

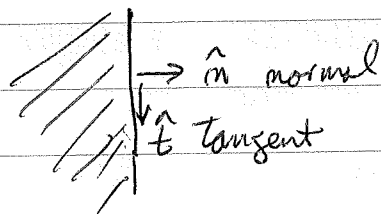
where ρ and \vec{j} are macroscopic charge + current densities
do not include bound charges or currents

$$\vec{D} = \vec{E} + 4\pi \vec{P}, \quad \vec{P} \text{ is polarization density}$$

$$\vec{H} = \vec{B} - 4\pi \vec{M}, \quad \vec{M} \text{ is magnetization density}$$

Boundary conditions for statics

electrostatics: at surface of a dielectric, or at interface between two different dielectrics



$$\vec{\nabla} \times \vec{E} = 0 \Rightarrow \hat{t} \cdot \vec{E}_{\text{above}} = \hat{t} \cdot \vec{E}_{\text{below}}$$

tangential component \vec{E} is continuous

proof same as before

$$\vec{\nabla} \cdot \vec{D} = 4\pi \rho \Rightarrow \hat{n} \cdot (\vec{D}_{\text{above}} - \vec{D}_{\text{below}}) = 4\pi \sigma$$

normal component of \vec{D} jumps by $4\pi \sigma$

magneto statics: at surface or interface of magnetic materials

$$\vec{\nabla} \cdot \vec{B} = 0 \Rightarrow \hat{n} \cdot \vec{B}_{\text{above}} - \hat{n} \cdot \vec{B}_{\text{below}}$$

normal component of \vec{B} is continuous

proof same as before

$$\vec{\nabla} \times \vec{H} = \frac{4\pi}{c} \vec{j} \Rightarrow \hat{t} \cdot (\vec{H}_{\text{above}} - \vec{H}_{\text{below}}) = \frac{4\pi}{c} (\vec{k} \times \hat{m}) \cdot \hat{t}$$

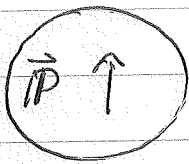
tangential component of \vec{H} jumps by $\frac{4\pi}{c} \vec{k} \times \hat{m}$

if $\sigma = 0$, i.e. no free surface charge, then $\hat{n} \cdot \vec{D}$ continuous

if $\vec{k} = 0$, i.e. no free surface current, then $\hat{t} \cdot \vec{H}$ continuous

Examples

① Uniformly polarized sphere of radius R $\vec{P} = P \hat{z}$



bound charge $\rho_b = -\nabla \cdot \vec{P} = 0$ as \vec{P} constant

$$\sigma_b = \hat{n} \cdot \vec{P} = \hat{r} \cdot \vec{P} = P \cos \theta$$

we saw earlier that a sphere with surface charge $\sigma(\theta) = \sigma_0 \cos \theta$ gives an electric field like a pure dipole for $r > R$, and is constant for $r < R$.

$$\vec{E}(\vec{r}) = \begin{cases} \left(\frac{4}{3} \pi R^3 P \right) \left[\frac{2 \cos \theta \hat{r} + \sin \theta \hat{\theta}}{r^3} \right] & r > R \\ -\frac{4\pi P}{3} \hat{z} & r < R \end{cases}$$

total dipole moment is $\vec{p} = \frac{4}{3} \pi R^3 \vec{P}$

check behavior at boundary

Tangential component \vec{E}

$$\vec{E}_{\text{above}}^{\perp} = \left(\frac{4}{3} \pi R^3 P \right) \frac{\sin \theta}{R^3} \hat{\theta} = \frac{4\pi P}{3} \sin \theta \hat{\theta}$$

$$\vec{E}_{\text{below}}^{\perp} = -\frac{4\pi P}{3} (\hat{z} \cdot \hat{\theta}) \hat{\theta} = \frac{4\pi P}{3} \sin \theta \hat{\theta}$$

\Rightarrow Tangential component \vec{E} is continuous

normal component of \vec{D}

outside: $\vec{P} = 0 \Rightarrow \vec{D} = \vec{E}$

$$\Rightarrow \hat{n} \cdot \vec{D} = \hat{r} \cdot \vec{E} = \int_0^{\pi} \left(\frac{4}{3} \pi R^3 P \right) \frac{2 \cos \theta \hat{r}}{R^3} = \frac{8}{3} \pi P \cos \theta$$

$$\text{inside: } \vec{E} = -\frac{4\pi\vec{P}}{3} \Rightarrow \vec{P} = -\frac{3}{4\pi}\vec{E}$$

$$\vec{D} = \vec{E} + 4\pi\vec{P} = \vec{E} - 3\vec{E} = -2\vec{E} = \frac{8\pi P}{3}\hat{z}$$

$$\hat{m} \cdot \vec{D} = \hat{r} \cdot \left(\frac{8\pi P}{3}\hat{z}\right) = \frac{8\pi}{3}P \cos\theta$$

\Rightarrow normal component \vec{D} is continuous

Note: normal component of \vec{E} should jump by $4\pi\sigma_b = 4\pi P \cos\theta$
inside

to check this: $\hat{m} \cdot \vec{E} = \hat{r} \cdot \left(-\frac{4}{3}\pi P \hat{z}\right) = -\frac{4}{3}\pi P \cos\theta$

$$\hat{m} \cdot (\vec{E}^{\text{above}} - \vec{E}^{\text{below}}) = \frac{8}{3}\pi P \cos\theta + \frac{4}{3}\pi P \cos\theta$$

$$= \frac{12}{3}\pi P \cos\theta = 4\pi P \cos\theta = \sigma_b(\theta)$$

(2) Uniformly magnetized sphere of radius R $\vec{M} = M \hat{z}$



bound current $\vec{j}_b = c \vec{\nabla} \times \vec{M} = 0$ as \vec{M} constant
 $\vec{K}_b = c \vec{M} \times \hat{m} = cM (\hat{z} \times \hat{r})$
 $= cM \sin \theta \hat{\phi}$

We saw earlier that a sphere with surface current $\vec{K}_b = K_0 \sin \theta \hat{\phi}$ gives a magnetic field that is pure dipole for $r > R$, and is constant for $r < R$.

$$\vec{B}(\vec{r}) = \begin{cases} \left(\frac{4}{3} \pi R^3 M \right) \left[\frac{2 \cos \theta \hat{r} + \sin \theta \hat{\theta}}{r^3} \right] & r > R \\ \frac{8}{3} \pi M \hat{z} & r < R \end{cases}$$

total dipole moment is $\vec{m} = \frac{4}{3} \pi R^3 \vec{M}$

check behavior at boundary

normal component of \vec{B}

$$\hat{n} \cdot \vec{B}^{\text{above}} = \hat{r} \cdot \vec{B}^{\text{above}} = \frac{8}{3} \pi M \cos \theta$$

$$\hat{n} \cdot \vec{B}^{\text{below}} = \hat{r} \cdot \vec{B}^{\text{below}} = \frac{8}{3} \pi M (\hat{r} \cdot \hat{z}) = \frac{8}{3} \pi M \cos \theta$$

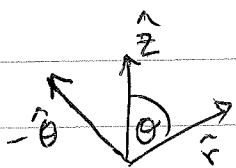
\Rightarrow normal component of \vec{B} is continuous

tangential component of \vec{H}

outside: $\vec{M} = 0 \Rightarrow \vec{H} = \vec{B}$

$$\vec{H}_{\text{above}}^t = \left(\frac{4}{3} \pi M\right) \sin \theta \hat{\theta}$$

inside: $\vec{H} = \vec{B} - 4\pi \vec{M} = \vec{B} - 4\pi \left(\frac{3}{8\pi} \vec{B}\right) = \vec{B} - \frac{3}{2} \vec{B} = -\frac{1}{2} \vec{B}$
 $= -\frac{4\pi M}{3} \hat{z}$



so $\vec{H}_{\text{below}}^t = -\frac{4\pi}{3} M (\hat{z} \cdot \hat{\theta}) = \frac{4\pi}{3} M \sin \theta \hat{\theta}$

\Rightarrow tangential component \vec{H} is continuous

Note: tangential component \vec{B} should jump by $\frac{4\pi}{c} \vec{K}_b \times \hat{n} = 4\pi M \sin \theta \hat{\theta}$

inside:

to check: $\vec{B}_{\text{below}}^t = \frac{8}{3} \pi M (\hat{z} \cdot \hat{\theta}) \hat{\theta} = -\frac{8}{3} \pi M \sin \theta \hat{\theta}$

$$\vec{H}_{\text{above}}^t = \vec{B}_{\text{above}}^t \Rightarrow \vec{B}_{\text{above}}^t - \vec{B}_{\text{below}}^t = \frac{4\pi}{3} M \sin \theta \hat{\theta} + \frac{8}{3} \pi M \sin \theta \hat{\theta}$$

$$= 4\pi M \sin \theta \hat{\theta} = \frac{4\pi}{c} \vec{K}_b \times \hat{r}$$

since $\hat{\theta} = \hat{\phi} \times \hat{r}$