

In homogeneous Maxwell's equations can be written  
in the form

$$\left[ \frac{\partial F_{\mu\nu}}{\partial x_\nu} = \frac{4\pi}{c} j_\mu \right] \Rightarrow \left[ \begin{array}{l} \vec{D} \cdot \vec{E} = 4\pi j \\ \vec{\nabla} \times \vec{B} - \frac{1}{c} \frac{\partial \vec{E}}{\partial t} = \frac{4\pi}{c} \vec{j} \end{array} \right] \quad \begin{array}{l} \mu=4 \\ \mu=1,2,3 \end{array}$$

$$= \frac{\partial}{\partial x_\nu} \left( \frac{\partial A_\nu}{\partial x_\mu} - \frac{\partial A_\mu}{\partial x_\nu} \right) = \frac{\partial}{\partial x_\mu} \left( \frac{\partial A_\nu}{\partial x_\nu} \right) - \frac{\partial^2 A_\mu}{\partial x_\nu^2}$$

" 0 "

$$\Rightarrow - \frac{\partial^2 A_\mu}{\partial x_\nu^2} = \frac{4\pi}{c} j_\mu \quad \text{agrees with previous equation for } A_\mu$$

transformation law for 2nd rank tensor  $F_{\mu\nu}$

$$F'_{\mu\nu} = \frac{\partial A'_\nu}{\partial x_\mu} - \frac{\partial A'_\mu}{\partial x_\nu} \quad \text{use } A'_\mu = \alpha_{\mu\sigma} A_\sigma$$

$$= \alpha_{\nu\lambda} \alpha_{\mu\sigma} \frac{\partial A_\lambda}{\partial x_\sigma} \quad \frac{\partial}{\partial x_\mu} = \alpha_{\mu\lambda} \frac{\partial}{\partial x_\lambda}$$

$$= \alpha_{\mu\sigma} \alpha_{\nu\lambda} \frac{\partial A_\sigma}{\partial x_\lambda}$$

$$F'_{\mu\nu} = \alpha_{\mu\sigma} \alpha_{\nu\lambda} F_{\sigma\lambda} \quad \begin{array}{l} \text{lets one find } \vec{E}' \text{ and } \vec{B}' \\ \text{if one knows } \vec{E} \text{ and } \vec{B} \end{array}$$

For  $n^{\text{th}}$  rank tensor

$$T'_{\mu_1 \mu_2 \dots \mu_n} = \alpha_{\mu_1 \nu_1} \alpha_{\mu_2 \nu_2} \dots \alpha_{\mu_n \nu_n} T_{\nu_1 \nu_2 \dots \nu_n}$$

$\frac{\partial F_{\mu\nu}}{\partial x^\nu}$  is a 4-vector: proof:

$$\frac{\partial F_{\mu\nu}}{\partial x^\nu} = \alpha_{\mu\sigma} \alpha_{\nu\lambda} \alpha_{\nu\gamma} \frac{\partial F_{\sigma\lambda}}{\partial x_\gamma}$$

but  $\alpha_{\nu\lambda} = \alpha_{\lambda\nu}^{-1}$  since inverse = transpose

$$\alpha_{\nu\lambda} \alpha_{\nu\gamma} = \alpha_{\lambda\nu}^{-1} \alpha_{\nu\gamma} = \delta_{\lambda\gamma}$$

$$\frac{\partial F_{\mu\nu}}{\partial x_\nu} = \alpha_{\mu\sigma} \frac{\partial F_{\sigma\lambda}}{\partial x_\lambda} \delta_{\lambda\gamma} = \alpha_{\mu\sigma} \frac{\partial F_{\sigma\lambda}}{\partial x_\lambda} \quad \begin{matrix} \text{transforms like} \\ \text{4-vector} \end{matrix}$$

To write the homogeneous Maxwell Equations

Construct 3rd rank co-variant tensor

$$G_{\mu\nu\lambda} = \frac{\partial F_{\mu\nu}}{\partial x_\lambda} + \frac{\partial F_{\nu\mu}}{\partial x_\lambda} + \frac{\partial F_{\mu\lambda}}{\partial x_\nu}$$

transforms as  $G_{\mu\nu\lambda} = \alpha_{\mu\alpha} \alpha_{\nu\beta} \alpha_{\lambda\gamma} G_{\alpha\beta\gamma}$

In principle  $G$  has  $4^3 = 64$  components

But can show that  $G$  is antisymmetric in exchange of any two indices

$$G_{\nu\mu\lambda} = \frac{\partial F_{\nu\mu}}{\partial x_\lambda} + \frac{\partial F_{\mu\nu}}{\partial x_\lambda} + \frac{\partial F_{\mu\lambda}}{\partial x_\nu}$$

$$= -\frac{\partial F_{\mu\nu}}{\partial x_\lambda} - \frac{\partial F_{\nu\lambda}}{\partial x_\mu} - \frac{\partial F_{\lambda\mu}}{\partial x_\nu} \quad \text{as } F \text{ anti-symmetric}$$

$$= -G_{\mu\nu\lambda}$$

Also  $G_{\mu\nu\lambda} = 0$  if any two indices are equal

⇒ only 4 independent components

$$G_{12}, G_{13}, G_{23}, G_{123}$$

all other components either vanish or are ± one of the above.

The 4 homogeneous Maxwell Equations:

$$\vec{\nabla} \cdot \vec{B} = 0, \quad \vec{\nabla} \times \vec{E} + \frac{1}{c} \frac{\partial \vec{B}}{\partial t} = 0$$

can be written as

$$\boxed{G_{\mu\nu\lambda} = 0}$$

to see, substitute in definition of  $G$  the definition of  $F$ .

$$G_{\mu\nu\lambda} = \underbrace{\frac{\partial^2 A_v}{\partial x_\lambda \partial x_\mu} - \frac{\partial^2 A_\mu}{\partial x_\lambda \partial x_v}}_{\text{cancel}} + \underbrace{\frac{\partial^2 A_\mu}{\partial x_\nu \partial x_\lambda} - \frac{\partial^2 A_\lambda}{\partial x_\nu \partial x_\mu}}_{\text{cancel}} + \underbrace{\frac{\partial^2 A_\lambda}{\partial x_\mu \partial x_\nu} - \frac{\partial^2 A_v}{\partial x_\mu \partial x_\lambda}}_{\text{cancel}}$$

all terms cancel in pairs

$$= 0$$

$$G_{123} = 0 \Rightarrow \vec{\nabla} \cdot \vec{B} = 0$$

$$G_{12} = -i \left[ \vec{\nabla} \times \vec{E} + \frac{\partial \vec{B}}{\partial t} \right]_z = 0 \quad \text{3 component Faraday's law}$$

Another way to write homogeneous Maxwell Equations

Define  $\epsilon_{\mu\nu\lambda\sigma} = \begin{cases} +1 & \text{if } \mu\nu\lambda\sigma \text{ is even permutation} \\ & \text{of } 1234 \\ -1 & \text{if } \mu\nu\lambda\sigma \text{ is odd permutation} \\ & \text{of } 1234 \\ 0 & \text{otherwise} \end{cases}$

4-d Levi-Civita symbol

$$\tilde{F}_{\mu\nu} = \frac{1}{2!} \epsilon_{\mu\nu\lambda\sigma} F_{\lambda\sigma} \quad \text{pseudo-tensor}$$

$$= \begin{pmatrix} 0 & -E_3 & E_2 & -iB_1 \\ E_3 & 0 & -E_1 & -iB_2 \\ -E_2 & E_1 & 0 & -iB_3 \\ iB_1 & iB_2 & iB_3 & 0 \end{pmatrix} \quad \begin{array}{l} \text{has wrong sign} \\ \text{under parity} \\ \text{transf} \end{array}$$

$$\frac{\partial \tilde{F}_{\mu\nu}}{\partial x_\nu} = 0 \quad \text{gives homogeneous Maxwell equations}$$

$$\frac{1}{2} F_{\mu\nu} F_{\mu\nu} = B^2 - E^2 \quad \text{Lorentz invariant scalars}$$

$$-\frac{1}{4} F_{\mu\nu} \tilde{F}_{\mu\nu} = \vec{B} \cdot \vec{E}$$

If  $\vec{E} \perp \vec{B}$  and  $|\vec{E}| = |\vec{B}|$  in one frame of reference, then it is so in all frames of reference.  
 $(\vec{E} \cdot \vec{B} = 0, |\vec{B}|^2 - |\vec{E}|^2 = 0)$   
satisfied by EM waves in the vacuum

If  $\vec{E} \cdot \vec{B} = 0$  in one frame, and  $E^2 > B^2$ , then there exists a frame in which  $B' = 0$ . If in one frame  $\vec{E} \cdot \vec{B} = 0$  and  $B^2 > E^2$ , then there exists a frame in which  $E' = 0$ .

From  $F_{\mu\nu} = \partial_\mu \partial_\nu F_{0x}$  we can get  
lengthy transf for  $\vec{E}$  and  $\vec{B}$

For a transformation from  $K$  to  $K'$  with  $K'$  moving  
with  $v$  along  $x$ , with respect to  $K$ ,

$$E'_1 = E_1$$

$$B'_1 = B_1$$

$$E'_2 = \gamma(E_2 - \frac{v}{c} B_3)$$

$$B'_2 = \gamma(B_2 + \frac{v}{c} E_3)$$

$$E'_3 = \gamma(E_3 + \frac{v}{c} B_2)$$

$$B'_3 = \gamma(B_3 - \frac{v}{c} E_2)$$

### Kinematics

"dot" is  $\frac{d}{ds}$

$$\text{4-momentum } p_\mu = m \dot{x}_\mu = m \dot{u}_\mu = (m\gamma \vec{v}, \gamma mc^2)$$

$$p_\mu^2 = m^2 \dot{u}_\mu^2 = -m^2 c^2$$

$$\text{4-force } K_\mu = (\vec{K}, iK_0) \quad \text{"Minkowski force"}$$

Newton's 2nd law

$$m \frac{d^2 x_\mu}{ds^2} = K_\mu$$

$$\Rightarrow m \frac{d u_\mu}{ds} = \frac{d p_\mu}{ds} = K_\mu$$

$$p_\mu^2 = -m^2 c^2 \Rightarrow \frac{d}{ds} (p_\mu^2) = p_\mu \frac{dp_\mu}{ds} = p_\mu K_\mu = 0$$

$$\Rightarrow m\gamma \vec{v} \cdot \vec{K} - mc\gamma K_0 = 0 \quad \text{or}$$

$$K_0 = \frac{\vec{v}}{c} \cdot \vec{K}$$

Define the usual 3-force by

$$\frac{d\vec{p}}{dt} = \vec{F}$$

(we identify Newtonian momentum  $\vec{p}$  with the space components of  $P_\mu$ )

$$\frac{d\vec{p}}{ds} = \vec{K} \text{ and } \frac{d\vec{p}}{ds} = \gamma \frac{d\vec{p}}{dt} = \gamma \vec{F} \Rightarrow \vec{K} = \gamma \vec{F}$$

$$K_0 = \gamma \vec{v} \cdot \vec{F}$$

Consider 4<sup>th</sup> component of Newton's eqn

$$\frac{m d u_4}{ds} = m \frac{d(\gamma c)}{ds} = i K_0 = i \gamma \frac{\vec{v}}{c} \cdot \vec{F}$$

$$d(mr) = \gamma \frac{\vec{v}}{c^2} \cdot \vec{F} ds = dt \frac{\vec{v} \cdot \vec{F}}{c^2} = d\vec{r} \cdot \vec{F}$$

i Work-energy theorem:  $d(m\gamma c^2) = d\vec{r} \cdot \vec{F}$  = work done

$\Rightarrow d(mrc^2)$  is change in kinetic energy

$E = m\gamma c^2$  is relativistic kinetic energy

$\vec{p}_\mu = (\vec{p}, \frac{E}{c})$	$\vec{p} = m\gamma \vec{v}$
	$E = m\gamma c^2$

$$E = \frac{mc^2}{\sqrt{1 - \frac{v^2}{c^2}}} \approx mc^2 \left(1 + \frac{1}{2} \frac{v^2}{c^2}\right) = mc^2 + \frac{1}{2} mv^2$$

↑      ↑  
small  $\frac{v}{c}$

rest mass energy      non-rel kinetic energy

$$\frac{dp_\mu}{ds} = k_\mu \therefore$$

relativistic analog of Newton's 3<sup>rd</sup> law  
as well as law of conservation of energy

## Lorentz force

$$\frac{dp_\mu}{ds} = K_\mu$$

What is the  $K_\mu$  that represents the Lorentz force  
and how can we write it in ~~relative~~ Lorentz  
covariant way?

$K_\mu$  should depend on the fields  $F_{\mu\nu}$   
and the particles trajectory  $x_\mu$

$$\text{as } \vec{v} \rightarrow 0 \quad \vec{K} = q \vec{E}$$

$K_\mu$  can't depend directly on  $x_\mu$  as should be  
indep of origin of coords. So can  
depend only on  $\overset{\circ}{x}_\mu, \overset{\circ}{x}_\mu$ , etc.

as  $v \rightarrow 0$ ,  $K$  does not depend on the  
acceleration, so  $K$  does not depend on  $\overset{\circ}{x}_\mu$

$K_\mu$  only depends on  $F_{\mu\nu}$  and  $\overset{\circ}{x}_\mu$   
we need to form a 4-vector out of  
 $F_{\mu\nu}$  and  $\overset{\circ}{x}_\mu$  that is linear in the fields  $F_{\mu\nu}$   
and proportional to the charge  $q$ .

The only possibility is

$$q f(\overset{\circ}{x}_\mu^2) F_{\mu\nu} \overset{\circ}{x}_\nu$$

But  $\dot{x}_\mu^2 = -c^2$  is a constant. Choose  $f(x_\mu^2) = \frac{1}{2}$

$K_\mu = \frac{g}{c} F_{\mu\nu} \dot{x}_\nu$  is only possibility

This gives force

$$\vec{F} = \frac{1}{c} \vec{K}$$

$$F_i = \frac{1}{c} K_i = \frac{g}{c} (F_{ij} \dot{x}_j + F_{i4} \dot{x}_4)$$

$$= \frac{g}{c} \left( \frac{\partial A_j - \partial A_c}{\partial x_i} \right) \dot{x}_j + \frac{g}{c} (-iE_i)(ic\gamma)$$

$$= \frac{g}{c} [ \epsilon_{ijk} B_k \gamma v_j ] + \frac{g}{c} E_i c \gamma$$

$$= g E_i + g \epsilon_{ijk} \frac{v_j}{c} B_k$$

$$\vec{F} = g \vec{E} + g \vec{v} \times \vec{B}$$

Lorentz force is the same form in all inertial frames.  
No relativistic modification is needed.

## Relativistic Larmor's formula

$$\text{non-relativistic } P = \frac{2}{3} \frac{g^2 [\text{alt o}]}{c^3}$$

Consider inertial frame in which charge is instantaneously at rest. Call this rest frame  $K'$ .

$$\text{power radiated in } K' \text{ is } \dot{P} = \frac{d\overset{\circ}{E}(t)}{dt}$$

where  $\overset{\circ}{E}$  is energy radiated. In  $K'$ , the momentum density  $\overset{\circ}{T} = \frac{1}{4\pi c} \overset{\circ}{E} \times \overset{\circ}{B} \sim \overset{\circ}{F}$  is in outward radial direction. Integrating over all directions, the radiated momentum vanishes  $\overset{\circ}{P} = 0$

energy-momentum is a 4-vector  $(\overset{\circ}{P}, \frac{i}{c} \overset{\circ}{E})$

To get radiated energy in original frame  $K$  we can use Lorentz transform

$$\frac{\overset{\circ}{E}}{c} = \gamma \left( \frac{\overset{\circ}{E}}{c} - \frac{\vec{v}}{c} \cdot \overset{\circ}{P} \right) \Rightarrow \overset{\circ}{E} = \gamma \overset{\circ}{E} \text{ as } \overset{\circ}{P} = 0$$

and  $dt = \gamma d\overset{\circ}{t}$  is time interval in  $K$

$(d\overset{\circ}{t} = 0 \text{ as charge stays at origin in } K')$

$$\text{So } \frac{d\overset{\circ}{E}}{dt} = \frac{\gamma d\overset{\circ}{E}}{\gamma dt} = \frac{d\overset{\circ}{E}}{dt} \Rightarrow \dot{P} = \overset{\circ}{P}$$

radiated power is Lorentz invariant!

in  $\hat{K}$  we can use non-relativistic Larmor's formula since  $v=0$ . So

$$P = \frac{2}{3} \frac{q^2 a^2}{c^3}$$

$\ddot{a}$  is acceleration in  $\hat{K}$

To write an expression with out explicitly making mention of frame  $\hat{K}$ , we need to find a Lorentz invariant scalar that reduces to  $a^2$  as  $v \rightarrow 0$ .

Only choice is  $\alpha_\mu^2$  the 4-acceleration  $\alpha_\mu = \frac{du_\mu}{ds}$

$$\alpha_\mu = \frac{du_\mu}{ds} = \gamma \frac{du_\mu}{dt} = \gamma \frac{d}{dt} (\gamma \vec{v}, cc\gamma)$$

$$\vec{\alpha} = \gamma^2 \frac{d\vec{v}}{dt} + \gamma \vec{v} \frac{d\gamma}{dt}$$

$$\alpha_4 = cc\gamma \frac{d\gamma}{dt}$$

$$\frac{d\gamma}{dt} = \frac{d}{dt} \left( \frac{1}{\sqrt{1-v^2/c^2}} \right) = \frac{\vec{v} \cdot \frac{d\vec{v}}{dt}}{(1-v^2/c^2)^{3/2}} = \frac{1}{c^2} \gamma^3 \vec{v} \cdot \vec{a}$$

$$\text{as } \vec{v} \rightarrow 0, \gamma \rightarrow 1, \frac{d\gamma}{dt} \rightarrow 0, \text{ so } \left\{ \begin{array}{l} \vec{\alpha} \rightarrow \frac{d\vec{v}}{dt} = \vec{a} \\ \alpha_4 \rightarrow 0 \end{array} \right.$$

$$\alpha_\mu^2 \rightarrow |\vec{a}|^2 \text{ as desired}$$

Relativistic Larmor's formula

$$P = \frac{2}{3} \frac{q^2}{c^3} \alpha_\mu^2 = \frac{2}{3} \frac{q^2}{c^3} (\ddot{u}_\mu)^2$$

$$\alpha_\mu = \left( \gamma^2 \frac{d\vec{v}}{dt} + \gamma \vec{v} \frac{d\gamma}{dt} \rightarrow c\gamma \frac{d\gamma}{dt} \right)$$

$$\frac{d\gamma}{dt} = \frac{1}{c^2} \gamma^3 \vec{v} \cdot \vec{a}$$

$$\alpha_\mu = \left( \gamma^2 \vec{a} + \gamma^4 \frac{1}{c^2} (\vec{v} \cdot \vec{a}) \vec{v} \rightarrow \frac{c\gamma^4 \vec{v} \cdot \vec{a}}{c^2} \right)$$

$$\begin{aligned}\alpha_\mu^2 &= \gamma^4 a^2 + \gamma^8 \frac{(\vec{v} \cdot \vec{a})^2 v^2}{c^4} + \frac{2\gamma^6 (\vec{v} \cdot \vec{a})^2}{c^2} - \frac{\gamma^8 (\vec{v} \cdot \vec{a})^2}{c^2} \\ &= \gamma^4 \left[ a^2 + \gamma^4 \frac{(\vec{v} \cdot \vec{a})^2}{c^2} \left( \frac{v^2}{c^2} - 1 \right) + \frac{2\gamma^2 (\vec{v} \cdot \vec{a})^2}{c^2} \right] \\ &= \gamma^4 \left[ a^2 - \gamma^2 \frac{(\vec{v} \cdot \vec{a})^2}{c^2} + \frac{2\gamma^2 (\vec{v} \cdot \vec{a})^2}{c^2} \right]\end{aligned}$$

$$\alpha_\mu^2 = \gamma^4 \left[ a^2 + \gamma^2 \frac{(\vec{v} \cdot \vec{a})^2}{c^2} \right]$$

$$\text{as } \vec{v} \rightarrow 0 \rightarrow \alpha_\mu^2 \rightarrow a^2$$

$\alpha_\mu^2 = a^2$  Lorentz invariant  
 $a$  = acceleration in  
instantaneous rest

For a charge accelerating  
in linear motion,  $\alpha_\mu^2 (\vec{v} \cdot \vec{a})^2 = v^2 a^2$

$$\alpha_\mu^2 = \gamma^4 a^2 \left( 1 + \underbrace{\gamma^2 \frac{v^2}{c^2}}_{= \gamma^2} \right) = \gamma^6 a^2$$

$$P = \frac{2\gamma a^2}{3c^3} \gamma^6$$

For a charge in circular motion  $(\vec{v} \cdot \vec{a}) = 0$

$$\alpha_\mu^2 = \gamma^4 a^2$$

$$P = \frac{2\gamma a^2}{3c^3} \gamma^4$$