

Physics 403

Frequentist Methods for Handling
Systematic Uncertainties

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Table of Contents

1 Review of Systematic Effects

- Producing an Error Budget
- How (Not) to Estimate a Systematic Uncertainty
- How (Not) to Report an Anomaly

2 Frequentist Approach to Systematics

- The Δ or “Shift” Method
- Monte Carlo Approach
- Covariance Matrix Approach
- Adding Constraints to the Likelihood
- The Pull Method

3 Summary

Review of Systematic Effects



- ▶ When designing an experiment and taking data, you need to worry about systematic effects and offsets
- ▶ Systematics are not caused by faulty calibration or equipment; those are **mistakes**
- ▶ When taking data, test the robustness of results by **varying the conditions**: analysis cuts, techniques, etc.
- ▶ Worry about offsets and unexpected results, try to remove them
- ▶ Assign a systematic uncertainty when other options are exhausted. Knowing **when to cut your losses** comes with experience

An Example Error Budget

- ▶ Here is a systematic **error budget** for the energy scale of an air fluorescence detector, discussed in the last class:

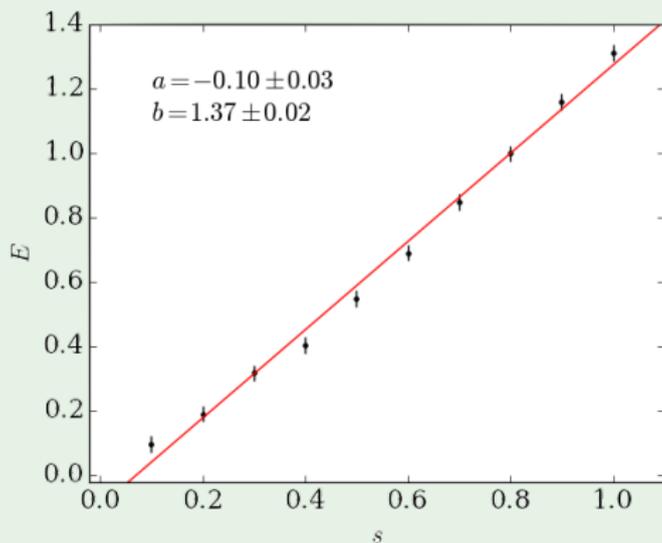
Source	Uncertainty
Fluorescence Yield Y	14%
ρ , T , e Effects on Y	7%
Calibration	9.5%
Atmosphere	4%
Reconstruction	10%
Invisible Energy	4%
Total	22%

- ▶ Note how the uncertainties are added in quadrature. What has been assumed here?
- ▶ If you were working on this experiment, which uncertainties would you try to minimize first? **What is the best use of your time?**

Case Study: Fitting an Inappropriate Function

Example

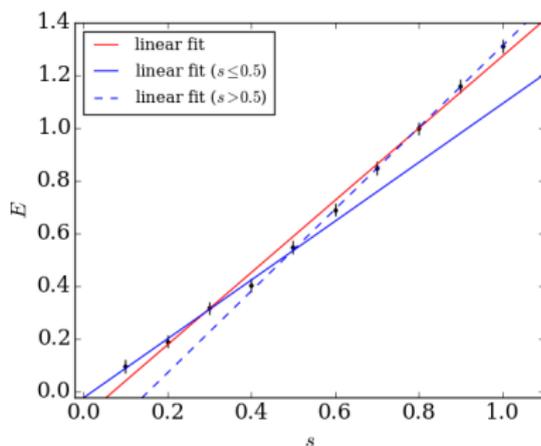
Suppose you have a calorimeter that gives you a signal s , which is related to energy by $E = s + 0.3s^2$ [1].



You take data and fit a straight line $E = a + b \cdot s$, and use the values \hat{a} and \hat{b} in your analysis.

Case Study: Fitting an Inappropriate Function

- ▶ You find that $\chi^2 = 16.94$ with 8 degrees of freedom, which is large but not unreasonable. (What is the approximate p -value?)
- ▶ So you stick with the linear fit, but as a check you calibrate (i.e., fit) the subranges $0 \leq s \leq 0.5$ and $0.5 < s \leq 1$ separately:



- ▶ Result: the slopes are 1.17 ± 0.03 and 1.57 ± 0.06 , definitely not agreeing within statistical uncertainties.

Case Study: Fitting an Inappropriate Function

- ▶ You follow the procedure for dealing with systematic effects (check, re-check, worry) but fail to spot that the linear calibration is itself inadequate.
- ▶ Result: you incorporate a systematic uncertainty of $1.57 - 1.37 = 1.37 - 1.17 = 0.2$ into the slope b , reporting

$$b = 1.37 \pm 0.02 \pm 0.20$$

Is this reasonable?

Case Study: Fitting an Inappropriate Function

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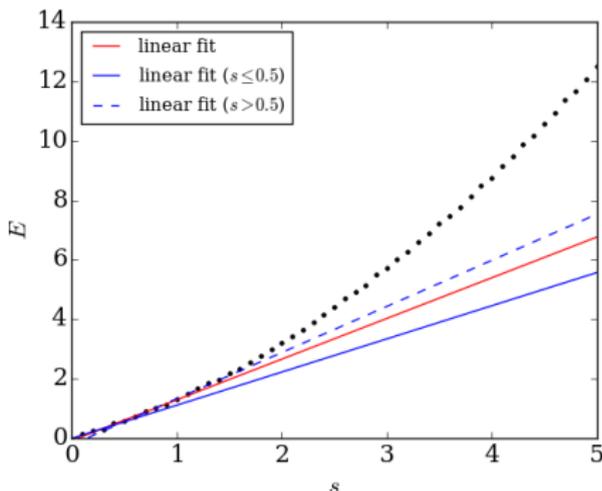
$$b = 1.37 \pm 0.02 \pm 0.20$$

Is this reasonable?

- ▶ In the region $0 \leq s \leq 1$ this systematic uncertainty **seriously overstates the error**.
- ▶ Look again at the fit. The slope 1.37 is a pretty reasonable description of the data

Case Study: Fitting an Inappropriate Function

- ▶ What happens if the “calibration” of $E(s)$ is **extrapolated** to $s = 5$?



- ▶ The linear extrapolation is clearly no good. Not only that, but the systematic uncertainty is **worthless** for describing the calibration offset
- ▶ Lesson: there is no correct procedure for incorporating a check that fails, but **folding it into the systematics is probably wrong and should be avoided unless there is no alternative**

Case Study: Superluminal Neutrinos

Example

- ▶ Recall the ν_μ time-of-flight anomaly measured by OPERA and discussed earlier in the semester [2]:

$$(v_\nu - c)/c = (2.48 \pm 0.28 \pm 0.30) \times 10^{-5}$$

- ▶ This result is in **significant tension with Einstein's relativity**. Later, a competitor experiment did not observe this effect [3]
- ▶ The OPERA collaboration carried out many checks of their analysis before making the announcement (Sep. 2011)
- ▶ Checks of the equipment were not redone until December 2011. In December they discovered that a partially unscrewed optical fiber was affecting the time-of-flight measurement
- ▶ **Question:** did the OPERA collaboration do the right thing by going public with their anomaly? What could/should they have done differently?

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Quantitative Approach to Handling Systematics

Suppose you've done your "homework" and identified and removed all the systematic effects you can. You are left with some irreducible uncertainties:

- ▶ Calibration uncertainties
- ▶ Contributions from known sources of background with statistical uncertainties
- ▶ "Theory errors," e.g., a cross section calculated to some finite accuracy
- ▶ Inputs with measurement uncertainties, e.g., Hubble's constant H_0

If you're a Bayesian, you would **propagate** these kinds of uncertainties using **marginalization** (recall your homework problem about distance and recession velocity)

In the frequentist approach, there are also standard methods for handling systematics. This is what we will discuss today

The Δ Method

- ▶ The Δ or Shift Method [4] is based on the linear propagation of errors
- ▶ Given N nuisance parameters μ_i with **uncorrelated Gaussian uncertainties** σ_i and an estimator of the parameter of interest $f(\mu_1, \dots, \mu_N)$, the linear approximation gives

$$\sigma_f^2 \approx \sum_{i=1}^N \left(\frac{\partial f}{\partial \mu_i} \right)^2 \sigma_i^2$$

- ▶ If f is roughly linear over the region $\mu_i \pm \sigma_i$, then

$$\frac{\partial f}{\partial \mu_i} \approx \frac{f(\mu_1, \dots, \mu_i + \sigma_i, \dots, \mu_N) - f(\mu_1, \dots, \mu_i, \dots, \mu_N)}{\sigma_i} = \frac{\Delta_i}{\sigma_i}$$

$$\therefore \sigma_f^2 \approx \sum_{i=1}^N \Delta_i^2$$

I.e., you just **add all the 1σ shifts in quadrature**.

△ Method Example: Linear Fit with Distorting Systematics

- ▶ Nice example from Scott Oser: we have a model that predicts $y = a + bx$ and data $x_i, y_i, \sigma_i = 1$ giving

$$\hat{a} = 4.60 \pm 0.93, \quad \hat{b} = 0.46 \pm 0.12$$

- ▶ Suppose the y_i are **systematically biased** by $\Delta y_i = \alpha x_i + \beta x_i^2$, where we believe that $\alpha = 0.00 \pm 0.05$ and $\beta = 0.00 \pm 0.01$
- ▶ Make a table with various permutations of the $\pm 1\sigma$ errors:

α	β	a	b	Δa	Δb
0	0	4.602	0.464	0.000	0.000
0.05	0	4.602	0.414	0.000	-0.050
-0.05	0	4.602	0.514	0.000	0.050
0	0.01	4.228	0.604	-0.374	0.140
0	-0.01	4.975	0.324	0.373	-0.140

Δ Method Example: Linear Fit with Distorting Systematics

- ▶ We treat the systematic uncertainties in the **nuisance parameters** α and β as uncorrelated and add them in quadrature:

$$\hat{a} = 4.60 \pm 0.93 \text{ (stat)} \pm 0.37 \text{ (sys)} = 4.60 \pm 1.00$$

$$\hat{b} = 0.46 \pm 0.12 \text{ (stat)} \pm 0.15 \text{ (sys)} = 0.46 \pm 0.19$$

- ▶ There is nothing in the Δ method that forces us to assume uncorrelated uncertainties. Given the full covariance matrix of the nuisance parameters \mathbf{V} including correlations, we could write

$$\begin{aligned}\sigma_f^2 &\approx \sum_{i=1}^N \sum_{j=1}^N \Delta_i \Delta_j \left(\frac{V_{ij}}{\sigma_i \sigma_j} \right) \\ &= \sum_{i=1}^N \sum_{j=1}^N \Delta_i \Delta_j \rho_{ij}\end{aligned}$$

where ρ_{ij} is the **correlation coefficient** for variables i and j

Monte Carlo Propagation of Systematics

If you can identify nuisance parameters and assign PDFs to them (not just Gaussians), Monte Carlo is a good way to propagate the uncertainties

1. Start by **randomly sampling values** of each nuisance parameter from its PDF
2. **Analyze the data** using the sampled values
3. Return to step 1 and repeat until you have enough statistics

Given the set of Monte Carlo samples you generated, you can plot the distribution of each parameter of interest. The **width of the distribution** gives the systematic uncertainty on the parameter

To identify the relative importance of each parameter, you can **marginalize** over the other parameters or rerun the Monte Carlo varying just one systematic uncertainty at a time

Monte Carlo Propagation of Systematics

Advantages of the Monte Carlo technique:

- ▶ **Free of assumptions** about the PDFs such as Gaussianity
- ▶ Considers effects of all systematics jointly
- ▶ **Handles correlations** between systematic uncertainties

Disadvantages of the Monte Carlo technique:

- ▶ The method does not allow the data to constrain the systematics; for that you use the **pull method**
- ▶ The technique does not allow you to identify the relative importance of each nuisance parameter unless you marginalize or vary the parameters one by one
- ▶ Monte Carlo can be a slow way to propagate uncertainties

Covariance Matrix Approach

Imagine measurements x_i which have **independent statistical uncertainties** σ_i and a common systematic uncertainty σ_s . E.g., the $\{x_i\}$ have a **systematic additive offset** $s \pm \sigma_s$, such that $x_i \rightarrow x_i + s$

$$\begin{aligned}\text{var}(x_i) &= \langle x_i^2 \rangle - \langle x_i \rangle^2 \\ &= \langle (x_i + s)^2 \rangle - \langle x_i + s \rangle^2 \\ &= \langle x_i^2 \rangle + \langle s^2 \rangle + \cancel{\langle 2sx_i \rangle} - \langle x_i \rangle^2 - \langle s \rangle^2 - \cancel{2\langle x_i \rangle \langle s \rangle} \\ &= \sigma_i^2 + \sigma_s^2\end{aligned}$$

$$\begin{aligned}\text{cov}(x_i, x_j) &= \langle x_i x_j \rangle - \langle x_i \rangle \langle x_j \rangle \\ &= \langle (x_i + s)(x_j + s) \rangle - \langle x_i + s \rangle \langle x_j + s \rangle \\ &= [\langle x_i x_j \rangle - \langle x_i \rangle \langle x_j \rangle] + [\langle x_i s \rangle - \langle x_i \rangle \langle s \rangle] + [\langle x_j s \rangle - \langle x_j \rangle \langle s \rangle] \\ &\quad + \langle s^2 \rangle - \langle s \rangle^2 \\ &= \cancel{\text{cov}(x_i, x_j)} + \cancel{\text{cov}(x_i, s)} + \cancel{\text{cov}(x_j, s)} + \text{var}(s) \\ &= \sigma_s^2\end{aligned}$$

Covariance Matrix Approach

- ▶ Thus, the covariance matrix \mathbf{V} is written

$$\begin{aligned} V_{ij} &= \text{cov}(x_i, x_j) = \delta_{ij}\sigma_i^2 + \sigma_s^2 \\ &= \begin{pmatrix} \sigma_1^2 + \sigma_s^2 & \sigma_s^2 & \dots \\ \sigma_s^2 & \sigma_2^2 + \sigma_s^2 & \dots \\ \vdots & \vdots & \ddots \end{pmatrix} \end{aligned}$$

with the systematic uncertainty σ_s **added in quadrature** to the statistical uncertainties σ_i

- ▶ Note that if the systematic uncertainty were **proportional to the measurement** such that $\sigma_s = \epsilon x$, we could have written

$$V_{ij} = \begin{pmatrix} \sigma_1^2 + \epsilon^2 x_1^2 & \epsilon^2 x_1 x_2 & \dots \\ \epsilon^2 x_1 x_2 & \sigma_2^2 + \epsilon^2 x_2^2 & \dots \\ \vdots & \vdots & \ddots \end{pmatrix}$$

Covariance Matrix Approach

- ▶ Generalizing, if there is another systematic uncertainty σ_T shared by x_1 and x_2 but not x_3 , the covariance matrix becomes

$$V_{ij} = \begin{pmatrix} \sigma_1^2 + \sigma_s^2 + \sigma_T^2 & \sigma_s^2 + \sigma_T^2 & \sigma_s^2 \\ \sigma_s^2 + \sigma_T^2 & \sigma_2^2 + \sigma_s^2 + \sigma_T^2 & \sigma_s^2 \\ \sigma_s^2 & \sigma_s^2 & \sigma_3^2 + \sigma_s^2 \end{pmatrix}$$

- ▶ Once we have a covariance matrix, we can write down

$$\chi^2 = \sum_{i=1}^N \sum_{j=1}^N (x_i - \mu - \hat{s}) V_{ij}^{-1} (x_j - \mu - \hat{s}).$$

if we have an existing estimator \hat{s} . Minimizing χ^2 will give a ML/LS estimator $\hat{\mu}$.

Handling a Systematic Offset

- ▶ Let $s = 2.0 \pm 0.4$, $\{x_i\} = (10.0, 10.0, 11.0, 12.0)$, and $\sigma_i = 1.0$
- ▶ What one would usually do is **solve for the central value** $\hat{\mu}$ given the estimator $\hat{s} = 2.0$:

$$\hat{\mu} = \frac{1}{N} \sum_{i=1}^4 x_i - \hat{s} = 8.75$$

$$\text{var}(\hat{\mu}) = \frac{1}{\sum_i 1/\sigma_i^2} = \frac{1}{4}$$

$$\therefore \hat{\mu} = 8.75 \pm 0.5 \text{ (stat)}$$

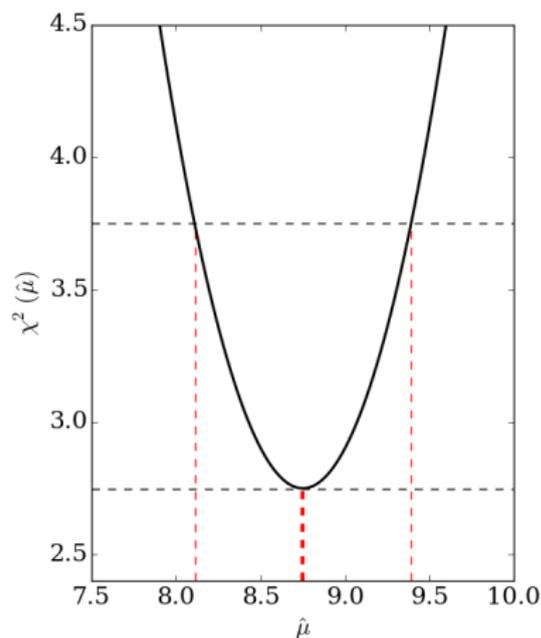
- ▶ There is also a systematic uncertainty on the parameter due to σ_s , which can be **added in quadrature** to the statistical uncertainty:

$$\begin{aligned}\hat{\mu} &= 8.75 \pm 0.5 \text{ (stat)} \pm 0.4 \text{ (sys)} = 8.75 \pm \sqrt{0.5^2 + 0.4^2} \\ &= 8.75 \pm 0.64\end{aligned}$$

Solution using χ^2 Minimization

Just to demonstrate that it works, here is the result of minimizing

$$\chi^2 = \sum_{i=1}^N \sum_{j=1}^N (x_i - \mu - \hat{s}) V_{ij}^{-1} (x_j - \mu - \hat{s})$$



- ▶ The χ^2 minimum is $\hat{\mu} = 8.75$
- ▶ Using $\Delta\chi^2 = 1$ to identify the 1σ uncertainty on $\hat{\mu}$ (exact this time because all errors are **Gaussian**) gives

$$\hat{\mu} = 8.75 \pm 0.64$$

- ▶ So the ML/LS methods we described last week can be applied in the presence of systematic uncertainties

Adding Constraints to the Likelihood

- ▶ Recall the definition of the posterior PDF given parameters θ and α :

$$p(\theta, \alpha | D, I) \propto p(D | \theta, \alpha, I) p(\theta | I) p(\alpha | I)$$

- ▶ The ML estimator $\ln \mathcal{L}(\theta) = \ln p(D | \theta, I)$ assumes a **flat prior on θ**
- ▶ This is easy to generalize to include a systematic in terms of a **nuisance parameter α** :

$$\ln \mathcal{L}(\theta, \alpha) = \ln \mathcal{L}(\theta | D, \alpha) + \ln p(\alpha)$$

- ▶ The first term is a regular likelihood. The second is a constraint or “penalty” term and behaves like a prior on α
- ▶ **Note:** $p(\alpha)$ can be any valid PDF, so this can handle **non-Gaussian uncertainties**

Adding Constraints to the Likelihood: Two Rulers

- ▶ We have discussed the example of measuring a length with two separate thermally expanding rulers made of different materials:

$$y_i = L_i + c_i(T - T_0),$$

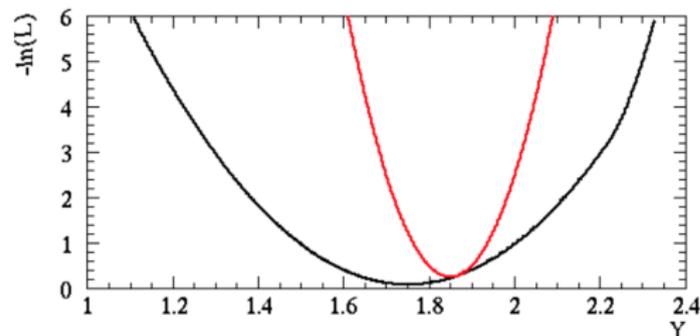
where y_i are the measured lengths, L_i are the lengths measured at T_0 , and c_i are the coefficients of expansion

- ▶ We want to calculate the “true length” y considering T as a **nuisance parameter** $T = 23 \pm 2$:

$$-2 \ln \mathcal{L}(y, T) = \sum_{i=1}^2 \left(\frac{y - L_i - c_i(T - T_0)}{\sigma_L} \right)^2 + \left(\frac{T - 23}{2} \right)^2$$

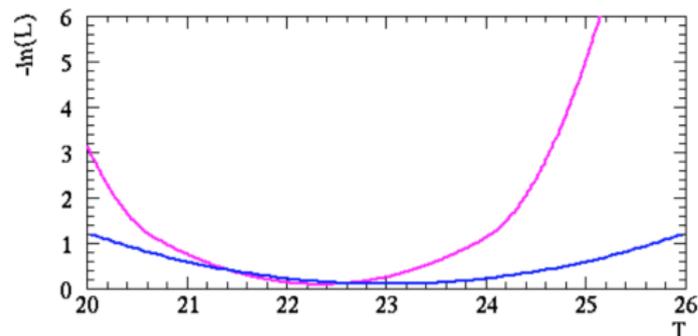
- ▶ The first term is the usual Gaussian likelihood, and the second is a Gaussian constraint on T
- ▶ Procedure: **marginalize over T** to get the shape of the likelihood as a function of y

Constraint Term in the Likelihood



Top plot: $-\ln \mathcal{L}(y, T)$ after marginalizing T

- ▶ Red: fixed T
- ▶ Black: marginalize $-\ln \mathcal{L}$ as function of T in $y \pm 1\sigma$ range



Bottom: marginalizing y

- ▶ Blue: “a priori” constraint on $T = 23 \pm 2$
- ▶ Magenta: log likelihood after marginalization of y

The “Pull” Method

- ▶ A technique equivalent to the use of the covariance matrix, but easier to apply in practice, is the **pull method**
- ▶ Given observables y_i , predictions $f_i = f(x_i)$, and a covariance matrix V_{ij} , minimize

$$\chi^2 = \sum_{i=1}^N \sum_{j=1}^N (y_i - f_i) V_{ij}^{-1} (y_j - f_j)$$

- ▶ In the pull method, factorize the uncertainties into **uncorrelated errors** u_i and **correlated systematic uncertainties** c_i^k (the shift of observable i by systematic error source k). Shift the difference $y_i - f_i$ by the amount $-c_i^k \xi_k$, where ξ_k is a Gaussian:

$$y_i - f_i \rightarrow (y_i - f_i) - \sum_{k=1}^K c_i^k \xi_k$$
$$\therefore \chi_{\text{pull}}^2 = \min_{\{\xi_k\}} \left[\sum_{i=1}^N \left(\frac{y_i - f_i - \sum_k c_i^k \xi_k}{u_i} \right)^2 + \sum_{k=1}^K \xi_k^2 \right]$$

The “Pull” Method

- ▶ Denote $\bar{\xi}_k$, the **pulls of the systematics**, as the values of ξ_k at the minimum
- ▶ Define \bar{x}_i , the **pulls of the observables** as

$$\bar{x}_i = \frac{y_i - (f_i + \sum_k \bar{\xi}_k c_i^k)}{u_i}$$

- ▶ We can then split χ_{pull}^2 into two diagonalized pieces:

$$\begin{aligned}\chi_{\text{pull}}^2 &= \chi_{\text{obs}}^2 + \chi_{\text{sys}}^2 \\ &= \sum_{i=1}^N \bar{x}_i^2 + \sum_{k=1}^K \bar{\xi}_k^2\end{aligned}$$

I.e., we separate the χ^2 into contributions from the **residuals of the observables x_i** and from the **systematics ξ_k**

Example: “Pull” Method

- ▶ To illustrate the method in practice, let's go back to the example of data of form $y = a + bx$ with systematic offsets $\Delta y_i = \alpha x_i + \beta x_i^2$
- ▶ The pull χ^2 is **minimized with respect to the nuisance parameters** α and β :

$$\chi_{\text{pull}}^2 = \sum_i \left(\frac{y_i - a - bx_i - \alpha x_i - \beta x_i^2}{1.0} \right)^2 + \left(\frac{\alpha - 0}{0.05} \right)^2 + \left(\frac{\beta - 0}{0.01} \right)^2$$

Case	a	b
fix α, β	4.64 ± 0.93	0.46 ± 0.12
min $\alpha, \text{fix } \beta$	4.65 ± 0.93	0.45 ± 0.13
fix $\alpha, \text{min } \beta$	4.65 ± 0.99	0.45 ± 0.18
min $\alpha, \text{min } \beta$	4.65 ± 0.99	0.45 ± 0.19

Example: “Pull” Method

- ▶ By minimizing with respect to the nuisance parameters α and β , we are doing the frequentist equivalent of **marginalization**
- ▶ To break the systematic uncertainty out of the total uncertainty, calculate the **quadrature difference** of the statistical and total uncertainties:

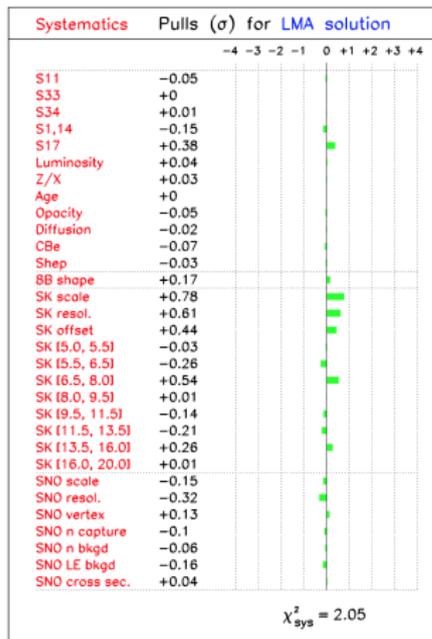
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fix $\alpha, \text{min } \beta$	4.65 ± 0.99	0.45 ± 0.18
min $\alpha, \text{min } \beta$	4.65 ± 0.99	0.45 ± 0.19

$$a = 4.65 \pm 0.93 \text{ (stat)} \pm \sqrt{0.99^2 - 0.93^2} = 4.65 \pm 0.93 \pm 0.34$$

$$b = 0.45 \pm 0.12 \text{ (stat)} \pm \sqrt{0.19^2 - 0.12^2} = 0.45 \pm 0.12 \pm 0.15$$

Plotting the Pulls

It is useful to plot the pulls \bar{x}_i and $\bar{\xi}_k$ for the N parameters and K systematics, since it helps you to pick out which parts of the fit (if any) are dominating the disagreement with a model. For example [5],



Pull vs. Covariance Method

- ▶ The pull method puts nuisance parameters on the same footing as other parameters by adding **penalty terms to the likelihood/ χ^2**
- ▶ The data are used to reject certain values of the nuisance parameters (α and β in our linear fit example) and keep their range reasonable
- ▶ So if you use a frequentist approach, your choices are to add constraint terms to the likelihood and minimize, or calculate the covariance matrix between all points and minimize that
- ▶ It is **easier to work with pulls** because the constraints on the systematics are more obvious
- ▶ Try not to use the Δ method if you don't have to. You won't get the same kinds of constraints from the data that you get using **marginalization** or the pull/covariance techniques

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Summary

- ▶ In frequentist statistics, it is convenient to separate uncertainties into values that depend on the **statistics in the data** and values that depend on **systematic effects**
- ▶ Don't get hung up on the idea that these uncertainties are completely different. As in the Bayesian world, you can combine the errors into a total uncertainty
- ▶ Systematics can be absorbed into ML/LS techniques by expressing them as correlated errors in a **covariance matrix** or using the **pull method**
- ▶ Systematics can be expressed in a likelihood as **penalty terms**, which you can marginalize or maximize to get a **profile likelihood**
- ▶ This approach lets you incorporate **asymmetric uncertainties**; see [6] for how to handle asymmetric error bars in published data

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- [6] Roger Barlow. “Asymmetric Errors”. In: *PHYSTAT 2003*. SLAC, 2003, pp. 250–255.