

# Magnetostatics

(1) charge conservation

$$\rho \text{ charge density}$$

$$\vec{j} = \rho \vec{v}$$

= charge current density

$\hat{n} \cdot \vec{j} \cdot d\vec{a}$  is total charge per unit time

flowing through area  $d\vec{a}$

where  $\hat{n}$  is normal to  $d\vec{a}$

$$\frac{dQ_{\text{enc}}}{dt} = - \oint_S \vec{j} \cdot d\vec{a}$$

$\oint_S$  flux of current through surface  $S$

change in total charge enclosed by  $S$

$$\Rightarrow \frac{d}{dt} \int_V d^3r \rho = - \int_V d^3r \nabla \cdot \vec{j} \Rightarrow \boxed{\frac{\partial \rho}{\partial t} = - \nabla \cdot \vec{j}}$$

charge  
conservation  
since integrals equal for any  $V$

If we want a "steady state" or "static" situation, we can only consider currents  $\vec{j}$  that satisfy  $\nabla \cdot \vec{j} = 0$  so that  $\partial \rho / \partial t = 0$ .

Magnetostatics deals with effects of moving charges, such that the current is always divergenceless

$$\boxed{\nabla \cdot \vec{j} = 0}$$

Simplest example: constant uniform current  $I$  flowing down a wire,  $I = \vec{j} \cdot d\vec{a}$  where  $d\vec{a}$  is cross section area of wire, points along tangent to wire

~~Electric steady state goes to Ampere's Law with  $\vec{B}$~~

units of current  $I$  is amps = coulombs/sec

units of current density  $\vec{j}$  is  $\frac{\text{amps}}{\text{m}^2}$

$\vec{j}$  is a "volume" current density.

Can also have "sheet" or "surface" current density

$\vec{K} = \sigma \vec{v}$  when surface charge  $\sigma$  on 2-d surface moves

Also have "line" current density

$\vec{I} = \alpha \vec{v}$  when line charge  $\alpha$  on 1-d line moves  
- like current flowing in a wire.

\* Steady State currents produce magnetic fields  $B(\vec{r})$

II) Biot - Savart Law (Analog to Coulombs Law)  
(<sup>steady state</sup>)

The magnetic field at point  $\vec{r}$ , due to a divergenceless current flow is:

$$\boxed{\vec{B}(\vec{r}) = \frac{\mu_0}{4\pi} \int_{\text{vol}} d^3r' \vec{j}(\vec{r}') \times \frac{(\vec{r}-\vec{r}')}{|\vec{r}-\vec{r}'|^3}}$$

for volume current density  
 $\vec{j}(\vec{r}')$

$$= \frac{\mu_0}{4\pi} \int_{\text{surface}} da' \vec{K}(\vec{r}') \times \frac{(\vec{r}-\vec{r}')}{|\vec{r}-\vec{r}'|^3}$$

for surface current density  
 $\vec{K}(\vec{r}')$   
 $\vec{r}'$  on surface

$$= \frac{\mu_0}{4\pi} \int_{\text{line}} dl' \vec{I}(\vec{r}') \times \frac{(\vec{r}-\vec{r}')}{|\vec{r}-\vec{r}'|^3}$$

for line current density  
 $\vec{I}(\vec{r}')$   
 $\vec{r}'$  on line

$$\mu_0 = 4\pi \times 10^{-7} \text{ Nt/amp}^2$$

fundamental constant of magnetostatics

"permeability" of free space

\* Magnetic fields produces forces on moving charges

III)  $\vec{F}_{\text{mag}} = q \vec{v} \times \vec{B}(\vec{r})$  Lorentz Force

force on charge  $q$ , at position  $\vec{r}$ , moving with velocity  $\vec{v}$ , due to magnetic field  $\vec{B}(\vec{r})$

electromagnetic  
total force is  $\vec{F}_{\text{em}} = q \vec{E}(\vec{r}) + q \vec{v} \times \vec{B}(\vec{r})$

magnetic force on a current density

$$\vec{F}_{\text{mag}} = \int_{\text{vol}} d^3r \ g(\vec{r}) \vec{v}(\vec{r}) \times \vec{B}(\vec{r})$$

$$= \int_{\text{vol}} d^3r \ \vec{j}(\vec{r}) \times \vec{B}(\vec{r}) \quad \text{for volume current density}$$

$$= \int_{\text{surface}} da \ \vec{K}(\vec{r}) \times \vec{B}(\vec{r}) \quad \text{for surface current density}$$

$\vec{r}$  on surface

$$= \int_{\text{line}} dl \ \vec{I}(\vec{r}) \times \vec{B}(\vec{r}) \quad \text{for line current density}$$

$\vec{r}$  on line

For line current, can rewrite:

$$\vec{I} = I \hat{\vec{t}} \quad \text{unit tangent vector to line}$$

$$\vec{F}_{\text{mag}} = I \int dl \hat{\vec{t}} \times \vec{B}(\vec{r}) = I \int (dl \hat{\vec{t}} \times \vec{B})$$

where  $dl \hat{\vec{t}} \equiv \vec{dl}$  as in vector line integrals

magnetic forces can do no work

$$W_{\text{mag}} = \int_{\vec{r}_a}^{\vec{r}_b} \vec{F}_{\text{mag}} \cdot d\vec{l}$$

work done by magnetic field  
in moving a charge from  
 $\vec{r}_a$  to  $\vec{r}_b$

$$= q \int_{\vec{r}_a}^{\vec{r}_b} (\vec{v} \times \vec{B}) \cdot d\vec{l}$$

$$= q \int_{t_a}^{t_b} (\vec{v} \times \vec{B}) \cdot \frac{d\vec{l}}{dt} dt$$

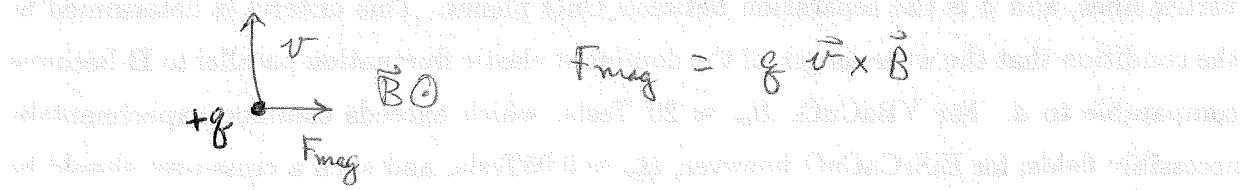
$$= q \int_{t_a}^{t_b} [(\vec{v} \times \vec{B}) \cdot \vec{v}] dt$$

integrate along  
trajectory  $\vec{r}(t)$   
that charge takes in  
going from  $\vec{r}_a$  to  $\vec{r}_b$   
 $\vec{r}(t_a) = \vec{r}_a$ ,  $\vec{r}(t_b) = \vec{r}_b$

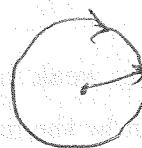
$$\begin{aligned} & \text{since } (\vec{v} \times \vec{B}) \cdot \vec{v} \\ &= (\vec{v} \times \vec{v}) \cdot \vec{B} \\ &= 0 \end{aligned}$$

$$\vec{v}(t) = \frac{d\vec{r}}{dt}$$

## Cyclotron Motion



→ orbital motion



$+q$  moves in  
clockwise direction  
when  $B$  out of page

$$\text{centrip accel } a_c = \frac{v^2}{R} = \frac{F_{\text{mag}}}{m} = \frac{qvB}{m}$$

∴  $R = \frac{mv}{qB}$  and  $\omega = \frac{qvB}{m}$

$$R = \frac{mv}{qB}$$

angular velocity is:  $\frac{v}{R} = \frac{qB}{m} \equiv \omega$  cyclotron frequency

IV) Maxwells Equations for Magneto statics:  $\vec{\nabla} \cdot \vec{B} = ?$   
 $\vec{\nabla} \times \vec{B} = ?$

Biot - Savart law:  $\vec{B}(\vec{r}) = \frac{\mu_0}{4\pi} \int d^3 r' \vec{j}(r') \times \frac{(\vec{r} - \vec{r}')}{|\vec{r} - \vec{r}'|^3}$

$$\vec{\nabla} \cdot \vec{B}(\vec{r}) = \frac{\mu_0}{4\pi} \int d^3 r' \vec{\nabla} \cdot \left( \vec{j}(r') \times \frac{(\vec{r} - \vec{r}')}{|\vec{r} - \vec{r}'|^3} \right)$$

use vector identity

$$\vec{\nabla} \cdot (\vec{v} \times \vec{w}(\vec{r})) = -\vec{v} \cdot (\vec{\nabla} \times \vec{w}(\vec{r}))$$

indep of  $\vec{r}$  depends on  $\vec{r}$

$$\Rightarrow \vec{\nabla} \cdot \vec{B}(\vec{r}) = -\frac{\mu_0}{4\pi} \int d^3 r' \vec{j}(r') \cdot \vec{\nabla} \times \left( \frac{\vec{r} - \vec{r}'}{|\vec{r} - \vec{r}'|^3} \right)$$

Gauss law for Magnetic fields

$$\boxed{\vec{\nabla} \cdot \vec{B}(\vec{r}) = 0}$$

"no magnetic monopoles"

curl of a radial function vanishes

$= 0$  - we saw this before when we used coulombs law to show that  $\vec{\nabla} \times \vec{E} = 0$  in electrostatics

$$\vec{\nabla} \times \vec{B}(\vec{r}) = \frac{\mu_0}{4\pi} \int d^3 r' \vec{\nabla} \times \left( \vec{j}(r') \times \frac{(\vec{r} - \vec{r}')}{|\vec{r} - \vec{r}'|^3} \right)$$

use vector identity

$$\vec{\nabla} \times (\vec{v} \times \vec{w}(\vec{r})) = -(\vec{v} \cdot \vec{\nabla}) \vec{w} + \vec{v} (\vec{\nabla} \cdot \vec{w})$$

indep of  $\vec{r}$  depends on  $\vec{r}$

$$\vec{\nabla} \times \vec{B}(\vec{r}) = \frac{\mu_0}{4\pi} \int d^3 r' \left\{ \vec{f}(\vec{r}') \cdot \vec{\nabla} \cdot \left( \frac{\vec{r} - \vec{r}'}{|\vec{r} - \vec{r}'|^3} \right) - (\vec{f}(\vec{r}') \cdot \vec{\nabla}) \left( \frac{\vec{r} - \vec{r}'}{|\vec{r} - \vec{r}'|^3} \right) \right\}$$

$$1^{\text{st}} \text{ term: } \vec{\nabla} \cdot \left( \frac{\vec{r} - \vec{r}'}{|\vec{r} - \vec{r}'|^3} \right) = 4\pi \delta^3(\vec{r} - \vec{r}')$$

$$\Rightarrow 1^{\text{st}} \text{ term gives } \frac{\mu_0}{4\pi} \int d^3 r' \vec{f}(\vec{r}') 4\pi \delta^3(\vec{r} - \vec{r}') = \mu_0 \vec{f}(\vec{r})$$

$$2^{\text{nd}} \text{ term is } \frac{\mu_0}{4\pi} \int d^3 r' (-) \sum_{i=1}^3 \vec{f}_i(\vec{r}') \frac{\partial}{\partial x_i} \left( \frac{\vec{r} - \vec{r}'}{|\vec{r} - \vec{r}'|^3} \right)$$

$$\text{use } \frac{\partial}{\partial x_i} \left( \frac{\vec{r} - \vec{r}'}{|\vec{r} - \vec{r}'|^3} \right) = - \frac{\partial}{\partial x'_i} \left( \frac{\vec{r} - \vec{r}'}{|\vec{r} - \vec{r}'|^3} \right)$$

$$= \frac{\mu_0}{4\pi} \int d^3 r' \sum_{i=1}^3 \vec{f}_i(\vec{r}') \frac{\partial}{\partial x'_i} \left( \frac{\vec{r} - \vec{r}'}{|\vec{r} - \vec{r}'|^3} \right)$$

integrate by parts: boundary term vanishes as take surface  $S \rightarrow \infty$   
if current  $\vec{f}$  is localized

$$= - \frac{\mu_0}{4\pi} \int d^3 r' \underbrace{\sum_{i=1}^3 \left( \frac{\partial}{\partial x'_i} \vec{f}_i(\vec{r}') \right)}_{\nabla' \cdot \vec{f}(\vec{r}') = 0} \left( \frac{\vec{r} - \vec{r}'}{|\vec{r} - \vec{r}'|^3} \right)$$

2<sup>nd</sup> term = 0

$$\Rightarrow \boxed{\vec{\nabla} \times \vec{B}(\vec{r}) = \mu_0 \vec{f}(\vec{r})} \quad \text{Amperes Law}$$

$$\left. \begin{aligned} \nabla \cdot \vec{B}(\vec{r}) &= 0 \\ \nabla \times \vec{B}(\vec{r}) &= \mu_0 \vec{J}(\vec{r}) \end{aligned} \right\} \text{Maxwell's eqn for magnetostatics}$$

Ampere's law in integral form:

$$\int_S d\vec{a} \cdot (\nabla \times \vec{B}(\vec{r})) = \mu_0 \int_S d\vec{a} \cdot \vec{J}(\vec{r}) \quad S \text{ is any open surface}$$

Stokes law

$$\oint_T d\vec{l} \cdot \vec{B} = \mu_0 I_{\text{enc}} \quad \begin{array}{l} \text{total flux of } \vec{B} \text{ through surface } S \\ \text{boundary curve of } S \end{array}$$

= "current enclosed" by boundary loop  $T$

## IV) Magnetic Vector Potential

Since  $\nabla \cdot \vec{B} = 0 \Rightarrow$  can always find  $\vec{A}(\vec{r})$  such that

$$\vec{B}(\vec{r}) = \nabla \times \vec{A}(\vec{r}) \quad \vec{A} \text{ is the "vector potential" for } \vec{B}$$

General result of vector calculus (see Theorem 2 sec 1.6.2)

Note:  $\vec{A}$  is not unique; if  $\vec{B}' = \vec{B} + \nabla \lambda$

and  $\vec{A}' = \vec{A} + \vec{\nabla} \lambda$  where  $\lambda(\vec{r})$  is any scalar function

$$\text{then } \vec{\nabla} \times \vec{A}' = \vec{\nabla} \times \vec{A} + \vec{\nabla} \times (\vec{\nabla} \lambda)$$

$$= \vec{B} + 0 \quad \text{as } \vec{\nabla} \times \vec{\nabla} \lambda = 0 \text{ always}$$

$\Rightarrow \vec{A}'$  can also be used as a vector potential for  $\vec{B}$ .

Note:

This is similar to case for electrostatic potential:

$\vec{E} = -\vec{\nabla}V \Rightarrow V$  is not unique - we can always add any arbitrary constant to  $V$  and still not change  $\vec{\nabla}V$ .

Here  $\vec{B} = \vec{\nabla} \times \vec{A} \Rightarrow \vec{A}$  is not unique - we can always add any arbitrary  $\vec{\nabla}\lambda$  to  $\vec{A}$  and not change  $\vec{\nabla} \times \vec{A}$ .

Ampere's Law in terms of vector potential:

$$\vec{\nabla} \times \vec{B} = \vec{\nabla} \times (\vec{\nabla} \times \vec{A}) = -\nabla^2 \vec{A} + \vec{\nabla}(\vec{\nabla} \cdot \vec{A}) = \mu_0 \vec{J}$$

definition of  $\vec{A}$                       vector identity                      Ampere's law

we can always use the non-uniqueness of  $\vec{A}$  to choose an  $\vec{A}$  that satisfies  $\vec{\nabla} \cdot \vec{A} = 0$ , called "Coulomb gauge".

proof: Suppose we have an  $\vec{A}'$  such that  $\vec{\nabla} \times \vec{A}' = \vec{B}$  but  $\vec{\nabla} \cdot \vec{A}' = C \neq 0$

1) Find a  $\lambda$  such that  $-\nabla^2 \lambda = C(r)$ .

This is Poisson's eqn, so we know that there is always a solution  $\lambda(r)$ .

2) Then construct  $\vec{A}(r) = \vec{A}'(r) + \vec{\nabla} \lambda(r)$

$$\vec{\nabla} \times \vec{A} = \vec{\nabla} \times \vec{A}' + \vec{\nabla} \times \vec{\nabla} \lambda = \vec{\nabla} \times \vec{A}' + 0 = \vec{B}$$

$$\vec{\nabla} \cdot \vec{A} = \vec{\nabla} \cdot \vec{A}' + \vec{\nabla} \cdot (\vec{\nabla} \lambda) = C + \nabla^2 \lambda = C - C = 0$$

So  $\vec{A}$  is a vector potential for  $\vec{B}$ , and  $\vec{\nabla} \cdot \vec{A} = 0$

For magneto<sub>statics</sub>, it is usually convenient to always work with vector potential that satisfies  $\nabla \cdot \vec{A} = 0$ .

Then Ampere's law becomes

$$-\nabla^2 \vec{A} = \mu_0 \vec{J}$$

Solution is  
for localized  
current

$$\vec{A}(\vec{r}) = \frac{\mu_0}{4\pi} \int d^3 r' \frac{\vec{J}(\vec{r}')}{|\vec{r} - \vec{r}'|}$$

vector equation

just like we solved  
 $-\nabla^2 V = \rho/\epsilon_0$  in  
electrostatics

for surface current density:  $\vec{A}(\vec{r}) = \frac{\mu_0}{4\pi} \int_S da' \frac{\vec{K}(\vec{r}')}{|\vec{r} - \vec{r}'|} \quad \vec{r}' \text{ on surface}$

for line current density:

$$\vec{A}(\vec{r}) = \frac{\mu_0}{4\pi} \int_P dl' \frac{\vec{I}(\vec{r}')}{|\vec{r} - \vec{r}'|} \quad \vec{r}' \text{ on line}$$