P235 - PROBLEM SET 9

To be handed in by 1800 hr on Friday, 13 November 2015.

1. Four masses, all of mass m, lie in the x - y plane at positions (x, y) = (a, 0), (-a, 0), (0, +2a), (0, -2a)T. These are joined by massless rods to form a rigid body

(a) Find the inertial tensor, using the x, y, z axes as a reference system. Exhibit the tensor as a matrix.

(b) Consider a direction given by the unit vector \hat{n} that lies equally between the positive x, y, z axes; that is it makes equal angles with these three directions. Find the moment of inertia for rotation about this \hat{n} axis.

(c) Given that at a certain time t the angular velocity vector lies along the above direction \hat{n} , find, for that instant, the angle between the angular momentum vector and \hat{n} .

2. A homogeneous cube, each edge of which has a length l, initially is in a position of unstable equilibrium with one edge of the cube in contact with a horizontal plane. The cube then is given a small displacement causing it to tip over and fall. Show that the angular velocity of the cube when one face strikes the plane is given by

$$\omega^2 = A\frac{g}{l}\left(\sqrt{2} - 1\right)$$

where $A = \frac{3}{2}$ if the edge cannot slide on the plane, and where $A = \frac{12}{5}$ if sliding can occur without friction.

- 3. Consider a thin disk composed of two homogeneous halves connected along a diameter of the disk. If one half has density ρ and the other half density 2ρ find the expression for the Lagrangian when the disk rolls without slipping along a horizontal surface.
- 4. A symmetric body moves without the influence of forces or torques. Let x_3 be the symmetry axis of the body and **L** be along x'_3 . The angle between $\boldsymbol{\omega}$ and x_3 is α . Let $\boldsymbol{\omega}$ and **L** initially be in the $x_2 x_3$ plane. What is the angular velocity of the symmetry axis about **L** in terms of $I_1, I_3, \boldsymbol{\omega}$, and α ?
- 5. Consider a thin rectangular plate with dimensions a by b and mass M. Determine the torque necessary to rotate the thin plate with angular velocity ω about a diagonal. Explain the physical behaviour for the case when a = b.