So far, electrostatics:
\[ \nabla \cdot E = 4\pi k_1 \phi \quad \text{Gauss} \]
\[ \nabla \times E = 0 \]

Magnetostatics:
\[ \nabla \cdot B = 0 \]
\[ \nabla \times B = 4\pi k_5 \mathbf{j} \quad \text{Amperé} \]

Current conservation:
\[ \frac{\partial \mathbf{J}}{\partial t} = 0 \]

True dependent situations

Faraday's law of induction:
\[ \nabla \times E \neq 0 \]
\[ \oint \mathbf{E} \cdot d\mathbf{l} = -k_3 \frac{\partial \mathbf{B}}{\partial t} \]

Voltage around closed loop = time rate of change of magnetic flux through loop.

\[ \Rightarrow \nabla \times E = -k_3 \frac{\partial \mathbf{B}}{\partial t} \]

\( k_3 \) is universal constant.

Maxwell correction to Ampère's law:

In our derivation of \( \nabla \times B = 4\pi k_5 \mathbf{j} \),
we used \( \nabla \cdot \mathbf{j} = 0 \). This is only true for magnetostatics. It is NOT true in general.

Alternatively, since \( \nabla \cdot (\nabla \times \mathbf{B}) = 0 \) always,
if Ampère's law was true, we would necessarily conclude that \( \nabla \cdot \mathbf{j} = 0 \). But
\[ \nabla \cdot \mathbf{j} = -\frac{\partial \mathbf{E}}{\partial t} \neq 0 \text{ in general.} \]
Proposed correction: \( \nabla \times \vec{B} = 4\pi k_5 \vec{J} + \vec{W} \)

where \( \vec{W} \) must be such that charge conservation holds.

Now
\[ \nabla \cdot (\nabla \times \vec{B}) = 0 = 4\pi k_5 \nabla \cdot \vec{J} + \nabla \cdot \vec{W} \]

\[ \Rightarrow \nabla \cdot \vec{W} = -4\pi k_5 \nabla \cdot \vec{J} = 4\pi k_5 \frac{\partial \vec{J}}{\partial t} \text{ by charge conservation} \]

\[ = \frac{k_5}{k_1} \frac{\partial \vec{E}}{\partial t} \text{ by Gauss law} \]

\[ \Rightarrow \vec{W} = \frac{k_5}{k_1} \frac{\partial \vec{E}}{\partial t} \]

So corrected Ampere's law is
\[ \nabla \times \vec{B} = 4\pi k_5 \vec{J} + \frac{k_5}{k_1} \frac{\partial \vec{E}}{\partial t} \]

⇒ EM waves

Now consider \( \nabla \times (\nabla \times \vec{B}) = \nabla (\nabla \cdot \vec{B}) - \nabla^2 \vec{B} \)

\[ = -\nabla^2 \vec{B} \text{ as } \nabla \cdot \vec{B} = 0 \]

If there are no sources \((\vec{J} = 0, \vec{E} = 0)\) then

\[ \nabla \times (\nabla \times \vec{B}) = -\nabla^2 \vec{B} = \frac{k_5}{k_1} \frac{\partial^2 \vec{E}}{\partial t^2} \]

\[ = -\frac{k_5 k_3}{k_1} \frac{\partial^2 \vec{B}}{\partial t^2} \text{ by Faraday} \]

\[ \nabla^2 \vec{B} = \frac{k_5 k_3}{k_1} \frac{\partial^2 \vec{B}}{\partial t^2} \text{ this is the wave equation} \]

\[ \Rightarrow \frac{k_5 k_3}{k_1} \text{ has units of } \text{(velocity)}^2 \]
Since we know that the above wave equation describes electromagnetic waves, i.e., light, then
\[
\frac{k_5 k_3}{k_1} = \frac{1}{c^2}
\]
we already had \( \frac{k_4 k_5}{k_1} = \frac{1}{c^2} \)

\[\Rightarrow k_3 = k_4\]

\[\Rightarrow k_1 \text{ and } k_4 \text{ are arbitrary - they can be chosen to be anything by adjusting the units of } \phi \text{ and } B. \text{ } k_3 \text{ and } k_5 \text{ are then fixed by } \frac{k_4 k_5}{k_1} = \frac{1}{c^2} \text{ and } k_3 = k_4\]

**Popular systems of E&M units**

<table>
<thead>
<tr>
<th>System</th>
<th>( k_1 )</th>
<th>( k_2 = k_4 )</th>
<th>( k_3 )</th>
<th>( k_5 )</th>
</tr>
</thead>
<tbody>
<tr>
<td>MKS or SI</td>
<td>( \frac{1}{4\pi \varepsilon_0} )</td>
<td>1</td>
<td>( \frac{\mu_0}{4\pi} )</td>
<td>( \varepsilon_0 = \frac{1}{c^2} )</td>
</tr>
<tr>
<td>Gaussian or CGS</td>
<td>1</td>
<td>( \frac{1}{c} )</td>
<td>( \frac{1}{c} )</td>
<td></td>
</tr>
<tr>
<td>Rationalized Gaussian</td>
<td>( \frac{1}{4\pi} )</td>
<td>( \frac{1}{c} )</td>
<td>( \frac{1}{4\pi c} )</td>
<td></td>
</tr>
</tbody>
</table>

In MKS, charges are measured in "Coulombs", current measured in "amps", magnetic field measured in "tesla" = "weber/m^2"
In CGS, charges are measured in "statcoulombs" 
current measured in "statamperes" 
magnetic field measured in "gauss"

We will use the CGS or Gaussian units

1) \( \nabla \cdot \vec{E} = 4\pi \rho \)
2) \( \nabla \times \vec{E} = -\frac{1}{c} \frac{\partial \vec{B}}{\partial t} \)
3) \( \nabla \cdot \vec{B} = 0 \)
4) \( \nabla \times \vec{B} = \frac{4\pi}{c} \vec{J} + \frac{1}{c} \frac{\partial \vec{E}}{\partial t} \)

Maxwell's Equations

\[ F = q(\vec{E} + \frac{\vec{v} \times \vec{B}}{c}) \]

Physical content of Maxwell's equations:

1) Gauss Law for electric field - charge is source of \( \vec{E} \) field. Field lines can begin and end at point charges.
2) Faraday's Law of Induction - time varying magnetic flux produces circulating \( \vec{E} \) field.
3) Gauss Law for magnetic fields - no magnetic monopoles. Magnetic field lines are continuous, they either close upon themselves or go off to infinity; they cannot begin nor end at any point.
4) Ampere's Law + Maxwell's Correction - electric current is a source for circulating \( \vec{B} \) field; so is a time varying \( \vec{E} \) field. Maxwell's correction is necessary to have charge conservation and to give electromagnetic waves.
Note:
\[ \nabla \cdot (\nabla \times \mathbf{E}) = 0 \text{ as div of curl always vanishes,} \]
then (2) \[ -\frac{1}{c^2} \frac{\partial}{\partial t} (\nabla \cdot \mathbf{B}) = 0 \]

So if \( \nabla \cdot \mathbf{B} = 0 \) at \( t = 0 \), Eqn (2) requires that \( \nabla \cdot \mathbf{B} \)
remains zero for all time.

Similarly
\[ \nabla \cdot (\nabla \times \mathbf{B}) = 0 \]
then (4) \[ \frac{4\pi}{c} \nabla \cdot \mathbf{J} + \frac{1}{c} \frac{\partial}{\partial t} (\nabla \cdot \mathbf{E}) = 0 \]

use charge continuity \( \nabla \cdot \mathbf{J} = -\frac{\partial \rho}{\partial t} \) to get
\[ -\frac{4\pi}{c} \frac{\partial \rho}{\partial t} + \frac{1}{c} \frac{\partial}{\partial t} (\nabla \cdot \mathbf{E}) = 0 \]

\[ \frac{1}{c^2} \frac{\partial}{\partial t} (\nabla \cdot \mathbf{E} - 4\pi \rho) = 0 \]

So if \( \nabla \cdot \mathbf{E} = 4\pi \rho \) at \( t = 0 \), Eqn (4) requires that \( \nabla \cdot \mathbf{E} = 4\pi \rho \) for all time.

Thus Eqns (1) and (3) can be viewed as "initial conditions". If they are true for any
particular moment in time, then Eqns (2) and (4)
ensure that they remain true for all time.

Eqns (2) and (3) are also referred to as the homogeneous
Maxwell eqns - they involve only the fields \( \mathbf{E} + \mathbf{B} \) and
not the sources \( \mathbf{J} \) or \( \rho \). Eqns (1) and (4) are referred
to as the inhomogeneous Maxwell's eqns - they
involve the sources \( \mathbf{J} \) and \( \rho \).
Electro magnetic Potentials & Gauge Invariance

$$\nabla \cdot E = 4\pi \rho$$

$$\nabla \cdot B = 0$$

$$\nabla \times E = -\frac{\partial B}{\partial t}$$

$$\nabla \times B = \frac{4\pi J}{c} + \frac{1}{c} \frac{\partial E}{\partial t}$$

Consider first statics.

Electro statics

$$\nabla \times E = 0 \quad \text{since} \quad \frac{\partial B}{\partial t} = 0 \quad \text{for statics}$$

From vector calculus we know that if the curl of a vector is everywhere zero, then we can always write that vector field as the gradient of some scalar function $\phi$.

$$\vec{E} = -\nabla \phi \quad \Rightarrow \quad \nabla \times \vec{E} = -\nabla \times (\nabla \phi) = 0$$

$\phi$ is electrostatic potential.

Gauss law becomes

$$\nabla \cdot \vec{E} = -\nabla \cdot (\nabla \phi) = -\nabla^2 \phi = 4\pi \rho$$

$$\nabla^2 \phi = -4\pi \rho$$  \[ \text{Poisson's Equation} \]

In regions where $\phi = 0$, we have

$$\nabla \phi = 0$$  \[ \text{Laplace's Equation} \]
In our discussion of Coulomb's Law we saw that the electric field from a distribution of localized charges was

\[ E(\mathbf{r}) = \int d^3r' \frac{\rho(\mathbf{r}') \mathbf{r} - \mathbf{r}'}{|\mathbf{r} - \mathbf{r}'|} \]

\[ = - \mathbf{\nabla} \left[ \int d^3r' \frac{\rho(\mathbf{r}')}{|\mathbf{r} - \mathbf{r}'|} \right] = - \mathbf{\nabla} \phi \]

We therefore see that the solution to Poisson's equation for a localized charge distribution \( \rho \) (with \( E = 0 \) as \( r \to \infty \)) is

\[ \phi(\mathbf{r}) = \int d^3r' \frac{\rho(\mathbf{r}')}{|\mathbf{r} - \mathbf{r}'|} \]

We will soon spend a fair amount of time learning new ways to solve \( \nabla^2 \phi = \rho \), both for arbitrary \( \rho \) where we want an approximate to the above integral (multipole expansion), and for cases where \( \phi \) or \( \nabla \phi \) are predetermined on the surfaces of specified regions of space, such as conducting surfaces (boundary value problems).
Magnetostatics

\[ \nabla \cdot \mathbf{B} = 0 \]

From vector calculus we know that if the divergence of a vector field vanishes everywhere, then it can always be written as the curl of another vector field \( \mathbf{A} \)

\[ \mathbf{B} = \nabla \times \mathbf{A} \Rightarrow \nabla \cdot \mathbf{B} = \nabla \cdot (\nabla \times \mathbf{A}) = 0 \]

\( \mathbf{A} \) is the magnetic vector potential.

This remains true in general - not just in magnetostatics.

Amperes' law becomes

\[ \nabla \times \mathbf{B} = \frac{4\pi}{c} \mathbf{j} \quad (\text{in magnetostatics } \frac{\partial \mathbf{E}}{\partial t} = 0) \]

\[ \nabla \times (\nabla \times \mathbf{A}) = \frac{4\pi}{c} \mathbf{j} \]

\[ \Rightarrow \nabla (\nabla \cdot \mathbf{A}) - \nabla^2 \mathbf{A} = \frac{4\pi}{c} \mathbf{j} \]

Magnetostatic gauge invariance.

There are many possible vector potentials \( \mathbf{A} \) that result in the same \( \mathbf{B} \). If \( \mathbf{A} \) is such that \( \nabla \times \mathbf{A} = \mathbf{B} \), then

\[ \mathbf{A}' = \mathbf{A} + \nabla \times \mathbf{X} \]

also satisfies \( \nabla \times \mathbf{A}' = \mathbf{B} \) since

\[ \nabla \times \nabla \times \mathbf{X} = 0 \]

for any scalar function \( \mathbf{X}(\mathbf{r}) \).
Therefore we can always choose to represent \( \vec{B} \) by a vector potential \( \vec{A} \) such that \( \nabla \cdot \vec{A} = 0 \).

Proof: Suppose we had \( \vec{B} = \nabla \times \vec{A} \) for some \( \vec{A} \) with \( \nabla \cdot \vec{A} = D(\vec{r}) \neq 0 \). Construct an \( \vec{A}' = \vec{A} + \nabla \chi \) with \( \chi \) chosen as follows:

\[
\nabla \cdot \vec{A}' = \nabla \cdot \vec{A} + \nabla^2 \chi = 0 \quad \Rightarrow \quad \nabla^2 \chi = -\nabla \cdot \vec{A} = D
\]

Solve for \( \chi \), for example

\[
\chi(\vec{r}) = \frac{\int d^3r' D(\vec{r}')}{4\pi |\vec{r} - \vec{r}'|}
\]

We then have constructed an \( \vec{A}' \) such that

\[
\nabla \cdot \vec{A}' = \vec{B} \quad \text{and} \quad \nabla \cdot \vec{A}' = 0.
\]

This freedom to choose various \( \vec{A} \)'s that give the same \( \vec{B} \) is called gauge invariance. Imposing a particular additional constraint on \( \vec{A} \) that removes this freedom is called fixing the gauge. The choice \( \nabla \cdot \vec{A} = 0 \) is customarily known as the Coulomb gauge (or sometimes the Landau gauge). Going from \( \vec{A} \) to \( \vec{A}' = \vec{A} + \nabla \chi \) is called making a gauge transformation.

"Working in the Coulomb gauge" with \( \nabla \cdot \vec{A} = 0 \), Ampère's law becomes

\[
\nabla^2 \vec{A} = \frac{-4\pi \hat{\vec{J}}}{c}
\]

Poisson's Eqn.

For a localized current density

\[
\vec{A}(\vec{r}) = \frac{1}{4\pi} \int d^3r' \frac{\hat{\vec{J}}(\vec{r}')}{|\vec{r} - \vec{r}'|}
\]
Back to dynamics

$\vec{V} \cdot \vec{B} = 0 \Rightarrow \vec{B} = \vec{V} \times \vec{A}$ remains true

but now instead of $\vec{V} \times \vec{E} = 0$ we have

$\vec{V} \times \vec{E} + \frac{1}{c^2} \frac{\partial \vec{B}}{\partial t} = 0$

$\Rightarrow \vec{V} \times \vec{E} + \frac{1}{c^2} \frac{\partial}{\partial t} (\vec{V} \times \vec{A}) = 0$

$\Rightarrow \vec{V} \times (\vec{E} + \frac{1}{c} \frac{\partial \vec{A}}{\partial t}) = 0$

$\Rightarrow$ there exists a scalar potential $\phi$ such that

$\vec{E} + \frac{1}{c} \frac{\partial \vec{A}}{\partial t} = -\vec{V} \phi$ or $\vec{E} = -\vec{V} \phi - \frac{1}{c} \frac{\partial \vec{A}}{\partial t}$

Gauss's law for electric field now becomes

$\vec{V} \cdot \vec{E} = 4\pi \rho = -\nabla^2 \phi - \frac{1}{c^2} \frac{\partial}{\partial t} (\vec{V} \cdot \vec{A}) = 4\pi \rho$

Amper's law becomes

$\vec{V} \times \vec{B} = \frac{4\pi \vec{I}}{c} + \frac{1}{c} \frac{\partial \vec{E}}{\partial t}$

$\vec{V} \times (\vec{V} \times \vec{A}) = \frac{4\pi \vec{I}}{c} + \frac{1}{c} \frac{\partial \vec{E}}{\partial t} - \vec{V} \phi - \frac{1}{c^2} \frac{\partial \vec{A}}{\partial t}$
\[- \nabla^2 \vec{A} + \nabla (\nabla \cdot \vec{A}) = \frac{4\pi}{c^2} \vec{J} - \frac{1}{c^2} \frac{\partial}{\partial t} \left( \nabla \phi + \frac{1}{c} \frac{\partial \vec{A}}{\partial t} \right) \]

or

\[- \nabla^2 \vec{A} + \frac{1}{c^2} \frac{\partial^2 \vec{A}}{\partial t^2} = \frac{4\pi}{c^2} \vec{J} - \nabla (\nabla \cdot \vec{A} + \frac{1}{c} \frac{\partial \phi}{\partial t}) \]

**Gauge Invariance**

As before, we can always construct \( \vec{A}' = \vec{A} + \nabla \chi \), for any scalar function \( \chi \), that gives the same \( \vec{B} \). But since \( \vec{A} \) now also enters expression for \( \vec{E} \), we need to make sure that if we change \( \vec{A} \) to \( \vec{A}' \), we must make some corresponding change \( \phi \) to \( \phi' \) so that \( \vec{E} \) does not change.

\[
\begin{bmatrix}
\vec{A}' = \vec{A} + \nabla \chi \\
\phi' = \phi - \frac{1}{c} \frac{\partial \chi}{\partial t}
\end{bmatrix} \quad \text{gauge transformation}
\]

For any scalar \( \chi \), the above \( \vec{A}' \) and \( \phi' \) give the same values of \( \vec{E} \) and \( \vec{B} \) as \( \vec{A} \) and \( \phi \).

**Proof:** \( \nabla \times \vec{A}' = \nabla \times \vec{A} + \nabla \times \nabla \chi = \nabla \times \vec{A} = \vec{B} \)

\[
(- \nabla \phi' - \frac{1}{c} \frac{\partial A'}{\partial t}) = - \nabla \phi + \frac{1}{c} \nabla \frac{\partial \chi}{\partial t} - \frac{1}{c} \frac{\partial \vec{A}}{\partial t} - \frac{1}{c^2} \frac{\partial^2 \chi}{\partial t^2}
\]

\[
= (- \nabla \phi - \frac{1}{c} \frac{\partial \phi}{\partial t}) = \vec{E}
\]

As before, we can fix the gauge by imposing some additional constraint on \( \vec{A} \) and \( \phi \). There are two popular choices: