

$\frac{\partial F_{\mu\nu}}{\partial x_\nu}$ is a 4-vector: proof:

$$\frac{\partial F'_{\mu\nu}}{\partial x'_\nu} = a_{\mu\sigma} a_{\nu\lambda} a_{\nu\gamma} \frac{\partial F_{\sigma\lambda}}{\partial x_\gamma}$$

but $a_{\nu\lambda} = a_{\lambda\nu}^{-1}$ since inverse = transpose
 $a_{\nu\lambda} a_{\nu\gamma} = a_{\lambda\nu}^{-1} a_{\nu\gamma} = \delta_{\lambda\gamma}$

$$\frac{\partial F'_{\mu\nu}}{\partial x'_\nu} = a_{\mu\sigma} \frac{\partial F_{\sigma\lambda}}{\partial x_\lambda} \delta_{\lambda\gamma} = a_{\mu\sigma} \frac{\partial F_{\sigma\lambda}}{\partial x_\lambda} \quad \text{transforms like 4-vector}$$

To write the homogeneous Maxwell Equations

Construct 3rd rank co-variant tensor

$$G_{\mu\nu\lambda} = \frac{\partial F_{\mu\nu}}{\partial x_\lambda} + \frac{\partial F_{\lambda\mu}}{\partial x_\nu} + \frac{\partial F_{\nu\lambda}}{\partial x_\mu}$$

transforms as $G'_{\mu\nu\lambda} = a_{\mu\alpha} a_{\nu\beta} a_{\lambda\gamma} G_{\alpha\beta\gamma}$

in principle G has $4^3 = 64$ components

But can show that G is antisymmetric in exchange of any two indices

$$G_{\nu\mu\lambda} = \frac{\partial F_{\nu\mu}}{\partial x_\lambda} + \frac{\partial F_{\lambda\nu}}{\partial x_\mu} + \frac{\partial F_{\mu\lambda}}{\partial x_\nu}$$

$$= -\frac{\partial F_{\mu\nu}}{\partial x_\lambda} - \frac{\partial F_{\nu\lambda}}{\partial x_\mu} - \frac{\partial F_{\lambda\mu}}{\partial x_\nu} \quad \text{as } F \text{ antisymmetric}$$

$$= -G_{\mu\lambda\nu}$$

also $G_{\mu\nu\lambda} = 0$ if any two indices are equal

$\Rightarrow$ only 4 independent components

$$G_{012}, G_{013}, G_{023}, G_{123}$$

all other components either vanish or are $\pm$ one of the above.

The 4 homogeneous Maxwell Equations:

$$\vec{\nabla} \cdot \vec{B} = 0, \quad \vec{\nabla} \times \vec{E} + \frac{1}{c} \frac{\partial \vec{B}}{\partial t} = 0$$

can be written as

$$\boxed{G_{\mu\nu\lambda} = 0}$$

to see, substitute in definition of G the definition of F

$$G_{\mu\nu\lambda} = \frac{\partial^2 A_\nu}{\partial x_\lambda \partial x_\mu} - \frac{\partial^2 A_\mu}{\partial x_\lambda \partial x_\nu} + \frac{\partial^2 A_\mu}{\partial x_\nu \partial x_\lambda} - \frac{\partial^2 A_\lambda}{\partial x_\nu \partial x_\mu} + \frac{\partial^2 A_\lambda}{\partial x_\mu \partial x_\nu} - \frac{\partial^2 A_\nu}{\partial x_\mu \partial x_\lambda}$$

all terms cancel in pairs

$$= 0$$

$$G_{123} = 0 \Rightarrow \vec{\nabla} \cdot \vec{B} = 0$$

$$G_{012} = -\frac{1}{c} \left[\vec{\nabla} \times \vec{E} + \frac{\partial \vec{B}}{\partial t} \right]_3 = 0 \quad \text{3 component Faraday's law}$$

Another way to write homogeneous Maxwell Equations

Define $\epsilon_{\mu\nu\lambda\sigma}$ = 4-d Levi-Civita symbol

$$\epsilon_{\mu\nu\lambda\sigma} = \begin{cases} +1 & \text{if } \mu\nu\lambda\sigma \text{ is even permutation of } 1234 \\ -1 & \text{if } \mu\nu\lambda\sigma \text{ is odd permutation of } 1234 \\ 0 & \text{otherwise} \end{cases}$$

Define $\tilde{F}_{\mu\nu} = \frac{1}{2i} \epsilon_{\mu\nu\lambda\sigma} F_{\lambda\sigma}$

pseudo-tensor
has wrong sign under parity transf

$$= \begin{pmatrix} 0 & -E_3 & E_2 & -iB_1 \\ E_3 & 0 & -E_1 & -iB_2 \\ -E_2 & E_1 & 0 & -iB_3 \\ iB_1 & iB_2 & iB_3 & 0 \end{pmatrix}$$

$\frac{\partial \tilde{F}_{\mu\nu}}{\partial x_\nu} = 0$ gives homogeneous Maxwell equations

$$\left. \begin{aligned} \frac{1}{2} F_{\mu\nu} F_{\mu\nu} &= B^2 - E^2 \\ -\frac{1}{4} F_{\mu\nu} \tilde{F}_{\mu\nu} &= \vec{B} \cdot \vec{E} \end{aligned} \right\} \text{Lorentz invariant scalars}$$

From $F_{\mu\nu} = a_{\mu\alpha} a_{\nu\lambda} F_{\alpha\lambda}$ we can get
Lorentz transf for $\vec{E}$ and $\vec{B}$

For a transformation from K to K' with K' moving
with v along x , with respect to K ,

$$E'_1 = E_1$$

$$B'_1 = B_1$$

$$E'_2 = \gamma (E_2 - \frac{v}{c} B_3)$$

$$B'_2 = \gamma (B_2 + \frac{v}{c} E_3)$$

$$E'_3 = \gamma (E_3 + \frac{v}{c} B_2)$$

$$B'_3 = \gamma (B_3 - \frac{v}{c} E_2)$$

Kinematics

"dot" is $\frac{d}{ds}$

4-momentum

$$p_\mu = m \dot{x}_\mu = m u_\mu = (m \gamma \vec{v}, i m c \gamma)$$

$$p_\mu^2 = m^2 \dot{x}_\mu^2 = -m^2 c^2$$

4-force

$$K_\mu = (\vec{K}, i K_0) \quad \text{"Minkowski force"}$$

Newton's 2nd law

$$m \frac{d^2 x_\mu}{ds^2} = K_\mu$$

$$\Rightarrow m \frac{d u_\mu}{ds} = \frac{d p_\mu}{ds} = K_\mu$$

$$p_\mu^2 = -m^2 c^2 \Rightarrow \frac{d}{ds} (p_\mu^2) = p_\mu \frac{d p_\mu}{ds} = p_\mu K_\mu = 0$$

$$\Rightarrow m \gamma \vec{v} \cdot \vec{K} - m c \gamma K_0 = 0 \quad \text{or}$$

$$K_0 = \frac{\vec{v}}{c} \cdot \vec{K}$$

Define the usual 3-force by

$$\frac{d\vec{p}}{dt} = \vec{F}$$

$$\frac{d\vec{p}}{ds} = \vec{K} \text{ and } \frac{d\vec{p}}{ds} = \gamma \frac{d\vec{p}}{dt} = \gamma \vec{F} \Rightarrow \vec{K} = \gamma \vec{F}$$

$$K_0 = \gamma \frac{\vec{v}}{c} \cdot \vec{F}$$

Consider 4th component of Newton's eqn

$$m \frac{d u_4}{ds} = m \frac{d (ic\gamma)}{ds} = i K_0 = i \gamma \frac{\vec{v}}{c} \cdot \vec{F}$$

$$d(m\gamma) = \gamma \frac{\vec{v}}{c^2} \cdot \vec{F} ds = \frac{dt}{c^2} \vec{v} \cdot \vec{F} = \frac{d\vec{r} \cdot \vec{F}}{c^2}$$

Work-energy theorem: $d(m\gamma c^2) = d\vec{r} \cdot \vec{F} = \text{work done}$

$\Rightarrow d(m\gamma c^2)$ is change in kinetic energy

$E = m\gamma c^2$ is relativistic kinetic energy

$$\boxed{\begin{aligned} \Phi_\mu &= \left(\vec{p}, \frac{iE}{c} \right) & \begin{cases} \vec{p} = m\gamma \vec{v} \\ E = m\gamma c^2 \end{cases} \end{aligned}}$$

$$E = \frac{mc^2}{\sqrt{1-\frac{v^2}{c^2}}} \approx mc^2 \left(1 + \frac{1}{2} \frac{v^2}{c^2} \right) = mc^2 + \frac{1}{2} m v^2$$

$\uparrow$ small $\frac{v}{c}$
 $\uparrow$ rest mass energy
 $\uparrow$ non-rel kinetic energy

$$\frac{d\Phi_\mu}{ds} = K_\mu \text{ is therefore}$$

relativistic analog of Newton's 3rd law
as well as law of conservation of energy

Lorentz force

$$\frac{dp_\mu}{ds} = K_\mu$$

what is the K_μ that represents the Lorentz force and how can we write it in ~~relative~~ Lorentz covariant way?

K_μ should depend on the fields $F_{\mu\nu}$ and the particles trajectory x_μ

$$\text{as } \vec{v} \rightarrow 0 \quad \vec{K} = g \vec{E}$$

K_μ can't depend directly on x_μ as should be indep of origin of coords. So can depend only on $\dot{x}_\mu$, $\ddot{x}_\mu$, etc.

as $v \rightarrow 0$, K does not depend on the acceleration, so K does not depend on $\ddot{x}_\mu$

K_μ only depends on $F_{\mu\nu}$ and $\dot{x}_\mu$
we need to form a 4-vector out of $F_{\mu\nu}$ and $\dot{x}_\mu$ that is linear in the fields $F_{\mu\nu}$ and proportional to the charge g .

The only possibility is

$$g f(\dot{x}_\mu^2) F_{\mu\nu} \dot{x}_\nu$$

But $\dot{x}_\mu^2 = -c^2$ is a constant. Choose $f(x_\mu^2) = \frac{1}{c}$

$$K_\mu = \frac{q}{c} F_{\mu\nu} \dot{x}_\nu \quad \text{is only possibility}$$

This gives force

$$\vec{F} = \frac{1}{\gamma} \vec{K}$$

$$F_i = \frac{1}{\gamma} K_i = \frac{q}{\gamma c} (F_{ij} \dot{x}_j + F_{i4} \dot{x}_4)$$

$$= \frac{q}{\gamma c} \left(\frac{\partial A_j}{\partial x_i} - \frac{\partial A_i}{\partial x_j} \right) \dot{x}_j + \frac{q}{\gamma c} (-iE_i)(ic\gamma)$$

$$= \frac{q}{\gamma c} [\epsilon_{ijk} B_k \gamma v_j] + \frac{q}{\gamma c} E_i c\gamma$$

$$= q E_i + q \epsilon_{ijk} \frac{v_j}{c} B_k$$

$$\vec{F} = q \vec{E} + q \frac{\vec{v}}{c} \times \vec{B}$$

Lorentz force is the same form in all inertial frames.
No relativistic modification is needed.

Relativistic Larmor's formula

non-relativistic $P = \frac{2}{3} \frac{q^2 [a(t_0)]^2}{c^3}$

Consider inertial frame in which charge is instantaneously at rest. Call the rest frame K .

power radiated in K is $P^0 = \frac{d\vec{E}^0(t)}{dt}$

where $\vec{E}^0$ is energy radiated. In K , the momentum density $\vec{T} = \frac{1}{4\pi c} \vec{E}^0 \times \vec{B}^0 \sim \hat{r}$ is in outward radial direction. Integrating over all directions, the radiated momentum vanishes $\vec{P} = 0$

energy-momentum is a 4-vector $(\vec{P}, i\frac{E}{c})$

To get radiated energy in original frame K we can use Lorentz transf

$$\frac{E}{c} = \gamma \left(\frac{E^0}{c} - \vec{v} \cdot \vec{P} \right) \Rightarrow E = \gamma E^0 \text{ as } \vec{P} = 0$$

and $dt = \gamma dt^0$ is time interval in K
($d\vec{r}^0 = 0$ as charge stays at origin in K)

$$\text{So } \frac{dE}{dt} = \frac{\gamma dE^0}{\gamma dt^0} = \frac{dE^0}{dt^0} \Rightarrow P = P^0$$

radiated power is Lorentz invariant!

in $\dot{K}$ we can use non-relativistic Larmor's formula since $v=0$. So

$$P = \frac{2}{3} \frac{q \dot{a}^2}{c^3}$$

$\dot{a}$ is acceleration in $\dot{K}$

To write an expression without explicitly making mention of frame $\dot{K}$, we need to find a Lorentz invariant scalar that reduces to $\dot{a}^2$ as $v \rightarrow 0$.

Only choice is α_μ^2 the 4-acceleration $\alpha_\mu = \frac{du_\mu}{ds}$

$$\alpha_\mu = \frac{du_\mu}{ds} = \gamma \frac{du_\mu}{dt} = \gamma \frac{d}{dt} (\gamma \vec{v}, ic\gamma)$$

$$\vec{\alpha} = \gamma^2 \frac{d\vec{v}}{dt} + \gamma \vec{v} \frac{d\gamma}{dt}$$

$$\alpha_4 = ic\gamma \frac{d\gamma}{dt}$$

$$\frac{d\gamma}{dt} = \frac{d}{dt} \left(\frac{1}{\sqrt{1-v^2/c^2}} \right) = \frac{\frac{\vec{v} \cdot d\vec{v}}{c^2} \frac{dt}{dt}}{(1-v^2/c^2)^{3/2}} = \frac{1}{c^2} \gamma^3 \vec{v} \cdot \vec{a}$$

$$\text{as } \vec{v} \rightarrow 0, \gamma \rightarrow 1, \frac{d\gamma}{dt} \rightarrow 0, \text{ so } \begin{cases} \vec{\alpha} \rightarrow \frac{d\vec{v}}{dt} = \vec{a} \\ \alpha_4 \rightarrow 0 \end{cases}$$

$$\alpha_\mu^2 \rightarrow |\vec{a}|^2 \text{ as desired}$$

Relativistic Larmor's formula

$$P = \frac{2}{3} \frac{q^2}{c^3} \alpha_\mu^2 = \frac{2}{3} \frac{q^2}{c^3} (\dot{u}_\mu)^2$$

$$\alpha_\mu = \left(\gamma^2 \frac{d\vec{v}}{dt} + \gamma \vec{v} \frac{d\gamma}{dt}, i c \gamma \frac{d\gamma}{dt} \right)$$

$$\frac{d\gamma}{dt} = \frac{1}{c^2} \gamma^3 \vec{v} \cdot \vec{a}$$

$$\alpha_\mu = \left(\gamma^2 \vec{a} + \gamma^4 \frac{1}{c^2} (\vec{v} \cdot \vec{a}) \vec{v}, i c \gamma^4 \frac{\vec{v} \cdot \vec{a}}{c^2} \right)$$

$$\alpha_\mu^2 = \gamma^4 a^2 + \gamma^8 \frac{(\vec{v} \cdot \vec{a})^2 v^2}{c^4} + \frac{2\gamma^6 (\vec{v} \cdot \vec{a})^2}{c^2} - \frac{\gamma^8 (\vec{v} \cdot \vec{a})^2}{c^2}$$

$$= \gamma^4 \left[a^2 + \gamma^4 \frac{(\vec{v} \cdot \vec{a})^2}{c^2} \left(\frac{v^2}{c^2} - 1 \right) + \frac{2\gamma^2 (\vec{v} \cdot \vec{a})^2}{c^2} \right]$$

$$= \gamma^4 \left[a^2 - \gamma^2 \frac{(\vec{v} \cdot \vec{a})^2}{c^2} + \frac{2\gamma^2 (\vec{v} \cdot \vec{a})^2}{c^2} \right]$$

$$\alpha_\mu^2 = \gamma^4 \left[a^2 + \gamma^2 \frac{(\vec{v} \cdot \vec{a})^2}{c^2} \right]$$

$$\text{as } \vec{v} \rightarrow 0, \alpha_\mu^2 \rightarrow a^2$$

$$\alpha_\mu^2 = \dot{a}^2 \quad \text{Lorentz invariant}$$

$\dot{a}$ = acceleration in instantaneous rest

For a charge accelerating in linear motion, $(\vec{v} \cdot \vec{a})^2 = v^2 a^2$ frame

$$\alpha_\mu^2 = \gamma^4 a^2 \left(1 + \gamma^2 \frac{v^2}{c^2} \right) = \gamma^6 a^2$$

$$P = \frac{2}{3} \frac{a^2}{c^3} \gamma^6 = \gamma^2$$

For a charge in circular motion $(\vec{v} \cdot \vec{a}) = 0$

$$\alpha_\mu^2 = \gamma^4 a^2$$

$$P = \frac{2}{3} \frac{a^2}{c^3} \gamma^4$$