

Inverse transform obtained by taking $v \rightarrow -v$ in above

$$\begin{cases} ct = \gamma ct' + \gamma(\frac{v}{c}) x' \\ x = \gamma(\frac{v}{c}) ct' + \gamma x' \end{cases}$$

4-vectors

4-position: $x_\mu = (x_1, x_2, x_3, i\gamma ct)$ $x_4 = i\gamma ct$

summation convention $x_\mu x_\mu = \sum_{\mu=1}^4 x_\mu^2 = r^2 - c^2 t^2$ Lorentz invariant scalar
- sum over repeated indices - has same value in all

Lorentz transf for $K \rightarrow K'$ where K' moves with v/c as seen by K . internal frames

$$\left. \begin{array}{l} x'_1 = \gamma(x_1 + i(\frac{v}{c})x_4) \\ x'_2 = x_2 \\ x'_3 = x_3 \\ x'_4 = \gamma(x_4 - i(\frac{v}{c})x_1) \end{array} \right\}$$

linear transf, can be represented by a matrix

or $x'_\mu = \alpha_{\mu\nu}(L) x_\nu$

L matrix of Lorentz transformation L

$$\alpha(L) = \begin{pmatrix} \gamma & 0 & 0 & i\frac{v}{c}\gamma \\ 0 & 1 & 0 & 0 \\ 0 & 0 & 1 & 0 \\ -i\frac{v}{c}\gamma & 0 & 0 & \gamma \end{pmatrix}$$

inverse: $x_\mu = \alpha_{\mu\nu}(L^{-1}) x'_\nu$

$\alpha_{\mu\nu}(L^{-1})$ is given by taking $v \rightarrow -v$ in $\alpha_{\mu\nu}(L)$

we see $\alpha_{\mu\nu}(L^{-1}) = \alpha_{\mu\nu}(L)$ "inverse = transpose \Rightarrow orthogonal"

More generally

Since x_μ^2 is Lorentz invariant scalar,

$$x_\mu^2 = \alpha_{\mu\nu}(L) \alpha_{\nu\lambda}(L) x_\nu x_\lambda = x_\lambda^2$$

$$\Rightarrow \alpha_{\mu\nu}(L) \alpha_{\nu\lambda}(L) = \delta_{\mu\lambda}$$

$$\Rightarrow \overset{t}{\alpha_{\mu\nu}(L)} \alpha_{\nu\lambda}(L) = \delta_{\mu\lambda}$$

$$\Rightarrow \overset{t}{\alpha_{\mu\nu}} = \alpha_{\mu\nu}^{-1}(L) \text{ transpose} = \text{inverse}$$

a matrix whose transpose equals its inverse is called an orthogonal matrix.

If L_1 is a Lorentz transf from K to K'

L_2 is a Lorentz transf from K' to K''

Then the Lorentz transf from K to K'' is given by the matrix

$$\alpha(L_2 L_1) = \alpha(L_2) \alpha(L_1)$$

if $L_1 \equiv L$ and $L_2 = L^\dagger$ so $L_2 L_1 = I$ identity

$$\Rightarrow \alpha^{-1}(L) = \alpha(L^\dagger)$$

particle on trajectory $\vec{r}(t)$

4-differential

$$dx_1 = x_1(t+dt) - x_1(t)$$

$$dx_\mu = (dx_1, dx_2, dx_3, icdt)$$

etc

$$-(dx_\mu)^2 \equiv c^2 ds^2 = c^2 dt^2 - dr^2 \quad \text{Lorentz invariant scalar}$$

$$ds^2 = dt^2 \left[1 - \frac{1}{c^2} \left(\frac{dx_1}{dt} \right)^2 - \frac{1}{c^2} \left(\frac{dx_2}{dt} \right)^2 - \frac{1}{c^2} \left(\frac{dx_3}{dt} \right)^2 \right]$$

$$ds^2 = \frac{dt^2}{c^2}$$

$$\vec{v} = \frac{d\vec{r}}{dt}$$

$$\boxed{ds = \frac{dt}{c}}$$

proper time interval

ds is the same in all inertial frames.

A 4-vector is any 4 numbers that transform under a Lorentz transformation the same way as does x_μ

4-velocity $u_\mu = \frac{dx_\mu}{ds} = \dot{x}_\mu$ dot indicates derivative with respect to s
 $= \gamma \frac{dx_\mu}{dt}$ since dx_μ is a 4-vector and ds is Lorentz invariant scalar, then $\frac{dx_\mu}{ds}$ is a

space components $\vec{u} = \gamma \vec{v}$ 4-vector.

$$u_0 = ic \gamma \quad u_\mu = \gamma(\vec{v}, ic)$$

$$\begin{aligned} u_\mu u^\mu &= \gamma^2 v^2 - c^2 \gamma^2 = \gamma^2 (v^2 - c^2) \\ &= \frac{v^2 - c^2}{1 - \frac{v^2}{c^2}} = -c^2 \text{ Lorentz invariant scalar} \end{aligned}$$

4-acceleration $a_\mu = \frac{du_\mu}{ds} = \gamma \frac{du_\mu}{dt}$

4-gradient $\frac{\partial}{\partial x_\mu} = (\vec{\nabla}, -i \frac{\partial}{\partial t}) = \left(\frac{\partial}{\partial x_1}, \frac{\partial}{\partial x_2}, \frac{\partial}{\partial x_3}, \frac{\partial}{\partial x_4} \right)$

proof $\frac{\partial}{\partial x_\mu}$ is a 4-vector

where $x_4 = ct$

by chain rule: $\frac{\partial}{\partial x_\mu} = \frac{\partial x_\lambda}{\partial x_\mu} \frac{\partial}{\partial x_\lambda} \rightarrow$ but $\frac{\partial x_\lambda}{\partial x_\mu} = \alpha_{\mu\lambda}(L^{-1})$
 $= \alpha_{\mu\lambda}(L)$

$$\text{So } \frac{\partial}{\partial x_\mu} = \alpha_{\mu\lambda}(L) \frac{\partial}{\partial x_\lambda} \text{ inverse = transpose}$$

so transforms same as x_μ

$$\left(\frac{\partial}{\partial x_\mu} \right)^2 = \vec{\nabla}^2 - \frac{1}{c^2} \frac{\partial^2}{\partial t^2} \text{ wave equation operator!}$$

main products

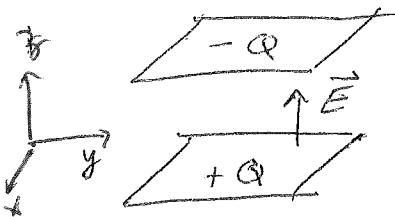
If u_μ and v_μ are 4-vectors, then
 $u_\mu v_\mu$ is Lorentz invariant scalar

Maxwell's Equations in Relativistic Form

How do \vec{E} and \vec{B} transform under Lorentz transformation?

\vec{E} and \vec{B} have much more complicated transformation laws than position 4-vectors ~~xyz~~^{position}. $x^\mu = (\vec{r}, i\sigma t)$

Example : parallel plate capacitor at rest in K
plates have area A, charge Q



$$\vec{E} = \frac{Q}{A\epsilon_0} \hat{z} \quad \text{uniform} \quad \frac{Q}{A} = \sigma \quad \text{surface charge den'}$$

$$\vec{B} = 0$$

In K' , moving with $\vec{v} = v\hat{y}$ wrt K, y dimension of plates is contracted by factor $1/\gamma$ (Fitzgerald Contraction)

$$\text{and } \sigma' = \frac{Q}{A'} = \frac{\gamma Q}{A} = \gamma \sigma$$

$$\vec{E}' = \frac{Q}{A'\epsilon_0} \hat{z} = \frac{\gamma Q}{A\epsilon_0} \hat{z} = \gamma \vec{E} \quad \vec{E} \text{ is along } \hat{z} \perp \vec{v}.$$

This is different than trans ~~E~~ law for \vec{r} .

Under L.T. components of $\vec{r} \perp \vec{v}$ do not change

But components of $\vec{E} \perp \vec{v}$ do change

Also, moving surface charge σ' gives rise to surface current density \Rightarrow there will be magnetic field \vec{B}' in frame K' . \Rightarrow Lorentz transf must couple together the components of \vec{E} and \vec{B} .

Electromagnetism

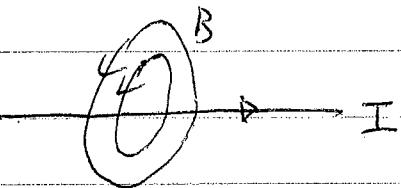
Clearly \vec{E} + \vec{B} must transform into each other under Lorentz transf.

in inertial frame K
stationary line charge λ

$$\vec{E} \leftarrow \uparrow \downarrow \rightarrow$$

\checkmark cylindrical outward
electric field
no B -field

in frame K' moving with $\vec{v} \parallel$ to wire



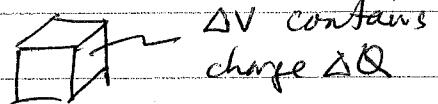
moving line charge gives current
 $\Rightarrow B$ circulating around wire
as well as outward radial E

Lorentz force

$$\vec{F} = q\vec{E} + q\vec{v} \times \vec{B}$$

What is the velocity \vec{v} here? velocity with respect to what inertial frame? Clearly \vec{E} and \vec{B} must change from inertial frame to another if this force law can make sense.

charge density, current density



Consider charge ΔQ contained in a vol ΔV .
 ΔQ is a Lorentz invariant scalar.

Consider the reference frame in which the charge is instantaneous at rest. In this frame

$$\Delta Q = \hat{\rho} \Delta \hat{V}$$

$\hat{\rho}$ is charge density in rest frame of charge
 $\Delta \hat{V}$ is volume of box in rest frame

$\hat{\rho}$ is a Lorentz invariant scalar by definition

Now transform to another frame moving with velocity \vec{v} with respect to the rest frame.

ΔQ remains the same.

$$\Delta V = \frac{\Delta \hat{V}}{\gamma} \text{ volume contracts in direction } \parallel \text{ to } \vec{v}$$

$$\Rightarrow \hat{\rho} = \frac{\Delta Q}{\Delta V} = \frac{\Delta Q}{\Delta \hat{V}} \gamma = \hat{\rho} \gamma$$

spatial components
of 4-velocity

$$\text{current density} \circ \vec{j} = \hat{\rho} \vec{v} = (\hat{\rho} \gamma) (\gamma \vec{v}) = \hat{\rho} \vec{u}$$

$$\text{Define 4-current } j^\mu = \hat{\rho} u^\mu = \hat{\rho} (\vec{u}, i c \gamma)$$

spatial components of j^μ are $\vec{j} = \hat{\rho} \vec{u} = \hat{\rho} \vec{v}$ current density

temporal component of j^μ is $j^4 = i c \hat{\rho} \gamma = i c \hat{\rho}$ charge density

$$\boxed{j^\mu = (\vec{j}, i c \hat{\rho})}$$

j^μ is a 4-vector since u^μ is a 4-vector and $\hat{\rho}$ is Lorentz invariant scalar

$$\text{length of the 4-current is } j_\mu j^\mu = |\vec{j}|^2 - c^2 \hat{\rho}^2 = \hat{\rho}^2 u_\mu u^\mu = -c^2 \hat{\rho}^2$$

charge conservation

$$0 = \vec{\nabla} \cdot \vec{j} + \frac{\partial \hat{\rho}}{\partial t} = \vec{\nabla} \cdot \vec{j} + \frac{\partial (i c \hat{\rho})}{\partial (i c t)} = \vec{\nabla} \cdot \vec{j} + \frac{\partial j^4}{\partial x^4}$$

$$\Rightarrow \boxed{\frac{\partial j^\mu}{\partial x^\mu} = 0}$$

charge conservation in
Lorentz covariant form

Equations for potentials in Lorentz Gauge

$$(\nabla^2 - \frac{1}{c^2} \frac{\partial^2}{\partial t^2}) \vec{A} = \square^2 \vec{A} = -\mu_0 \vec{f}$$

$$c^2 = \frac{1}{\mu_0 \epsilon_0}$$

$$(\nabla^2 - \frac{1}{c^2} \frac{\partial^2}{\partial t^2}) V = \square^2 V = -\rho/\epsilon_0 = -c^2 \mu_0 \rho$$

$$= -\mu_0 (ic\rho) \left(\frac{c}{\lambda} \right)$$

So

$$\square^2 \vec{A} = -\mu_0 \vec{f}$$

$$= -\mu_0 \vec{f} + \left(\frac{c}{\lambda} \right)$$

$$\square^2 (iV/c) = -\mu_0 \vec{f}_4$$

Define 4-potential $A_\mu = (\vec{A}, iV/c)$

$$\Rightarrow \square^2 A_\mu = -\mu_0 \vec{f}_\mu \quad \text{equation for potentials}$$

$$\square^2 = \frac{\partial^2}{\partial x_\nu^2} \quad \text{is Lorentz invariant operator}$$

So we can write the above as

$$\frac{\partial^2 A_\mu}{\partial x_\nu^2} = -\mu_0 \vec{f}_\mu$$

Lorentz gauge condition is

$$0 = \vec{\nabla} \cdot \vec{A} + \mu_0 \epsilon_0 \frac{\partial V}{\partial t} = \vec{\nabla} \cdot \vec{A} + \frac{1}{c^2} \frac{\partial V}{\partial t}$$

$$= \vec{\nabla} \cdot \vec{A} + \frac{\partial (iV/c)}{\partial (ict)} = \vec{\nabla} \cdot \vec{A} + \frac{\partial A_4}{\partial x_4}$$

$$= \frac{\partial A_\mu}{\partial x_\mu}$$

So Lorentz Gauge condition is

$$\frac{\partial A_\mu}{\partial x_\mu} = 0$$

Electric and Magnetic Fields

$$\vec{B} = \vec{\nabla} \times \vec{A} \Rightarrow B_i = \frac{\partial A_k}{\partial x_j} - \frac{\partial A_j}{\partial x_k}$$

where i, j, k
are a cyclic
permutation of 1, 2, 3

$$\vec{E} = -\vec{\nabla}V - \frac{\vec{\partial}A}{\partial t}$$

$$V = \frac{cA_4}{i}, \quad x_4 = ict$$

$$\Rightarrow E_i = -\frac{\partial (\frac{c}{i}A_4)}{\partial x_i} - \frac{\partial A_i}{\partial (\frac{x_4}{ic})} = -\frac{c}{i} \frac{\partial A_4}{\partial x_i} - ic \frac{\partial A_i}{\partial x_4}$$

$$\frac{E_i}{c} = i \left(\frac{\partial A_4}{\partial x_i} - \frac{\partial A_i}{\partial x_4} \right)$$

has a similar form to B_i

We define the field strength tensor

$$F_{\mu\nu} = \frac{\partial A_\nu}{\partial x_\mu} - \frac{\partial A_\mu}{\partial x_\nu} = -F_{\nu\mu} \quad \begin{matrix} 4 \times 4 \text{ antisymmetric} \\ 2^{\text{nd}} \text{ rank tensor} \end{matrix}$$

$$F_{\mu\nu} = \begin{pmatrix} 0 & B_3 & -B_2 & -iE_1/c \\ -B_3 & 0 & B_1 & -iE_2/c \\ B_2 & -B_1 & 0 & -iE_3/c \\ iE_1/c & iE_2/c & iE_3/c & 0 \end{pmatrix}$$

"curl" of a 4-vector is a 4×4 antisymmetric
2nd rank tensor

4×4 antisymmetric 2nd rank tensor has only 6
independent components - just the right number
to specify the \vec{E} and \vec{B} fields!

$F_{\mu\nu}$ transforms under a Lorentz transformation just like a tensor (ie not like a vector)

$$F'_{\mu\nu} = \frac{\partial A'_\nu}{\partial x^\mu} - \frac{\partial A'_\mu}{\partial x^\nu} \quad \text{use } A'_\lambda = \alpha_{\lambda\lambda} A_\lambda \quad \left. \begin{array}{l} \text{since} \\ \frac{\partial}{\partial x^\mu} = \alpha_{\mu 0} \frac{\partial}{\partial x_0} \\ A_\mu \text{ ad} \\ \frac{\partial}{\partial x^\nu} \end{array} \right\} \alpha_{\mu\nu}$$

$$\begin{aligned} F'_{\mu\nu} &= \alpha_{\lambda\lambda} \alpha_{\mu 0} \frac{\partial A_\lambda}{\partial x_0} - \alpha_{\mu 0} \alpha_{\nu\lambda} \frac{\partial A_\lambda}{\partial x_\nu} \\ &= \alpha_{\mu 0} \alpha_{\nu\lambda} \left(\frac{\partial A_\lambda}{\partial x_0} - \frac{\partial A_\lambda}{\partial x_\nu} \right) \end{aligned}$$

$F'_{\mu\nu} = \alpha_{\mu 0} \alpha_{\nu\lambda} F_{\lambda 0}$

← transformation law for a 2nd rank tensor

In terms of matrix multiplication, and writing for the transpose of a matrix $\alpha_{\lambda\lambda} = \alpha_{\lambda\lambda}^t$, the above can be written as

$$F'_{\mu\nu} = \alpha_{\mu 0} F_{\lambda 0} \alpha_{\lambda\nu}^t$$

The above has the form of the product of three matrices

If we write out the above transformation law component by component we get the following transformation law for the \vec{E} and \vec{B} fields.

For a transformation from K to K', where K' moves with velocity $v \hat{x}$ as seen from K,

$$E'_1 = E_1$$

$$B'_1 = B_1$$

$$E'_2 = \gamma(E_2 - v B_3)$$

$$B'_2 = \gamma(B_2 + \frac{v}{c^2} E_3)$$

$$E'_3 = \gamma(E_3 + v B_2)$$

$$B'_3 = \gamma(B_3 - \frac{v}{c^2} E_2)$$

where $(1, 2, 3) = (x, y, z)$