

Alternatively, thinking of entropy (not energy) as the basic thermo function

$$\left(\frac{\partial S}{\partial E}\right)_{V,N} = \frac{1}{T}$$

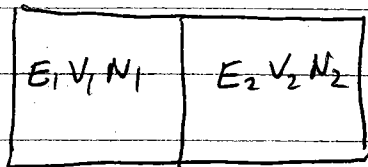
$$T dS = dE + p dV - \mu dN$$

$$\rightarrow dS = \frac{1}{T} dE + \frac{p}{T} dV - \frac{\mu}{T} dN$$

$$\left(\frac{\partial S}{\partial V}\right)_{E,N} = \frac{p}{T}$$

$$\left(\frac{\partial S}{\partial N}\right)_{E,V} = -\frac{\mu}{T}$$

Thermal equilibrium



$$E = E_1 + E_2$$

$$S = S_1(E_1, N_1, V_1) + S_2(E_2, N_2, V_2)$$

↑ immoveable, impermeable, insulating wall.
 ("adiabatic" wall \rightarrow no flows of heat)

as long as wall is in place, subsystems cannot exchange energy, volume, or particles

("diathermal" wall - conducts heat)

- 1) suppose now the wall is changed to a thermally conducting one, so the systems can exchange energy? what will be the new E_1 and E_2 after the system equilibrates?

$E = E_1 + E_2$ is fixed constant by conservation of energy

But E_1 and $E_2 = E - E_1$ can change

$$E = E_1 + E_2 \quad \text{fixed} \Rightarrow dE = dE_1 + dE_2 = 0$$

$$dE_2 = -dE_1$$

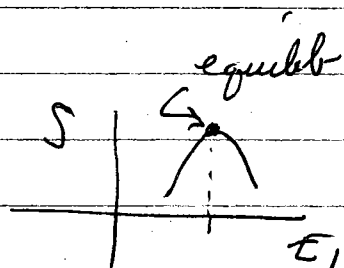
change in entropy
as system equilibrates

$$S = S_1 + S_2$$

$$dS = \left(\frac{\partial S_1}{\partial E_1} \right)_{V_1, N_1} dE_1 + \left(\frac{\partial S_2}{\partial E_2} \right)_{V_2, N_2} dE_2$$

$$= \frac{1}{T_1} dE_1 + \frac{1}{T_2} dE_2$$

$$= \left(\frac{1}{T_1} - \frac{1}{T_2} \right) dE_1$$



equilibrium is when S becomes maximum

$\Rightarrow dS = 0$, i.e. S will not change for small changes in dE_1 ,

$$\Rightarrow \boxed{T_1 = T_2}$$

system is in equilibrium when the two subsystems have the same temperature.

Mechanical Equilibrium

\Rightarrow Now suppose the wall is made thermally conducting
AND it is allowed to slide.

$$E = E_1 + E_2$$

$$V = V_1 + V_2$$

V_1 and $V_2 = V - V_1$ may change, but total volume V stays fixed

$$\Rightarrow dE_1 = -dE_2$$

$$dV_1 = -dV_2$$

assume wall moves slowly so that no energy is dissipated in friction of moving wall.

as system equilibrates the change in entropy is

$$dS = \left(\frac{\partial S_1}{\partial E_1} \right)_{V_1, N_1} dE_1 + \left(\frac{\partial S_1}{\partial V_1} \right)_{E_1, N_1} dV_1 + \left(\frac{\partial S_2}{\partial E_2} \right)_{V_2, N_2} dE_2 + \left(\frac{\partial S_2}{\partial V_2} \right)_{E_2, N_2} dV_2$$

$$= \frac{1}{T_1} dE_1 + \frac{P_1}{T_1} dV_1 + \frac{1}{T_2} dE_2 + \frac{P_2}{T_2} dV_2$$

$$= \left(\frac{1}{T_1} - \frac{1}{T_2} \right) dE_1 + \left(\frac{P_1}{T_1} - \frac{P_2}{T_2} \right) dV_2$$

$$dS = 0 \text{ at equilib so } \Rightarrow T_1 = T_2$$

$$P_1 = P_2$$

When volume can change, equilib is reached when pressure of ~~subsystem~~ subsystems are equal.

Chemical Equilib

3) Now suppose wall becomes conducting, can slide, and is permeable to particles?

$$E = E_1 + E_2 \Rightarrow dE_1 = -dE_2$$

$$V = V_1 + V_2 \Rightarrow dV_1 = -dV_2$$

$$N = N_1 + N_2 \Rightarrow dN_1 = -dN_2$$

tot number N fixed, but N_1 and $N_2 = N - N_1$ vary

$$dS = \left(\frac{\partial S_1}{\partial E_1} \right)_{V_1, N_1} dE_1 + \left(\frac{\partial S_1}{\partial V_1} \right)_{E_1, N_1} dV_1 + \left(\frac{\partial S_1}{\partial N_1} \right)_{E_1, V_1} dN_1$$

$$+ \left(\frac{\partial S_2}{\partial E_2} \right)_{V_2, N_2} dE_2 + \left(\frac{\partial S_2}{\partial V_2} \right)_{E_2, N_2} dV_2 + \left(\frac{\partial S_2}{\partial N_2} \right)_{E_2, V_2} dN_2$$

$$= \left(\frac{1}{T_1} - \frac{1}{T_2} \right) dE_1 + \left(\frac{P_1}{T_1} - \frac{P_2}{T_2} \right) dV_1 - \left(\frac{\mu_1}{T_1} - \frac{\mu_2}{T_2} \right) dN_1$$

$$dS = 0 \Rightarrow T_1 = T_2, \quad P_1 = P_2, \quad \mu_1 = \mu_2$$

when particles can be exchanged, equilib is reached when the subsystems have equal chemical potential.

The role of statistical mechanics is to calculate the entropy from the microscopic details of the system. Once the entropy is known, all thermodynamic properties follow.

~~Convexity of the Entropy~~

~~From postulate II we know S will be maximized whenever a constraint is removed. We can use this to show that S is a convex function of its variables. Consider a system that we conceptually split in half (no physical wall~~

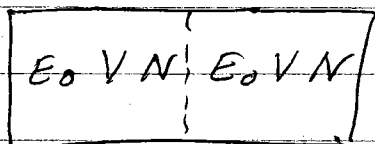
$\frac{E}{2} + \Delta E$	$\frac{E}{2} - \Delta E$
$\frac{N}{2}$	$\frac{N}{2}$

~~in equilibrium, $\Delta E = 0$, as the two halves must have equal energy. But consider how the entropy changes if ΔE is allowed to vary.~~

Concavity

Concavity of the Entropy

Callen Chpt 3 + 5

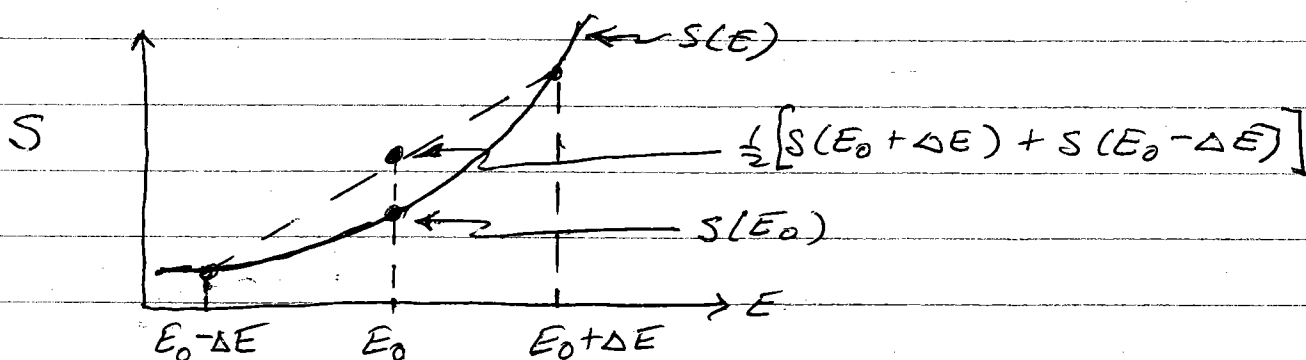


consider a container of gas
conceptually divide into two
equal halves (no physical wall)

If N and V are fixed to be the same on both sides,
we expect the energy will be equal on both sides

$$S^{\text{total}} = S(2E_0, 2V, 2N) = S(E_0, V, N) + S(E_0, V, N)$$

Consider how S depends on E . If S were not
^{concave} a ~~convex~~ function of E (i.e. if $\partial^2 S / \partial E^2 > 0$) then
the system would be unstable as follows:



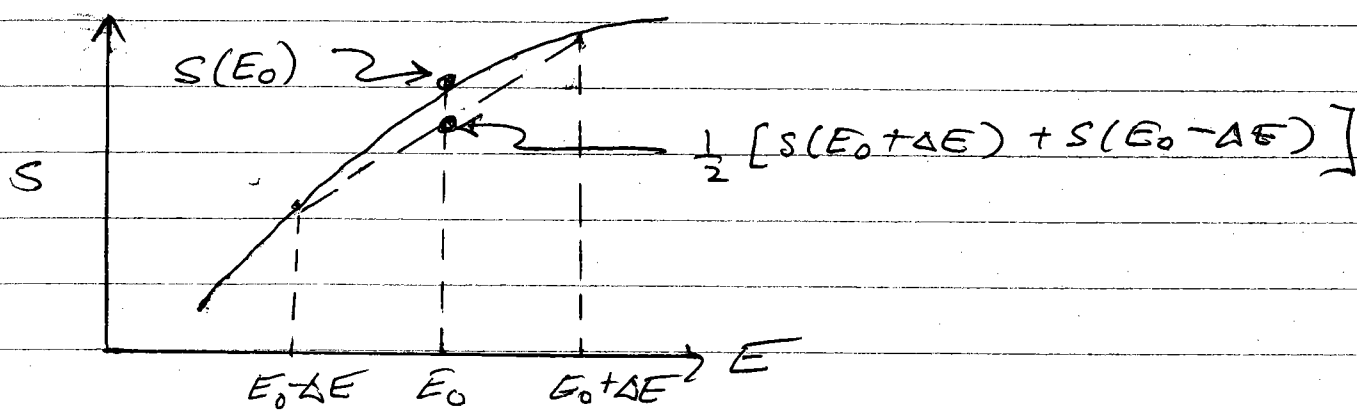
If $S(E)$ is not ^{concave} convex, then we have from above

$$S^{\text{total}} = 2S(E_0) < S(E_0 + \Delta E) + S(E_0 - \Delta E)$$

Therefore, the total system would increase its
entropy by having the LHS with $E_0 - \Delta E$, and
the RHS with $E_0 + \Delta E$ — the system would
not be stable with equal energies on both sides!

Since, by Postulate II, the system acts so as to maximize its entropy, we see that the system will be unstable if $S(E)$ is not ~~convex~~ ^{concave}.

If $S(E)$ is ~~convex~~ ^{concave}, i.e. $\frac{\partial^2 S}{\partial E^2} < 0$, this does not happen



$$\text{Now } 2S(E_0) > S(E_0 + \Delta E) + S(E_0 - \Delta E)$$

The maximum total entropy S^{total} will be when both halves have equal energy E_0 .

$\Rightarrow S(E)$ is ~~convex~~ concave

By similar argument, S must be a ~~convex~~ ^{concave} function of all its variables.

$$d^2 S < 0 \quad \text{concave}$$

Further consequences of S being a 1st order homogeneous function

$$\lambda S(E, V, N) = S(\lambda E, \lambda V, \lambda N)$$

$\Rightarrow \lambda E(S, V, N) = E(\lambda S, \lambda V, \lambda N)$ E is also a 1st order homogeneous function

differentiate with respect to S .

$$\Rightarrow \lambda \left(\frac{\partial E(S, V, N)}{\partial S} \right)_{V, N} = \left(\frac{\partial E(\lambda S, \lambda V, \lambda N)}{\partial (\lambda S)} \right)_{\lambda V, \lambda N} \left(\frac{\partial (\lambda S)}{\partial S} \right)$$

$$\Rightarrow \lambda T(S, V, N) = T(\lambda S, \lambda V, \lambda N) \lambda$$

$$T(S, V, N) = T(\lambda S, \lambda V, \lambda N)$$

similarly from $p = -\left(\frac{\partial E}{\partial V}\right)_{S, N}$ and $\mu = \left(\frac{\partial E}{\partial N}\right)_{S, V}$
we conclude

$$\left. \begin{aligned} T(S, V, N) &= T(\lambda S, \lambda V, \lambda N) \\ p(S, V, N) &= p(\lambda S, \lambda V, \lambda N) \\ \mu(S, V, N) &= \mu(\lambda S, \lambda V, \lambda N) \end{aligned} \right\}$$

T, p, μ are homogeneous functions of zeroth order

let $\lambda = \frac{1}{N}$, then

$$\left. \begin{aligned} T(S, V, N) &= T\left(\frac{S}{N}, \frac{V}{N}, 1\right) = T(\alpha, \nu) \\ p(S, V, N) &= p\left(\frac{S}{N}, \frac{V}{N}, 1\right) = p(\alpha, \nu) \\ \mu(S, V, N) &= \mu\left(\frac{S}{N}, \frac{V}{N}, 1\right) = \mu(\alpha, \nu) \end{aligned} \right\} \text{ "equation of state"}$$

T, p, μ are really functions of only two
intensive variables $s = S/N$ and $v = V/N$

Since the three variables T, p, μ are all
functions of the two variables u, v , there
must exist a relation among them - T, p, μ
are not independent.

For example, one could imagine taking the two
equations $T = T(s, v)$ and $p = p(s, v)$
and solving for s and v in terms of T and p .
One could then take this result and substitute
it into the third equation $\mu = \mu(s, v)$ to
get a relation $\mu = \mu(T, p)$.

The differential form for this constraint on
 T, p, μ is known as the Gibbs-Duhem
relation. We derive it as follows:

Consider:

$$\lambda E(S, V, N) = E(\lambda S, \lambda V, \lambda N)$$

differentiate with respect to λ

$$\begin{aligned} E(S, V, N) &= \left(\frac{\partial E(\lambda S, \lambda V, \lambda N)}{\partial(\lambda S)} \right)_{\lambda V, \lambda N} \left(\frac{\partial(\lambda S)}{\partial \lambda} \right) \\ &+ \left(\frac{\partial E(\lambda S, \lambda V, \lambda N)}{\partial(\lambda V)} \right)_{\lambda S, \lambda N} \left(\frac{\partial(\lambda V)}{\partial \lambda} \right) \\ &+ \left(\frac{\partial E(\lambda S, \lambda V, \lambda N)}{\partial(\lambda N)} \right)_{\lambda S, \lambda V} \left(\frac{\partial(\lambda N)}{\partial \lambda} \right) \end{aligned}$$

$$\Rightarrow E(S, V, N) = T(\lambda_S, \lambda_V, \lambda_N) S \\ - p(\lambda_S, \lambda_V, \lambda_N) V \\ + \mu(\lambda_S, \lambda_V, \lambda_N) N$$

$$E(S, V, N) = T(S, V, N) S - p(S, V, N) V + \mu(S, V, N) N$$

$$(*) \quad \boxed{E = TS - pV + \mu N} \quad \underline{\text{Euler relation}}$$

or dividing by N

$$u = Ts - pV + \mu$$

Now from the fundamental definitions of T, p, μ we can write

$$dE = \left(\frac{\partial E}{\partial S} \right)_{V, N} dS + \left(\frac{\partial E}{\partial V} \right)_{S, N} dV + \left(\frac{\partial E}{\partial N} \right)_{S, V} dN$$

$$\Rightarrow dE = TdS - pdV + \mu dN$$

But from (*) above we can write

$$dE = TdS + SdT - pdV - Vdp + \mu dN - Nd\mu$$

Subtracting these two differential relations gives

$$\boxed{SdT - Vdp + Nd\mu = 0}$$

or

$$\boxed{d\mu = -s dT + v dp}$$

Gibbs-Duhem
relation

one cannot vary $T, P, \text{ and } \mu$ independently.

The Gibbs-Duhem relation gives the variation of one in terms of the variation in the other two.

We can also derive a Gibbs-Duhem relation in the entropy formulation:

$$S = \frac{E}{T} + \frac{P}{T} V - \frac{\mu}{T} N \quad \text{from Euler relation}$$

$$\Rightarrow dS = E d\left(\frac{1}{T}\right) + \frac{1}{T} dE + V d\left(\frac{P}{T}\right) + \frac{P}{T} dV - N d\left(\frac{\mu}{T}\right) - \frac{\mu}{T} dN$$

but from definitions $\left(\frac{\partial S}{\partial E}\right)_{V,N} = \frac{1}{T}$, $\left(\frac{\partial S}{\partial V}\right)_{E,N} = \frac{P}{T}$, $\left(\frac{\partial S}{\partial N}\right)_{E,V} = -\frac{\mu}{T}$
we get

$$dS = \left(\frac{1}{T}\right) dE + \left(\frac{P}{T}\right) dV - \left(\frac{\mu}{T}\right) dN$$

combining with the above we get

$$E d\left(\frac{1}{T}\right) + V d\left(\frac{P}{T}\right) - N d\left(\frac{\mu}{T}\right) = 0$$

$$\text{or } d\left(\frac{\mu}{T}\right) = u d\left(\frac{1}{T}\right) + v d\left(\frac{P}{T}\right)$$

Summary

The fundamental thermodynamic function, which determines all thermodynamic behavior, is the entropy

$S(E, V, N)$ as function of the extensive variables
 E, V, N

or equivalently the total internal energy

$E(S, V, N)$ as function of the extensive variable
 S, V, N

The partial derivatives

$$\left. \begin{aligned} \left(\frac{\partial E}{\partial S}\right)_{V, N} &= T(S, V, N) \\ -\left(\frac{\partial E}{\partial V}\right)_{S, N} &= p(S, V, N) \\ \left(\frac{\partial E}{\partial N}\right)_{S, V} &= \mu(S, V, N) \end{aligned} \right\} \begin{array}{l} \text{give the three} \\ \text{"equations of state"} \end{array}$$

If one knows the three equations of state, then it is equivalent to knowing the fundamental thermodynamic function since by Euler's relation

$$E = TS - pV + \mu N$$

If one knows any two of the equations of state one can find the third by using the Gibbs-Duhem relation