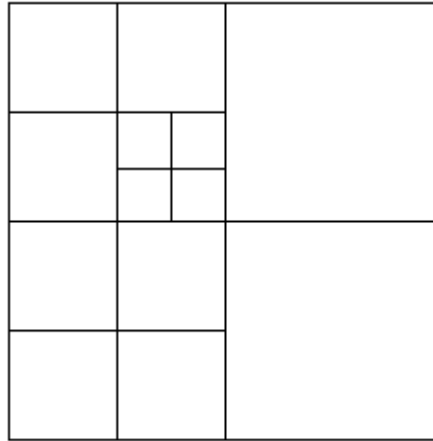
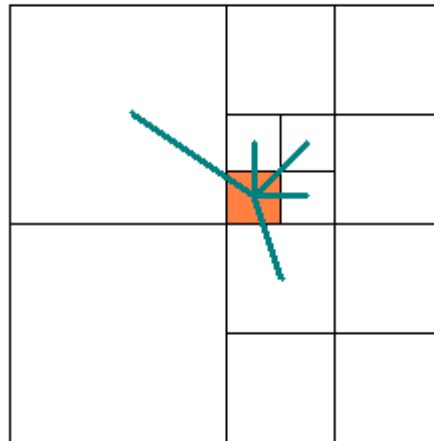


For a cell with configuration as follows:



First the cell and its surrounding cells are flipped around to ensure the cells on the same level are located on upper-right:



The different patterns of the above configurations are indexed by the left/down information. For improper nesting depth < 5 (for 2D. For 3D, max depth should be smaller than 3), look for the table to return the stencil coefficients. For more complicated situations, a function `calc_coeffs` is called. This function returns the stencil coefficients given `mglobal` and dimensions. Inside `calc_coeffs`, `matrixloader` is called which loads the matrix `A` and vector `B` (based on dimensions and coordinate system) in the equation $Ax = B$.

In 2D, `x` has 6 dimensions, for 3D, `x` has 10 dimensions. The linear system is solved by using Crout's algorithm to do a LU decomposition with partial pivoting on matrix `A` then using backward substitution to find `x`. This method is introduced in the book "Numerical Recipes". The tolerance is set to be $10e-16$. For cylindrical system, `A` and `B` both depend on `r`, which can be computed from `mglobal`, thus `matrixloader` will be called at all cells.

Once the stencil coefficients (stored in a 9-array for 2D, 19-array for 3D) are returned, this array is flipped back. For a nonlinear system, the stencil coefficients array is then manipulated according to the temperature in the surrounding 9 cells. Also, a source term generated by the Taylor expansion is returned. This source term should be coupled to the right-hand side vector in setting up the solution vector. The whole process is shown in the flow chart:

