

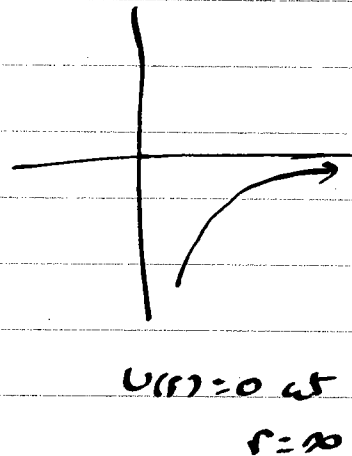
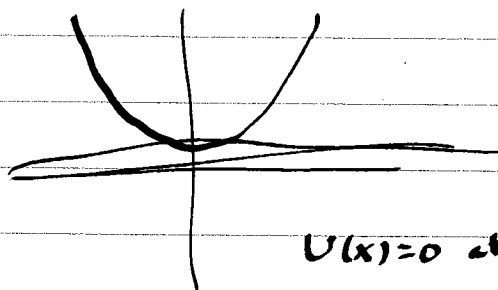
can discover functional dependence of PE $\rightarrow U$

gravity

$$U(r) = -\frac{GMm}{r}$$

Spring

$$U(x) = \frac{1}{2} K x^2$$



Force vs. Potential

$$\boxed{-\frac{dU}{dx} = F_x}$$

$$-\frac{d(\frac{1}{2} K x^2)}{dx} = -Kx = F_x$$

$$-\frac{d(-\frac{GMm}{r})}{dr} = -\frac{GMm}{r^2} = F_r$$

Consider system w/ Movement along x

$$F_x \Delta x = -\Delta PE \equiv -\Delta U$$

$$F_x = -\frac{\Delta U}{\Delta x}$$

$\Rightarrow$
in limit
of
small Δx

$$F_x = -\frac{dU}{dx}$$

do for
spring

do for
gravity

Generalize to 3d

$$\vec{F} = F_x \hat{i} + F_y \hat{j} + F_z \hat{k}$$

$$\vec{F} = -\frac{dU}{dx} \hat{i} + \frac{dU}{dy} \hat{j} + \frac{dU}{dz} \hat{k}$$

but F is fn of x, y, z $\therefore$ can't use normal derivatives
Must use partial derivatives

$$\text{Let } B(x, y, z) \quad \frac{\partial B}{\partial x} = \frac{dB}{dx} \Big|_{y, z \text{ treated as constants}}$$

$$\vec{F} = -\frac{\partial U}{\partial x} \hat{i} - \frac{\partial U}{\partial y} \hat{j} - \frac{\partial U}{\partial z} \hat{k}$$

Why do you care?

$\Rightarrow$ In the end physics often boils down to determining $\vec{F}$ at a point or in a region

$\Rightarrow$ If we know $\vec{F}$, we know motions of particles

$\vec{F}$ is a vector "field" — Sometimes hard to determine

for gravity $\frac{\vec{F}}{m} = \vec{g} \equiv \text{gravitational field}$

for electromagnetism

$$\frac{\vec{F}}{q} = \vec{E} \equiv \text{electric field}$$

Knowing $\vec{F}$ is to know $\vec{g}$ or $\vec{E}$

$\Rightarrow$ These are vector fields: often hard to calculate

But we just learned if we can understand the Potential Energy function in space we can derive the force (or $\vec{g}$ or $\vec{E}$)

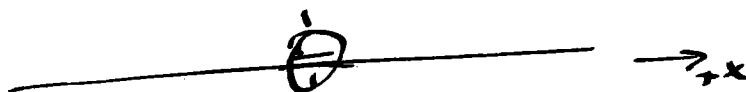
Potential Energy function is a Scalar field
often easier to understand + get than
 $\vec{E}$ or $\vec{g}$ directly!

$$\vec{F} = -\frac{\partial U}{\partial x} \hat{i} - \frac{\partial U}{\partial y} \hat{j} - \frac{\partial U}{\partial z} \hat{k}$$

define $\vec{\nabla} \equiv \frac{\partial}{\partial x} \hat{i} + \frac{\partial}{\partial y} \hat{j} + \frac{\partial}{\partial z} \hat{k}$

vector operator "del" $\equiv$ gradient

$\vec{F} = -\vec{\nabla} U$... We say the Force is
the negative gradient of the
Potential Energy function!



1
0

A bead is constrained to move along the x-axis

some combination of bubblegum, spring, + string exert force on the bead such that

~~$F_{\text{net}} = F_x = Ax^4$~~

The potential energy, $U = Ax^4$

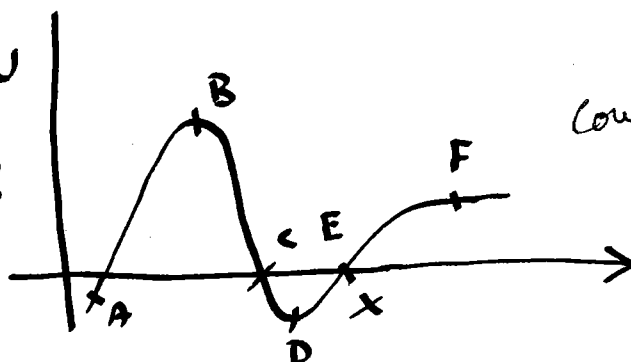
What is $F_x(x)$?

$$F_x = - \frac{dU}{dx} = - \frac{Ax^3}{3}$$

Where is force = 0? $x=0$

~~≠~~

Some system has Potential Energy Described by this curve



Could ASK TO do for Next class

At each point is F_x +, -, or 0?

At which point does F_x have the greatest Magnitude?

At which points can system be in equilibrium?

~~≠~~

do spring and gravity 1st

Example

Two atoms interact via the Van der ~~Waals~~ ^{Waals} interaction

$$U(r) = \frac{a}{r^{12}} - \frac{b}{r^6}$$



lets simplify & do as
1 d problem

$$U(x) = \frac{a}{x^{12}} - \frac{b}{x^6}$$

$$\vec{F} = -\nabla U = -\frac{\partial U}{\partial x} \hat{i} - \frac{\partial U}{\partial y} \hat{j} - \frac{\partial U}{\partial z} \hat{k}$$

because U has no y or z
dependence

$$\vec{F} = \left(-\frac{12a}{x^{13}} + 6\frac{b}{x^7} \right) \hat{i} = \left(\frac{12a}{x^{13}} - \frac{6b}{x^7} \right) \hat{i}$$

Example

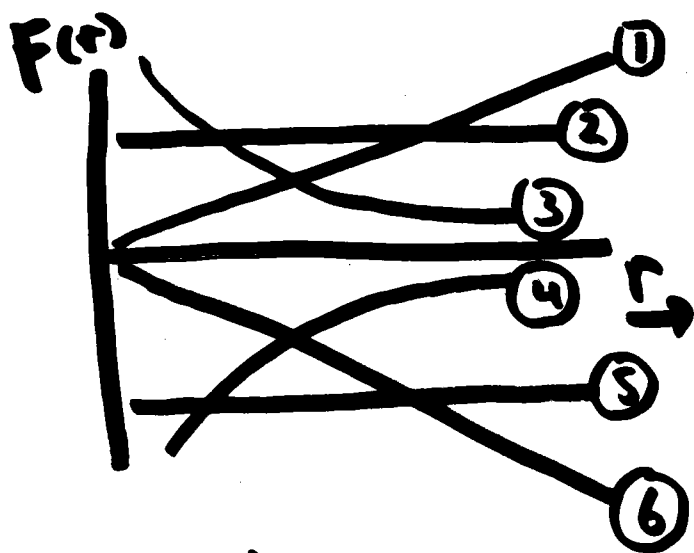
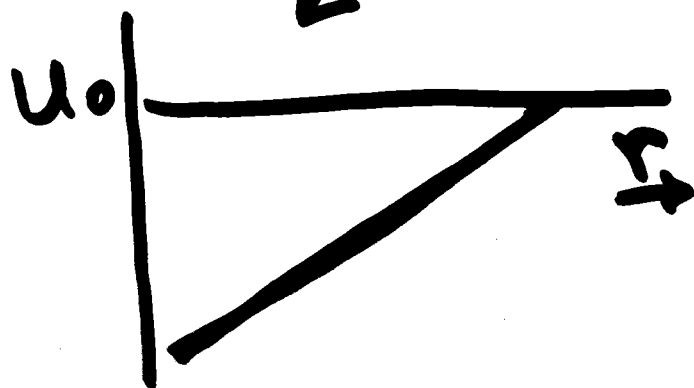
Spring

$$U(x) = \frac{1}{2} k x^2$$

$$\vec{F}(x) = -\nabla U = -kx \hat{i}$$

You discover a new subatomic particle called a Squark. Book a ticket for Stockholm!

The potential energy between two Squarks as a fn of $r \equiv \text{dist. between them}$ looks like



The force between Squarks is best described by which curve? ↗

Linear Momentum - Momentum Conservation

$$\Sigma \vec{F} = m \vec{a} = m \frac{d\vec{v}}{dt} = \frac{d(m\vec{v})}{dt}$$

define $m\vec{v} \equiv \vec{p} \equiv \text{momentum}$

vector quantity

$$p_x = mv_x$$

$$p_y = mv_y$$

$$p_z = mv_z$$

Typically $\frac{d(m\vec{v})}{dt} \Rightarrow m \text{ constant}$

$$\frac{d(m\vec{v})}{dt} = m \frac{d\vec{v}}{dt} + \vec{v} \frac{dm}{dt}$$

NOT always!

Consider a Rocket ... Burns fuel

$$\frac{d\vec{p}}{dt} = m \frac{d\vec{v}}{dt} + \vec{v} \frac{dm}{dt}$$

$$\vec{F} = \frac{d\vec{p}}{dt} \Rightarrow d\vec{p} = \vec{F} dt \Rightarrow \int_{\vec{p}_1}^{\vec{p}_2} d\vec{p} = \int_{t_1}^{t_2} \vec{F} dt$$

$$\Delta \vec{p} = \vec{p}_2 - \vec{p}_1 = \int_{t_1}^{t_2} \vec{F} dt$$

1 = initial
2 = final

> here

↙
↘
 $\equiv J \equiv \text{impulse}$

Consider two bodies colliding



not complicated
complicated

$$\Delta \vec{P}_1 = \int_{t_i}^{t_f} \vec{F}_1 dt$$

$$\Delta \vec{P}_2 = \int_{t_i}^{t_f} \vec{F}_2 dt$$

but we know from Newton's 3rd Law
that $\vec{F}_1 = -\vec{F}_2$ at all times

$$\therefore \underbrace{\int_{t_i}^{t_f} \vec{F}_1 dt}_{\Delta \vec{P}_1} = \int_{t_i}^{t_f} (-\vec{F}_2) dt = - \underbrace{\int_{t_i}^{t_f} \vec{F}_2 dt}_{\Delta \vec{P}_2}$$

$$\therefore \Delta \vec{P}_1 = -\Delta \vec{P}_2 \quad \text{or} \quad \Delta \vec{P}_1 + \Delta \vec{P}_2 = 0$$

Momentum of individual parts has changed

Σ changes in the momentum $\rightarrow 0$!

Momentum Conservation

If There are no external Forces acting on a system, the
Total Momentum of that system is conserved.

$$\text{-or- } \Sigma \Delta \vec{P} = 0 \quad \text{-or- } \Sigma \vec{P}_i = \Sigma \vec{P}_f$$



Ballistic pendulum

Don't know V_{Bullet}

Know $V_{\text{Bullet}} + V_{\text{Block}}$

is energy conserved?

always

Write it for me

$$\frac{1}{2} m v_{\text{Bullet}}^2 = \frac{1}{2} (m_{\text{Bullet}} + M_{\text{Block}}) V^2$$

X

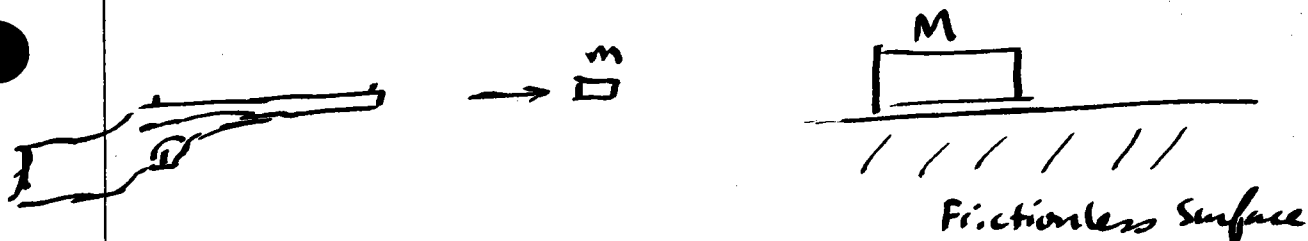
$\vec{P}$ Always conserved

KE NOT " "

if it is $\rightarrow$ elastic collision

if NOT $\rightarrow$ inelastic collision

Example



bullet fired w/

unknown velocity $\vec{V}_{\text{bullet}}$ ← Find This

embeds in block "instantaneously"

block + bullet move, $\vec{V}_f$ measured ~~B~~

Momentum cons $\rightarrow$

(Block + Bullet combo)

$$\sum \vec{P}_i = \sum \vec{P}_f$$

$$m_{\text{bullet}} \vec{V}_{\text{bullet}} + M_{\text{block}} \vec{V}_{\text{block}} = (m+M) \vec{V}_f$$

$\uparrow$
0

$$\vec{V}_{\text{bullet}} = \left(\frac{m+M}{m} \right) \vec{V}_f$$

Is energy conserved? $\rightarrow$ yes

$$KE_{\text{bullet}} = KE_{\text{bullet} + \text{Block}} \quad ? \quad \Rightarrow \underline{\underline{\text{No}}}$$

(No change in Pot energy here)

Frictional energy loss to stop bullet

$\Rightarrow$ Known as an inelastic collision

in other words

$$\frac{1}{2} m v_i^2 \neq \frac{1}{2} (m+M) v_f^2$$

You drive around a curve on a narrow, one-way Street at 25 mph when you notice a car identical to yours coming straight toward you at 25 mph.

You have 2 choices:

- hit other car head on
- Swerve into a Massive concrete wall head on

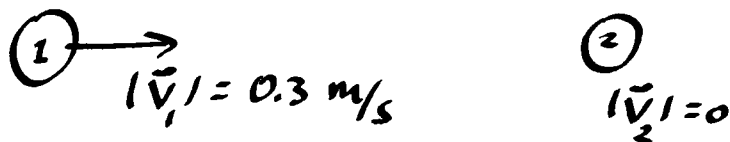
You should →

- ① Hit the other car
- ② Hit the wall
- ③ Hit either one - it makes No difference.
- ④ Consult your lecture Notes.

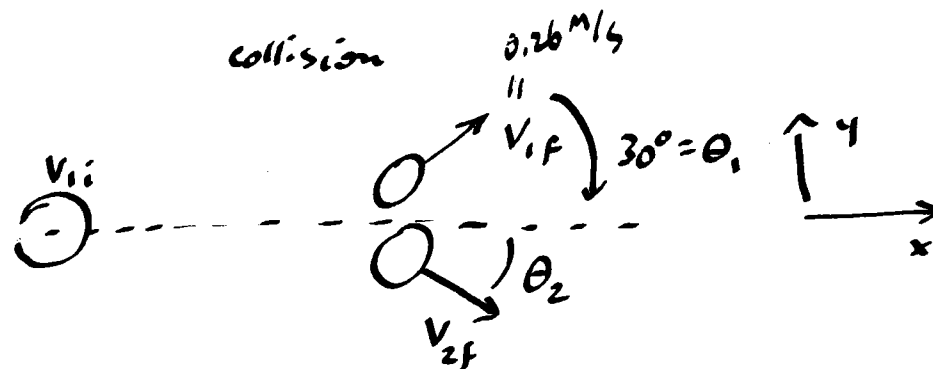
Example 4

Consider the collision of two hockey pucks
each of mass 0.1 kg

initially



Final



$$V_{1f} = 0.26 \text{ m/s}$$

What is the final ^{velocity} ~~speed~~ of the 2nd puck?

$$\sum \vec{P}_i = \sum \vec{P}_f$$

← vector eqn

same as

$$\left\{ \begin{array}{l} \sum P_{ix} = \sum P_{fx} \\ \text{— and —} \\ \sum P_{iy} = \sum P_{fy} \end{array} \right.$$

Momentum Conserved
for each component

x eqn

$$m_1 V_{1ix} + m_2 \underset{\substack{\uparrow \\ 0}}{V_{2ix}} = m_1 \underset{\substack{\uparrow \\ V_{1f} \cos 30}}{V_{1fx}} + m_2 \underset{\substack{\uparrow \\ V_{2f} \cos \theta_2}}{V_{2fx}}$$

$$\textcircled{1} \quad m_1 V_{1ix} = m_1 V_{1f} \cos 30 + m_2 V_{2f} \cos \theta_2$$

y eqn

$$m_1 \cancel{V_{1iy}} + m_2 \cancel{V_{2iy}} = m_1 \overset{\uparrow}{V_{1fy}} + m_2 \overset{\uparrow}{V_{2fy}}$$

$V_{1f} \sin 30$ $-V_{2f} \sin \theta_2$

(II) $V_{2f} \sin \theta_2 = V_{1f} \sin 30$

I $(.1)(0.3) = (.1)(0.26) \cos 30 + (.1) V_{2f} \cos \theta_2$

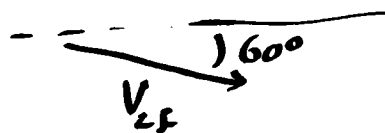
II $V_{2f} \sin \theta_2 = (0.26) \sin 30$

2 eqns, 2 unknowns V_{2f} , θ_2

should find

$$|\vec{V}_{2f}| = 0.15 \text{ m/s}$$

$\theta_2 = 60^\circ$ down from horizontal



Is The collision "elastic"?

$$\text{initial KE} = \frac{1}{2} m_1 V_{1i}^2 = \frac{1}{2} (0.1) (0.3)^2 = 4.5 \times 10^{-3} \text{ J}$$

$$\text{Final KE} = \frac{1}{2} m_1 V_{1f}^2 + \frac{1}{2} m_2 V_{2f}^2$$

$$= \frac{1}{2} (0.1) (0.26)^2 + \frac{1}{2} (0.1) (0.15)^2 = 4.5 \times 10^{-3} \text{ J}$$

Yes collision is elastic.

Kinetic Energy is conserved!