

Enhancing Parallelism

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Chapter 5, Optimizing Compilers for Modern Architectures, Allen and Kennedy
www.cs.rice.edu/~ken/comp515/lectures/

Fine-Grained Parallelism

Techniques to enhance fine-grained parallelism:

- Loop Interchange
- Scalar Expansion
- Scalar Renaming
- Array Renaming
- Node Splitting

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Motivational Example

```
DO J = 1, M
  DO I = 1, N
    T$(I) = 0.0
    DO K = 1, L
      T$(I) = T$(I) + A(I,K) * B(K,J)
    ENDDO
    C(I,J) = T$(I)
  ENDDO
ENDDO
```

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Where Does Vectorization Fail?

```
procedure vectorize (L, k, D)
// L is the maximal loop nest containing the statement.
// k is the current loop level
// D is the dependence graph for statements in L.
find the set {S1, S2, ..., Sm} of SCCs in D
construct Lp from L by reducing each Si to a single node
use topological sort to order nodes in Lp to {p1, p2, ..., pm}

for i = 1 to m do begin
  if pi is a dependence cycle then
    generate a level-k DO
    construct Di be pi dependence edges in D at level k+1 or greater
    codegen (pi, k+1, Di)
    generate the level-k ENDDO
  else
    vectorize pi with respect to every loop containing it
  end
end
end vectorize
```

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Motivational Example

```
DO J = 1, M
  DO I = 1, N
    T = 0.0
    DO K = 1, L
      T = T + A(I,K) * B(K,J)
    ENDDO
    C(I,J) = T
  ENDDO
ENDDO
```

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Motivational Example II

• Loop Distribution gives us:

```
DO J = 1, M
  DO I = 1, N
    T$(I) = 0.0
  ENDDO
  DO I = 1, N
    DO K = 1, L
      T$(I) = T$(I) + A(I,K) * B(K,J)
    ENDDO
  ENDDO
  DO I = 1, N
    C(I,J) = T$(I)
  ENDDO
ENDDO
```

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Motivational Example III

Finally, interchanging I and K loops, we get:

```
DO J = 1, M
  TS(1:N) = 0.0
  DO K = 1, L
    TS(1:N) = TS(1:N) + A(1:N,K) * B(K,J)
  ENDDO
  C(1:N,J) = TS(1:N)
ENDDO
```

- A couple of new transformations used:
 - Loop interchange
 - Scalar Expansion

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Loop Interchange

```
DO I = 1, N
  DO J = 1, M
    S  A(I,J+1) = A(I,J) + B
  ENDDO
ENDDO
```

• DV:

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Loop Interchange

- Loop interchange is a reordering transformation
- Why?
 - Think of statements being parameterized with the corresponding iteration vector
 - Loop interchange merely changes the execution order of these statements.
 - It does not create new instances, or delete existing instances

```
DO J = 1, M
  DO I = 1, N
    S  <some statement>
  ENDDO
ENDDO
```

- If interchanged, S(2, 1) will execute before S(1, 2)

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Loop Interchange: Safety

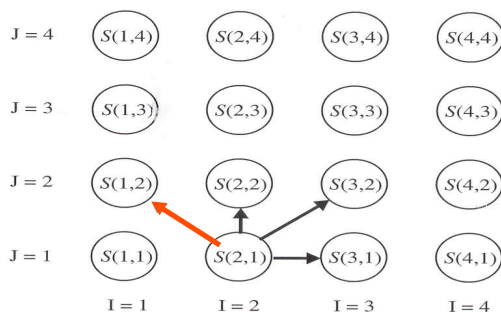
- Safety: not all loop interchanges are safe

```
DO J = 1, M
  DO I = 1, N
    A(I,J+1) = A(I+1,J) + B
  ENDDO
ENDDO
```

- If we interchange loops, will we violate a dependence

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Loop Interchange: Safety



- A dependence is interchange-preventing with respect to a given pair of loops if interchanging those loops would reorder the endpoints of the dependence.

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Scalar Expansion

Scalar Expansion

- Can we vectorize the following code?

```

DO I = 1, N
  S1  T = A(I)
  S2  A(I) = B(I)
  S3  B(I) = T
ENDDO

```

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Scalar Expansion

- However, not always profitable. Consider:

```

DO I = 1, N
  T = T + A(I) + A(I+1)
  A(I) = T
ENDDO

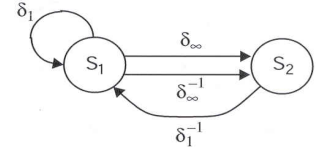
```

- Scalar expansion gives us:

```

T$(0) = T
DO I = 1, N
  S1  T$(I) = T$(I-1) + 2
  S2  A(I) = T$(I)
ENDDO
T = T$(N)

```



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Scalar Expansion: Safety

- Scalar expansion is always safe
- When is it profitable?
 - Naïve approach: Expand all scalars, vectorize, shrink all unnecessary expansions.
 - However, we want to predict when expansion is profitable
- Dependences due to reuse of memory location vs. flow of values
 - Dependences due to flows of values must be preserved
 - Dependences due to reuse of memory location can be deleted by expansion

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Scalar Expansion: Covering Definitions

- A definition X of a scalar S is a covering definition for loop L if a definition of S placed at the beginning of L reaches no uses of S that occur past X.

```

DO I = 1, 100
  S1  T = X(I)
  S2  Y(I) = T
ENDDO

```

covering

```

DO I = 1, 100
  IF (A(I) .GT. 0) THEN
    S1  T = X(I)
    S2  Y(I) = T
  ENDDIF
ENDDO

```

covering

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Scalar Expansion: Covering Definitions

- A covering definition does not always exist:

```

DO I = 1, 100
  IF (A(I) .GT. 0) THEN
    S1  T = X(I)
  ENDDIF
  S2  Y(I) = T
ENDDO

```

- In SSA terms: There does not exist a covering definition for a variable T if the edge out of the first assignment to T goes to a ϕ -function later in the loop which merges its values with those for another control flow path through the loop

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Scalar Expansion: Covering Definitions

- We will consider a collection of covering definitions
- There is a collection C of covering definitions for T in a loop if either:
 - There exists no ϕ -function at the beginning of the loop that merges versions of T from outside the loop with versions defined in the loop, or,
 - The ϕ -function within the loop has no SSA edge to any ϕ -function including itself

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Scalar Expansion: Covering Definitions

- Remember the loop which had no covering definition:

```
DO I = 1, 100
  IF (A(I) .GT. 0) THEN
    S1    T = X(I)
  ENDIF
  S2    Y(I) = T
ENDDO
```

- To form a collection of covering definitions, we can insert dummy assignments:

```
DO I = 1, 100
  IF (A(I) .GT. 0) THEN
    S1    T = X(I)
  ELSE
    S2    T = T
  ENDIF
  S3    Y(I) = T
ENDDO
```

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Scalar Expansion: Covering Definitions

- Algorithm to insert dummy assignments and compute the collection, C , of covering definitions:

- Central idea: Look for parallel paths to a ϕ -function following the first assignment, until no more exist
- Algorithm: see textbook

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Scalar Expansion: Covering Definitions

```
DO I = 1, 100
  IF (A(I) .GT. 0) THEN
    S1    T = X(I)
  ENDIF
  S2    Y(I) = T
ENDDO
```

After inserting covering definitions:

```
DO I = 1, 100
  IF (A(I) .GT. 0) THEN
    S1    T = X(I)
  ELSE
    S2    T = T
  ENDIF
  S3    Y(I) = T
ENDDO
```

After scalar expansion:

```
T$(0) = T
DO I = 1, 100
  IF (A(I) .GT. 0) THEN
    S1    T$(I) = X(I)
  ELSE
    T$(I) = T$(I-1)
  ENDIF
  S2    Y(I) = T$(I)
ENDDO
```

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Deletable Dependences

- Uses of T before covering definitions are expanded as T(I - 1)$
- All other uses are expanded as T(I)$
- The deletable dependences are:
 - Backward carried antidependences
 - Backward carried output dependences
 - Forward carried output dependences
 - Loop-independent antidependences into the covering definition
 - Loop-carried true dependences from a covering definition

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Scalar Expansion: Drawbacks

- Expansion increases memory requirements
- Solutions:
 - Expand in a single loop
 - Strip mine loop before expansion
 - Forward substitution:

```
DO I = 1, N
  T = A(I) + A(I+1)
  A(I) = T + B(I)
ENDDO
```

```
DO I = 1, N
  A(I) = A(I) + A(I+1) + B(I)
ENDDO
```

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Scalar and Array Renaming

Scalar Renaming

```
DO I = 1, 100
S1   T = A(I) + B(I)
S2   C(I) = T + T
S3   T = D(I) - B(I)
S4   A(I+1) = T * T
ENDDO
```

• Renaming scalar T:

```
DO I = 1, 100
S1   T1 = A(I) + B(I)
S2   C(I) = T1 + T1
S3   T2 = D(I) - B(I)
S4   A(I+1) = T2 * T2
ENDDO
```

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Scalar Renaming

• will lead to:

```
S3   T2$(1:100) = D(1:100) - B(1:100)
S4   A(2:101) = T2$(1:100) * T2$(1:100)
S1   T1$(1:100) = A(1:100) + B(1:100)
S2   C(1:100) = T1$(1:100) + T1$(1:100)
      T = T2$(100)
```

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Scalar Renaming

- Renaming algorithm partitions all definitions and uses into equivalent classes, each of which can occupy different memory locations:
 - Use the definition-use graph to:
 - Pick definition
 - Add all uses that the definition reaches to the equivalence class
 - Add all definitions that reach any of the uses...
 - ..until fixed point is reached

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Scalar Renaming: Profitability

- Scalar renaming will break recurrences in which a loop-independent output dependence or antidependence is a critical element of a cycle
- Relatively cheap to use scalar renaming
- Usually done by compilers when calculating live ranges for register allocation

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Array Renaming

```
DO I = 1, N
S1   A(I) = A(I-1) + X
S2   Y(I) = A(I) + Z
S3   A(I) = B(I) + C
ENDDO
```

• $S_1 \delta_\infty S_2$ $S_2 \delta_\infty^{-1} S_3$ $S_3 \delta_1 S_1$ $S_1 \delta_\infty^0 S_3$

• Rename A(I) to A\$(I):

```
DO I = 1, N
S1   A$(I) = A(I-1) + X
S2   Y(I) = A$(I) + Z
S3   A(I) = B(I) + C
ENDDO
```

- Dependences remaining: $S_1 \delta_\infty S_2$ and $S_3 \delta_1 S_1$

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Array Renaming: Profitability

- Examining dependence graph and determining minimum set of critical edges to break a recurrence is NP-complete!
- Solution: determine edges that are removed by array renaming and analyze effects on dependence graph
- procedure `array_partition`:
 - Assumes no control flow in loop body
 - identifies collections of references to arrays which refer to the same value
 - identifies deletable output dependences and antidependences
- Use this procedure to generate code
 - Minimize amount of copying back to the "original" array at the beginning and the end

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Node Splitting

Node Splitting

- Can we vectorize the following loop?

```
DO I = 1, N
  S1: A(I) = X(I+1) + X(I)
  S2: X(I+1) = B(I) + 32
ENDDO
```

Node Splitting

Node Splitting Algorithm

```
DO I = 1, N
  S1: A(I) = X(I+1) + X(I)
  S2: X(I+1) = B(I) + 32
ENDDO
```

- Break critical antidependence
- Make copy of node from which antidependence emanates

```
DO I = 1, N
  S1': X$(I) = X(I+1)
  S1: A(I) = X$(I) + X(I)
  S2: X(I+1) = B(I) + 32
ENDDO
```

- Recurrence broken
- Vectorized to


```
X$(1:N) = X(2:N+1)
X(2:N+1) = B(1:N) + 32
A(1:N) = X$(1:N) + X(1:N)
```

- Takes a constant loop independent antidependence D
- Add new assignment x: T\$=source(D)
- Insert x before source(D)
- Replace source(D) with T\$
- Make changes in the dependence graph

Node Splitting

Summary

- Determining minimal set of critical antidependences is in NP-C
- Perfect job of Node Splitting difficult
- Heuristic:
 - Select antidependences
 - Delete it to see if acyclic
 - If acyclic, apply Node Splitting

- Enhancing fine-grained parallelism
 - break dependence cycles
 - pick false dependences
 - caused by memory reuse not value flow
 - can be removed by renaming
 - not dependence cycles can be made acyclic
- Transformations discussed