

example: The ideal monatomic gas

$$\text{From expt: } PV = Nk_B T \Rightarrow \frac{P}{T} = \frac{N}{V} k_B = \frac{k_B}{v}$$
$$E = \frac{3}{2} Nk_B T \Rightarrow \frac{1}{T} = \frac{3}{2} k_B \frac{N}{E} = \frac{3}{2} \frac{k_B}{u}$$

if we can find μ , then we have entropy S via

$$S = \frac{E}{T} + \frac{P}{T} V - \frac{\mu}{T} N$$

From Gibbs-Duhem relation in entropy representation

$$d\left(\frac{\mu}{T}\right) = u d\left(\frac{1}{T}\right) + v d\left(\frac{P}{T}\right)$$
$$= u \frac{3}{2} k_B d\left(\frac{1}{u}\right) + v k_B d\left(\frac{1}{v}\right)$$

$$d\left(\frac{\mu}{T}\right) = -\frac{3}{2} \frac{k_B}{u} du - \frac{k_B}{v} dv$$

integrate to get

$$\left(\frac{\mu}{T}\right) - \left(\frac{\mu}{T}\right)_0 = -\frac{3}{2} k_B \ln\left(\frac{u}{u_0}\right) - k_B \ln\left(\frac{v}{v_0}\right)$$

where u_0 at v_0 are some reference state, and $(\mu/T)_0$ is an unknown constant of integration. Then one gets

$$S = \frac{E}{T} + \frac{P}{T} V - \frac{\mu}{T} N = \frac{3}{2} \frac{k_B E}{(E/N)} + \frac{k_B V}{(V/N)}$$
$$+ \frac{3}{2} N k_B \ln\left(\frac{u}{u_0}\right) + k_B N \ln\left(\frac{v}{v_0}\right) - \left(\frac{\mu}{T}\right)_0 N$$

$$S = \frac{3}{2} k_B N + k_B N - \left(\frac{\mu}{T}\right)_0 N + N k_B \ln\left[\left(\frac{u}{u_0}\right)^{3/2} \left(\frac{v}{v_0}\right)\right]$$

$$E = uN, E_0 = u_0 N_0, V = vN, V_0 = v_0 N_0$$

$$S = \frac{N}{N_0} S_0 + N k_B \ln \left[\left(\frac{E}{E_0} \right)^{3/2} \left(\frac{V}{V_0} \right) \left(\frac{N}{N_0} \right)^{-5/2} \right]$$

where $S_0 = \frac{5}{2} k_B N_0 + \left(\frac{\mu}{T_0} \right) N_0$ a constant
fundamental equation, expresses S in terms of E, V, N

alternatively

$$dS = \frac{1}{T} dE + \frac{P}{T} dV - \frac{\mu}{T} dN$$

$$\Rightarrow d\alpha = \frac{1}{T} du + \frac{P}{T} dv$$

$$= \frac{3}{2} \frac{k_B}{u} du + \frac{k_B}{v} dv$$

$$\alpha - \alpha_0 = \frac{3}{2} k_B \ln(u/u_0) + k_B \ln(v/v_0)$$

$$\alpha = \alpha_0 + \frac{3}{2} k_B \ln(u/u_0) + k_B \ln(v/v_0)$$

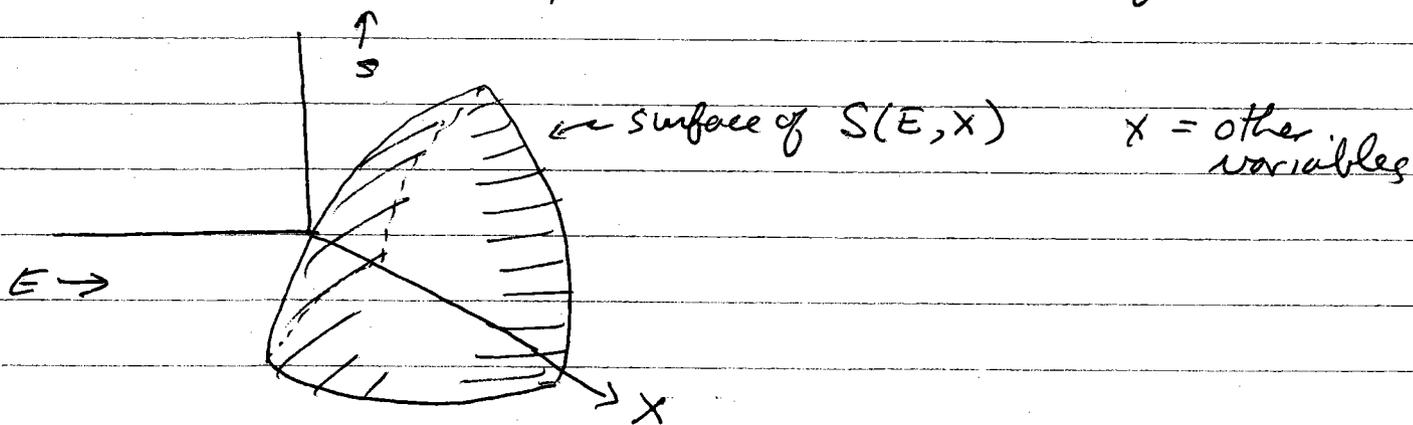
$$\alpha = \alpha_0 + k_B \ln \left[\left(\frac{u}{u_0} \right)^{3/2} \left(\frac{v}{v_0} \right) \right] \text{ same as above}$$

fundamental equation, expresses α in terms of u and v

Energy Minimum Principle

Postulate II stated that when constraints are removed, the equilibrium state will be the one that maximizes the entropy $S(E, V, N, \dots)$

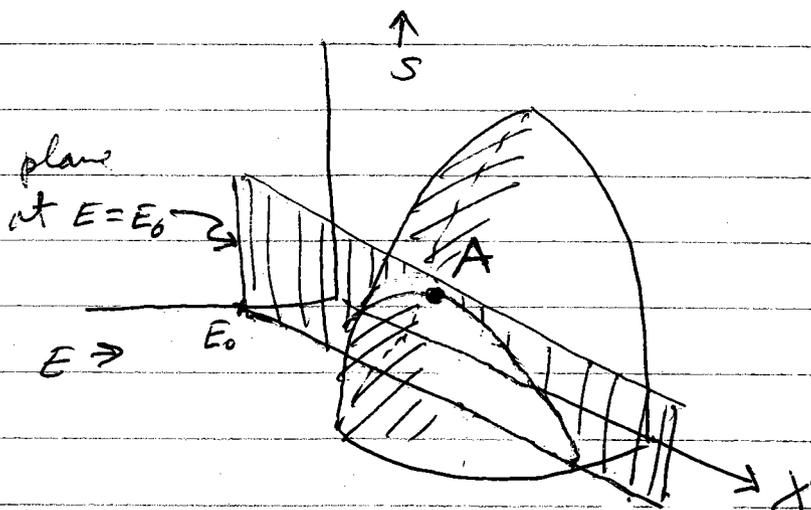
We saw that entropy is a ^{concave} convex function of its variables



For a situation where the total E is held fixed, at value E_0 , then if X is an unconstrained degree of freedom, it will take in equilibrium that value X_0 that maximizes S for the given fixed E_0 . This is determined by the intersection of the surface $S(E_0, X)$ with the plane at fixed $E = E_0$.

X_0 is given by the point A that maximizes S along this curve of intersection

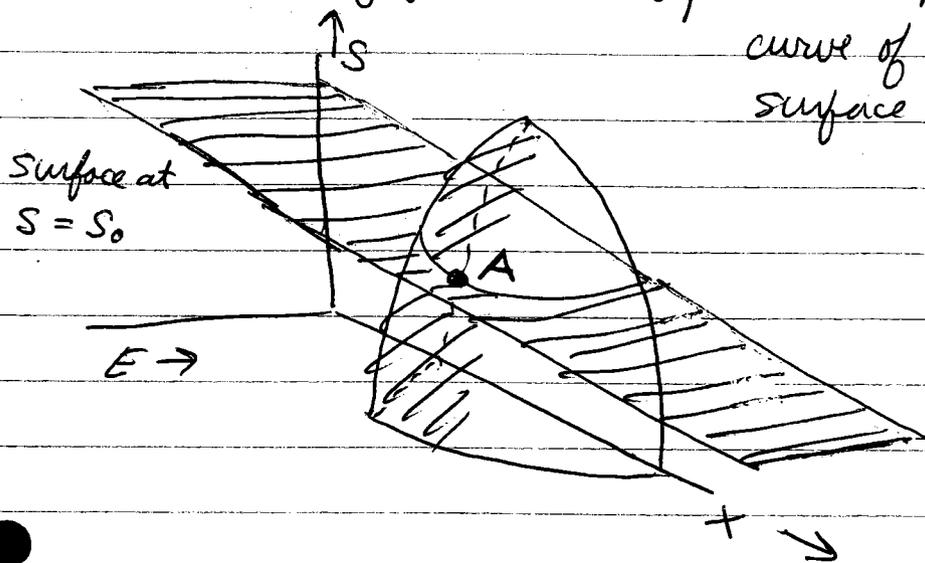
$$S_0 = \max_X [S(E_0, X)]$$



Callen Fig 5.1

Suppose now an alternative situation in which the total entropy S is held fixed at value S_0 .

Then if X is an unconstrained degree of freedom we see that the equilibrium state at S_0, E_0 corresponds to minimizing the energy with respect to X , along the curve of intersection between $S(E, X)$ surface and plane of const $S = S_0$.



Callen Fig 5.2

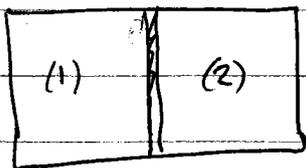
$$E_0 = \min_X [E(S_0, X)]$$

We thus have two contrasting formulations:

Entropy formulation: fundamental function is $S(E, X_1, X_2, \dots)$
 if constraint on some X_i is removed, X_i will take the value that maximizes S for the fixed total energy E . In equilib, $d^2S < 0$. S ~~convex~~ ^{concave}

Energy formulation: fundamental function is $E(S, X_1, X_2, \dots)$
 if constraint on some X_i is removed, X_i will take the value that minimizes E for the fixed total entropy S . In equilib $d^2E > 0$
 E ~~concave~~ ^{convex}

Example



$$\underline{dQ = T_1 ds_1 = T_2 ds_2 = 0}$$

thermally insulating wall
allowed to slide

Since wall is thermally insulating, no heat flows across it. $\Rightarrow dQ = T ds = 0$ So entropy on each side remains constant. S_1, S_2 fixed... or $ds_1 = ds_2 = 0$. What condition determines equilib?

Total $S = S_1 + S_2$ is const. Use energy for minimization

$$E = E_1(S_1, V_1, N_1) + E_2(S_2, V_2, N_2) \quad \left. \begin{array}{l} N_1, N_2 \\ S_1, S_2 \end{array} \right\} \text{fixed}$$

$$V_1 + V_2 = V \text{ fixed} \Rightarrow dV_1 = -dV_2$$

$$dE = \left(\frac{\partial E_1}{\partial S_1} \right)_{VN} ds_1 + \left(\frac{\partial E_1}{\partial V_1} \right)_{SN} dV_1 + \left(\frac{\partial E_1}{\partial N_1} \right)_{SV} dN_1 \\ + \left(\frac{\partial E_2}{\partial S_2} \right)_{VN} ds_2 + \left(\frac{\partial E_2}{\partial V_2} \right)_{SN} dV_2 + \left(\frac{\partial E_2}{\partial N_2} \right)_{SV} dN_2$$

$$= T_1 ds_1 - p_1 dV_1 + \mu_1 dN_1 + T_2 ds_2 - p_2 dV_2 + \mu_2 dN_2$$

$$= -p_1 dV_1 - p_2 dV_2 \quad \text{as } ds_1 = ds_2 = dN_1 = dN_2 = 0$$

$$= (-p_1 + p_2) dV_1$$

as expected

at equilib, E is minimum, $dE = 0 \Rightarrow \boxed{p_1 = p_2}$
energy is lowered as system does work by moving wall

We could also do this in the entropy formulation

$$\begin{aligned} ds_1 &= \frac{1}{T_1} dE_1 + \frac{P_1}{T_1} dV_1 - \frac{\mu_1}{T_1} dN_1 = 0 \\ ds_2 &= \frac{1}{T_2} dE_2 + \frac{P_2}{T_2} dV_2 - \frac{\mu_2}{T_2} dN_2 = 0 \end{aligned} \quad \left. \begin{array}{l} \text{since wall is} \\ \text{thermally insulating} \end{array} \right\}$$

$$\text{wall impermeable} \Rightarrow dN_1 = dN_2 = 0$$

$$ds_1 = 0 \Rightarrow dE_1 + P_1 dV_1 = 0$$

$$ds_2 = 0 \Rightarrow dE_2 + P_2 dV_2 = 0$$

$$P_1 = - \frac{dE_1}{dV_1} \quad P_2 = - \frac{dE_2}{dV_2}$$

$$V_1 + V_2 = V \text{ fixed} \Rightarrow dV_1 = -dV_2$$

$$\text{at equilibrium, } E \text{ is a minimum} \Rightarrow dE = dE_1 + dE_2 = 0$$

$$\Rightarrow dE_1 = -dE_2$$

$$\Rightarrow P_1 = P_2 \quad \text{same as by energy method.}$$

Suppose we had some equilib state for which E was not the minimum possible value for the given S .

Then can withdraw energy from the system by doing mechanical work (for example drive a piston) while keeping S constant.

$$\begin{array}{ccccc} \text{start} & \text{do mechanical} & & \text{add heat} & \\ & \text{work} & & & \\ E_0, S_0 & \xrightarrow{\quad} & E_1, S_0 & \xrightarrow{\quad} & E_0, S_1 \\ & & \text{where } E_1 < E_0 & & \text{where } S_1 > S_0 \end{array}$$

now return this energy to the system in the form of heat $E_0 - E_1 = dQ = T dS$. The energy is now back to E_0 , but the entropy has increased by $dS = (E_0 - E_1)/T$.

The system is restored to its original energy but with a higher value of entropy. But this contradicts the requirement that the original equilib state was a maximum of entropy. \Rightarrow original E had to have been the minimum.

We have now two equivalent representations

- 1) entropy $S(E, V, N)$ energy E , volume V , number N held fixed
- 2) energy $E(S, V, N)$ entropy S , volume V , number N held fixed

In certain cases it is more natural to regard temperature T as held constant, rather than S ; or to regard pressure p as held constant, rather than V ; or to regard chemical potential μ as held constant, rather than N .

We therefore wish to develop new formulations of thermodynamics that will allow us to regard T , p , or μ as a fundamental variable rather than S , V , or N . These new formulations will lead to the Helmholtz and Gibbs free energies that play the role of ~~entropy~~ ^{energy} analogous to ~~entropy~~ as the fundamental thermodynamic function of these new formulations.

For example, we have $E(S, V, N)$ with $T = \left(\frac{\partial E}{\partial S}\right)_{V, N}$

How can we make a thermodynamic "potential" that contains all the information of $E(S, V, N)$ but depends on T rather than S .